

CONVEGNO ALIG - PISA 13/05/2011

NUOVE TECNOLOGIE RADAR COLLAUDO MONITORAGGIO E INDAGINI NON INVASIVE PER MANUFATTI

Interventi Relatori

Breve presentazione di IDS Ingegneria dei Sistemi SpA e della Divisione Georadar

Ing. Francesco Coppi (IDS)

Principi teorici della tecnologia interferometrica

Dott. Paolo Farina (IDS)

Le applicazioni della tecnologia interferometrica da terra ed alcuni casi di studio M, L, S

Prof. Carmelo Gentile (Politecnico di Milano)

La tecnologia radar interferometrica da terra applicata ai ponti: innovazione, vantaggi ed esempi applicativi

Dott. Paolo Papeschi (IDS)

Principi teorici della tecnologia GPR; le configurazioni georadar di IDS specializzate per il controllo NDT di ponti e strade. Ris Hi Bright, Ris Hi-Pave

Parte 1°

Parte 2°

Parte 3°

Dott. P. Papeschi Dott. G. Manacorda Dott. A. Simi (IDS)

La tecnologia georadar per la diagnostica non distruttiva dei manufatti

Parte 1°

Parte 2°

Foto Convegno ALIG - PISA



Inviare a alig@associazionealig.it un messaggio di posta elettronica contenente domande o commenti su questo sito Web.

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CONVEGNO ALIG

13 maggio 2011 ore 9⁰⁰-18⁰⁰



sede del convegno

P I S A

Loc. Montacchiello via E. Calabresi, 24

NUOVE TECNOLOGIE RADAR

**COLLAUDO. MONITORAGGIO E
INDAGINI NON INVASIVE PER MANUFATTI**

con il patrocinio :

ORDINE GEOLOGI REGIONE TOSCANA



con la collaborazione :

IDS Ingegneria dei Sistemi SpA



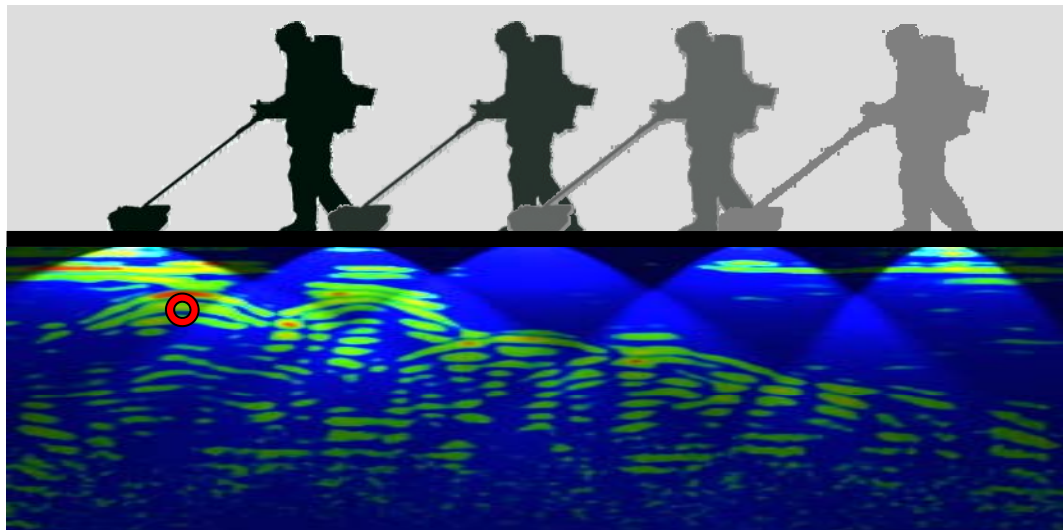
POLITECNICO DI MILANO

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Breve presentazione di IDS Ingegneria dei Sistemi SpA e della Divisione Georadar

Innovative radar technology for engineering, environment and security





IDS Ingegneria dei Sistemi S.p.A.

- Founded in 1980
- About 380 employed
- Main expertise in Applied Electromagnetics, Radar Systems, System Engineering

The offices:

- Headquarter in Pisa - Montacchiello
- GeoRadar office in Pisa - Montacchiello
- Branch office in Rome
- Subsidiary in Brisbane (IDS-Australasia)
- Subsidiary in Southampton (IDS-UK)
- Subsidiary in Sao Paulo (IDS-Brazil)
- Subsidiary in Montreal (IDS-North America)



Organization



IDS UK | IDS Brazil | IDS North America | IDS Australasia

Local offices across the world provide expertise, services and 24/7 support for industries with time, quality and cost critical requirements. Highly trained agents and distributors worldwide extend the IDS network over 40 countries.

Customers



Naval Division



Aeronautical Division



Aeronavigation Division



Georadar Division

IDS Laboratories

Computer Science & Information Technology Lab.

EM Design
Framework
Lab.

Avionics
Lab.

RADAR
Systems Lab.

Air Navigation
Systems Lab.

Signatures
Technologies
Lab.

Measurements & Trials Lab.

Naval Division

Mission

*To provide Navies and Industries with
an **innovative design capability**
aimed at optimizing ship EM
performances and signature control.*

That means:

**Maximizing mission
success probability**



Aeronautical Division

Mission

To support governmental authorities and aeronautic industry with product and services aimed at improving design process' efficiency, especially in conceiveng stealth aircrafts .

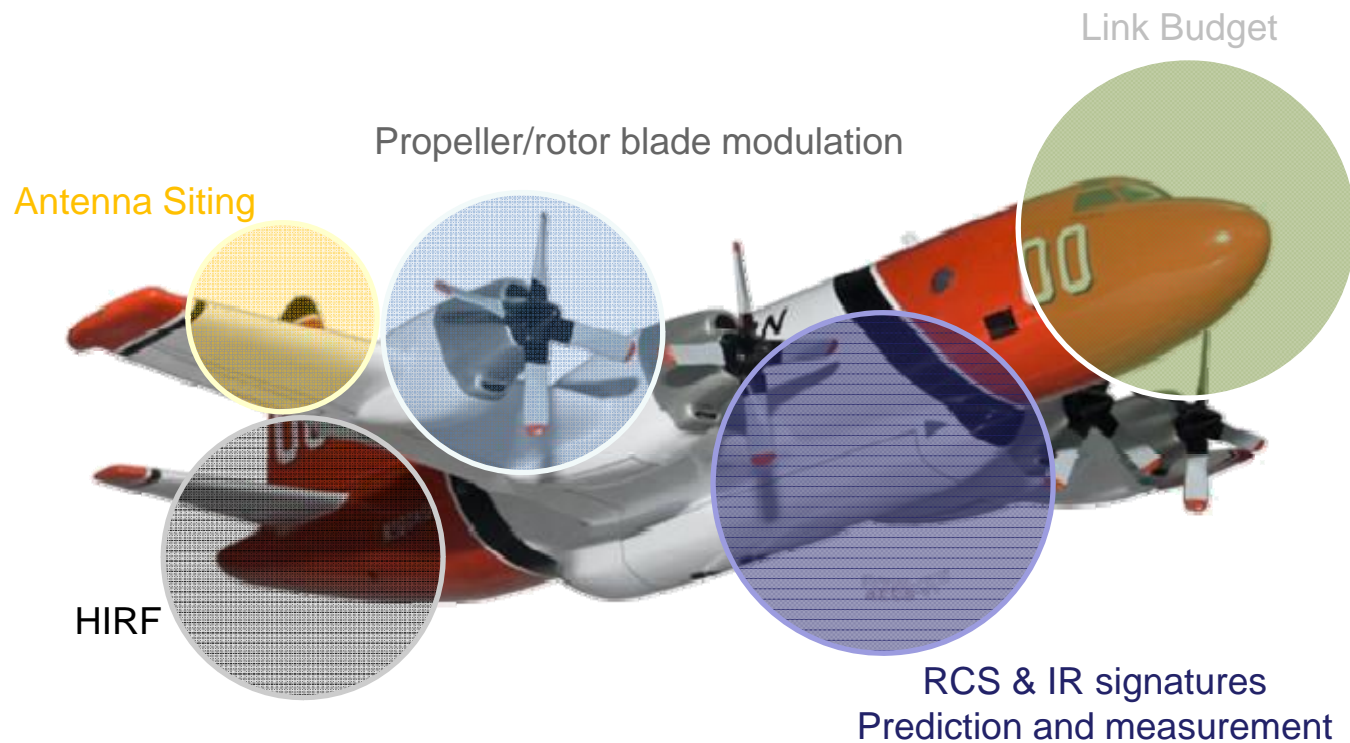
To provide also flight control systems and avionics design services for fixed/rotary wing platforms and UAVs.



Aeronautical Division

Analysis and EM design

EM design means to deal with the following matters:



*A **different approach** in the design phase, integrating EM simulation and innovative prediction tools ensure the attainment of the **desired performances**.*

Aeronautical Division

Main programs



Air Navigation Division

Mission, product

Delivering systems and performing services for the air transport market segment and specifically targeted to Air Navigation Service Providers and Aviation Authorities (Civil, Military)

Systems are mainly **built and maintained in house** with minor off-the-shelf components from third party providers

Operating worldwide through and with the four IDS subsidiaries and through a number of dealers/partners

IDS Aeronavigation Systems are now installed in about **30 countries** for a total of **40 accounts**

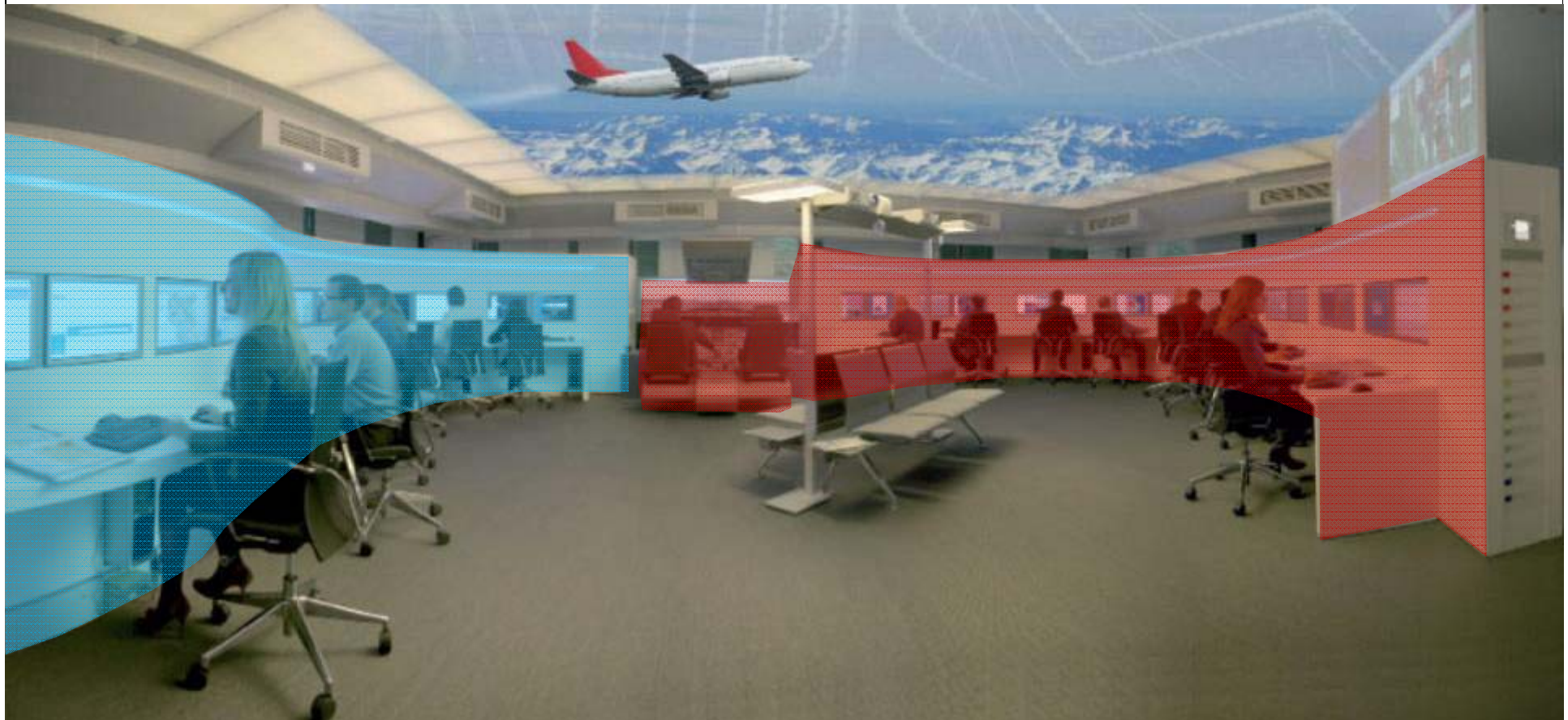
“..IDS has the largest installed base of any supplier in the field, including four of the five most influential operators in air navigation. Customers, including all the organisations represented here and more, range from large standard setting ANSPs on four continents to specialist service providers...”

Airnavigation Division

Operational testing room

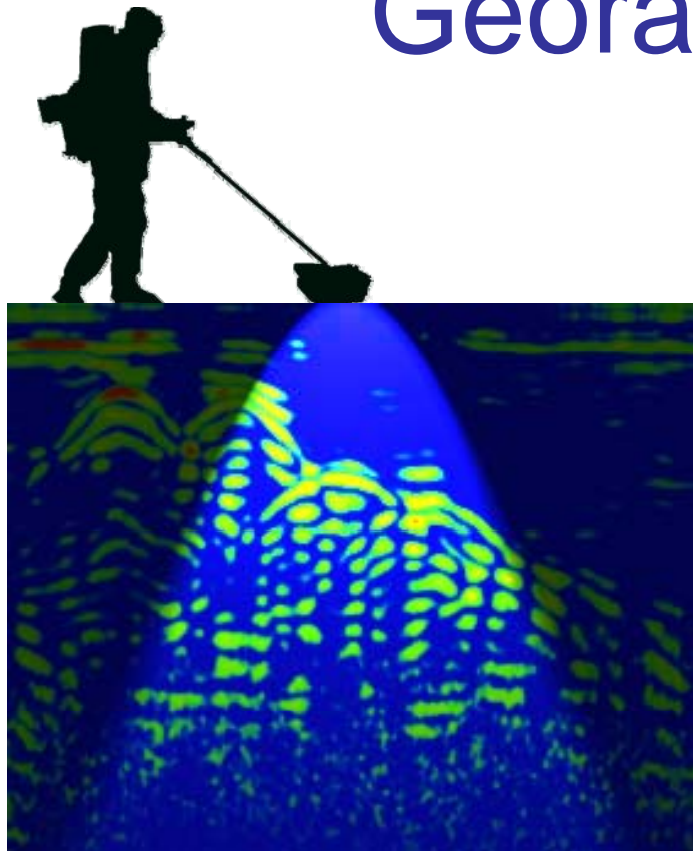
AIS Production Systems
(Information Management and Data Distribution)

Engineering Systems
(Design and Validation)



Georadar Division

Mission



*To transfer IDS competencies in the radar field and system engineering to “low power” **radar systems for engineering, environmental and security applications***

Pursuing the product excellence through the creation of application-specific, innovative products, able to bring valuable benefits to the user

IDS GeoRadar Division

- ***Leader nei Sistemi GPR multi-canale e multi-frequenza per applicazioni specifiche***
- IDS ha iniziato a studiare la tecnologia GPR sin dal 1991, su incarico di Telecom Italia. Il Progetto Socrate richiedeva infatti lo sviluppo di soluzioni GPR specifiche per migliorare le prestazioni di localizzazione dei Sottoservizi
- IDS è stata la prima ad introdurre nel mercato GPR i sistemi ad array multi-canale e multi-frequenza, migliorando in maniera decisiva le prestazioni di mappatura dei Sottoservizi
- Dal 1999 IDS ha iniziato l'introduzione su scala mondiale dei suoi sistemi
- IDS è ad oggi uno dei principali costruttori mondiali di soluzioni GPR, differenziandosi per lo sviluppo di soluzioni altamente specializzate per applicazione
- ***Tecnologia Radar Interferometrica per il monitoraggio del territorio e delle strutture***
- Nel 2007 IDS introduce sul mercato il primo radar interferometrico per il monitoraggio dei fronti instabili e dei movimenti/vibrazioni di grandi strutture

Linee di prodotti

Ground Penetrating Radar (GPR):

*Innovative, application-specific products
for geo-applications*



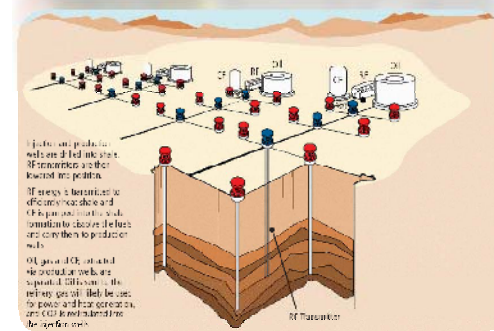
Interferometric Radar:

*A new approach, through radar
interferometric technology, for monitoring
ground and structure displacements*



Solutions:

*Provide high-level, specialized solutions
and services, based on the Division
technology and know-how*



La nostra presenza nei mercati internazionali



PROGRAMMA DELLA GIORNATA

9.30 – 10.00	Ing. Francesco Coppi (IDS)	Principi teorici della tecnologia interferometrica
10.00 - 10.30	Dott. Paolo Farina (IDS)	Le applicazioni della tecnologia interferometrica da terra ed alcuni casi di studio M, L , S
10.30 – 10.45	Pausa Caffè	
10.45 – 11.45	Prof. Carmelo Gentile (Politecnico di Milano)	La tecnologia radar interferometrica da terra applicata ai ponti: innovazione, vantaggi ed esempi applicativi
11.45 – 12.30	Dott. Paolo Papeschi (IDS)	Principi teorici della tecnologia GPR; le configurazioni georadar di IDS specializzate per il controllo NDT di ponti e strade. Ris Hi Bright, Ris Hi-Pave.
12.30-13.00	Discussione	
13.15	Pranzo	
14.15 – 14.30	Visita ai laboratori di IDS	
14.45 – 15.15	Dott. Cristian Altobelli (IDS)	Dimostrazione IBIS S
15.20 – 16.00	Ing. Alessandro Simi Dott. Valter Baroncini	Dimostrazione con Hi-Bright
16.00	Saluti finali e ringraziamenti	

IBIS Image by Interferometric Survey

Working Principles



Summary

- **IBIS Introduction**
- **Radar Basics**
- **Stepped Frequency Continuous Wave (SFCW)**
- **Synthetic Aperture Radar Technique (SAR)**
- **Differential Interferometry Technique**
- **Conclusion**

IBIS Introduction

IBIS is a Stepped-Frequency Continuous Wave (SFCW) coherent radar with SAR and interferometric capabilities, dedicated to remote monitoring of static or dynamic displacement such as terrain deformation or structure vibrations.

For Static monitoring



IBIS – L

For Dynamic and Static monitoring



IBIS – S

Summary

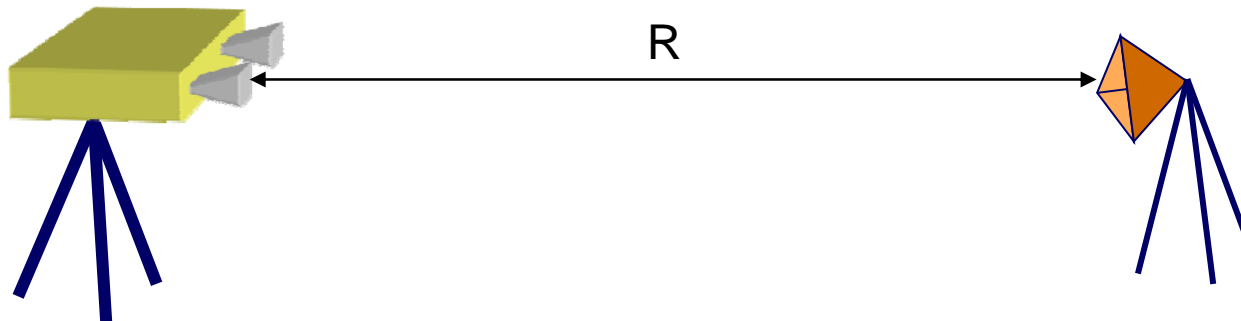
- IBIS Introduction
- **Radar Basics**
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- Differential Interferometry Technique
- Conclusions

Radar Basics

Radar stands for:

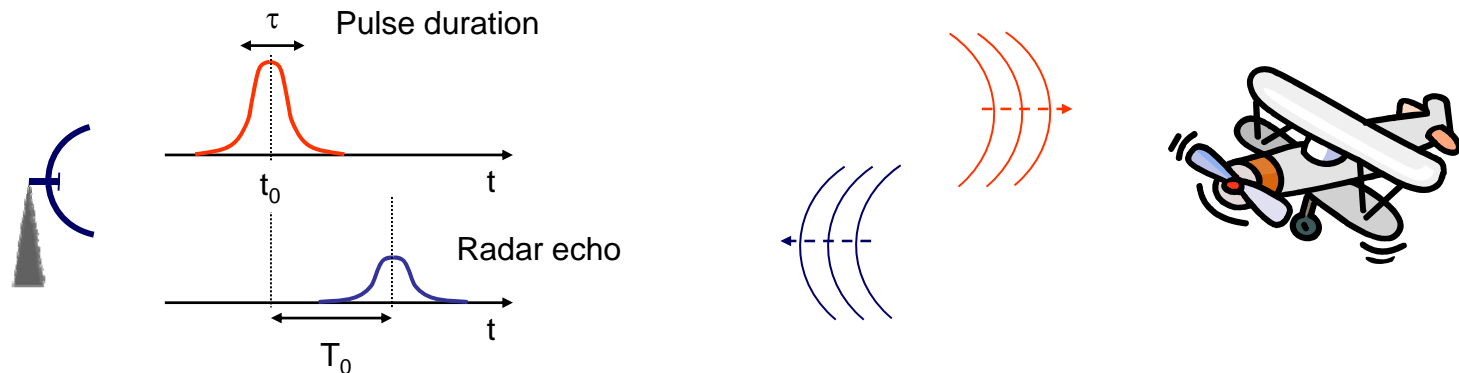
RAdio **D**etection **A**nd **R**anging

An instrument able to detect the presence of object and able to measure the distance between the apparatus and an object



Pulse Radar

Pulse Radar working principle

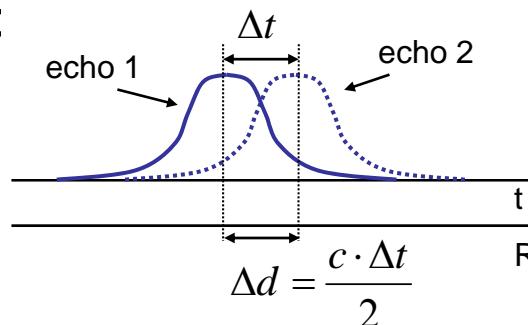


Time space equivalence for range determination:

Echo delay T_0 $\longrightarrow R_0 = \frac{c \cdot T_0}{2}$

Range resolution concept:

$$\Delta R = \frac{c \cdot \tau}{2}$$

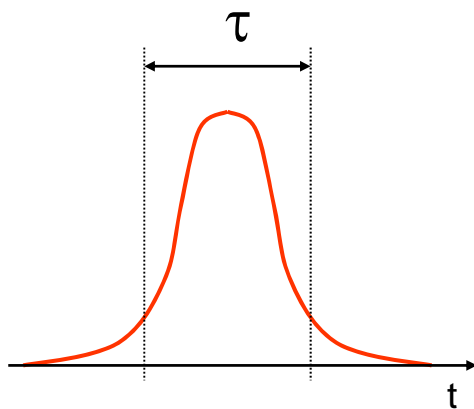


The radar is able to resolve two targets if:

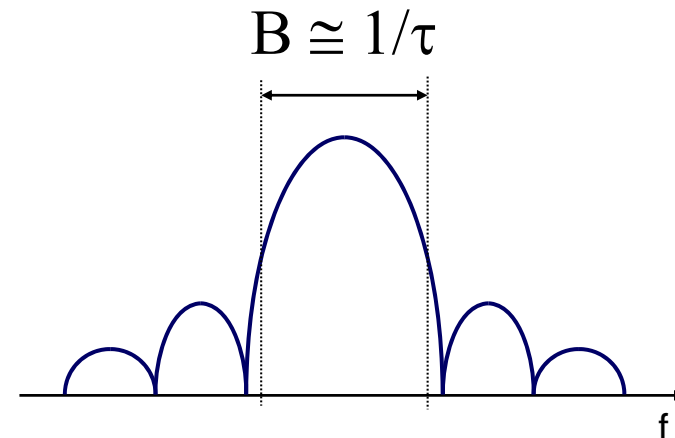
$$\Delta t > \tau \iff \Delta d > \Delta R$$

Time-Frequency Duality

Time Domain



Frequency Domain



The range resolution can be expressed either in term of pulse duration or pulse bandwidth:

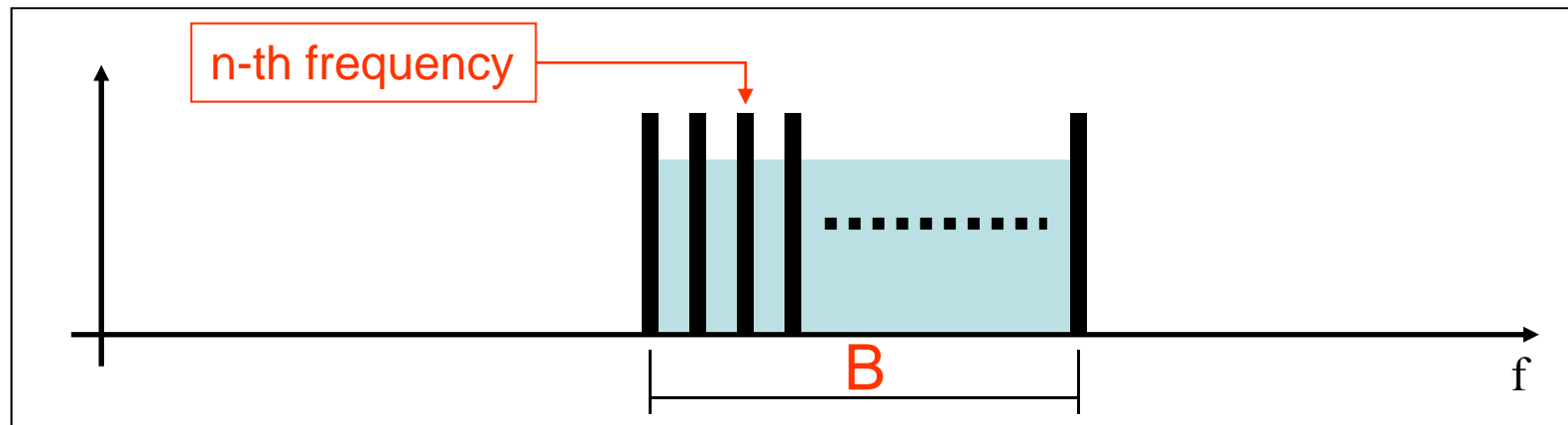
$$\Delta R = \frac{c\tau}{2} = \frac{c}{2B}$$

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Stepped Frequency Continuous Wave (SFCW)

The system transmits a **sweep** consisting of N electromagnetic waves of T_{tone} duration (*Continuous Wave*) at different frequencies (*Stepped Frequency*).

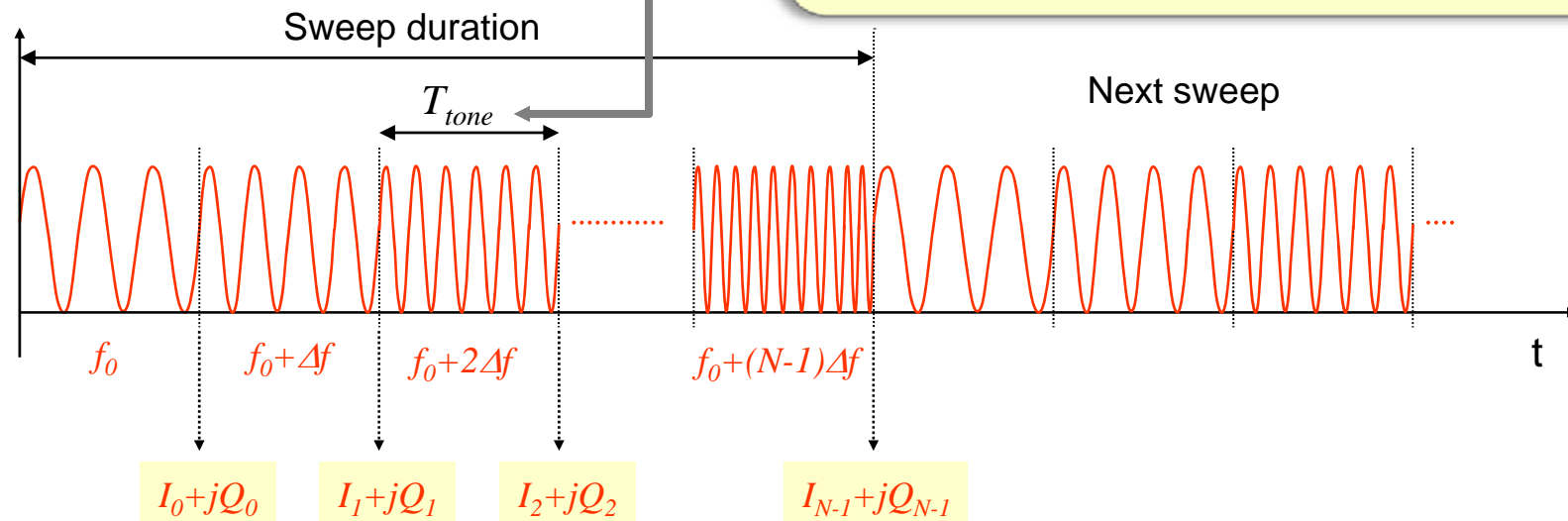


The SFCW technique allows IBIS to obtain the same performance of a synthetic pulse of duration $\tau = \frac{1}{B}$ to which corresponds a **range resolution** of $\Delta R = \frac{c \cdot \tau}{2}$

IBIS provides a Range resolution up to 0.5m

Stepped Frequency Continuous Wave (SFCW)

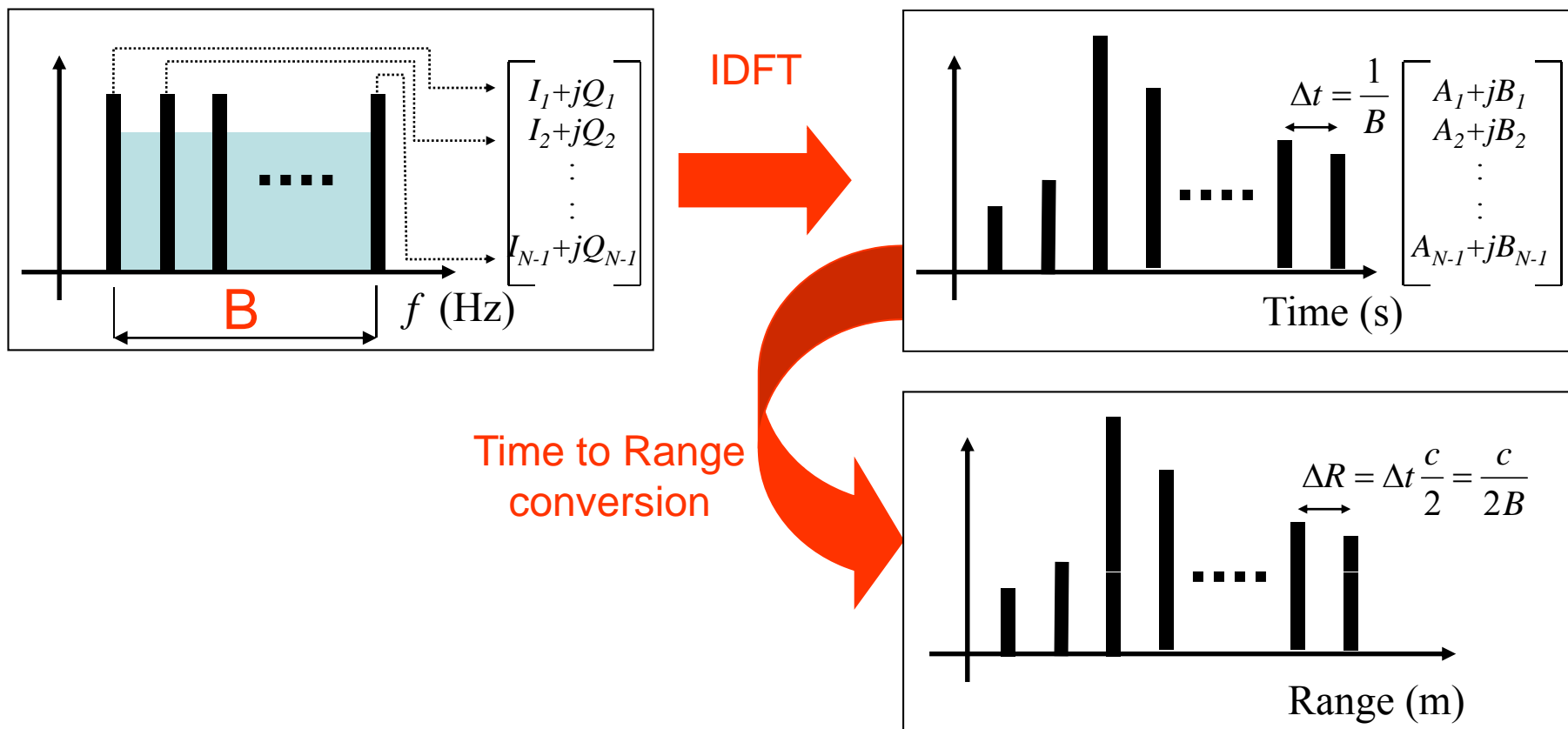
Time representation of a SFCW signal:



At the end of a sweep IBIS has acquired a vector of complex numbers that corresponds to a **frequency sampling of the observed scenario**.

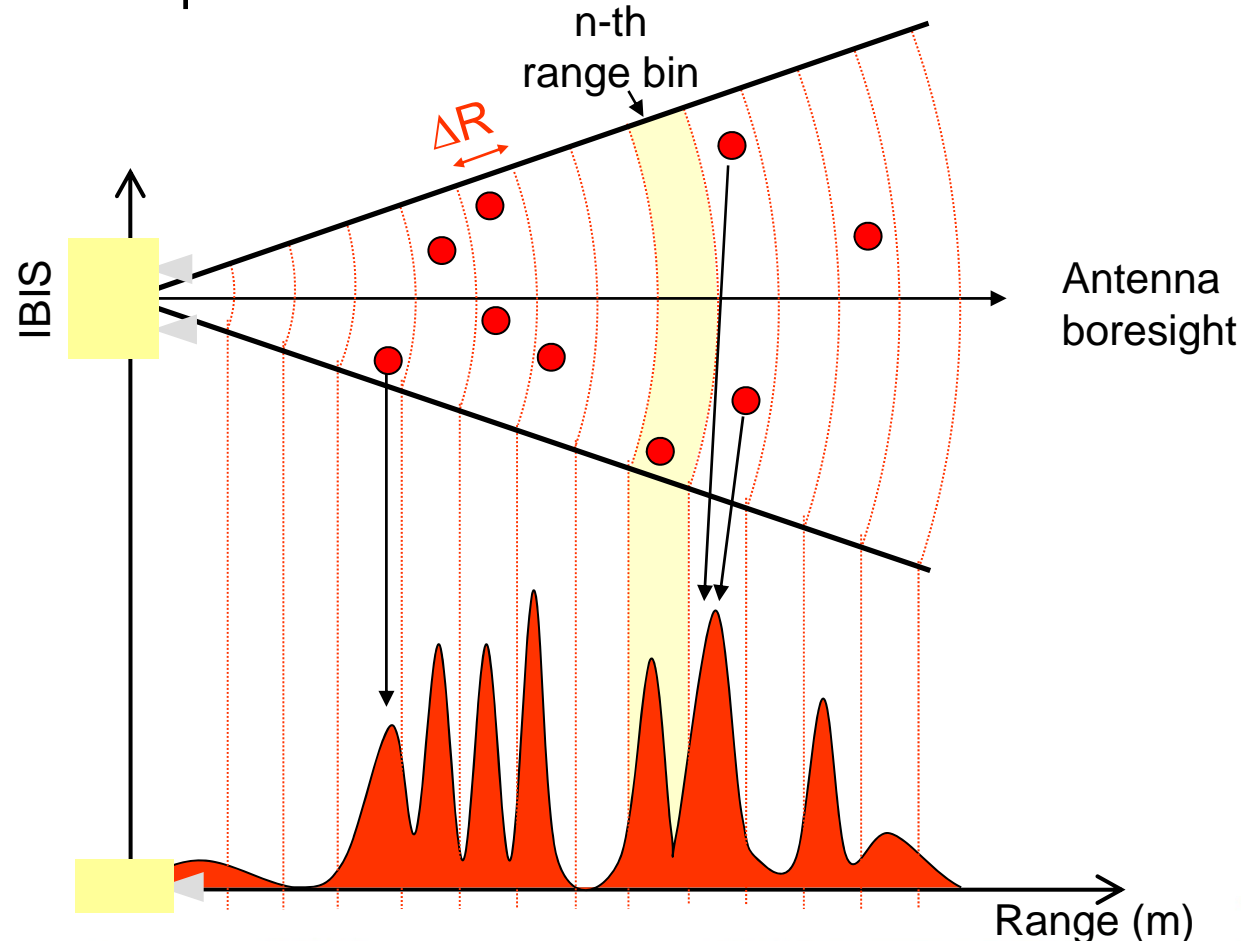
Stepped Frequency Continuous Wave (SFCW)

The data elaboration that enables to synthesize the impulse is a Inverse Discrete Fourier Transform (IDFT) of the samples acquired.



Stepped Frequency Continuous Wave (SFCW)

Through SFCW IBIS builds a one dimensional image, called **Range Profile**, where the targets in the illuminated scenario are resolved with a **range resolution** independent from the distance.

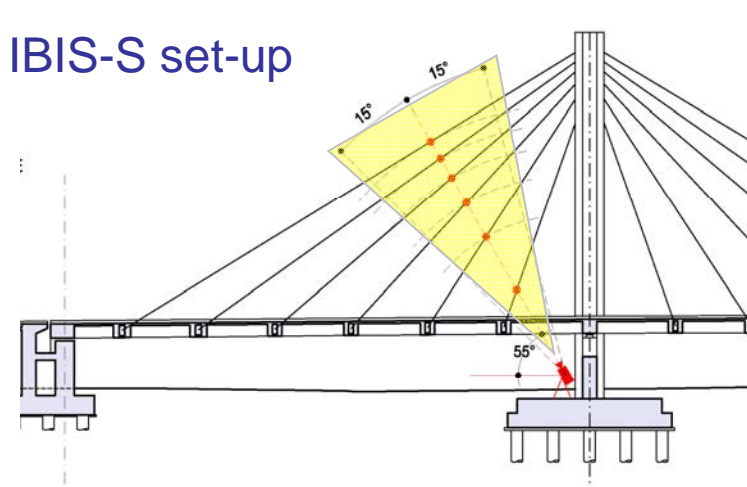


Range Profile Example



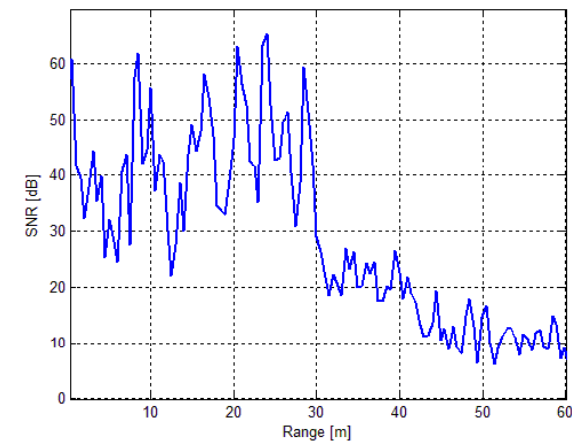
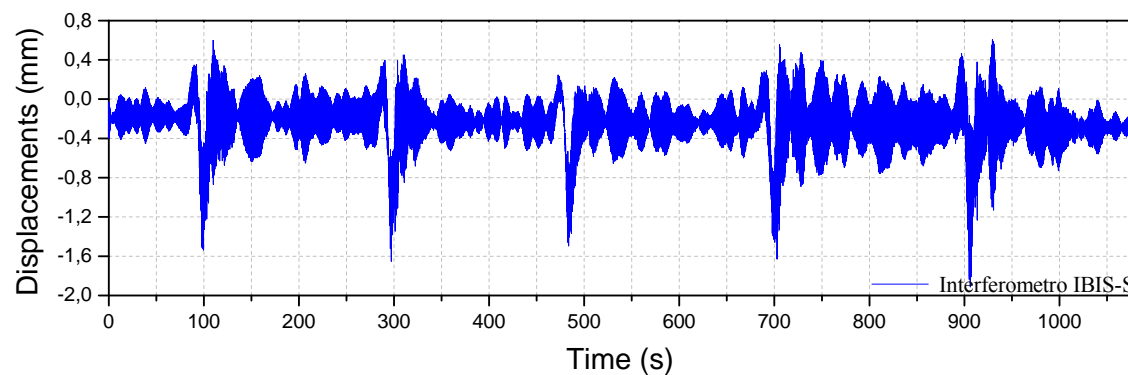
Olginate bridge (Italy)

IBIS-S set-up



Range Profile

Displacement graph



Summary

- IBIS Introduction
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- **Synthetic Aperture Radar Technique (SAR)**
- Differential Interferometry Technique
- Conclusions

Synthetic Aperture Radar (SAR)

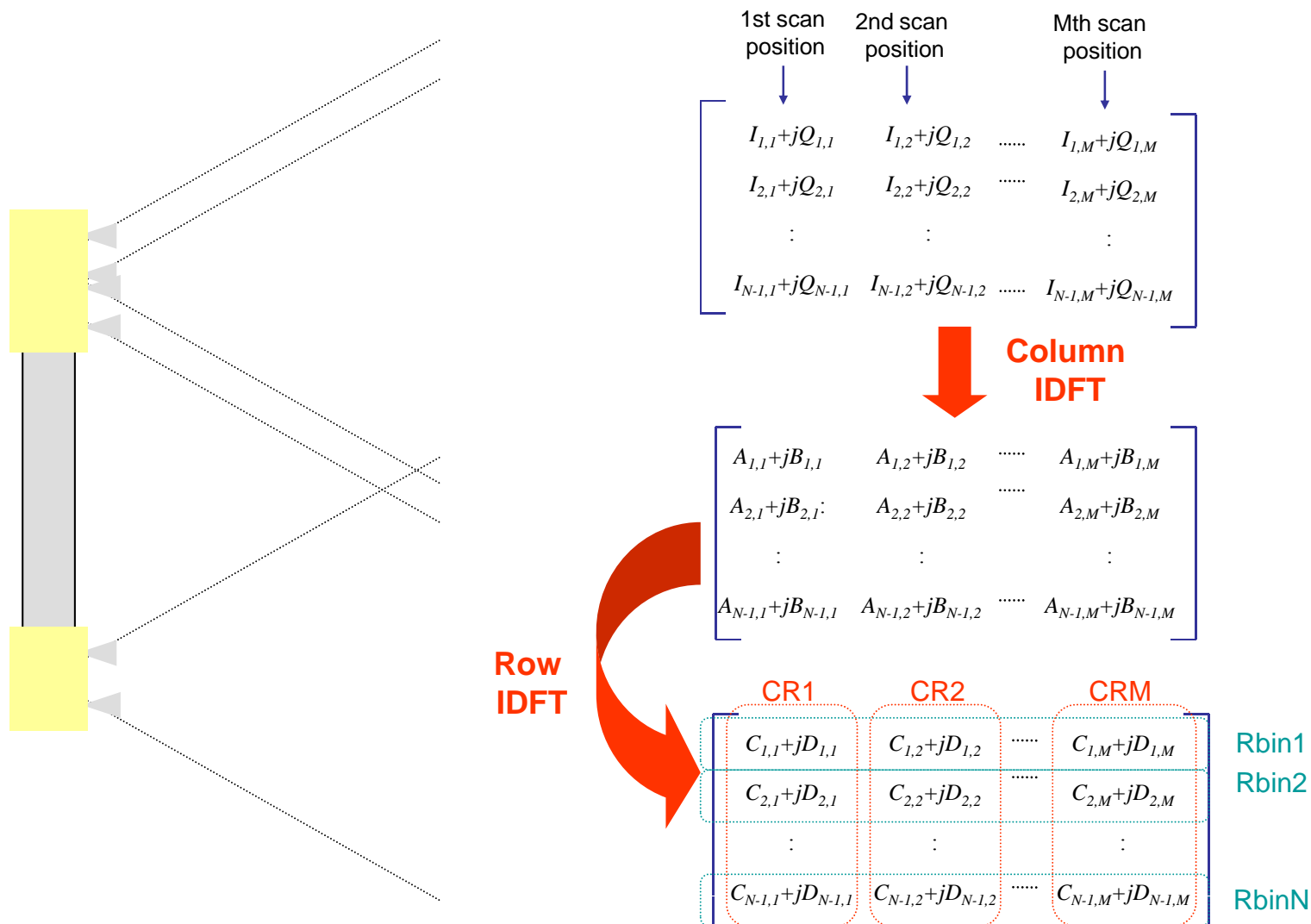
SAR technique is performed by moving the sensor through a 2mt long motorized axis and enables IBIS to provide angular resolution



Using 2 m rail
IBIS provides 4.5mrad
angular resolution
(Cross-Range Resolution)

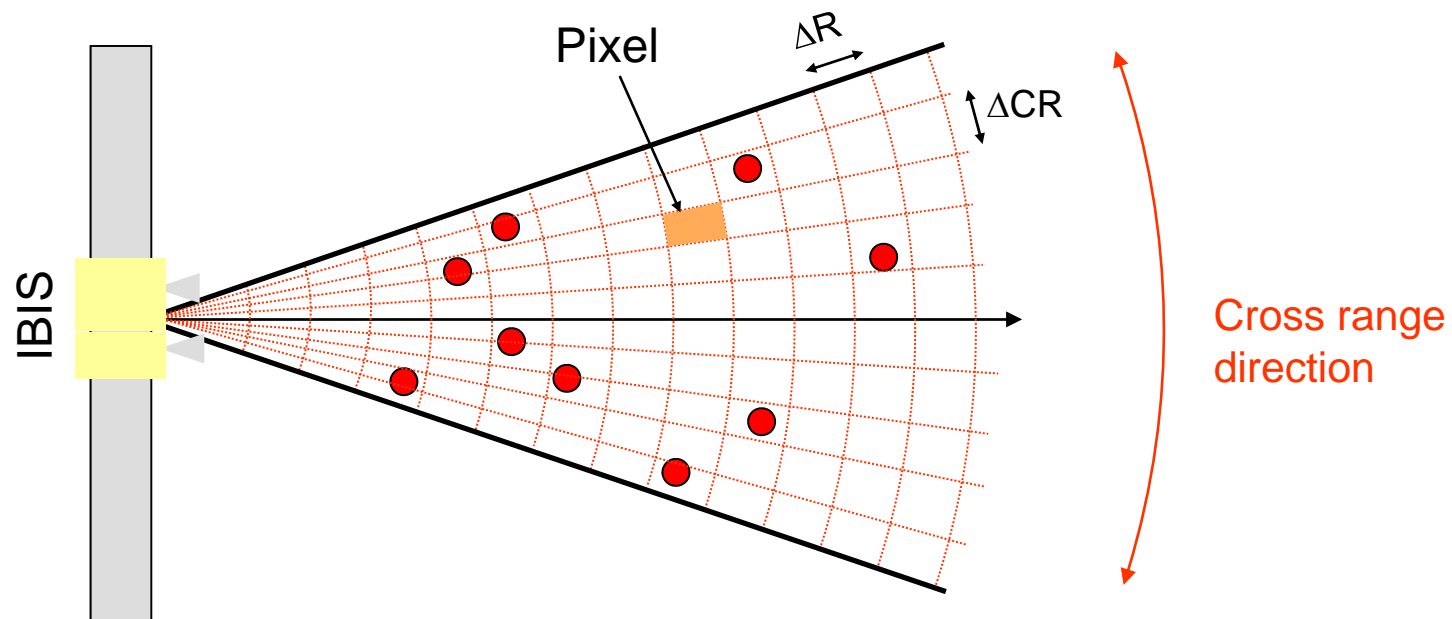
$$\Delta\varphi = \frac{\lambda}{2 \cdot L} = 4.5mrad$$

Synthetic Aperture Radar (SAR)



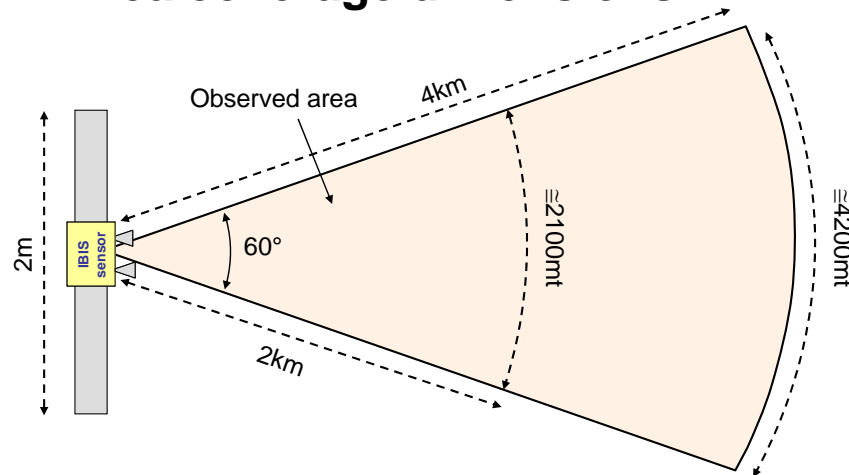
IBIS-L Resolution

The combination of SAR and SF-CW techniques allows IBIS to build a two-dimensional image of the scenario. The image is divided into pixels, corresponding to the resolution area.

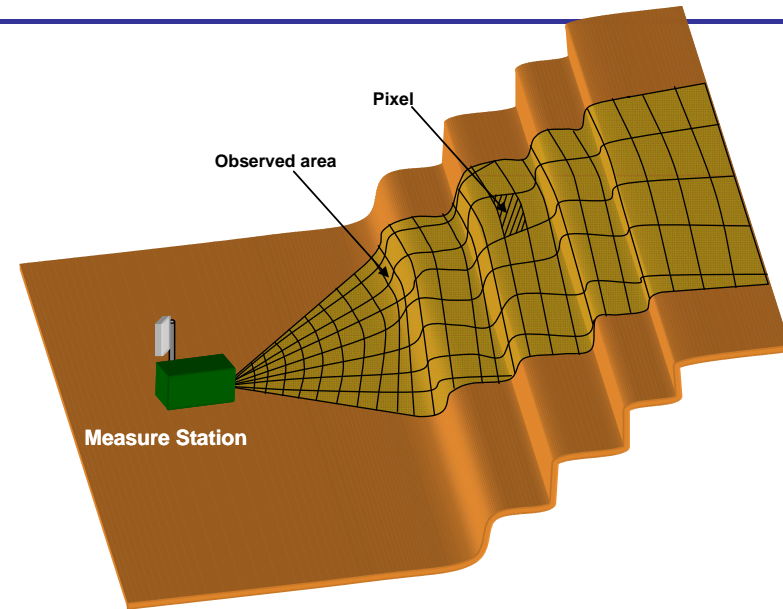
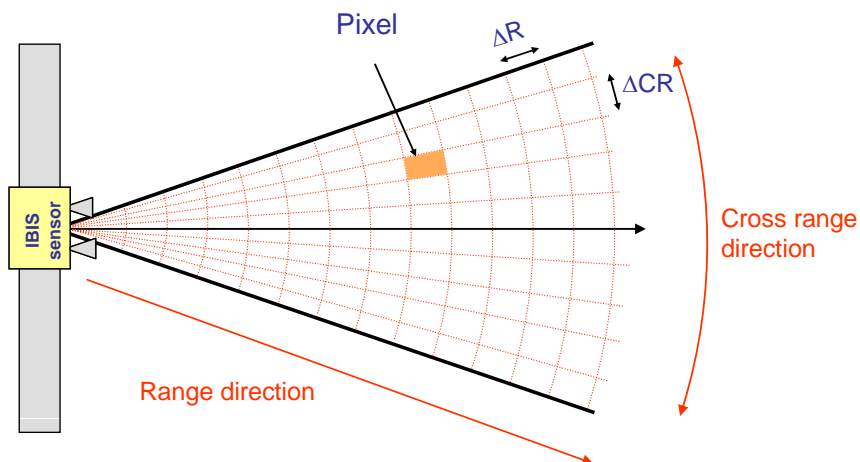


IBIS-L Resolution

Area coverage dimensions



Spatial resolution



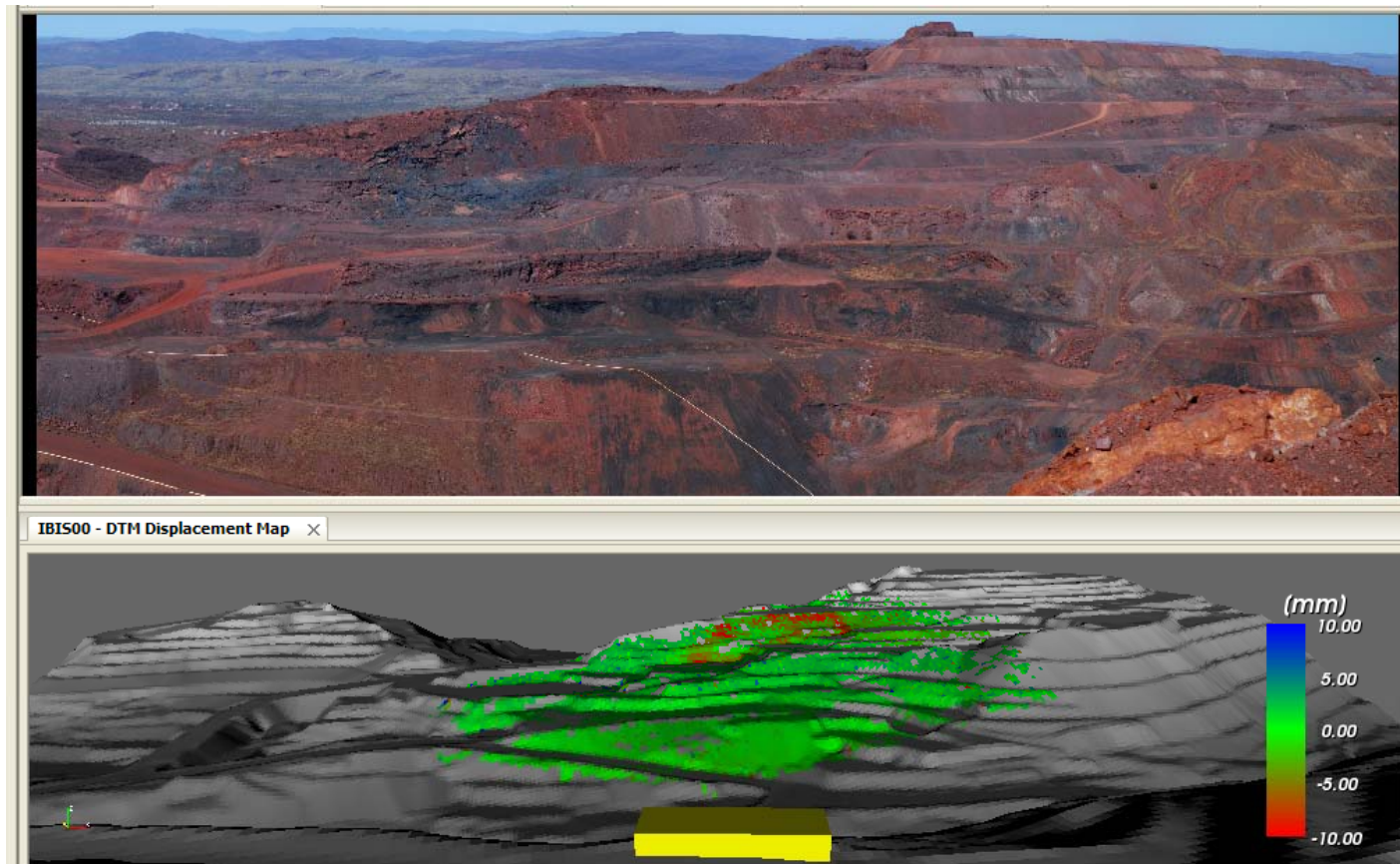
Typical spatial resolutions:

- range: 0.5 m
- cross-range: 4.5 m at 1000 m

High spatial resolution enables the identification of small failures.

IBIS-L Resolution

The radar image can be geocoded over Digital Terrain Model to help the interpretation



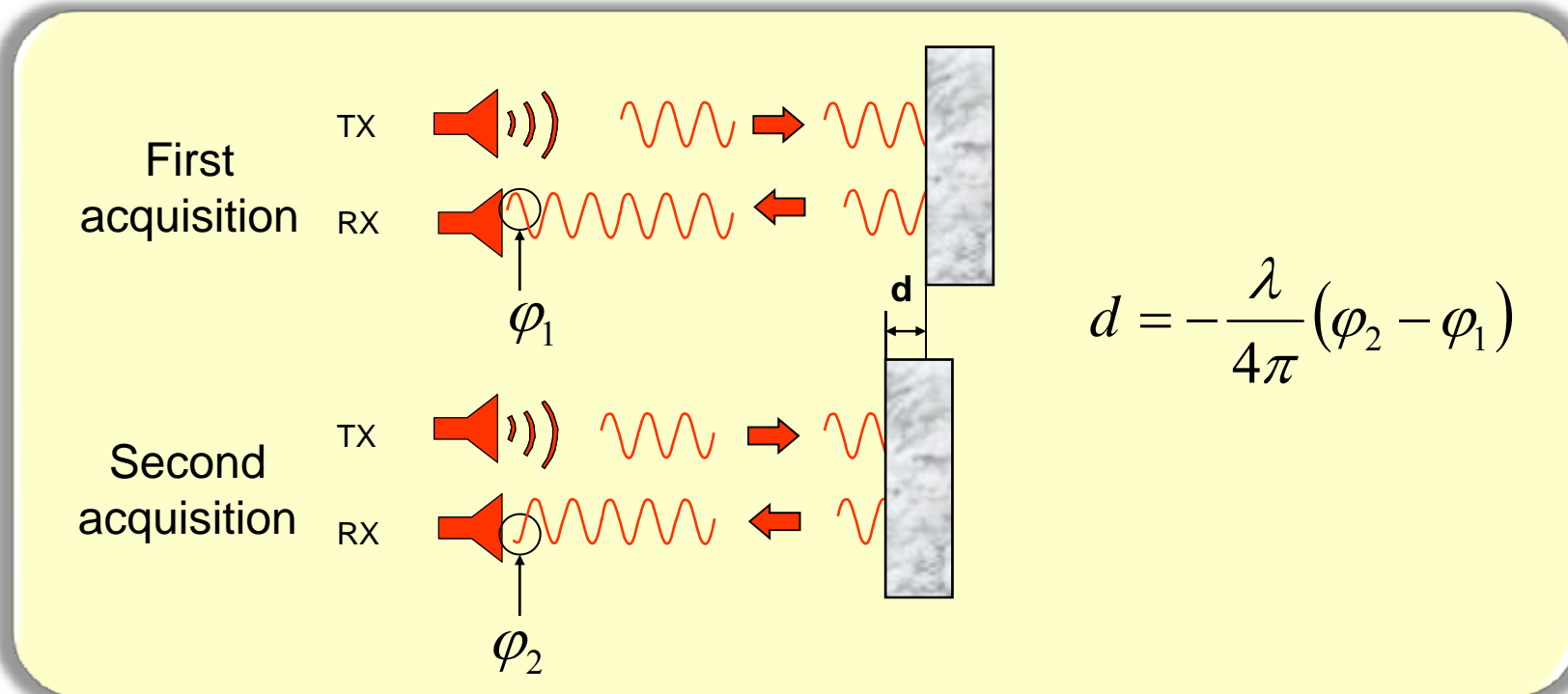
Summary

- IBIS Introduction
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- Synthetic Aperture Radar Technique (SAR)
- **Differential Interferometry Technique**
- Conclusions

Differential Interferometry

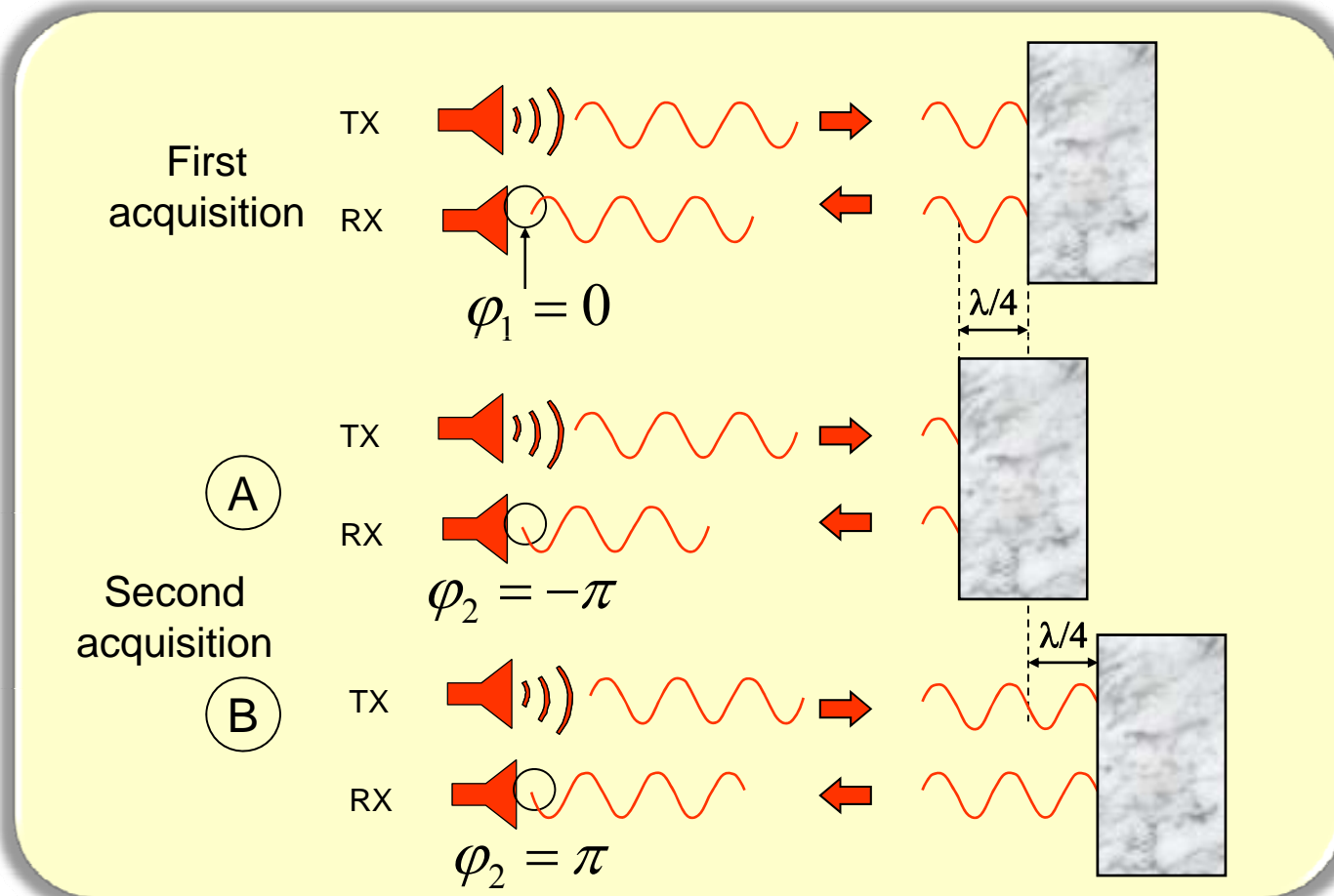
The **differential interferometric analysis** allows object displacement measurement, by comparing phase information of the wave reflected from the object at different time instants.

IBIS provides a displacement measurement with an accuracy of less than 0.01mm (intrinsic radar accuracy in the order of 0.001 mm.)



Differential Interferometry

The **phase ambiguity** bounds the maximum displacement measurable between two consecutive acquisition to $\lambda / 4$ (about 4,5mm)



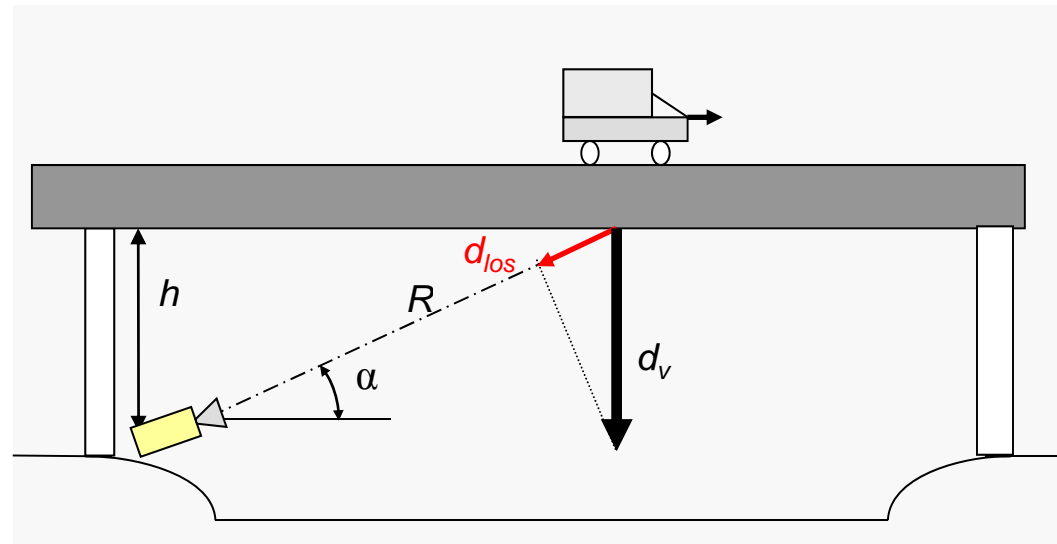
Differential Interferometry

IBIS measures the **line of sight** displacement (**LoS**). The real displacement evaluation requires the knowledge of the acquisition geometry and real movement direction.

d_{los} Line of sight displacement

d_v Vertical displacement

R Measurement point distance (measured by IBIS)



$$d_v = \frac{d_{los}}{\sin(\alpha)} \quad \Rightarrow \quad \sin(\alpha) = \frac{h}{R} \quad \Rightarrow \quad d_v = d_{los} \cdot \frac{R}{h}$$

Summary

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- **Synthetic Aperture Radar Technique (SAR)**
- **Differential Interferometry Technique**
- **Conclusions**

Conclusions

- The **Stepped Frequency Continuous Wave** techniques allows the resolution of the scenario along range direction independently from the distance.

IBIS Range Resolution up to 0.5m

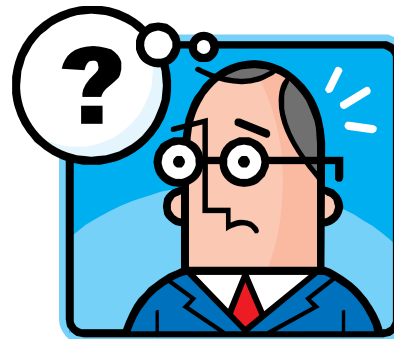
- The **Synthetic Aperture Radar** technique allows the resolution of the scenario along cross-range direction.

IBIS CrossRange Resolution up to 4.5mrad

- The **Differential Interferometry technique** enables the measure of the displacement of the resolved objects

IBIS Displacement accuracy 0,01mm (intrinsic 0,001mm)

Questions ?



IBIS

Image by Interferometric Survey



IBIS: radar interferometrici terrestri

IDS presenta IBIS:

Un'innovativa famiglia di **avanzati** strumenti **geodetici** basata sulla tecnica dell'interferometria radar terrestre progettati per fornire misure accurate di spostamento su vaste aree

I sistemi IBIS sono stati progettati per rispondere alle specifiche esigenze dei settori dell'**ingegneria civile**, della **geotecnica** e dell'**industria mineraria**.

L'approccio rivoluzionario di questa tecnica consente all'utente di ottenere misure accurate da remoto senza la necessità di accedere all'area di interesse ed in qualsiasi condizione meteo.

Configurazioni disponibili IBIS

PRODOTTO



IBIS - L



IBIS - M



IBIS - S

APPLICAZIONE



MONITORAGGIO FRANE E DIGHE



MONITORAGGIO FRONTI DI SCAVO



**MONITORAGGIO E COLLAUDO
STRUTTURE**

IBIS-S: sistema e campi di applicazione



COLLAUDI DI PONTI



BENI CULTURALI



IBIS-S



IMPIANTI INDUSTRIALI

IBIS-L: sistema e campi di applicazione



IBIS-L



MONITORAGGIO FRANE



MONITORAGGIO DIGHE



**MONITORAGGIO
CEDIMENTI/SUBSIDENZA**

IBIS-M: sistema e campi di applicazione



IBIS-M



**MONITORAGGIO FRONTI DI SCAVO IN
CAVE E MINIERE A CIELO APERTO**

IBIS: principali vantaggi

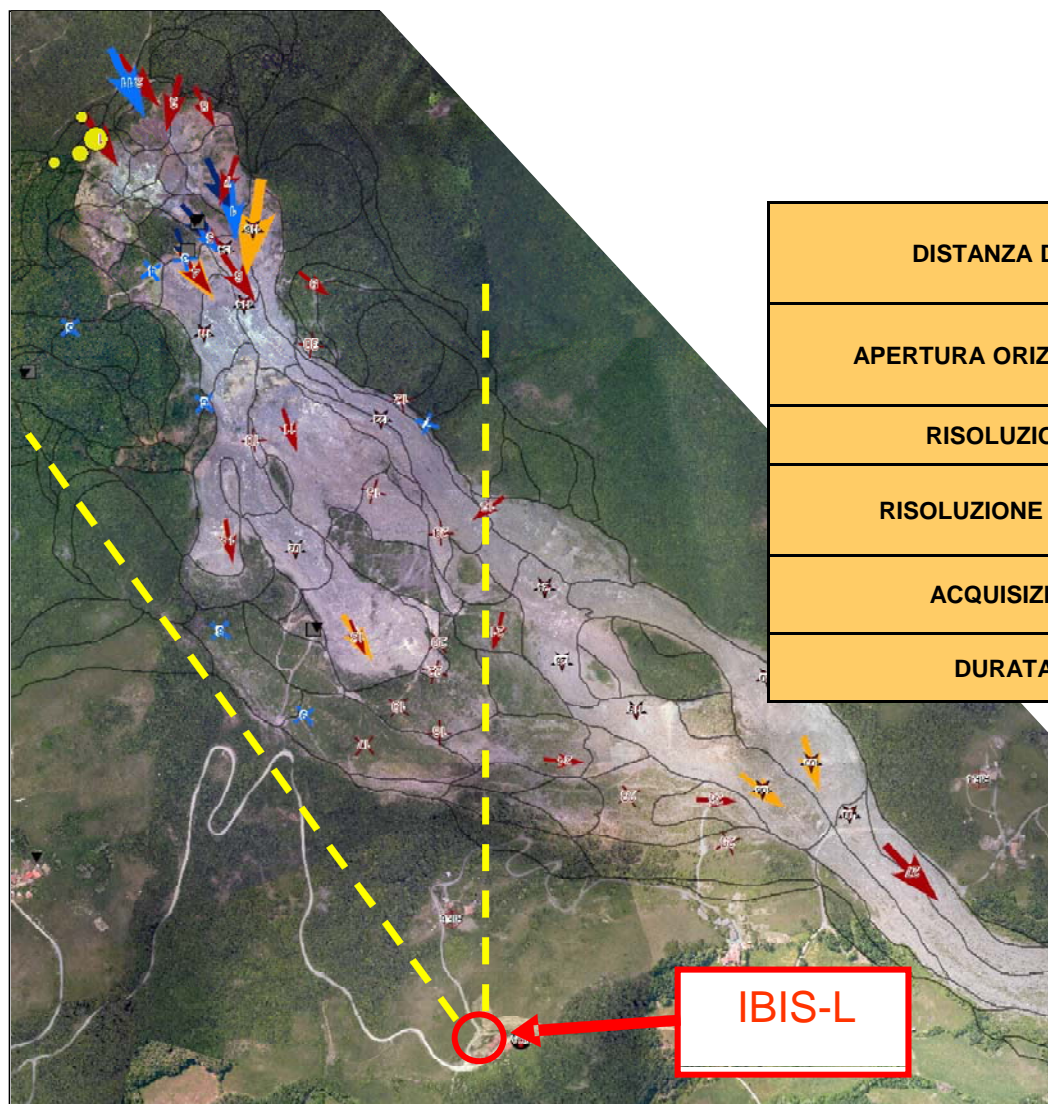
I più importanti vantaggi dei sistemi IBIS sono i seguenti:

- possibilità di effettuare le misure **senza accedere all'area di misura**
- ottenere **misure dall'intera area** illuminata dal fascio delle antenne
- **elevata accuratezza delle misure di spostamento**, fino a 0,02 mm
- **Monitoraggio in continuo** in qualsiasi condizione
- Sistema **completamente autonomo**
- **Elevata frequenza di acquisizione**, minuti for IBIS-L, IBIS-M msec per IBIS-S

IBIS-L: monitoraggio frane



IBIS-L: monitoraggio frane

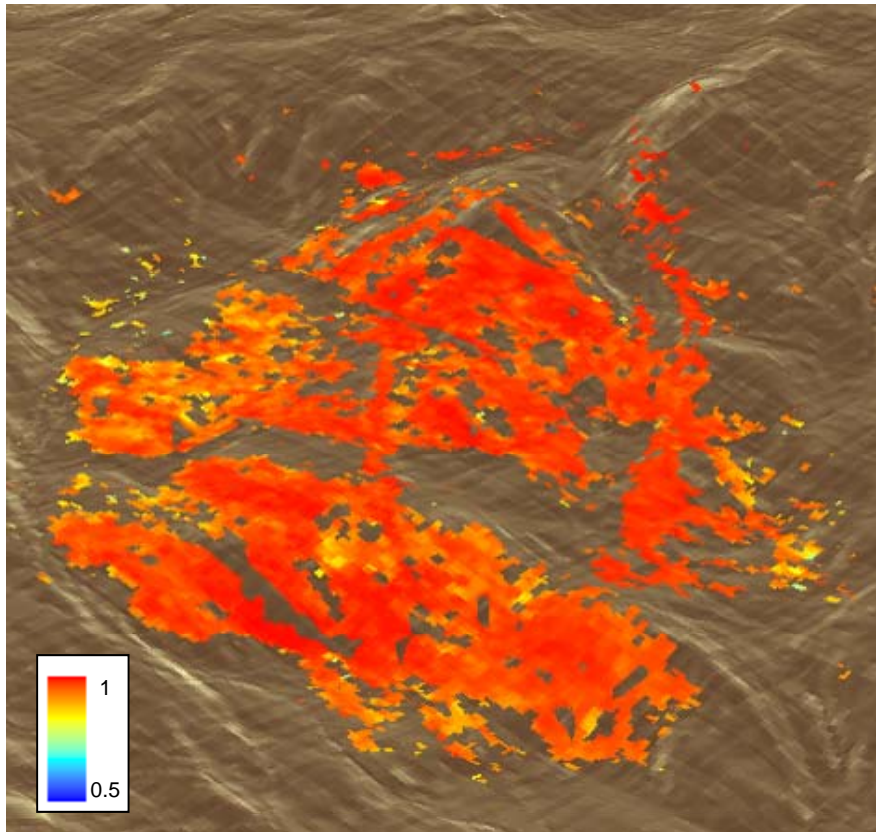


DISTANZA DAL VERSANTE	[m]	450-1300
APERTURA ORIZZONTALE ANTENNE	[gradi]	38
RISOLUZIONE IN RANGE	[m]	0.5
RISOLUZIONE IN CROSS-RANGE	[mrad]	4.5
ACQUISIZIONI PER ORA	-	9
DURATA SESSIONE	[ore]	24



IBIS-L System set-up

IBIS-L: monitoraggio frane



Geocoded quality map

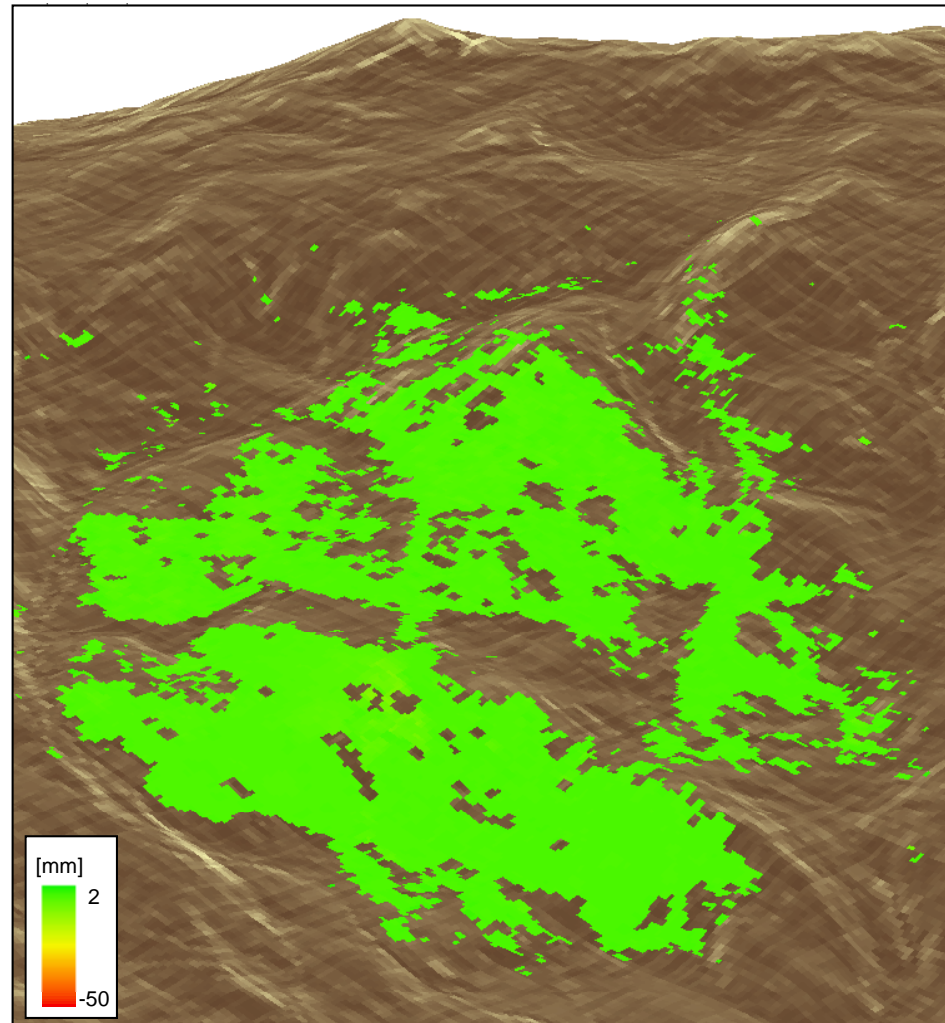


Picture taken from the radar location

More than 40.000 measurement points
are identified on the quality map

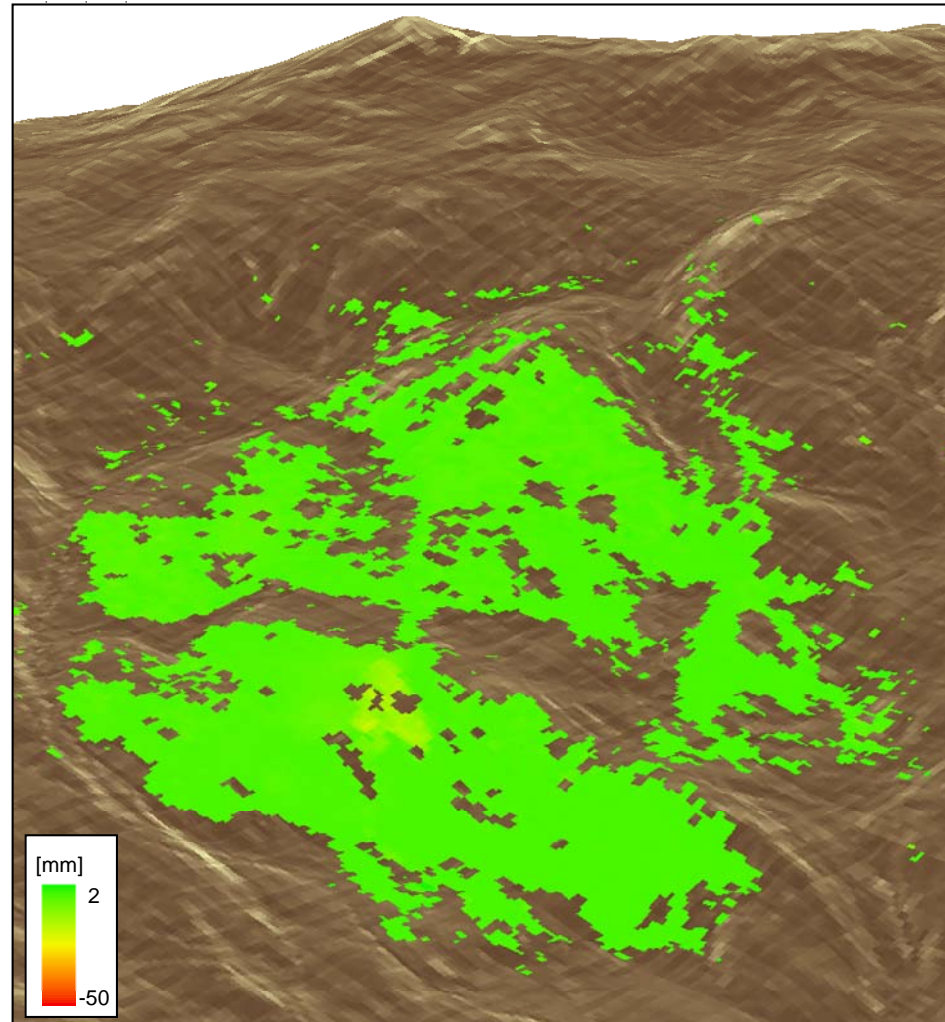
IBIS-L: monitoraggio frane (1 h)

Geocoded Line Of Sight Displacement Map



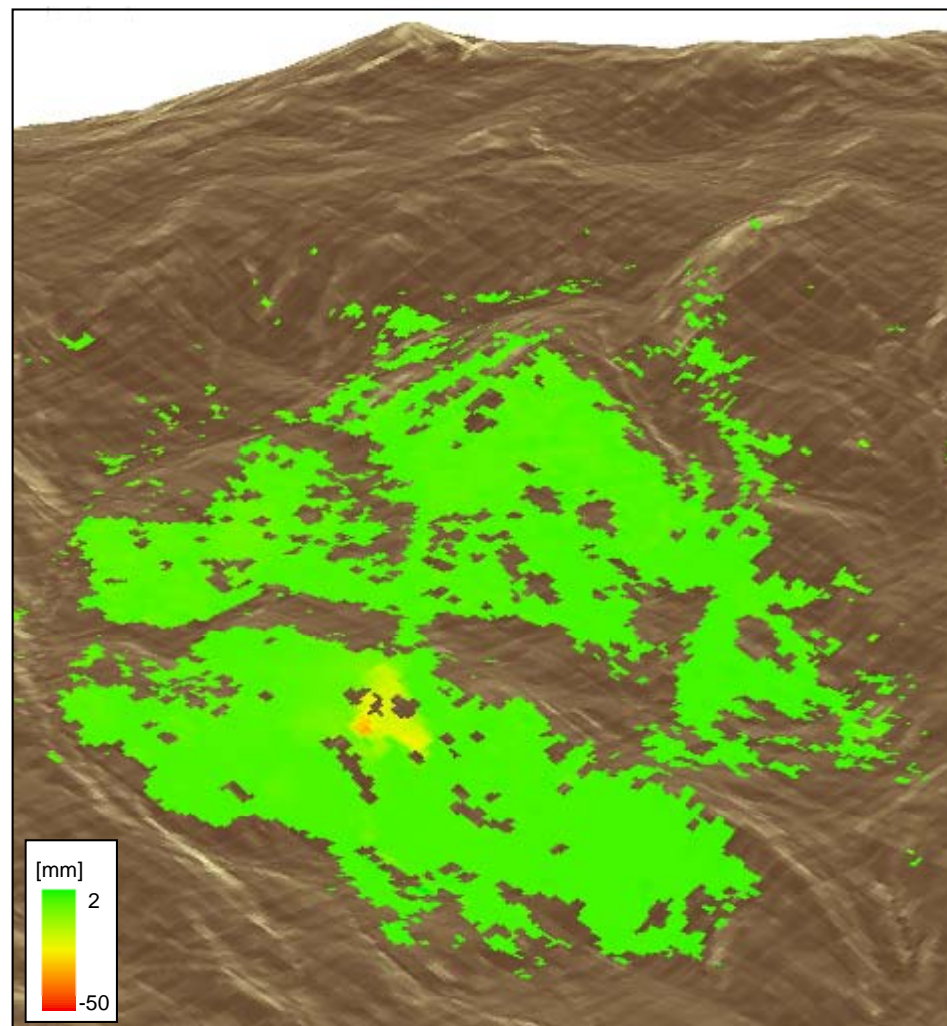
IBIS-L: monitoraggio frane (2 h)

Geocoded Line Of Sight Displacement Map



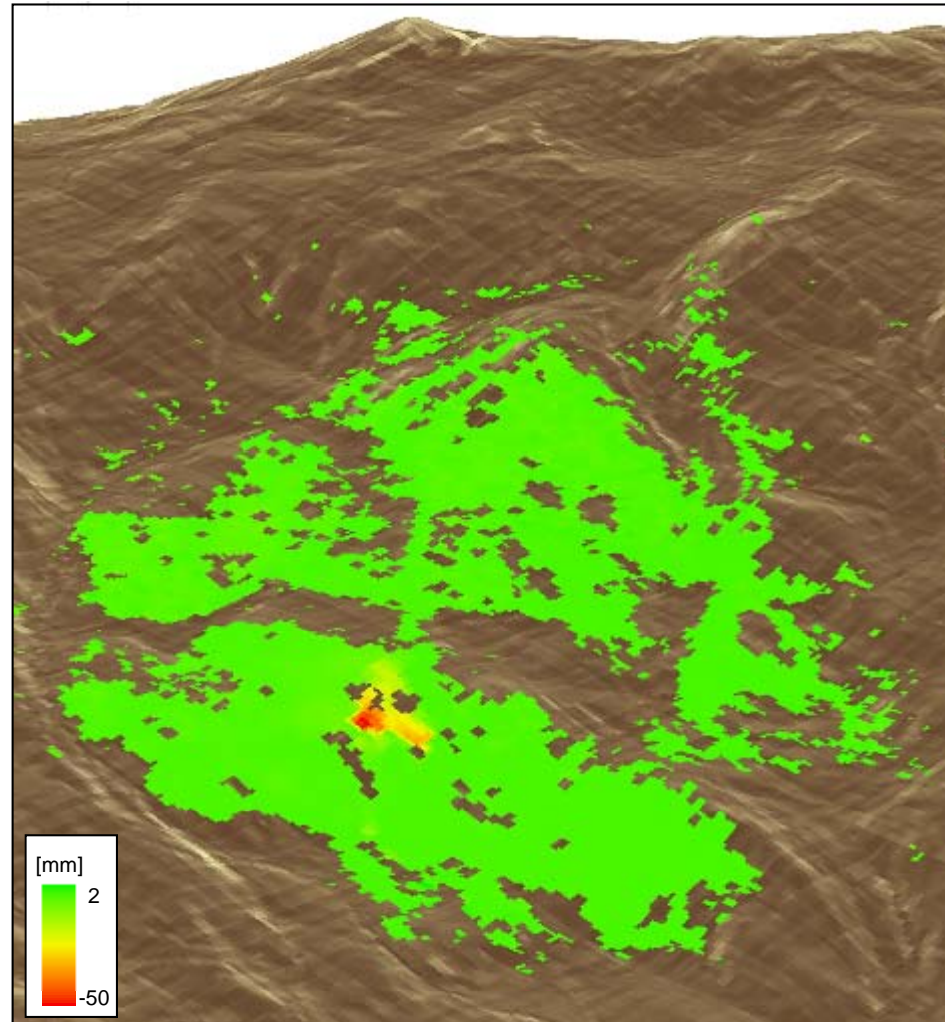
IBIS-L: monitoraggio frane (3 h)

Geocoded Line Of Sight Displacement Map



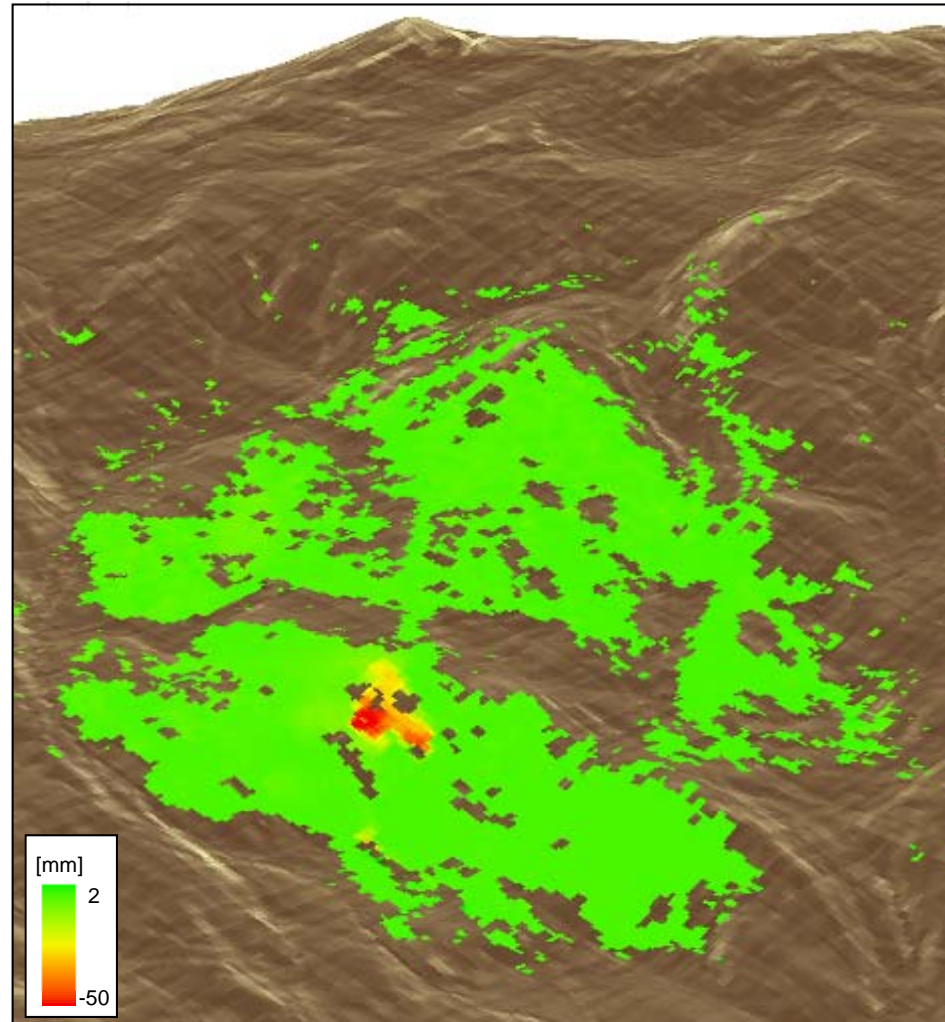
IBIS-L: monitoraggio frane (4 h)

Geocoded Line Of Sight Displacement Map



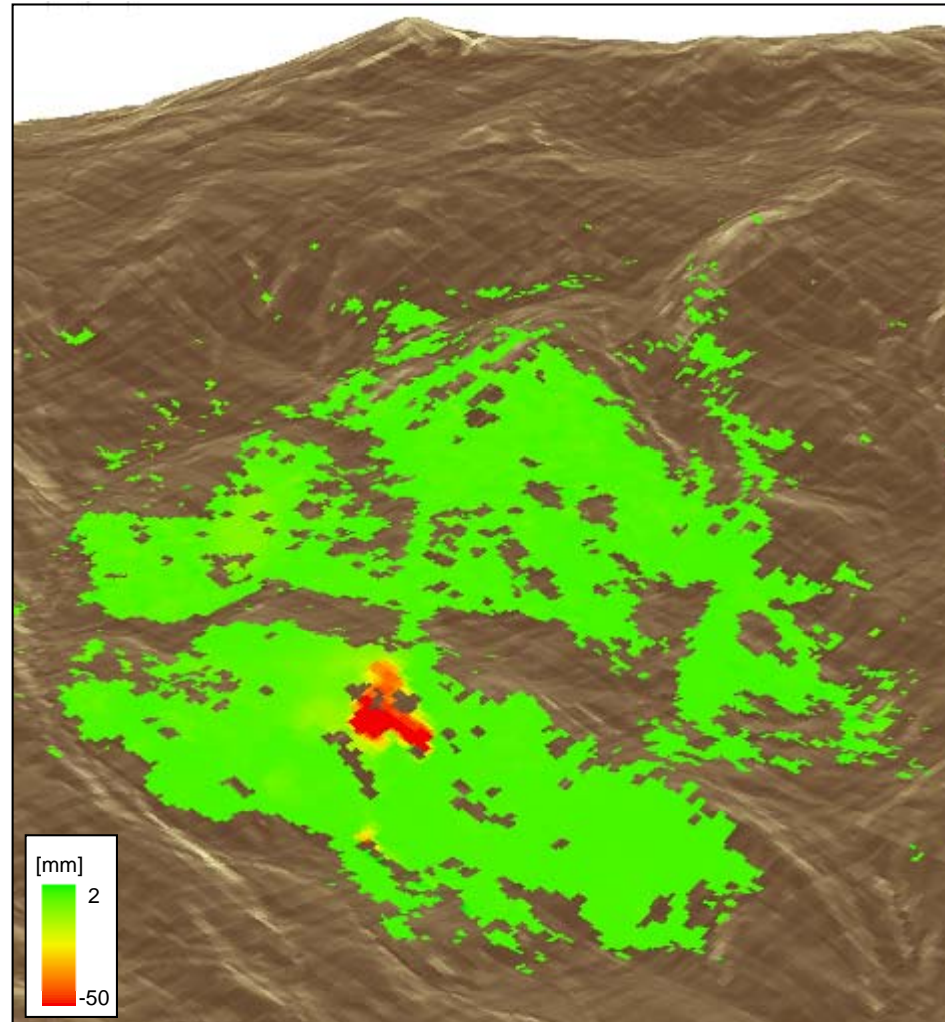
IBIS-L: monitoraggio frane (5 h)

Geocoded Line Of Sight Displacement Map



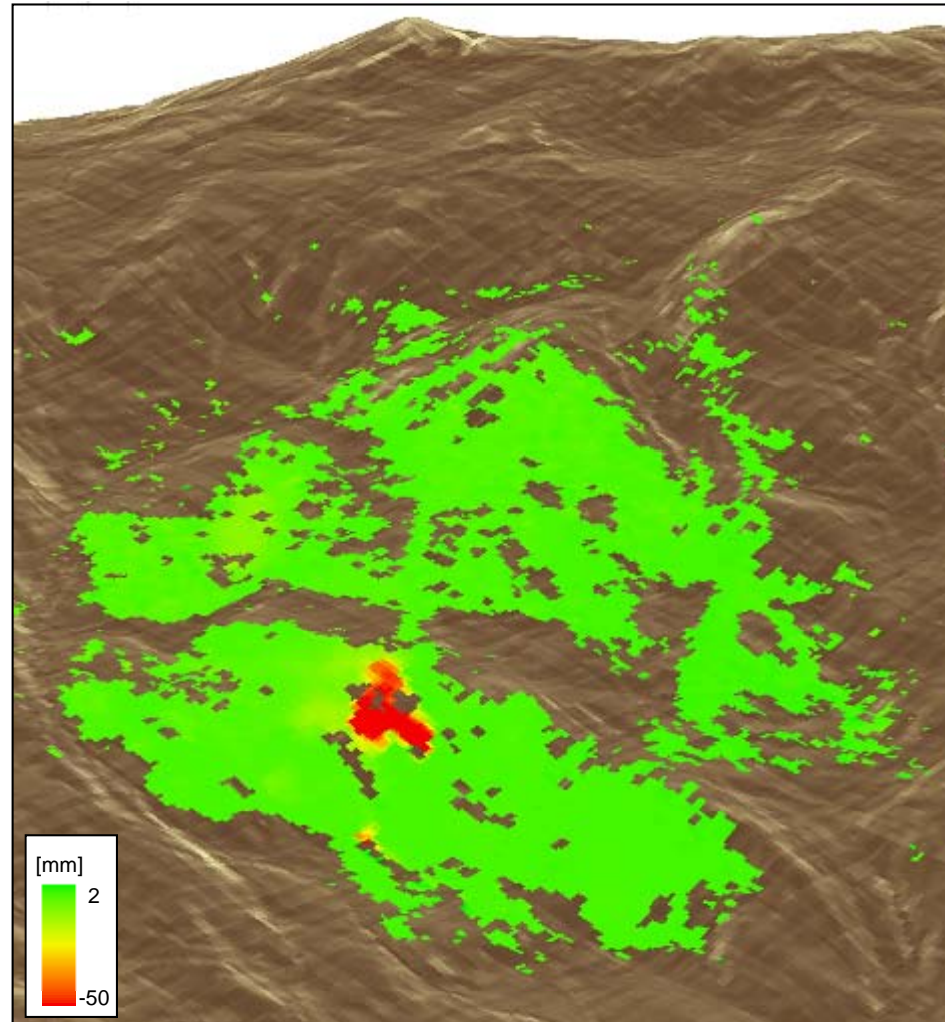
IBIS-L: monitoraggio frane (6 h)

Geocoded Line Of Sight Displacement Map



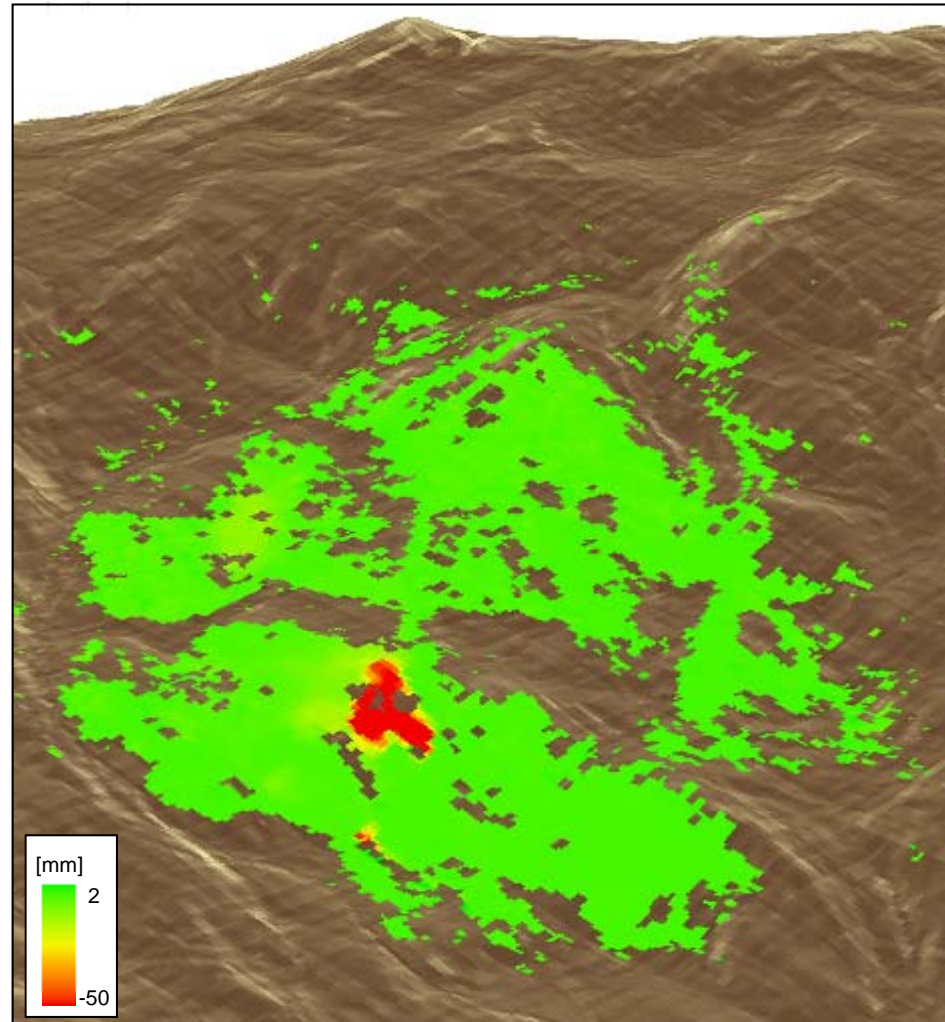
IBIS-L: monitoraggio frane (7 h)

Geocoded Line Of Sight Displacement Map



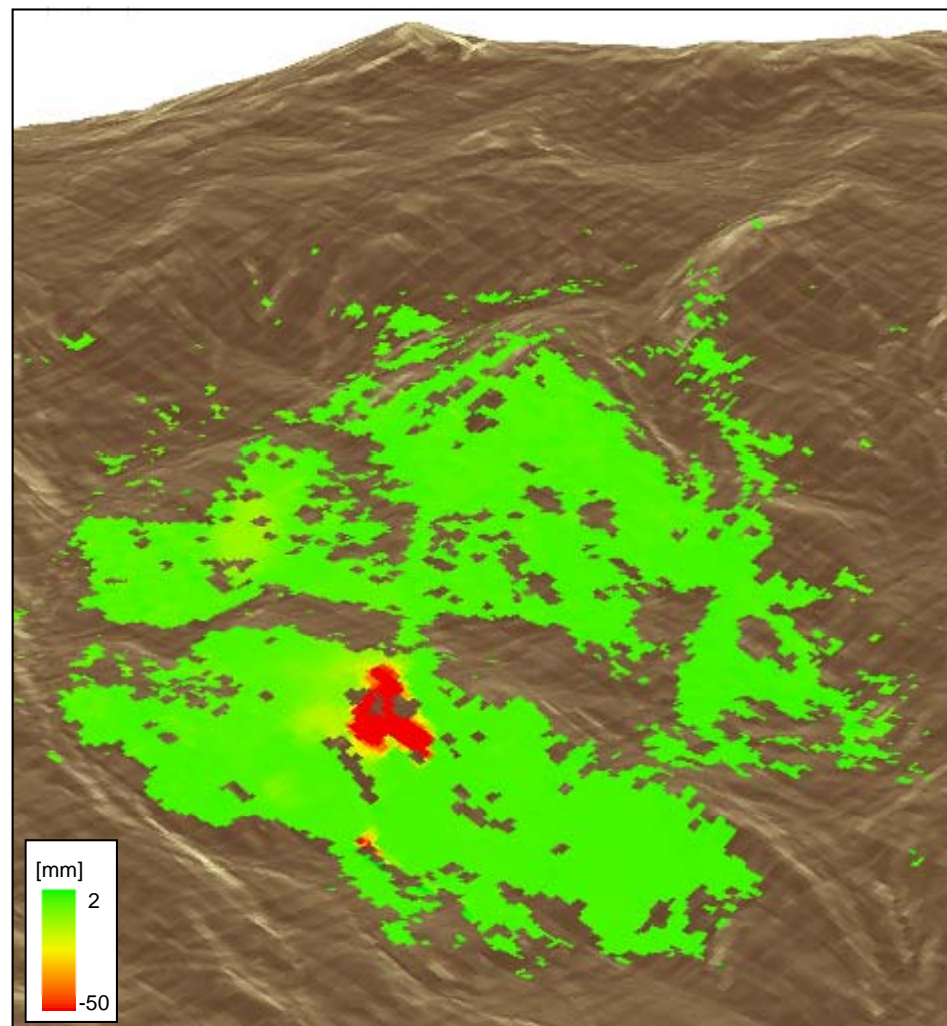
IBIS-L: monitoraggio frane (8 h)

Geocoded Line Of Sight Displacement Map



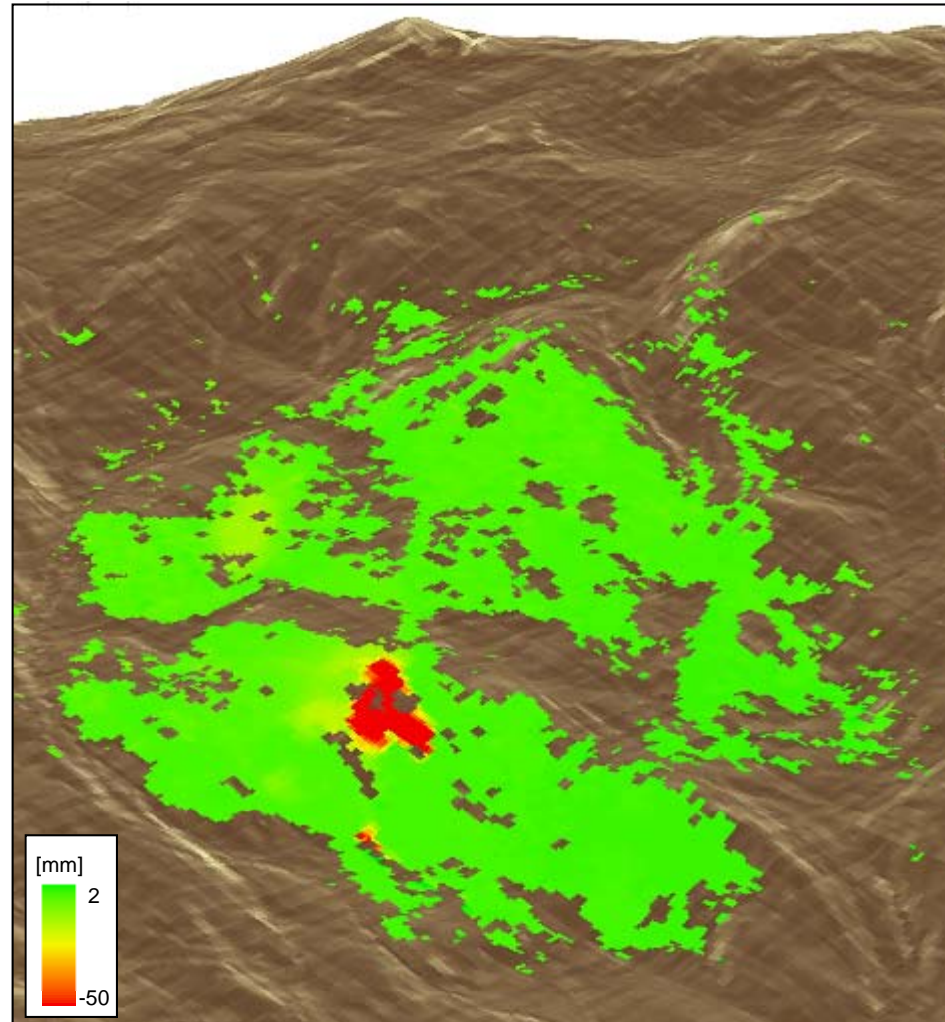
IBIS-L: monitoraggio frane (9 h)

Geocoded Line Of Sight Displacement Map



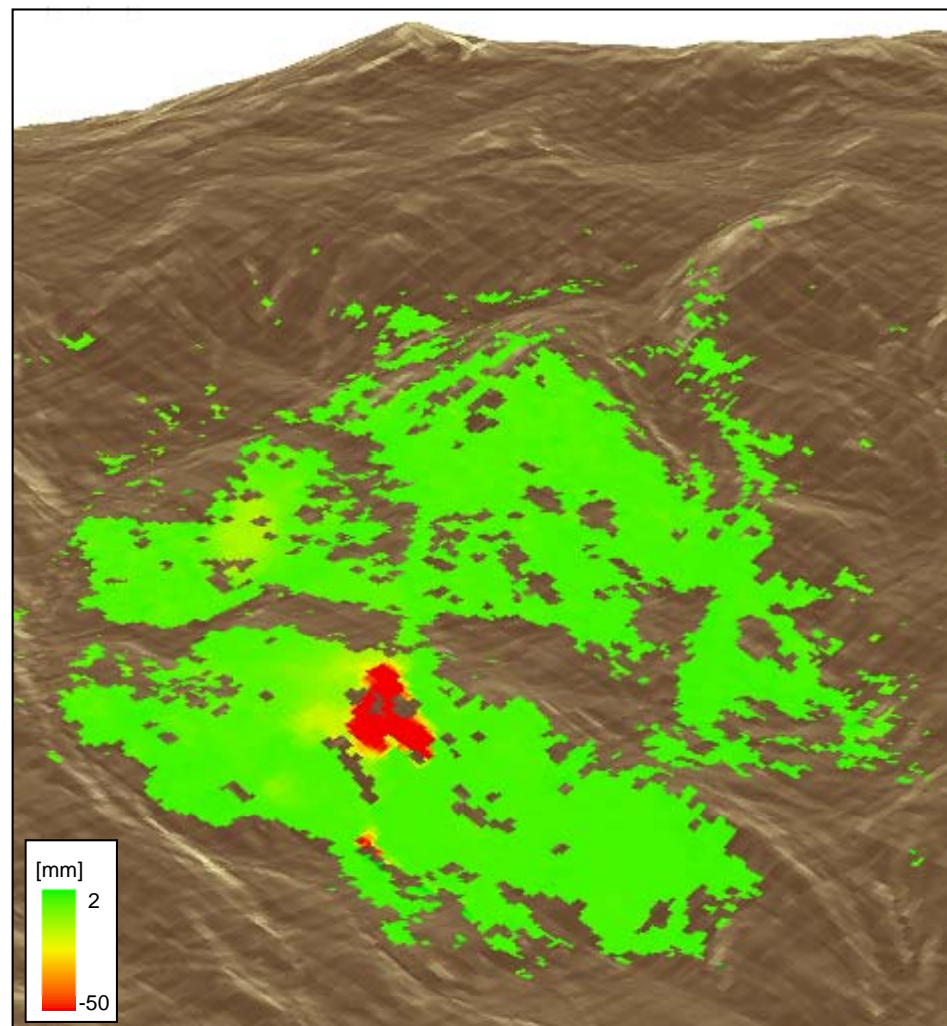
IBIS-L: monitoraggio frane (10 h)

Geocoded Line Of Sight Displacement Map



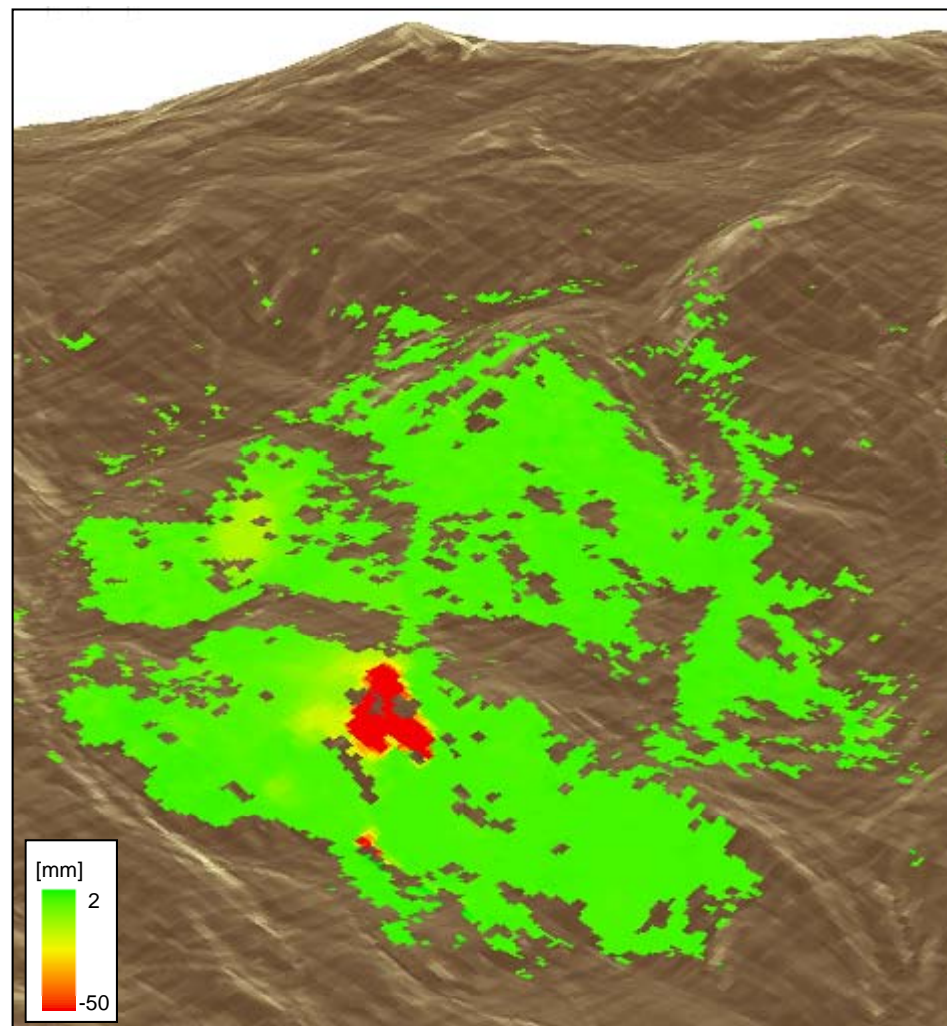
IBIS-L: monitoraggio frane (11 h)

Geocoded Line Of Sight Displacement Map



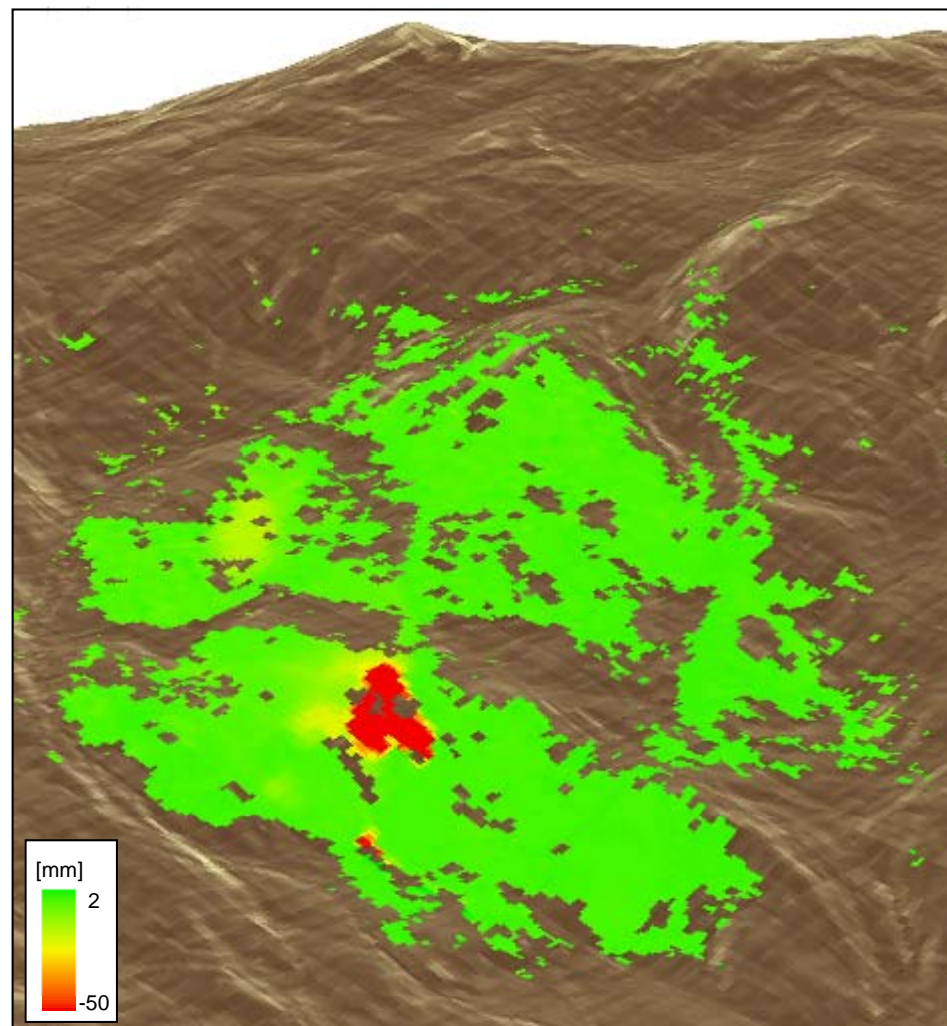
IBIS-L: monitoraggio frane (12 h)

Geocoded Line Of Sight Displacement Map



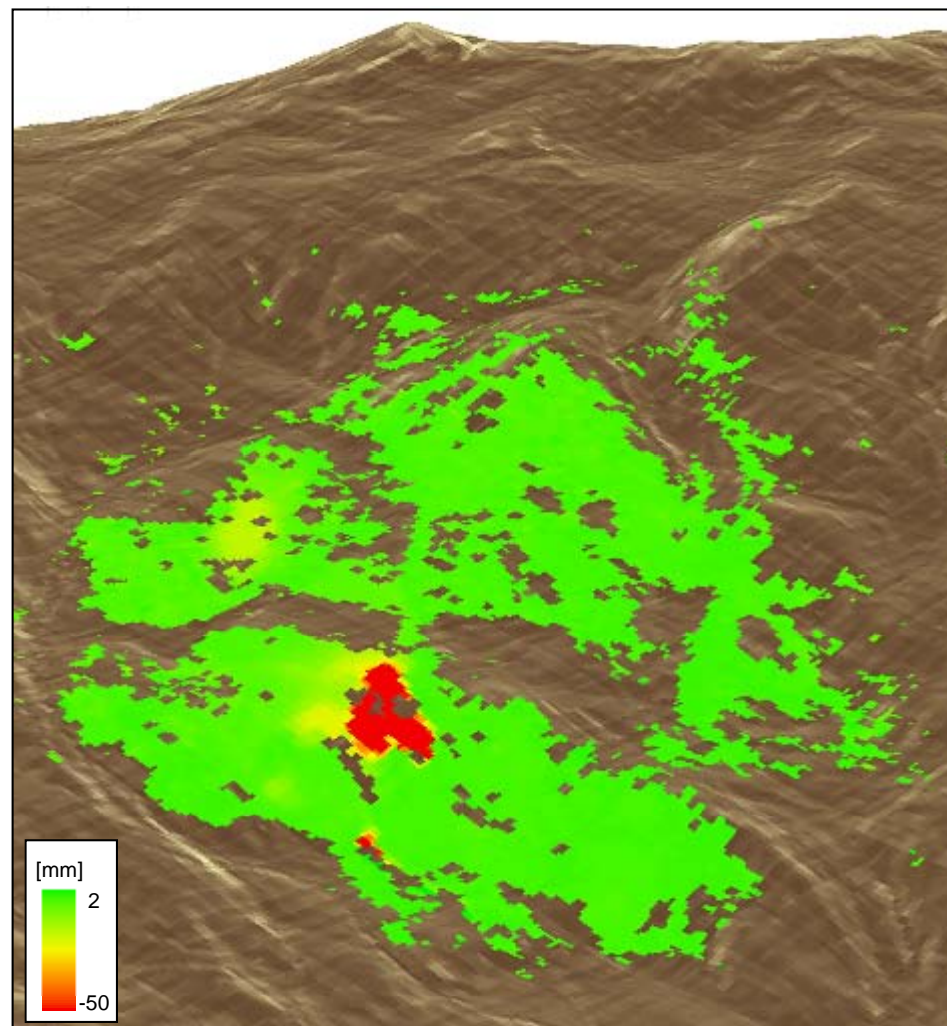
IBIS-L: monitoraggio frane (13 h)

Geocoded Line Of Sight Displacement Map



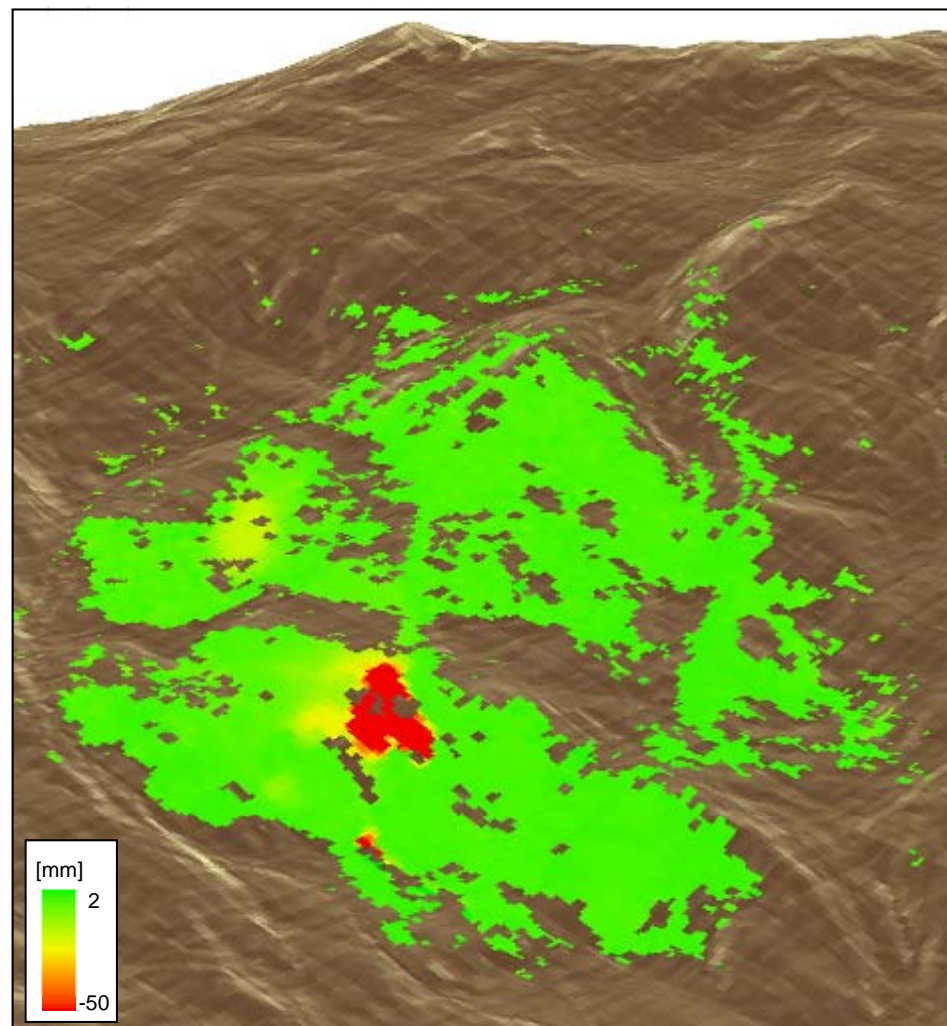
IBIS-L: monitoraggio frane (14 h)

Geocoded Line Of Sight Displacement Map



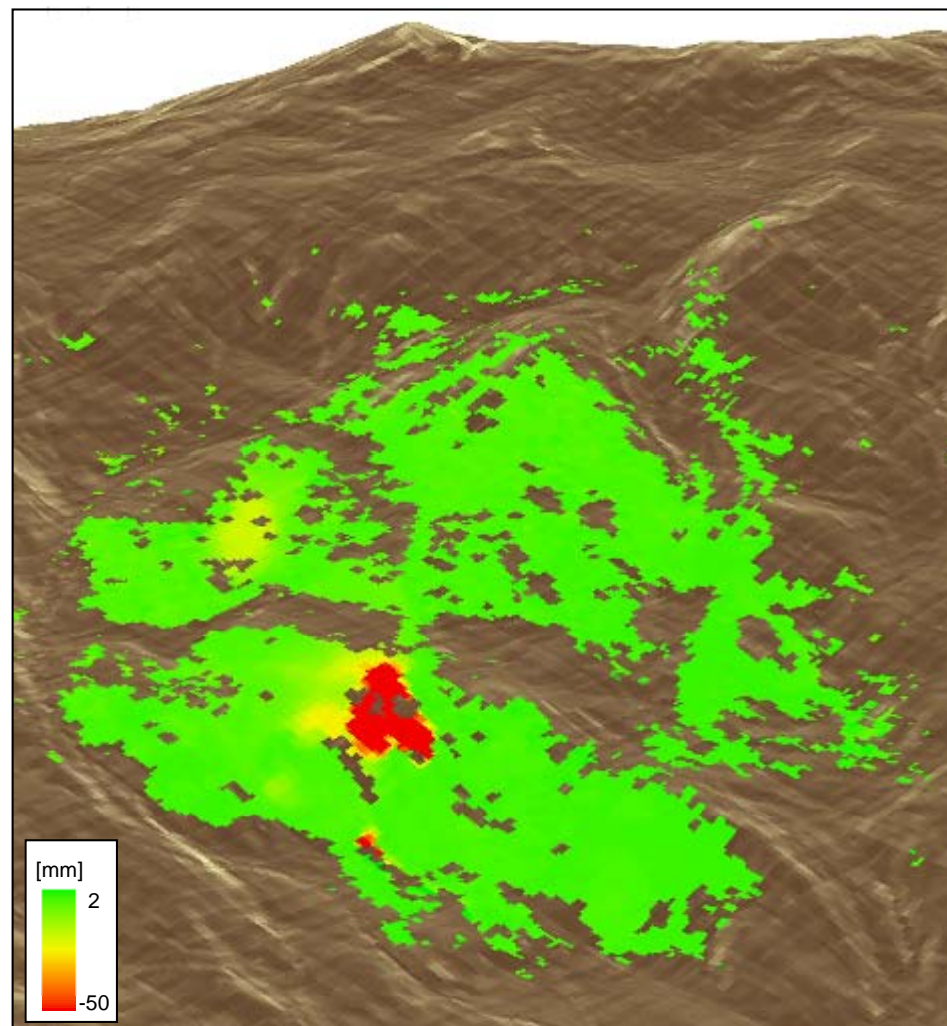
IBIS-L: monitoraggio frane (15 h)

Geocoded Line Of Sight Displacement Map



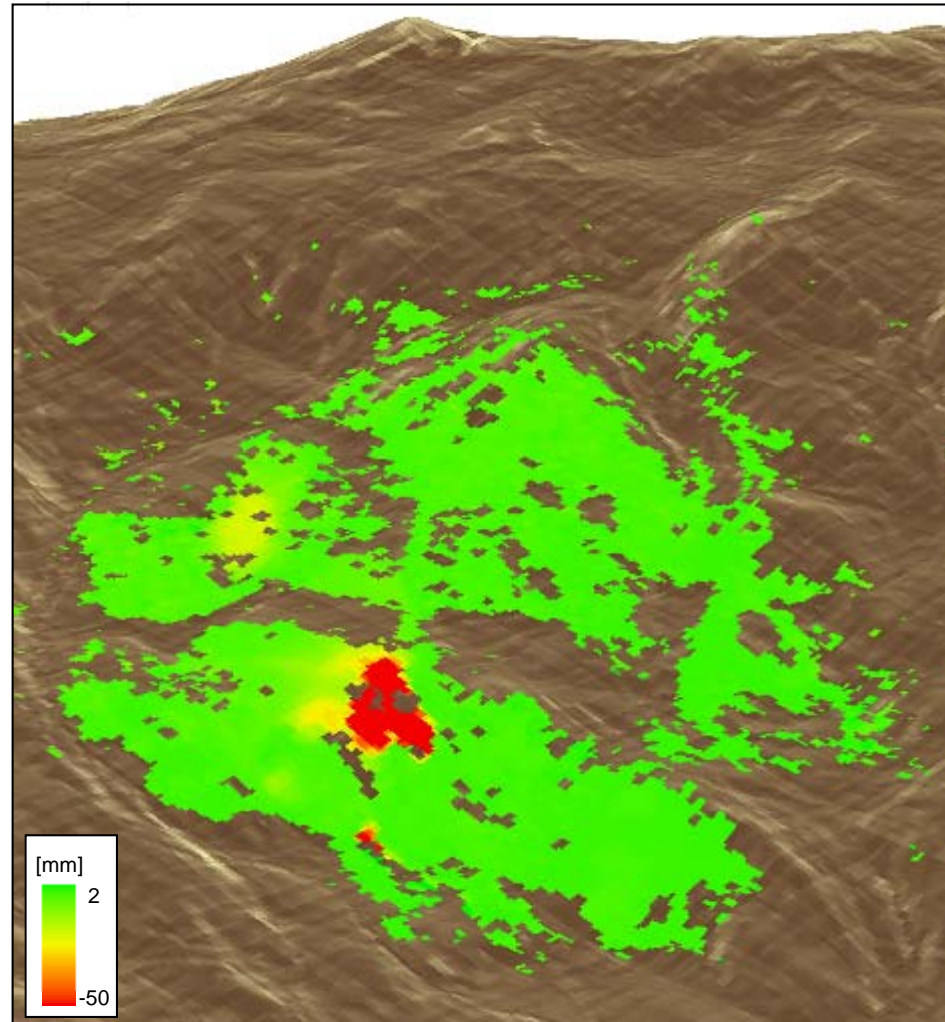
IBIS-L: monitoraggio frane (16 h)

Geocoded Line Of Sight Displacement Map



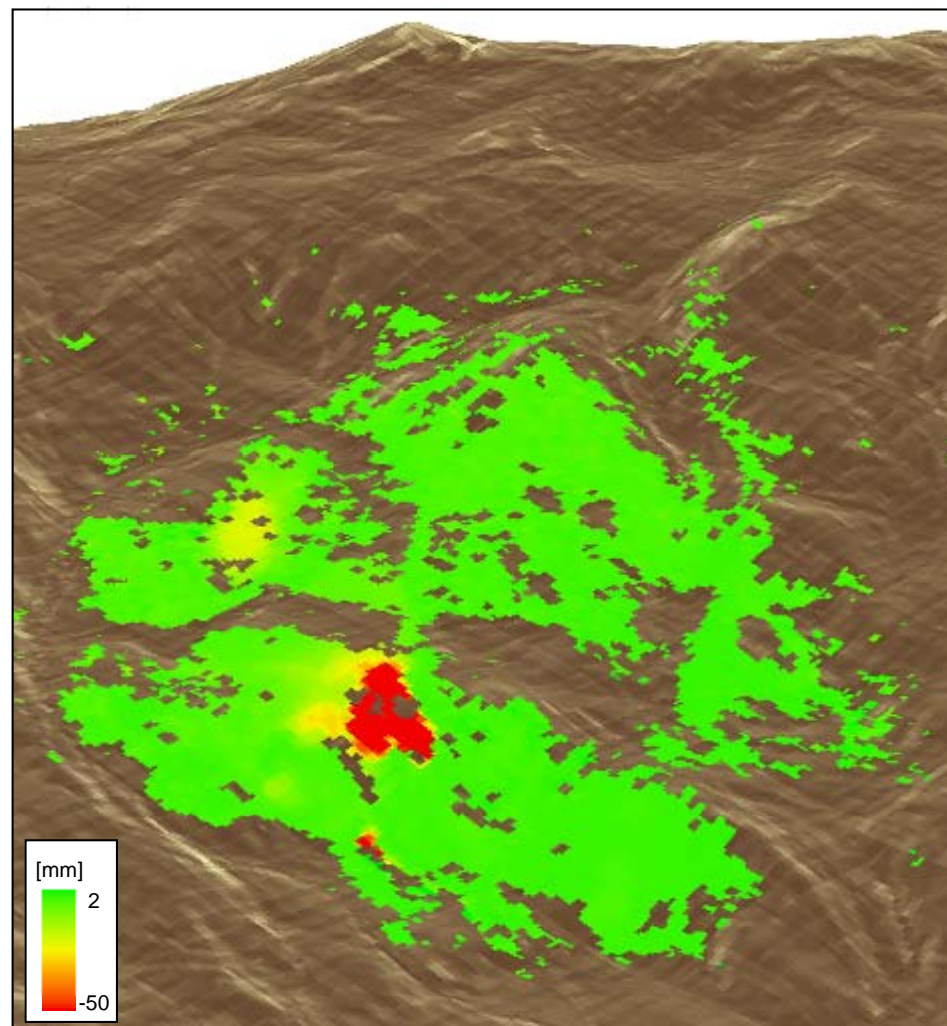
IBIS-L: monitoraggio frane (17 h)

Geocoded Line Of Sight Displacement Map



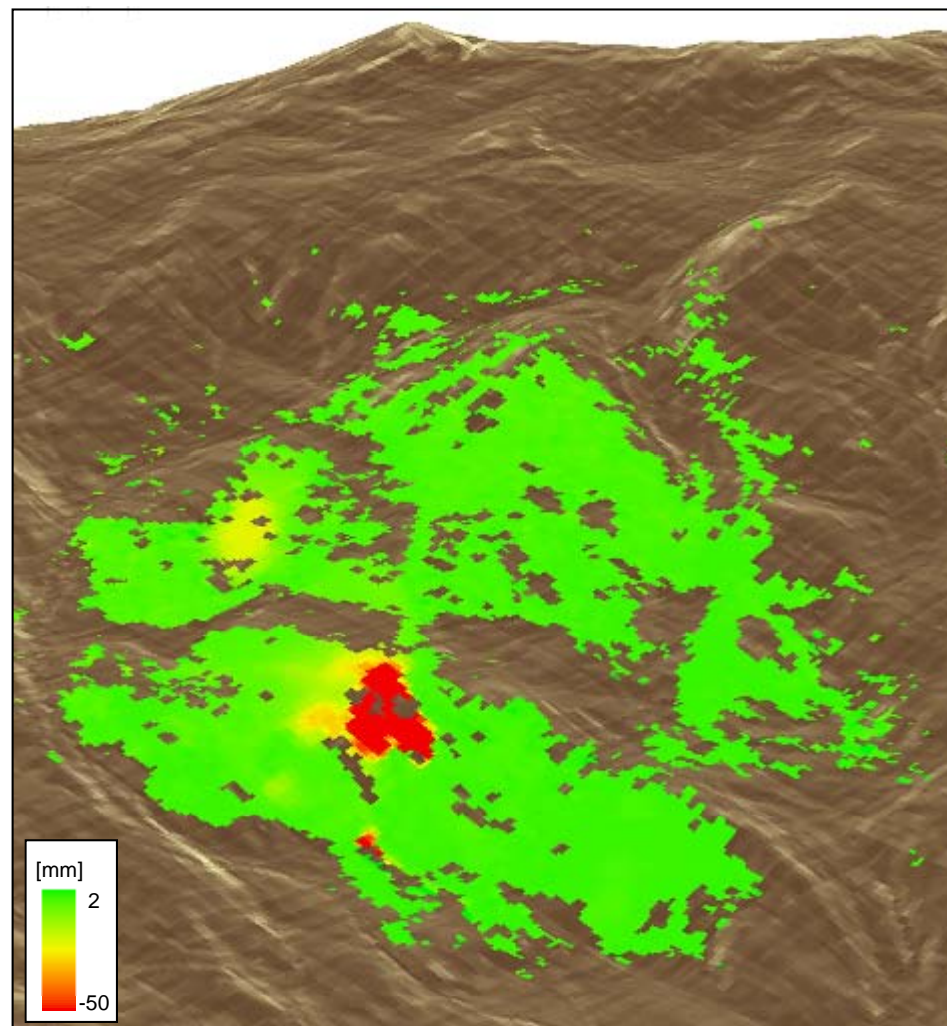
IBIS-L: monitoraggio frane (18 h)

Geocoded Line Of Sight Displacement Map



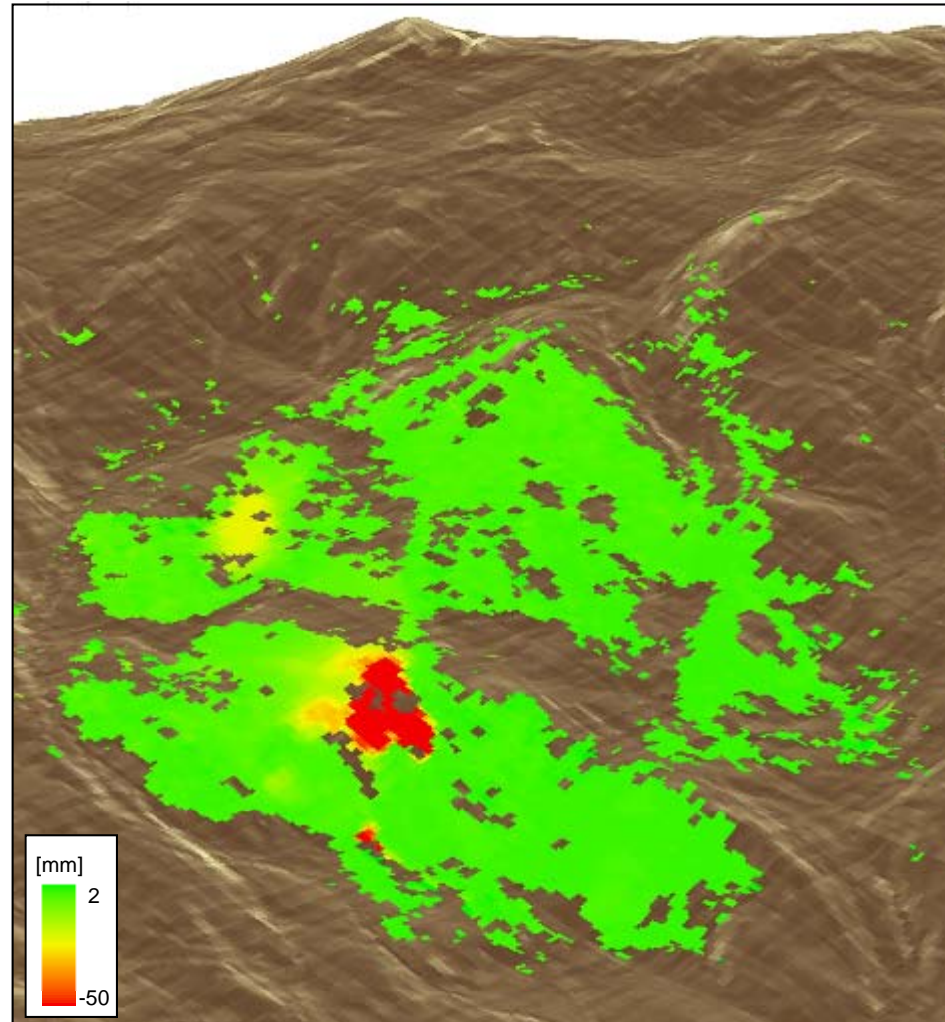
IBIS-L: monitoraggio frane (19 h)

Geocoded Line Of Sight Displacement Map



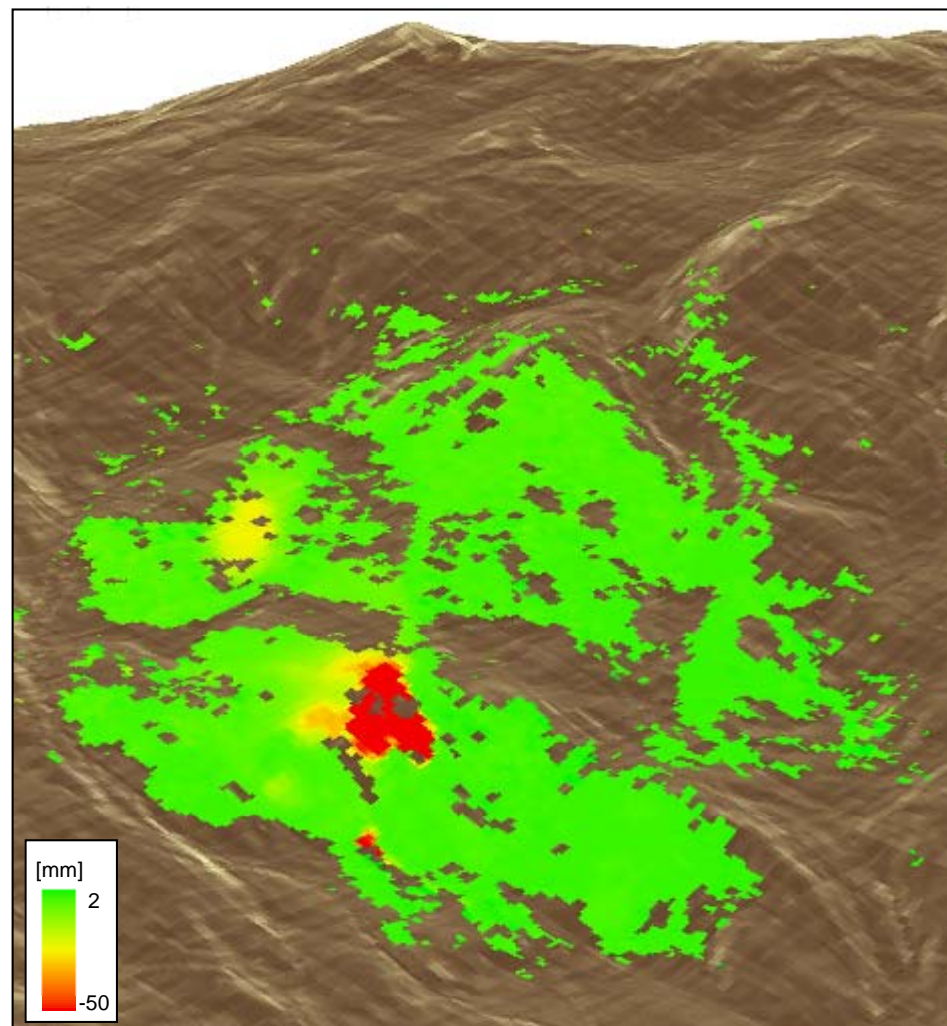
IBIS-L: monitoraggio frane (20 h)

Geocoded Line Of Sight Displacement Map



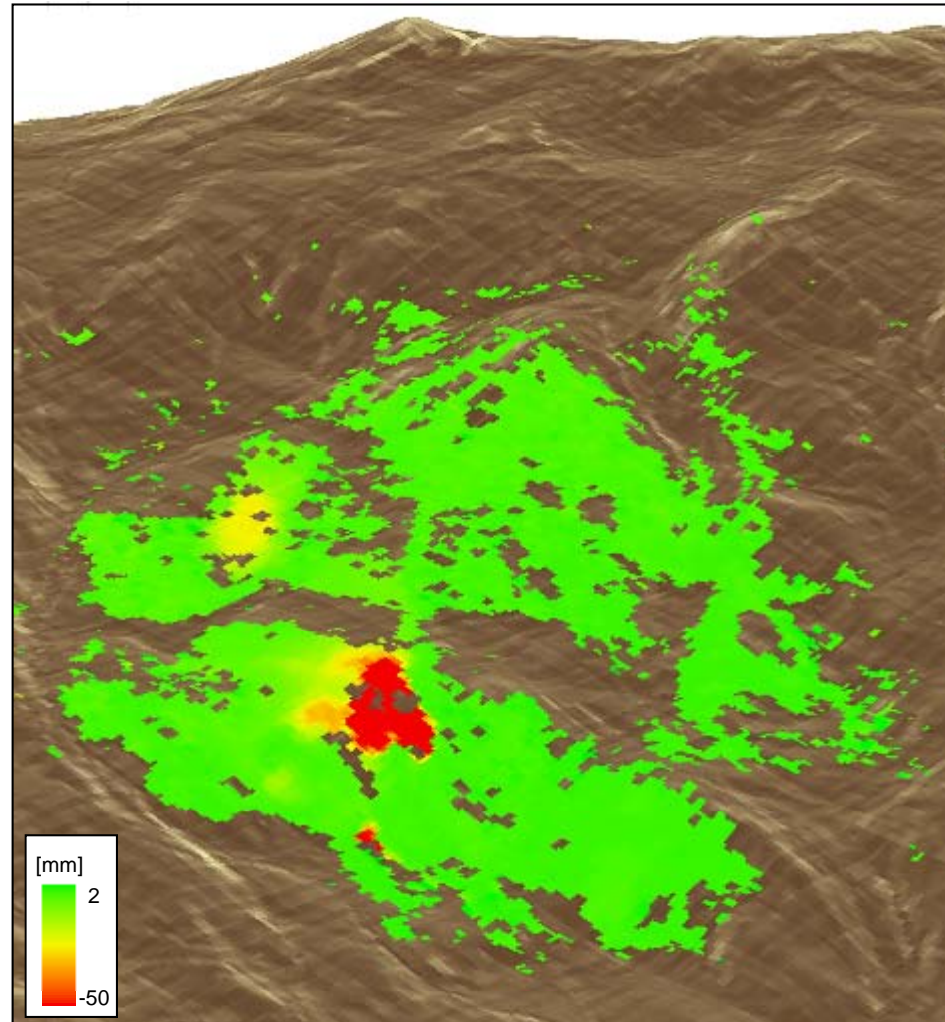
IBIS-L: monitoraggio frane (21 h)

Geocoded Line Of Sight Displacement Map



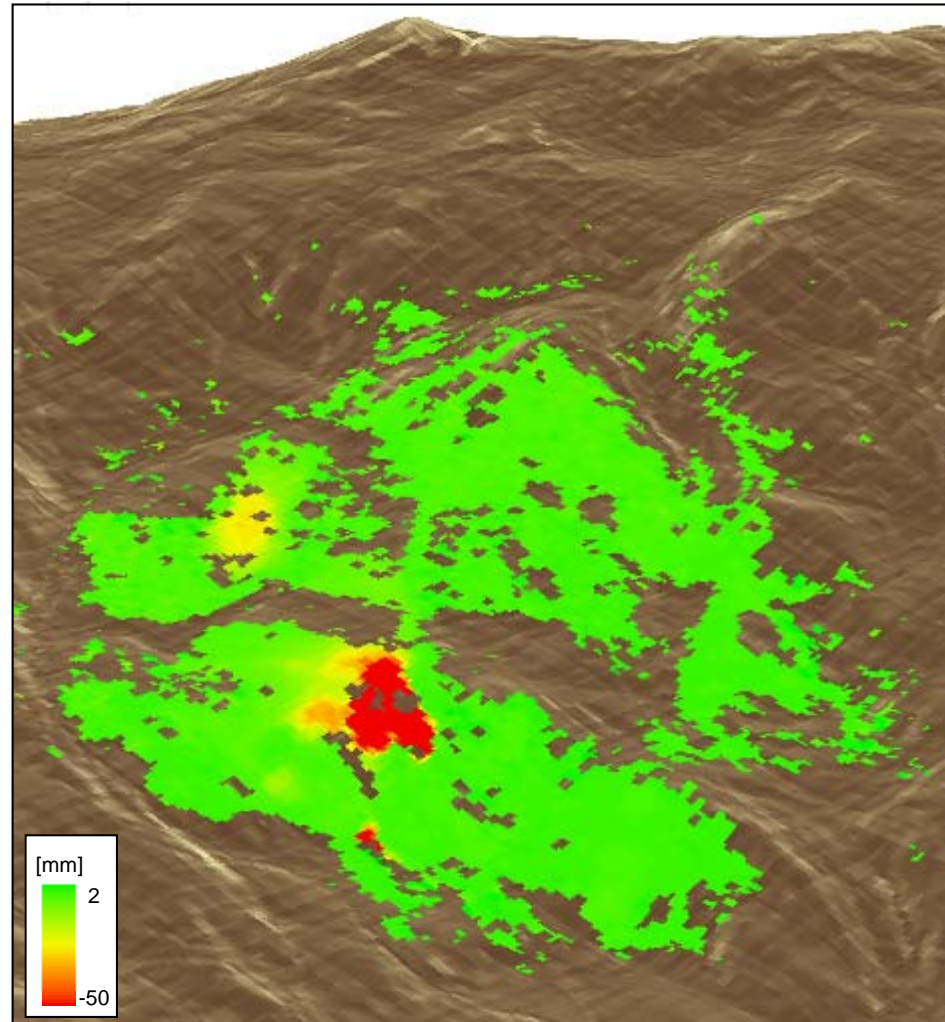
IBIS-L: monitoraggio frane (22 h)

Geocoded Line Of Sight Displacement Map



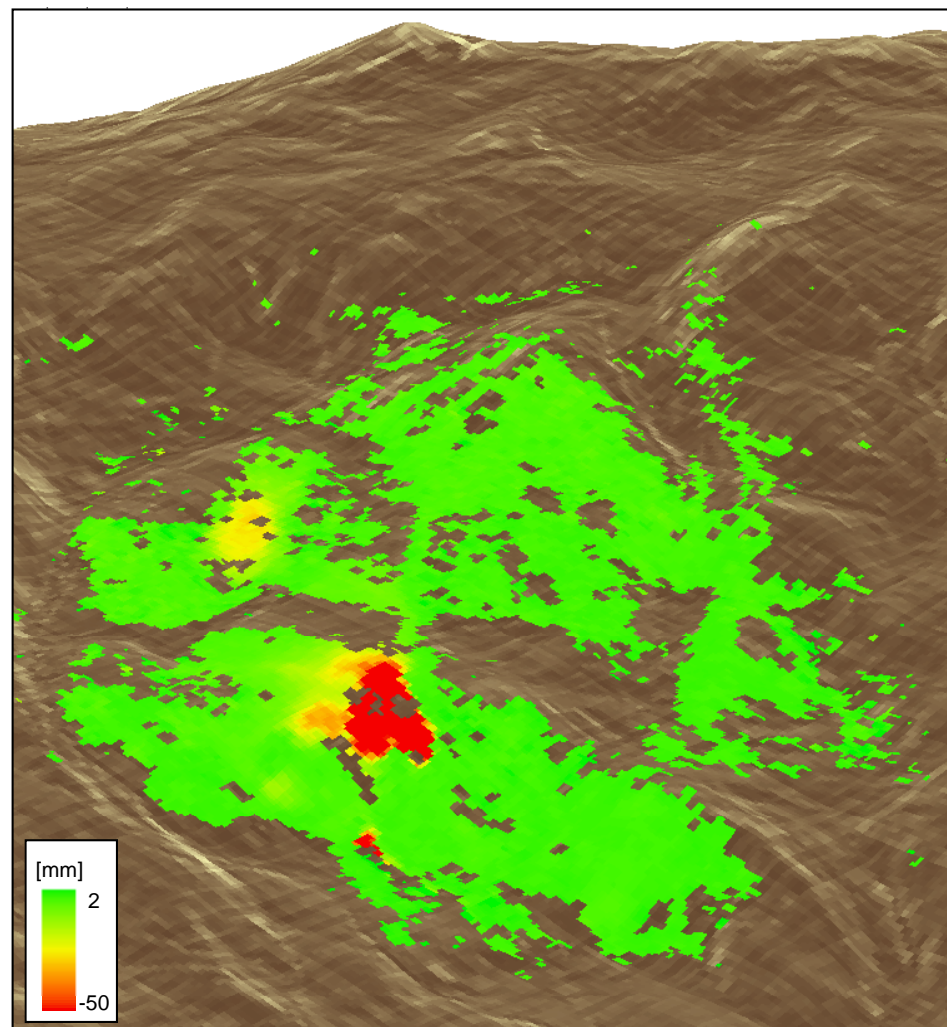
IBIS-L: monitoraggio frane (23 h)

Geocoded Line Of Sight Displacement Map



IBIS-L: monitoraggio frane (24 h)

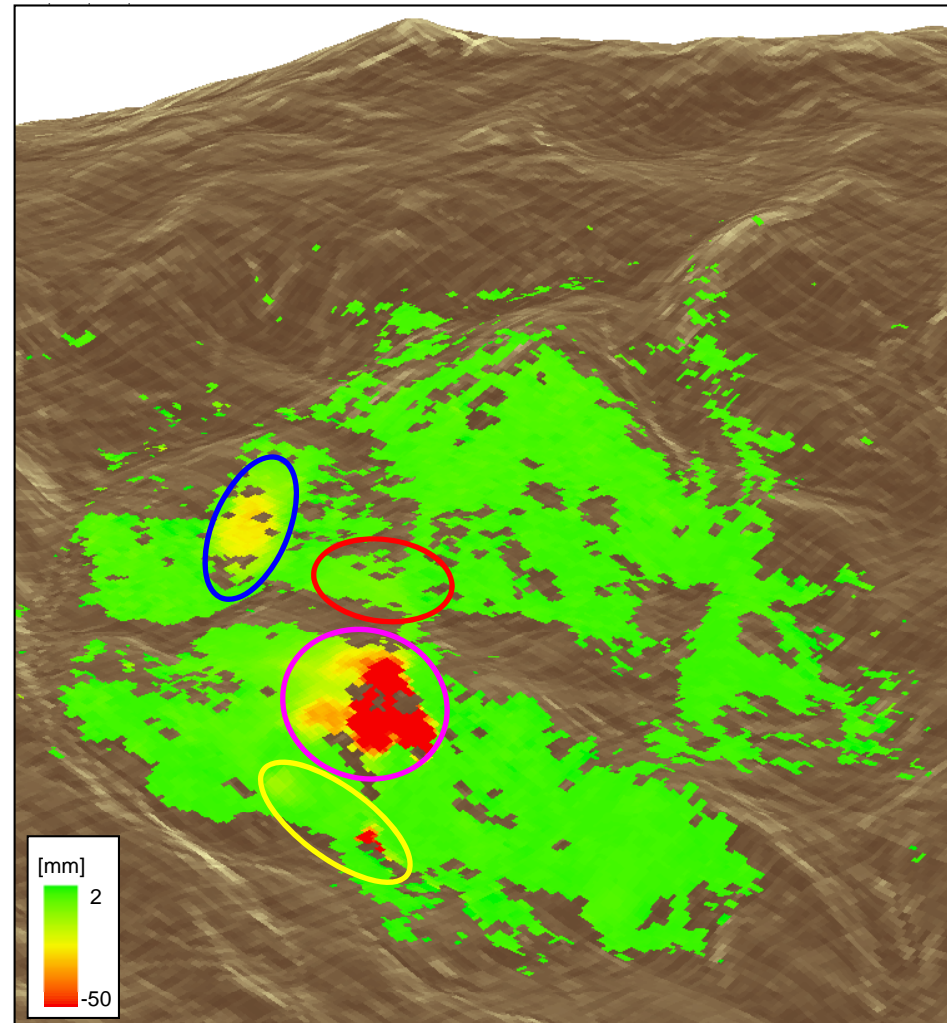
Geocoded Line Of Sight Displacement Map



IBIS-L: monitoraggio frane

Geocoded Line Of Sight Displacement Map

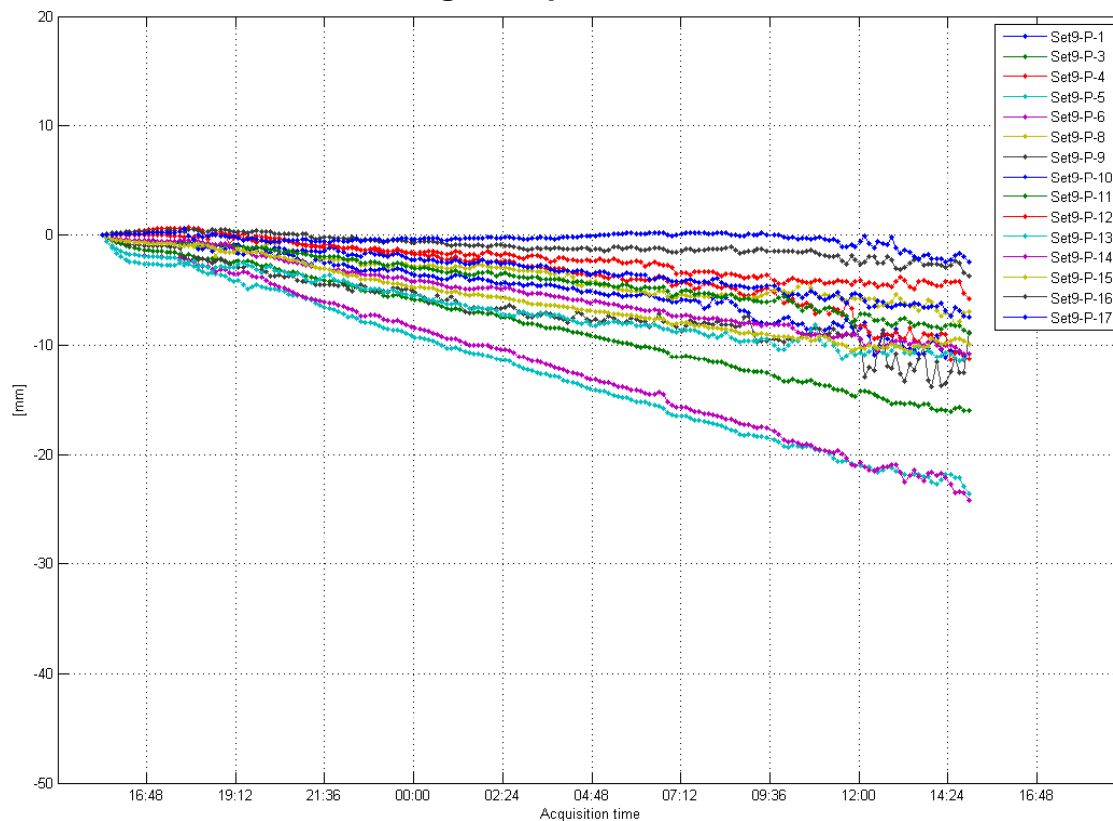
Zona A	Blue
Zona B	Magenta
Zona C	Yellow
Zona D	Red



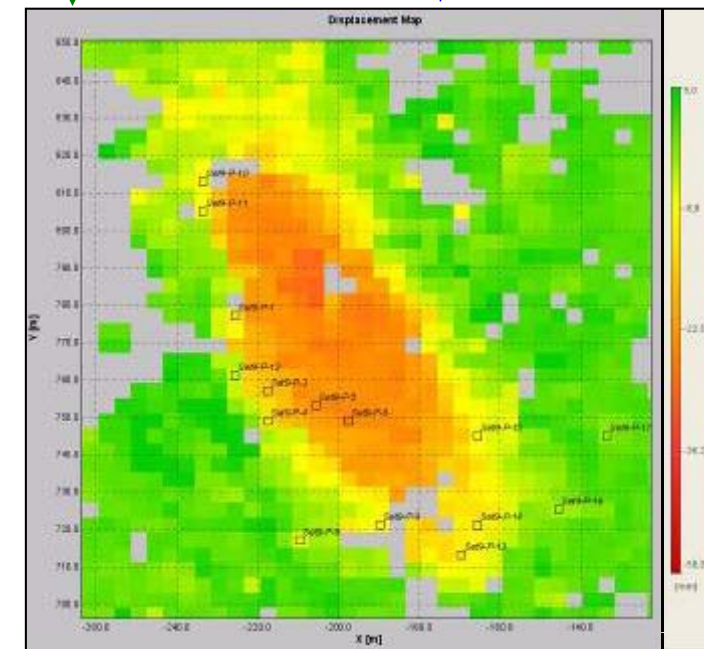
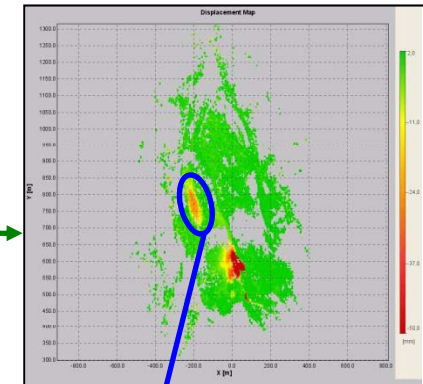
IBIS-L: monitoraggio frane

ZONA A - movimento di alcuni punti di misura selezionati

Line Of Sight Displacement Time Series



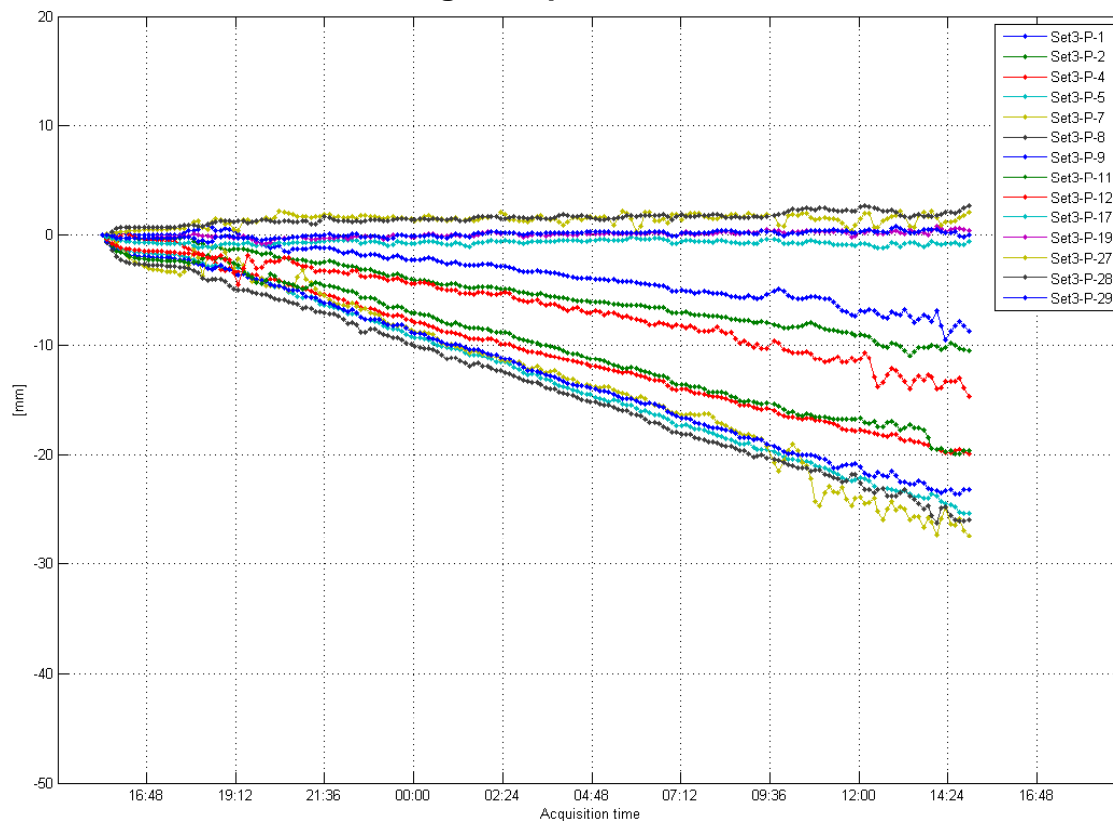
Mappe di
spostamento
cumulato dopo
24 ore



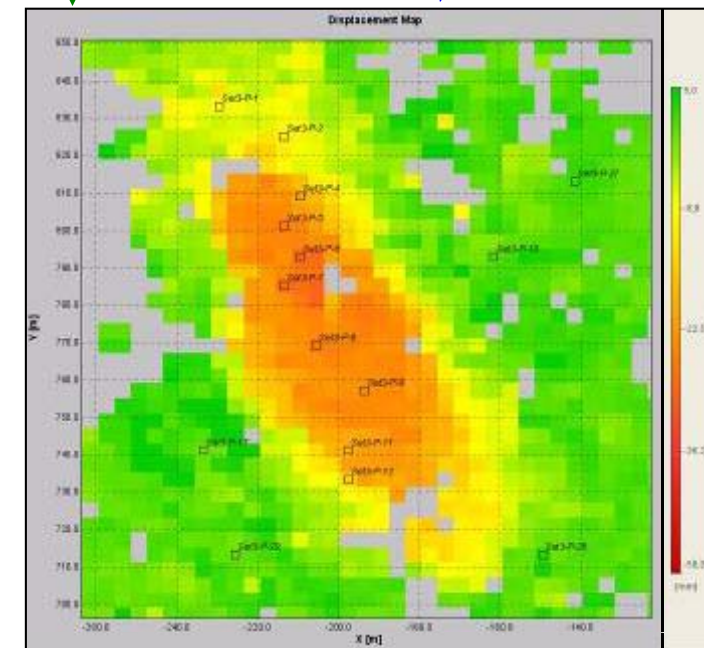
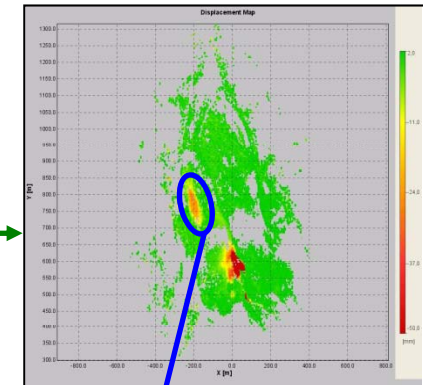
IBIS-L: monitoraggio frane

ZONE A - displacement of a few points

Line Of Sight Displacement Time Series



Mappe di
spostamento
cumulato dopo
24 ore



IBIS-M: stabilità dei fronti di scavo

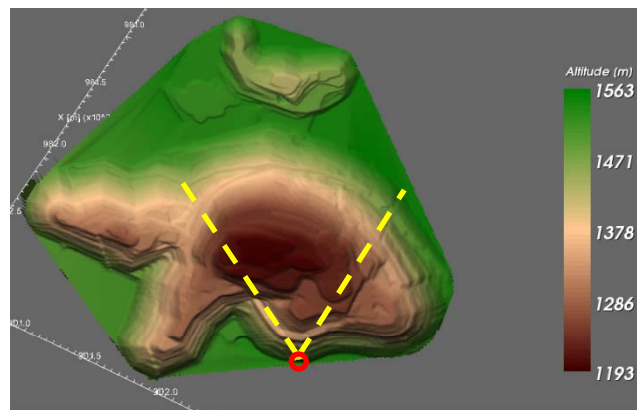


Following a 80,000 ton slip occurred in late 2009 and the consequent closure of operations, an IBIS-M unit was deployed in January 2010 at the Pipeline pit in Cortez, Nevada, owned by Barrick.

The IBIS-M system was aimed at providing early warnings and support for geotechnical evaluation purposes.

After 7 months of rental of the equipment, in July 2010, the IBIS-M unit was purchased by Barrick.

IBIS-M: stabilità dei fronti di scavo



DISTANCE FROM THE SLOPE	[m]	800 – 1500
ANTENNA BEAM WIDTH	[deg]	68
NUMBER OF POINTS	-	90.000
RANGE RESOLUTION	[m]	0.5 (1.64 ft)
CROSS-RANGE RESOLUTION	[mrad]	4.5
SCANNING TIME	[min]	5

IBIS-M: stabilità dei fronti di scavo

Shelter (pit rim)

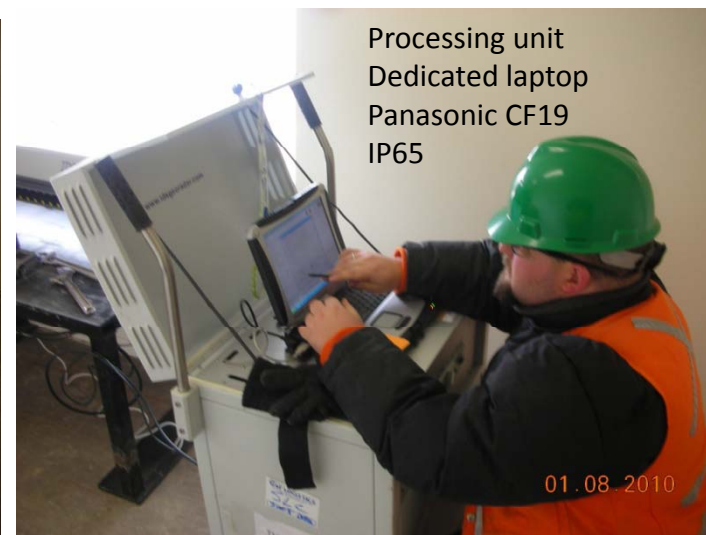
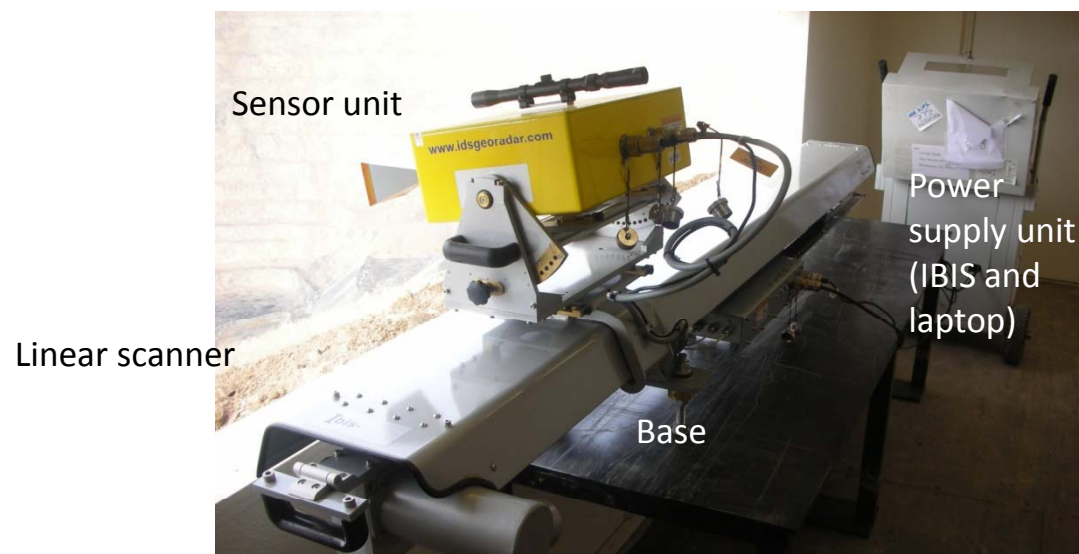
IBIS-M basic configuration unit
Fully enclosed (HVAC, WiFi)
Mine grid power supply
Backup power (1 day with genset)
IBIS Controller Software
24/7 functioning



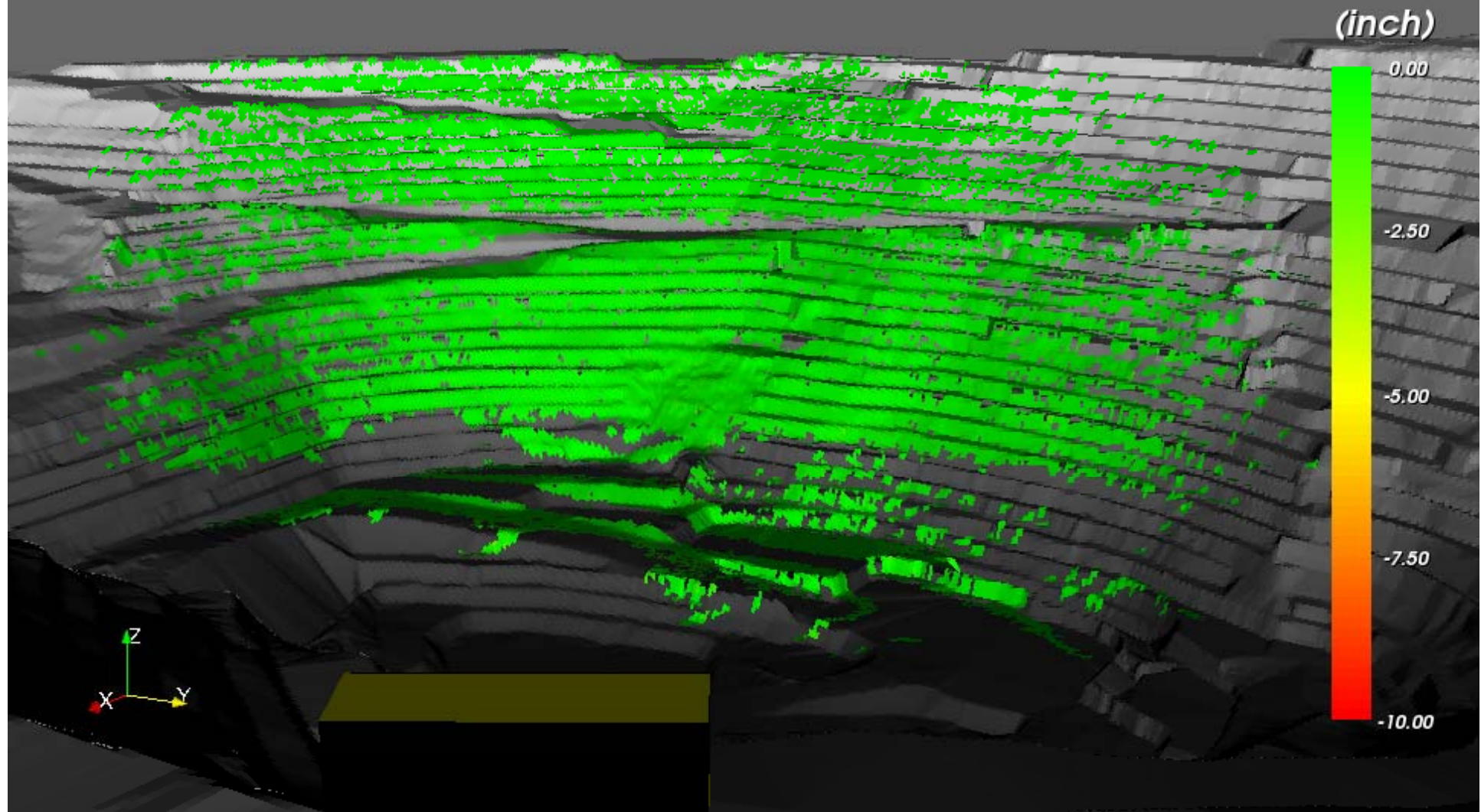
VPN, VNC
connections



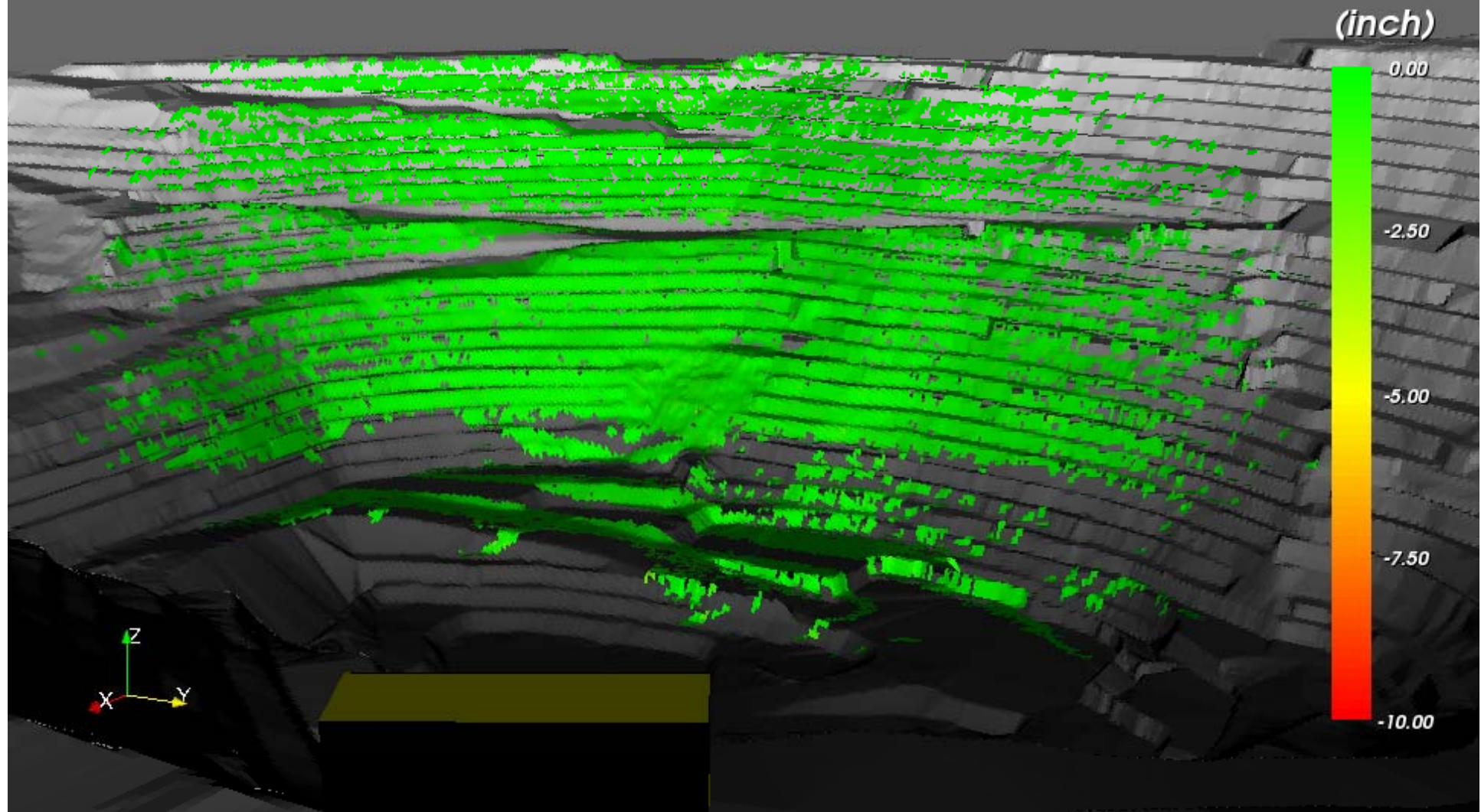
IBIS-M: stabilità dei fronti di scavo



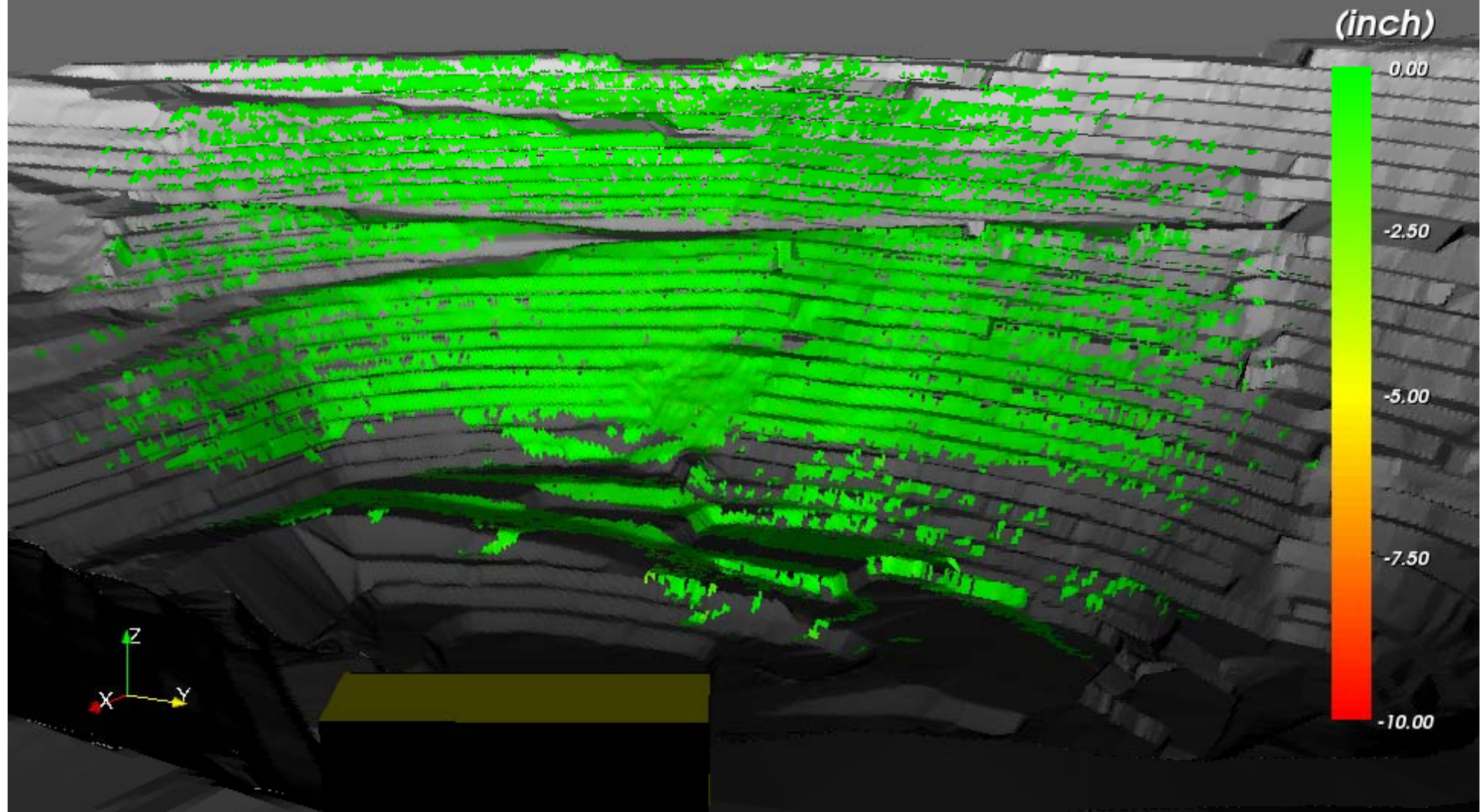
Cumulative displacement from 03/02 to 18/02



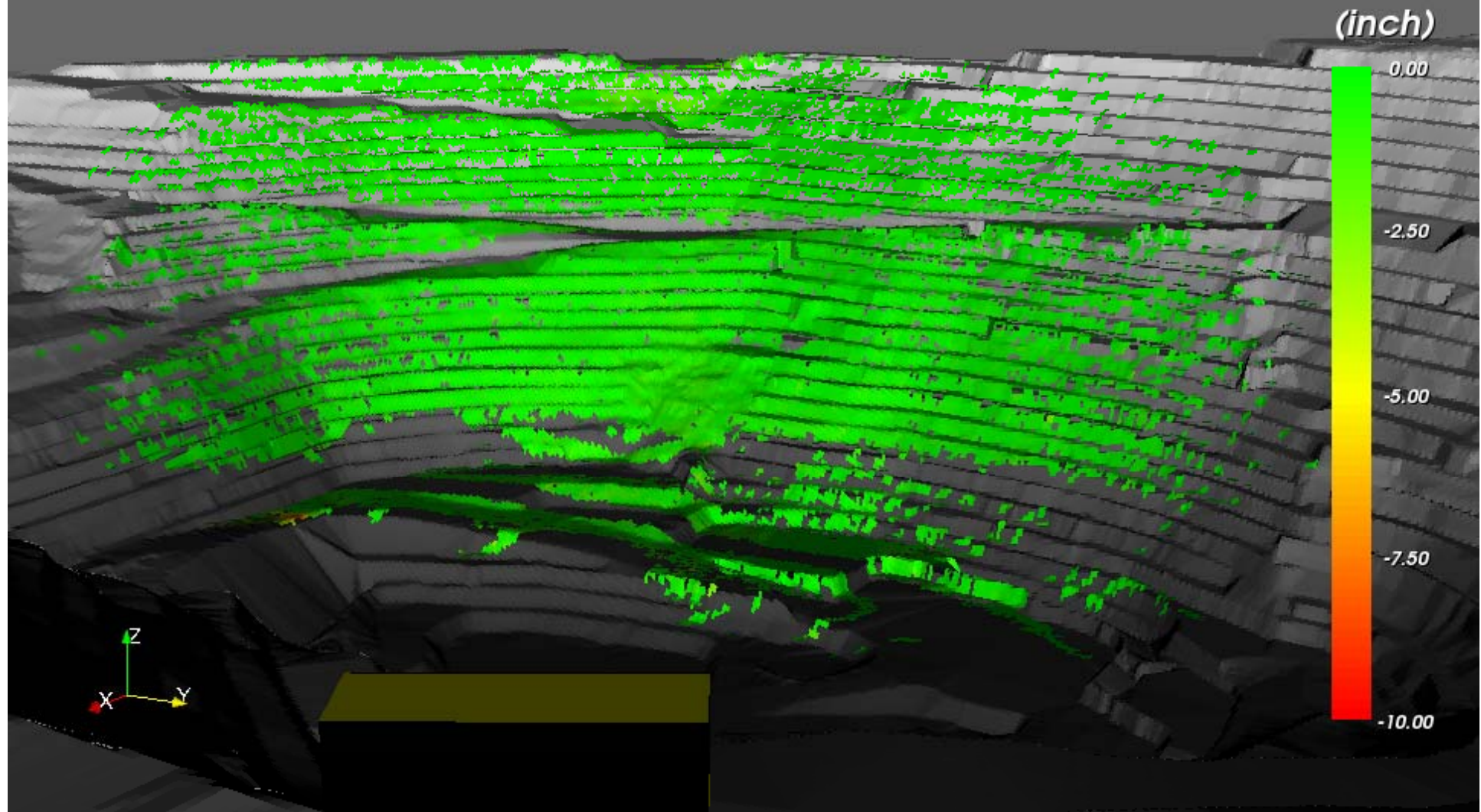
Cumulative displacement from 03/02 to 25/02



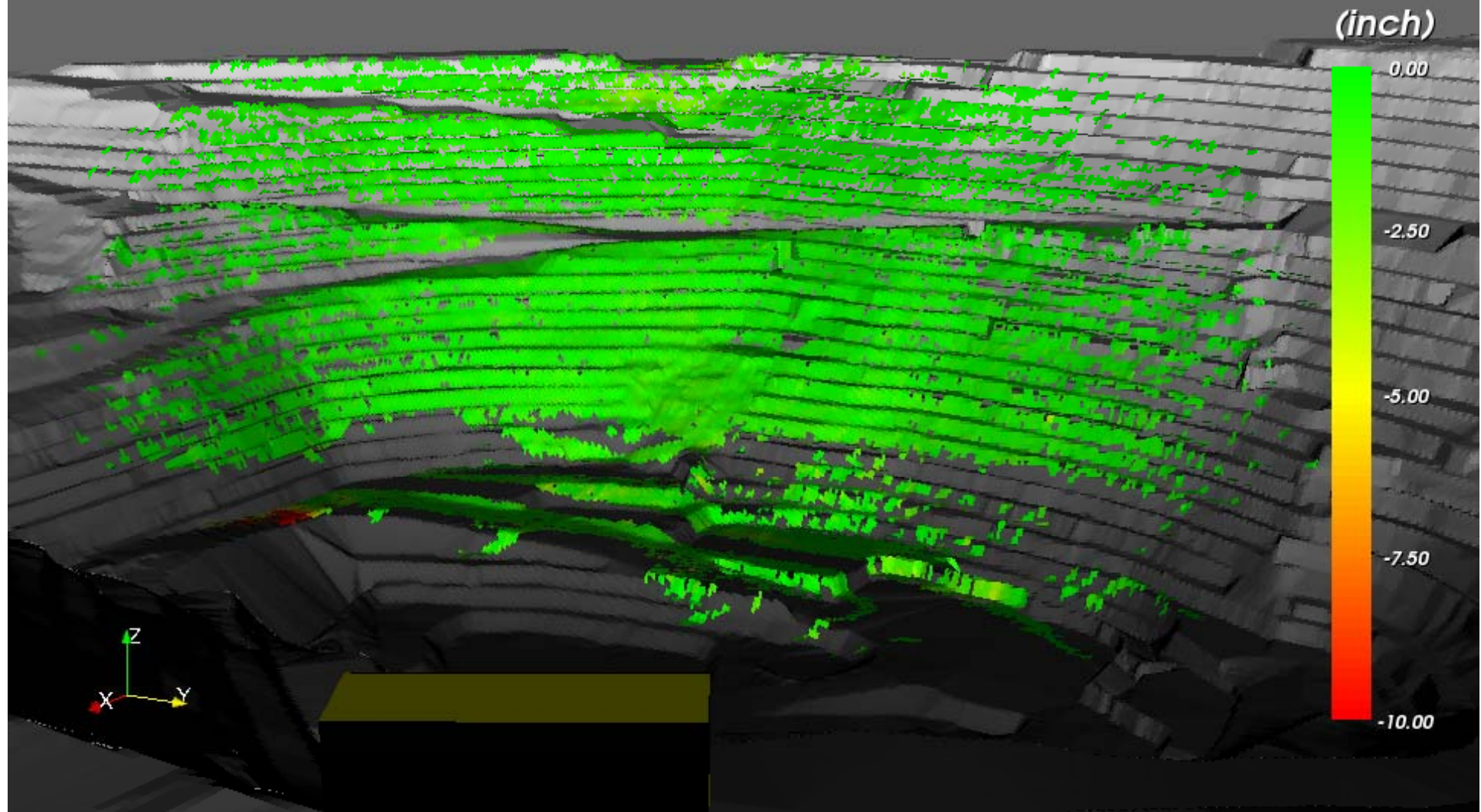
Cumulative displacement from 03/02 to 07/03



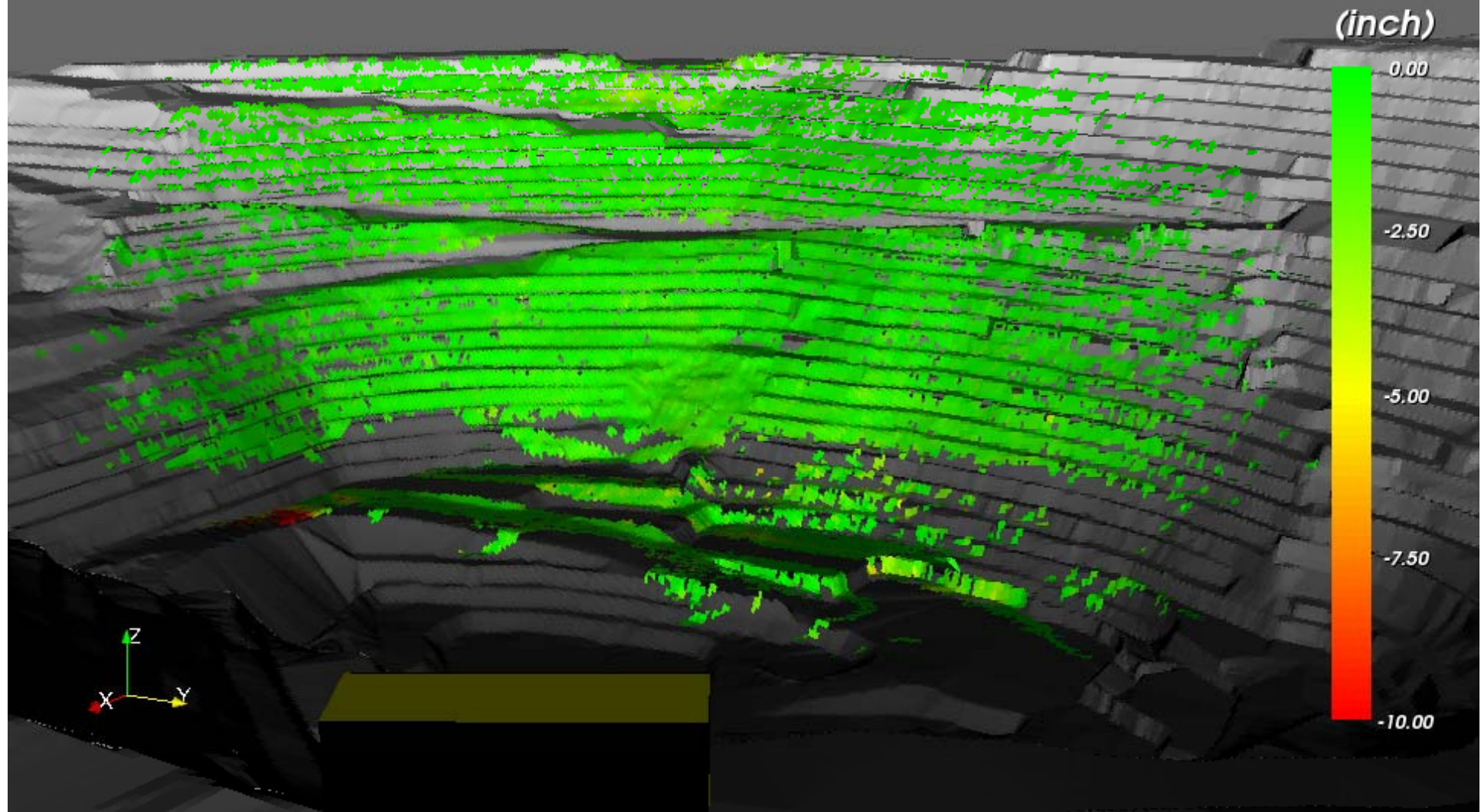
Cumulative displacement from 03/02 to 21/03



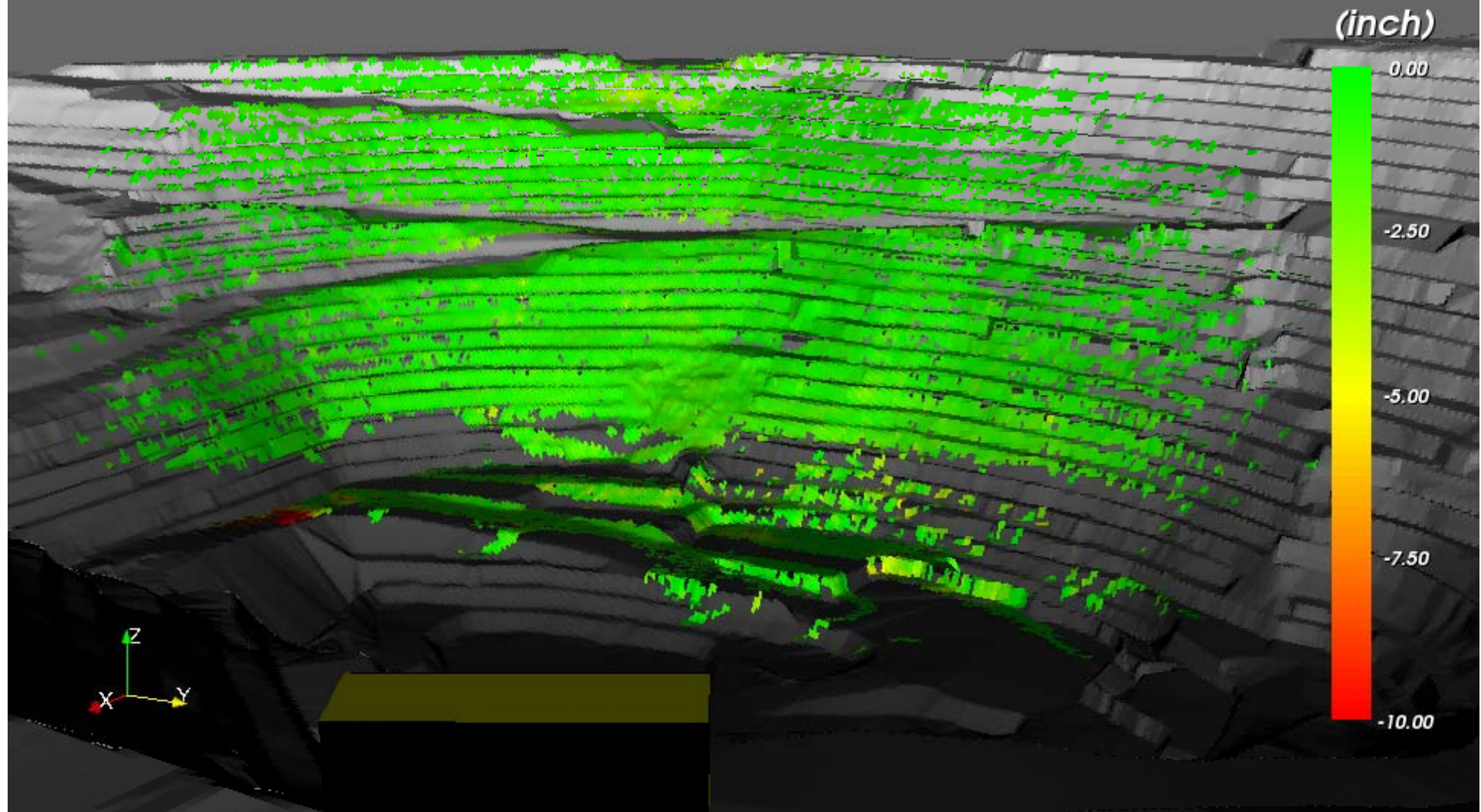
Cumulative displacement from 03/02 to 04/04



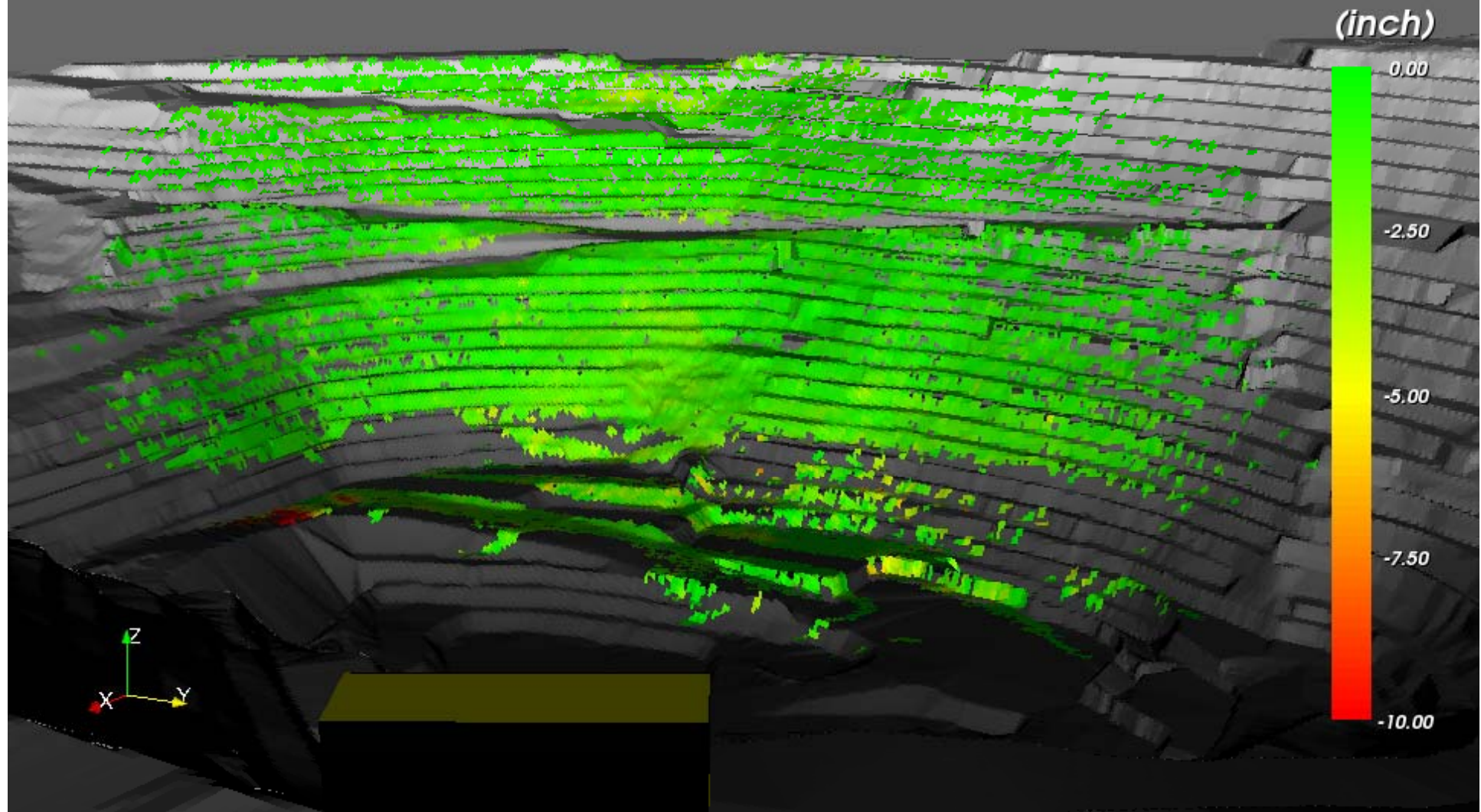
Cumulative displacement from 03/02 to 19/04



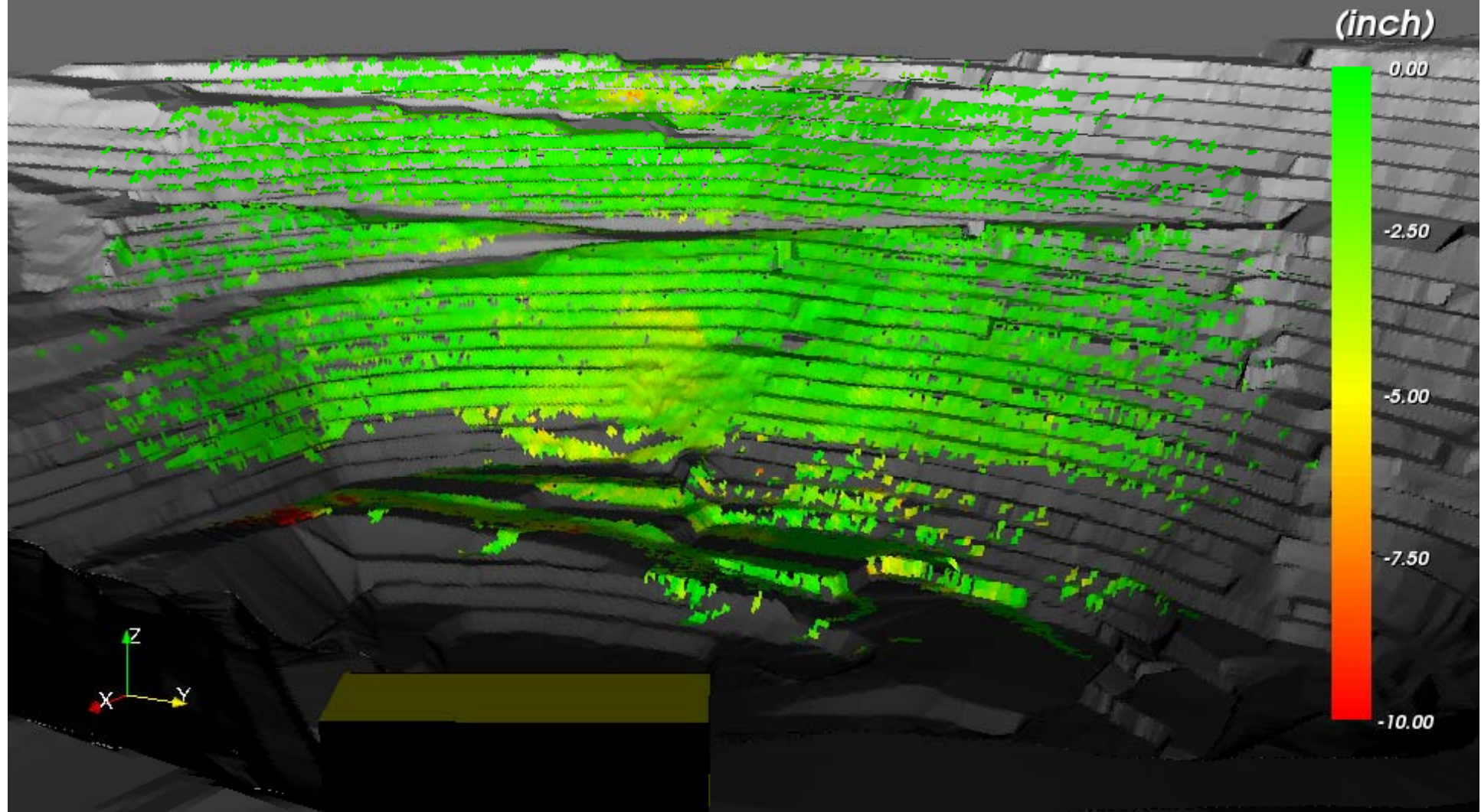
Cumulative displacement from 03/02 to 04/05



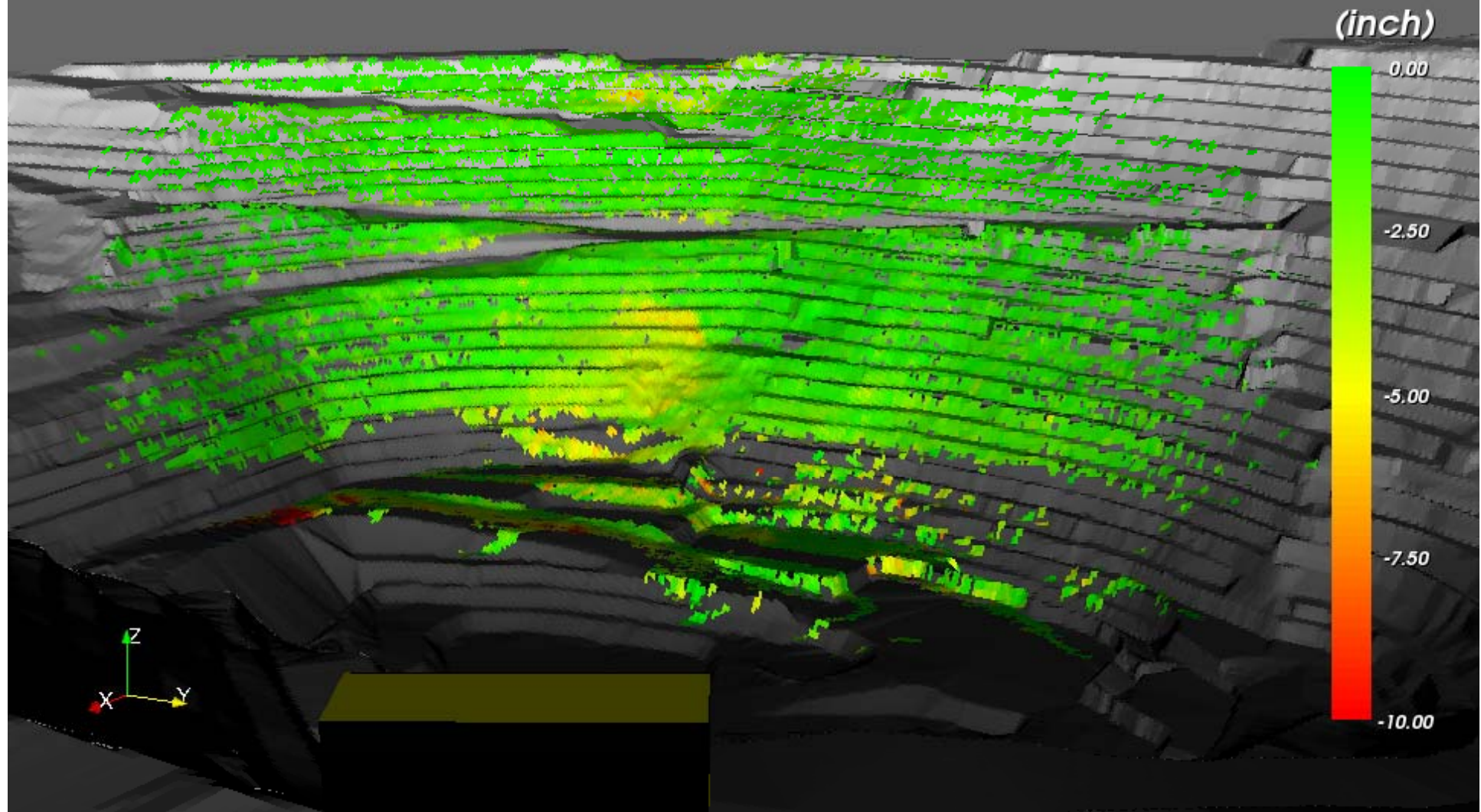
Cumulative displacement from 03/02 to 18/05



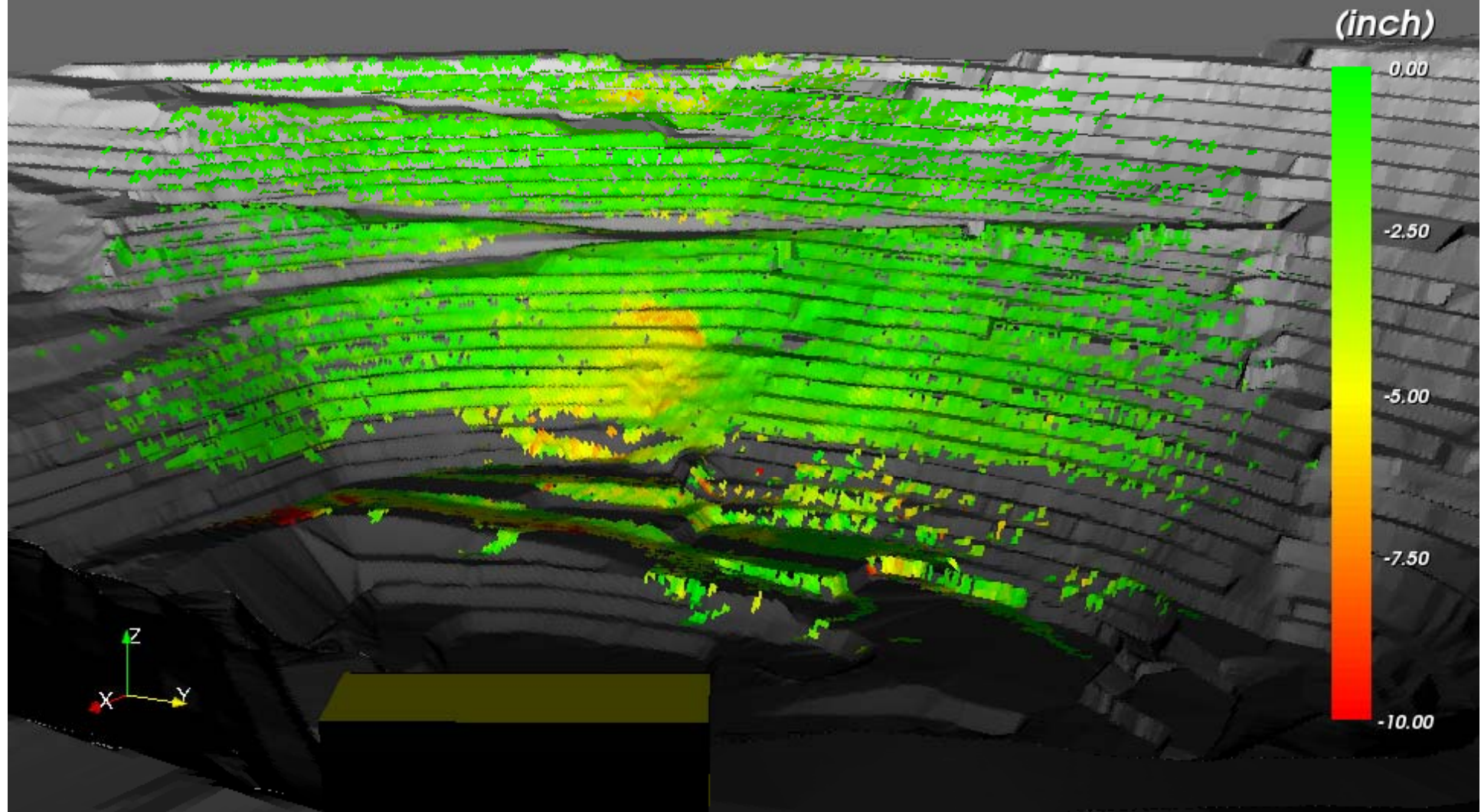
Cumulative displacement from 03/02 to 01/06



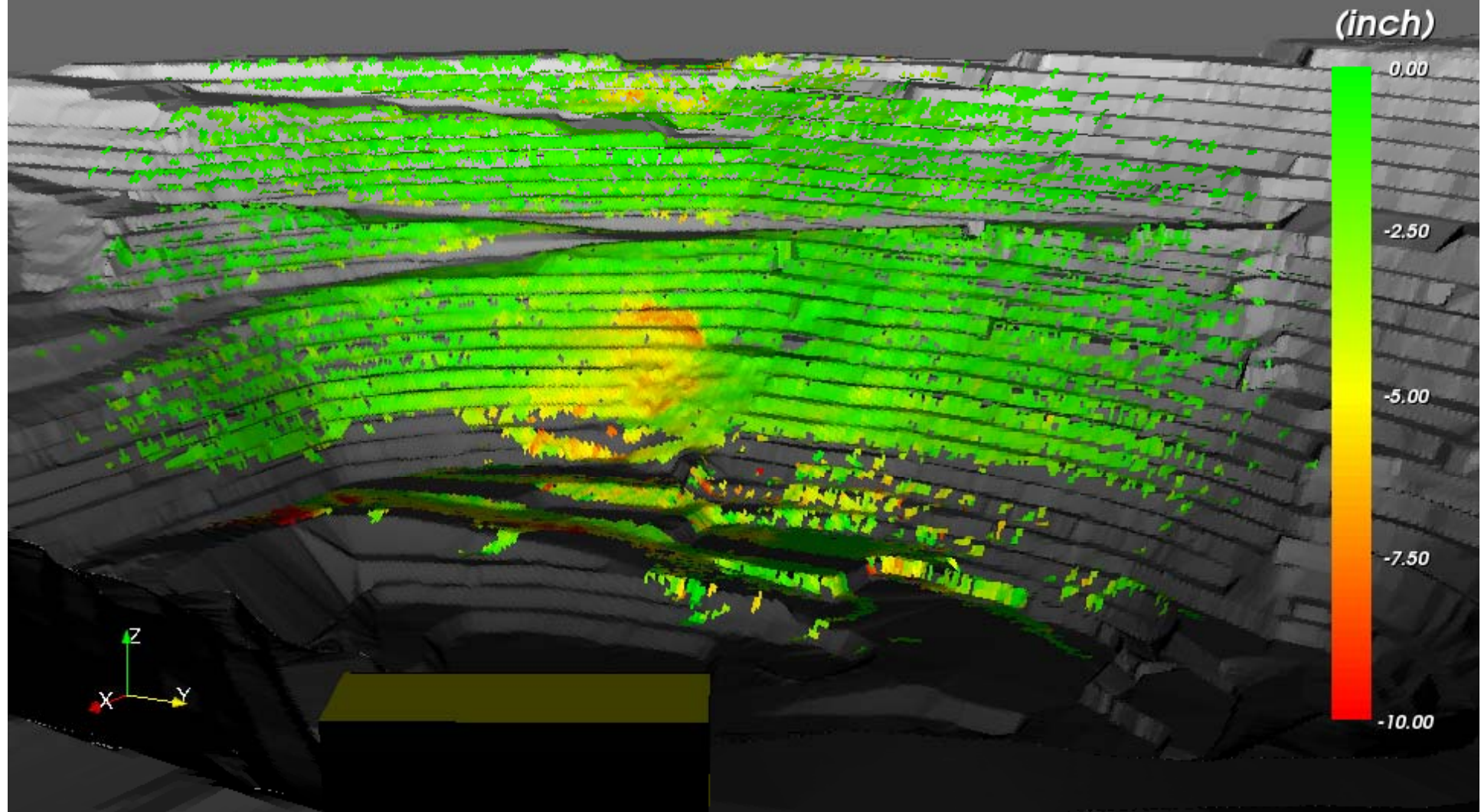
Cumulative displacement from 03/02 to 15/06



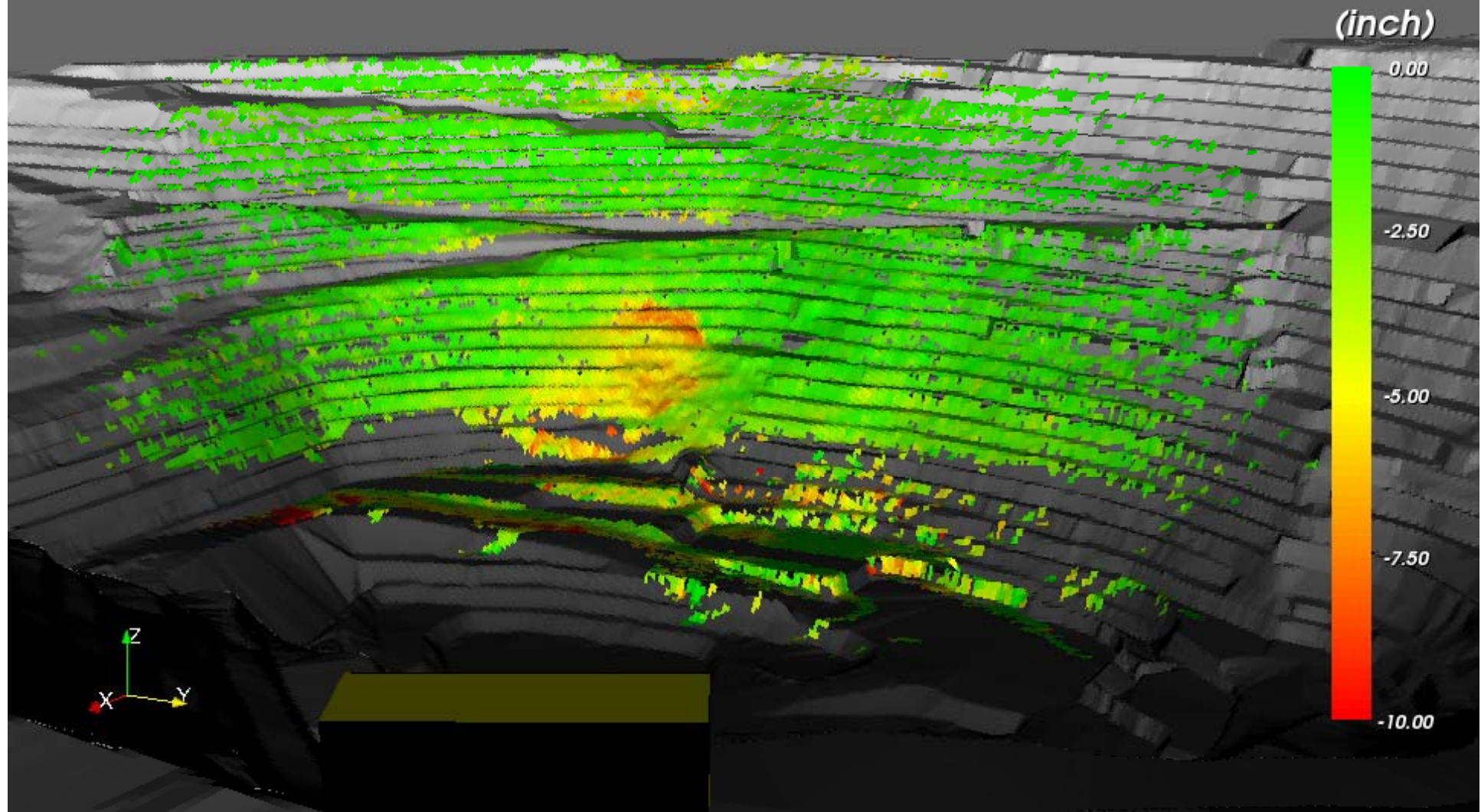
Cumulative displacement from 03/02 to 29/06



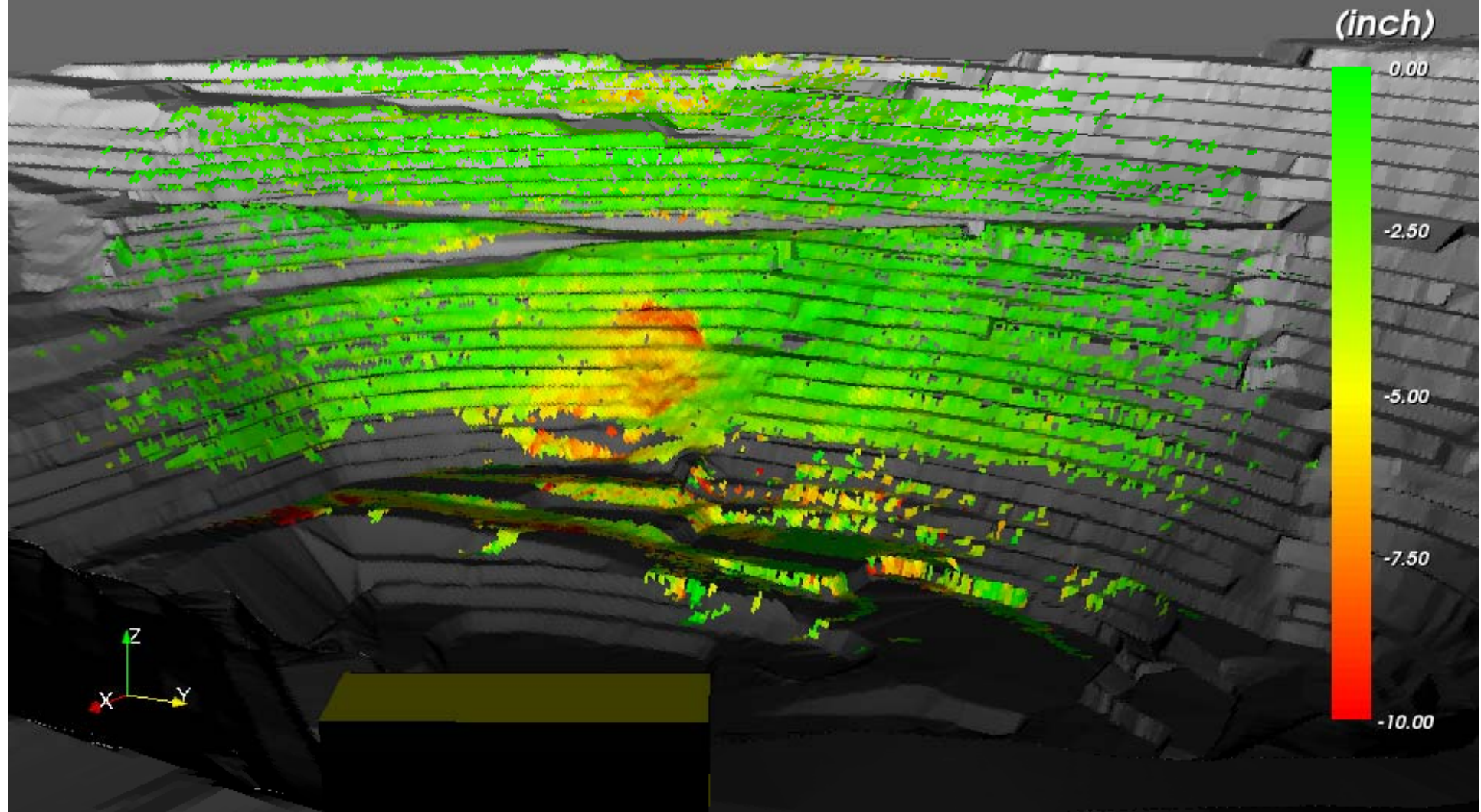
Cumulative displacement from 03/02 to 14/07



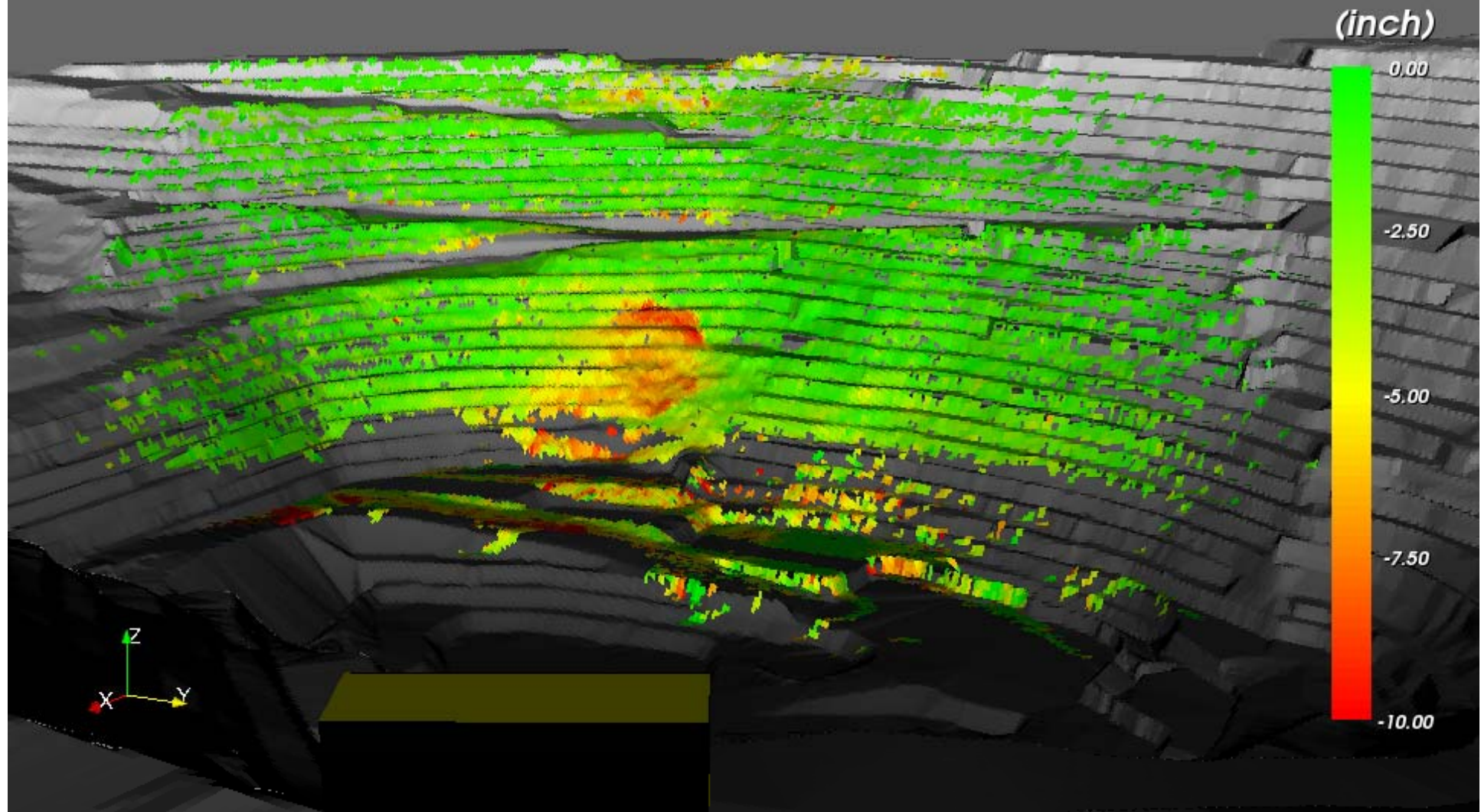
Cumulative displacement from 03/02 to 29/07



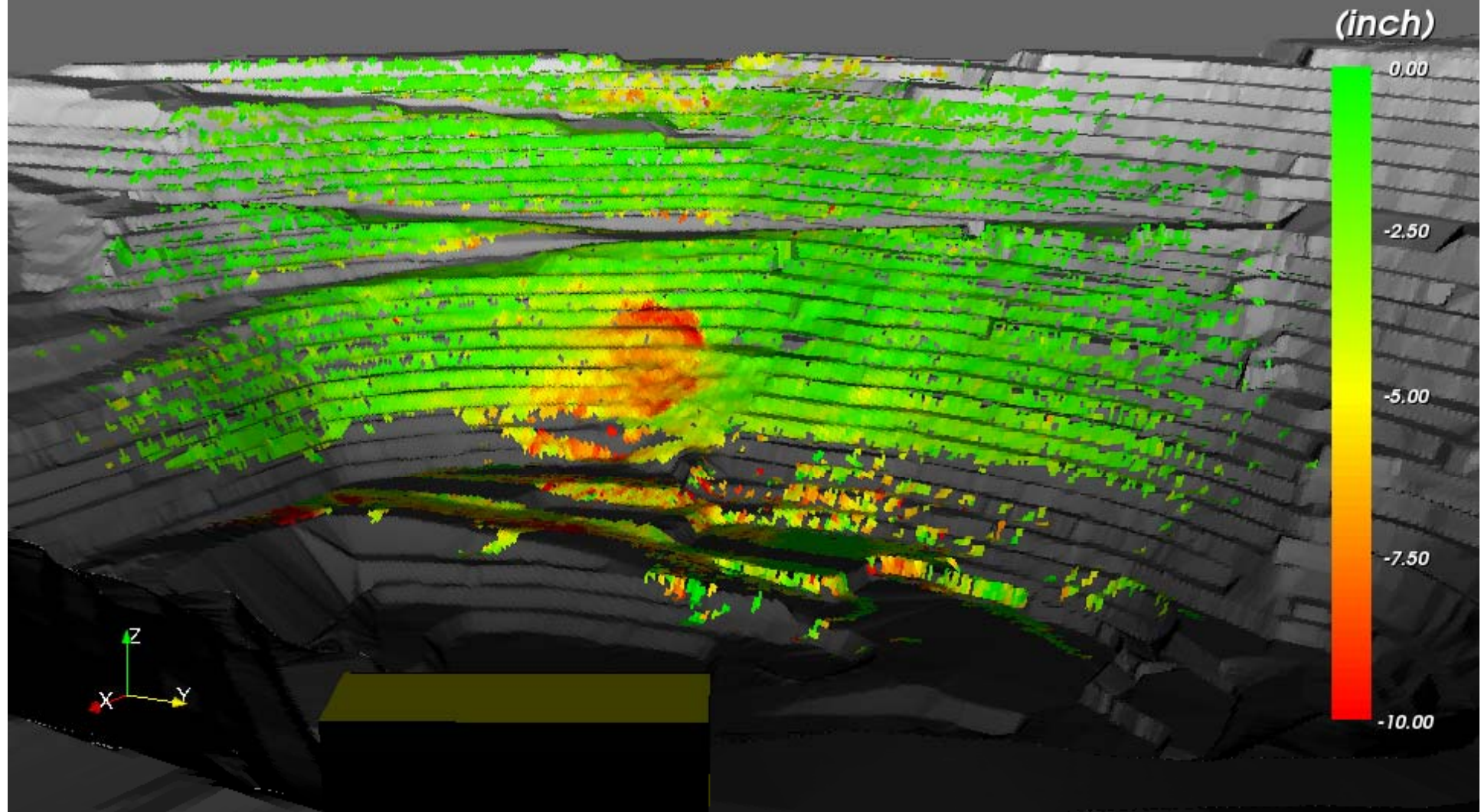
Cumulative displacement from 03/02 to 13/08



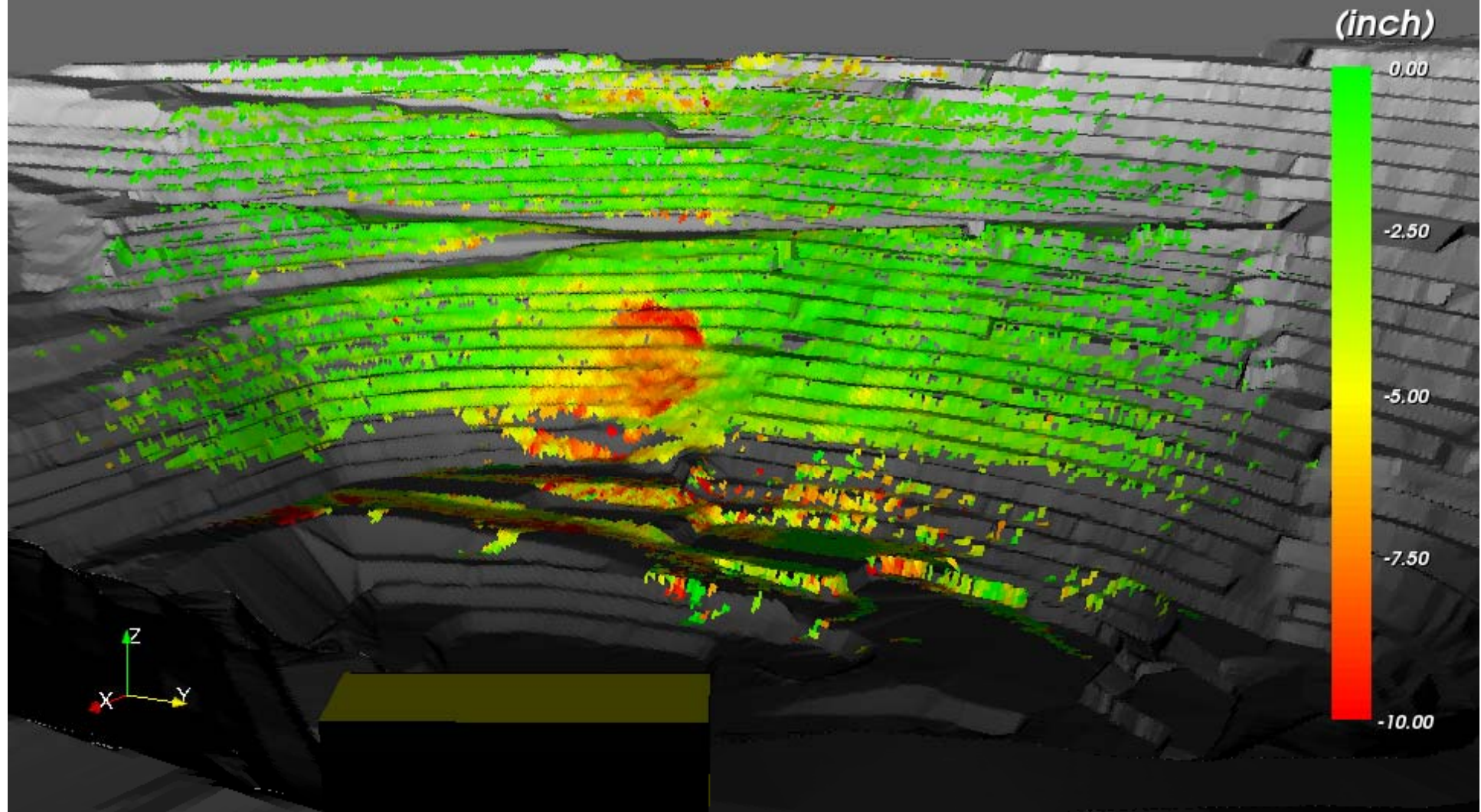
Cumulative displacement from 03/02 to 27/08



Cumulative displacement from 03/02 to 10/09

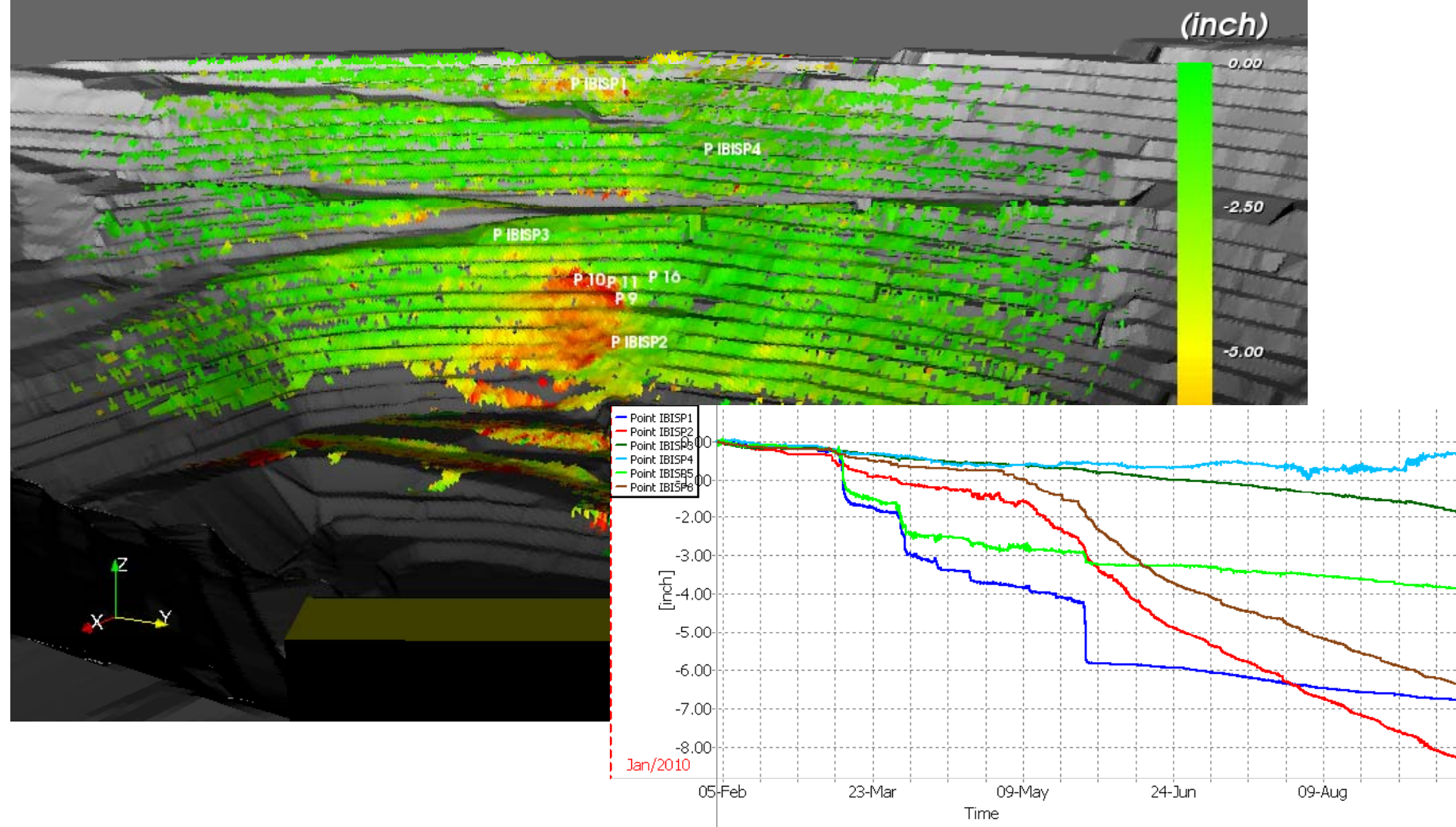


Cumulative displacement from 03/02 to 21/09



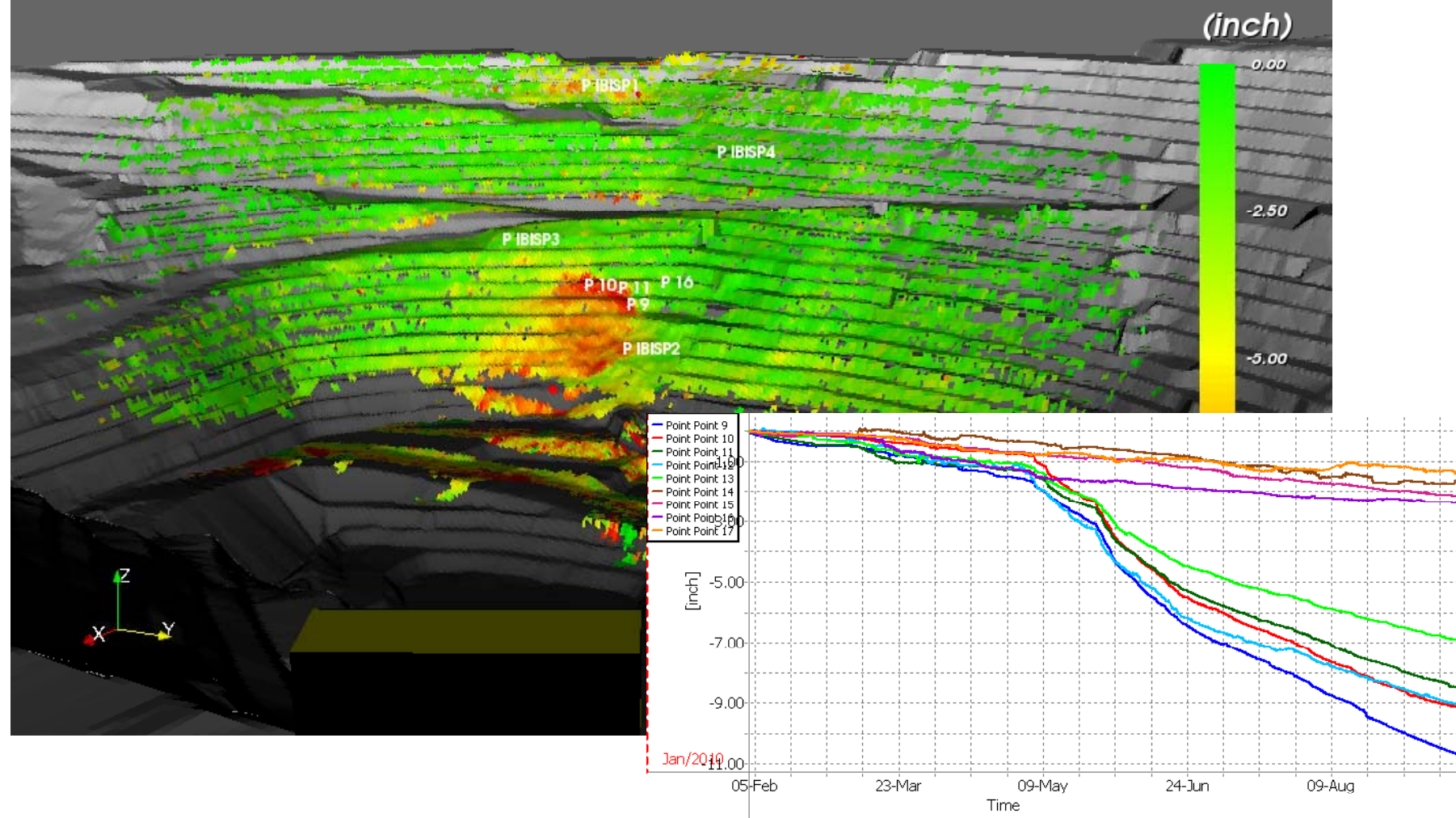
Start Time: 15:33 03/02/10
Stop Time: 08:37 21/09/10

Cumulative displacement from 03/02 to 21/09: time series



Start Time: 15:33 03/02/10
Stop Time: 08:37 21/09/10

Cumulative displacement from 03/02 to 21/09: time series

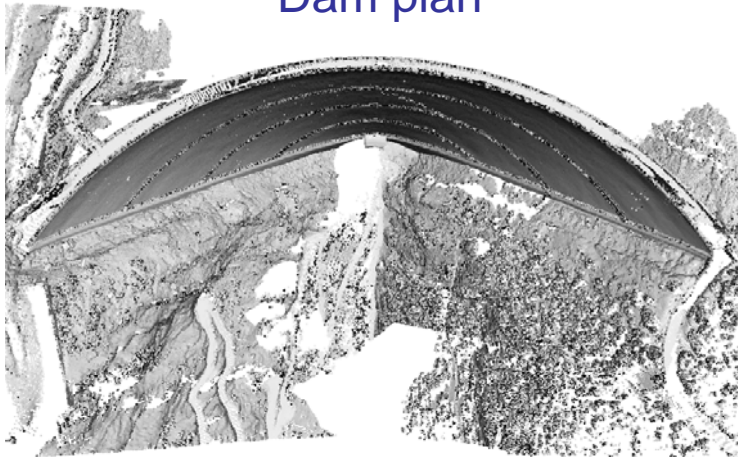


IBIS-L: monitoraggio dighe

Cancano Dam view



Dam plan



Dam characteristics

Dam Type	Gravity arch
Location	Alpi Retiche - Italy
Dam height (m)	125.5
Crowing length (m)	381

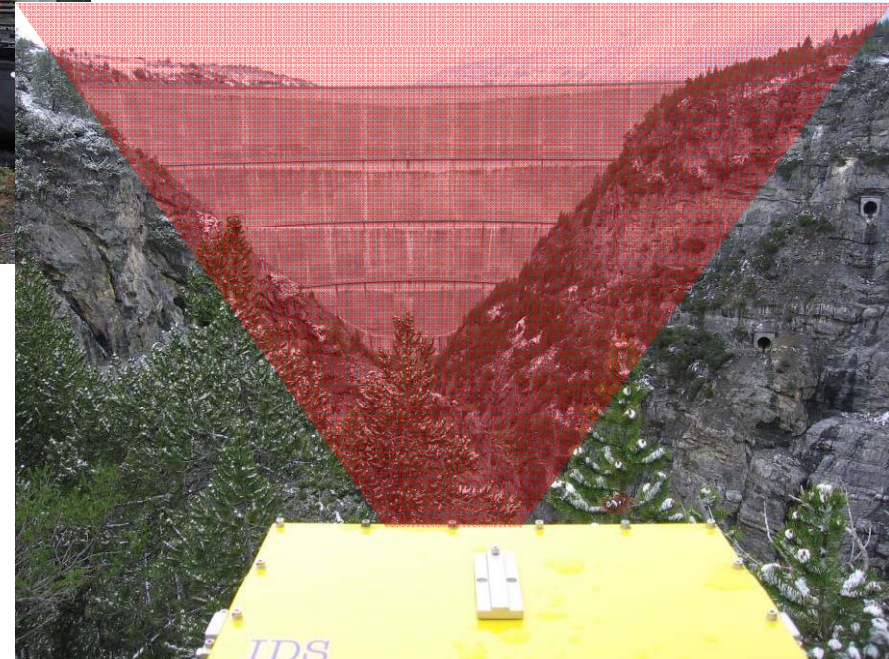
Survey performed with the
Surveying Dept. of Milan Polytechnic

IBIS-L: monitoraggio dighe



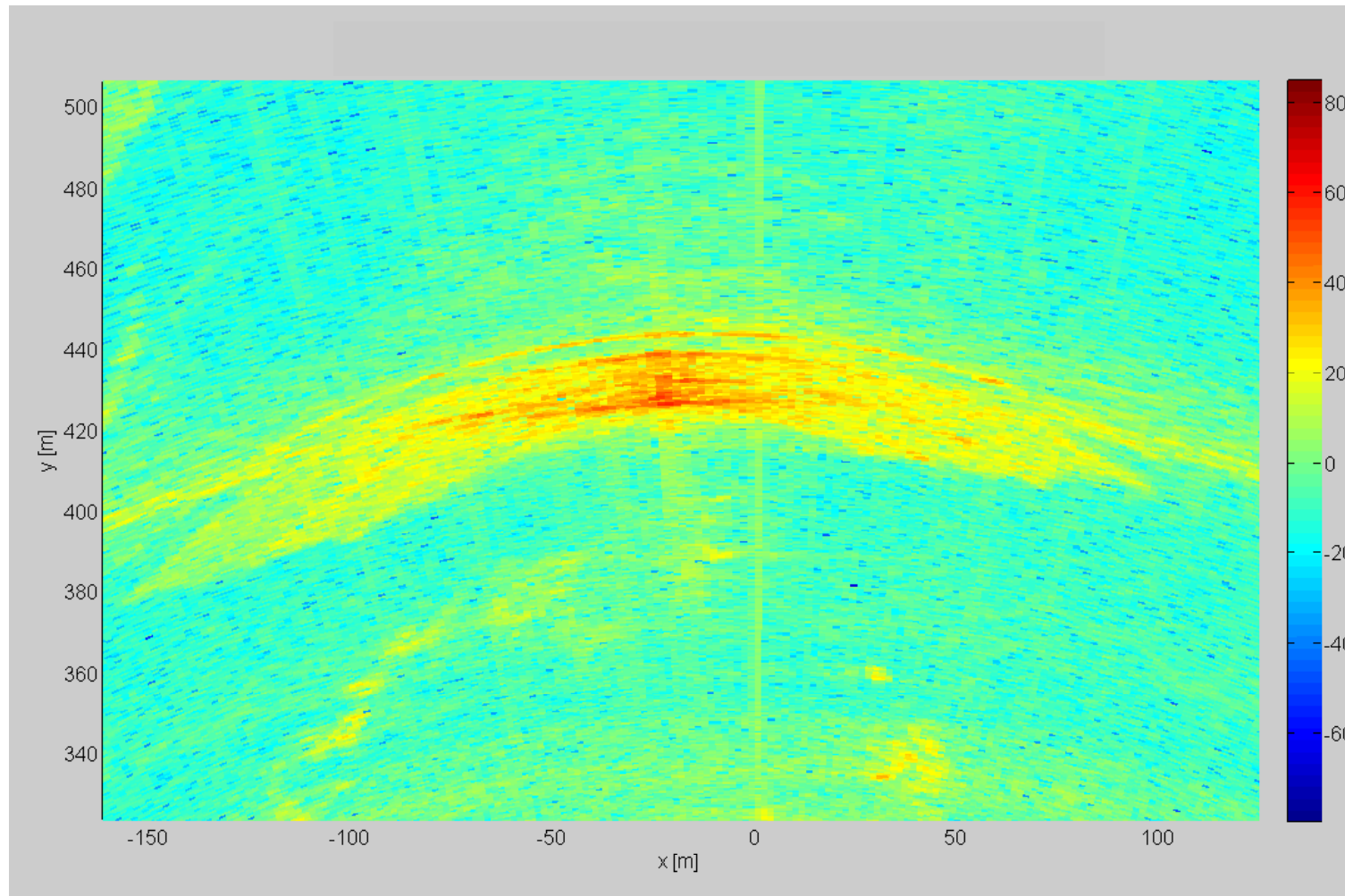
IBIS-L configuration

- Dam-sensor distance: 400m
- Range resolution: 0.5m
- Angle resolution: 4.7mrad
- Sampling interval: ca. 9 minutes



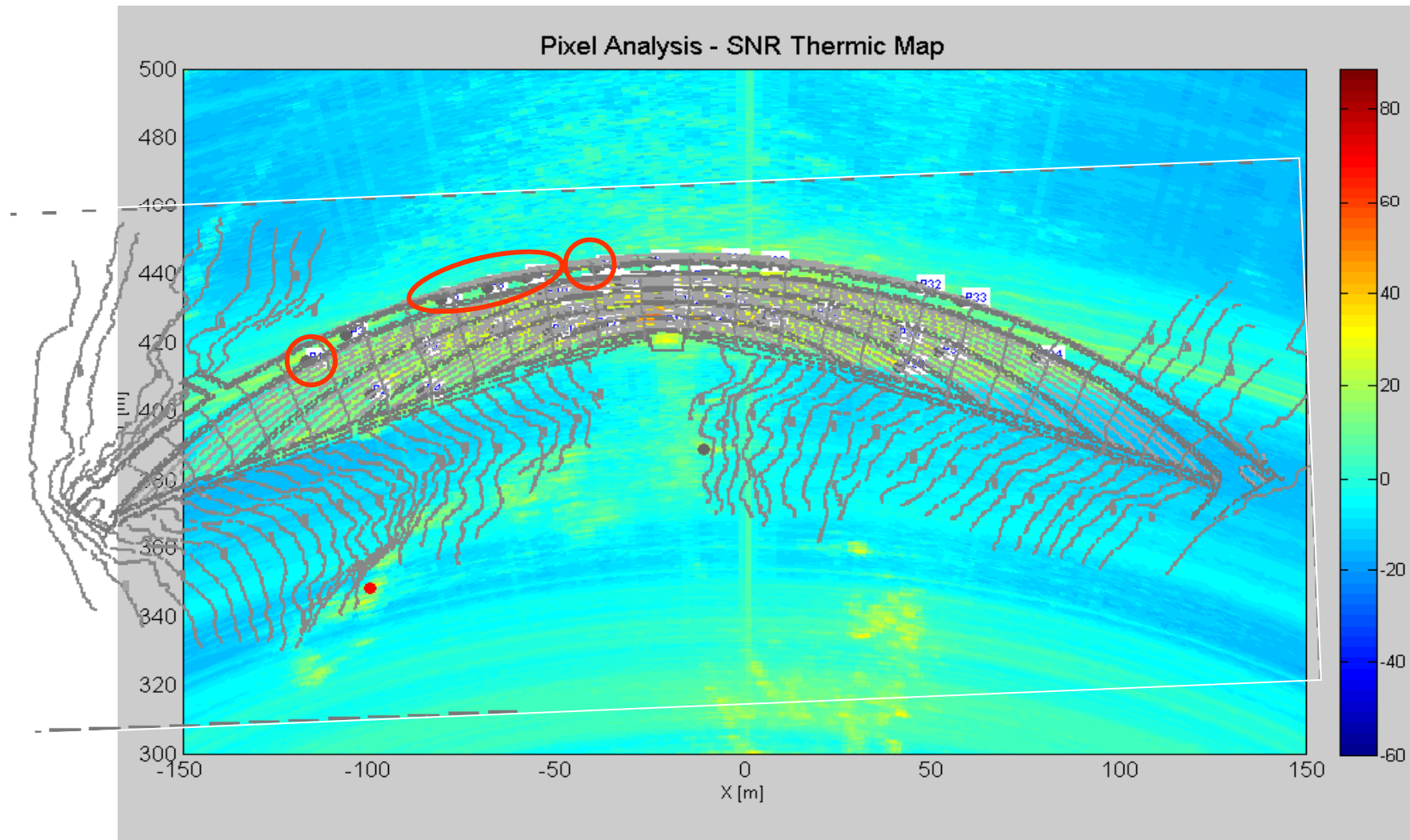
IBIS-L: monitoraggio dighe

Zoom on dam area



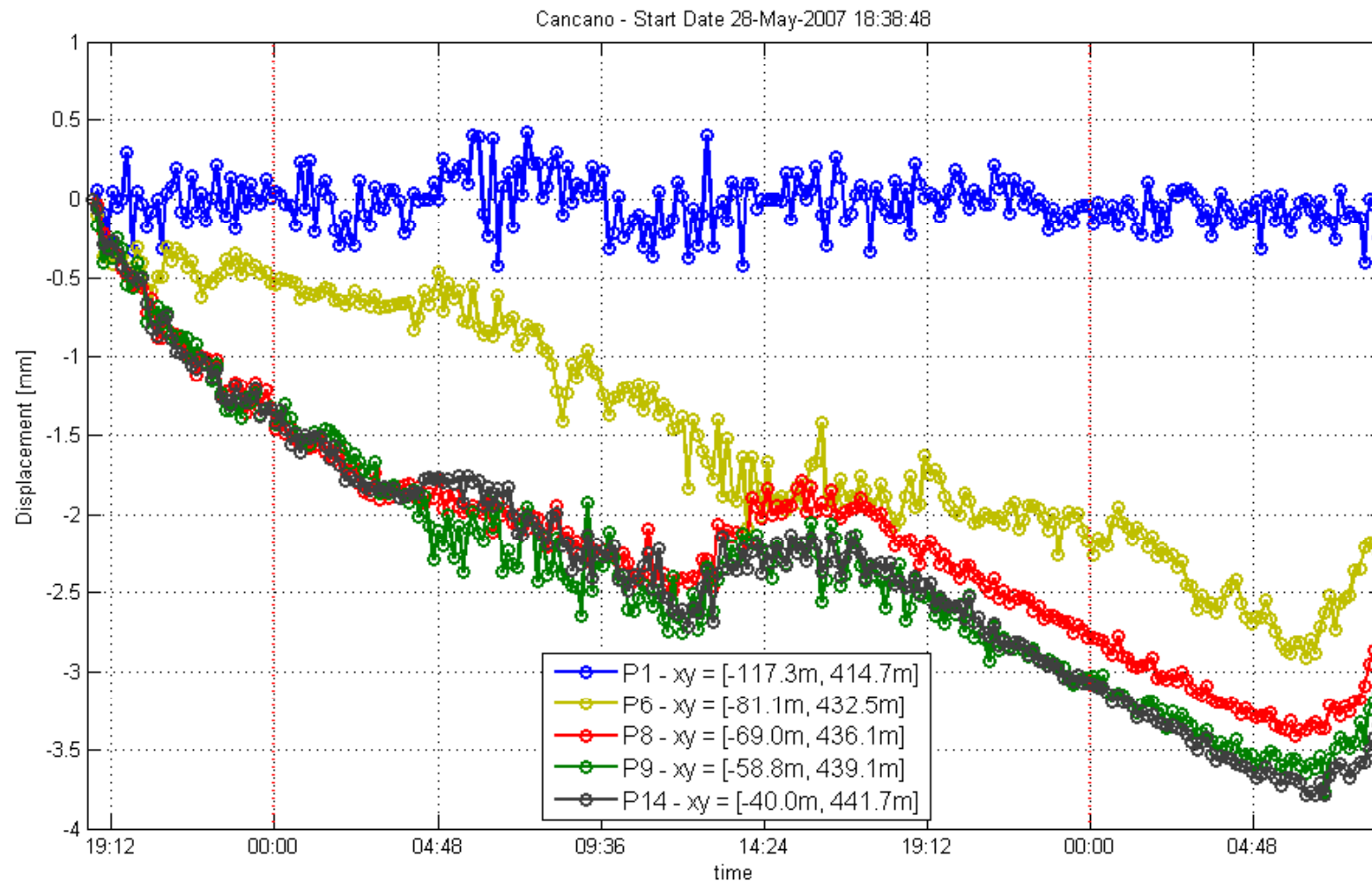
IBIS-L: monitoraggio dighe

Dam Power map projected over plan

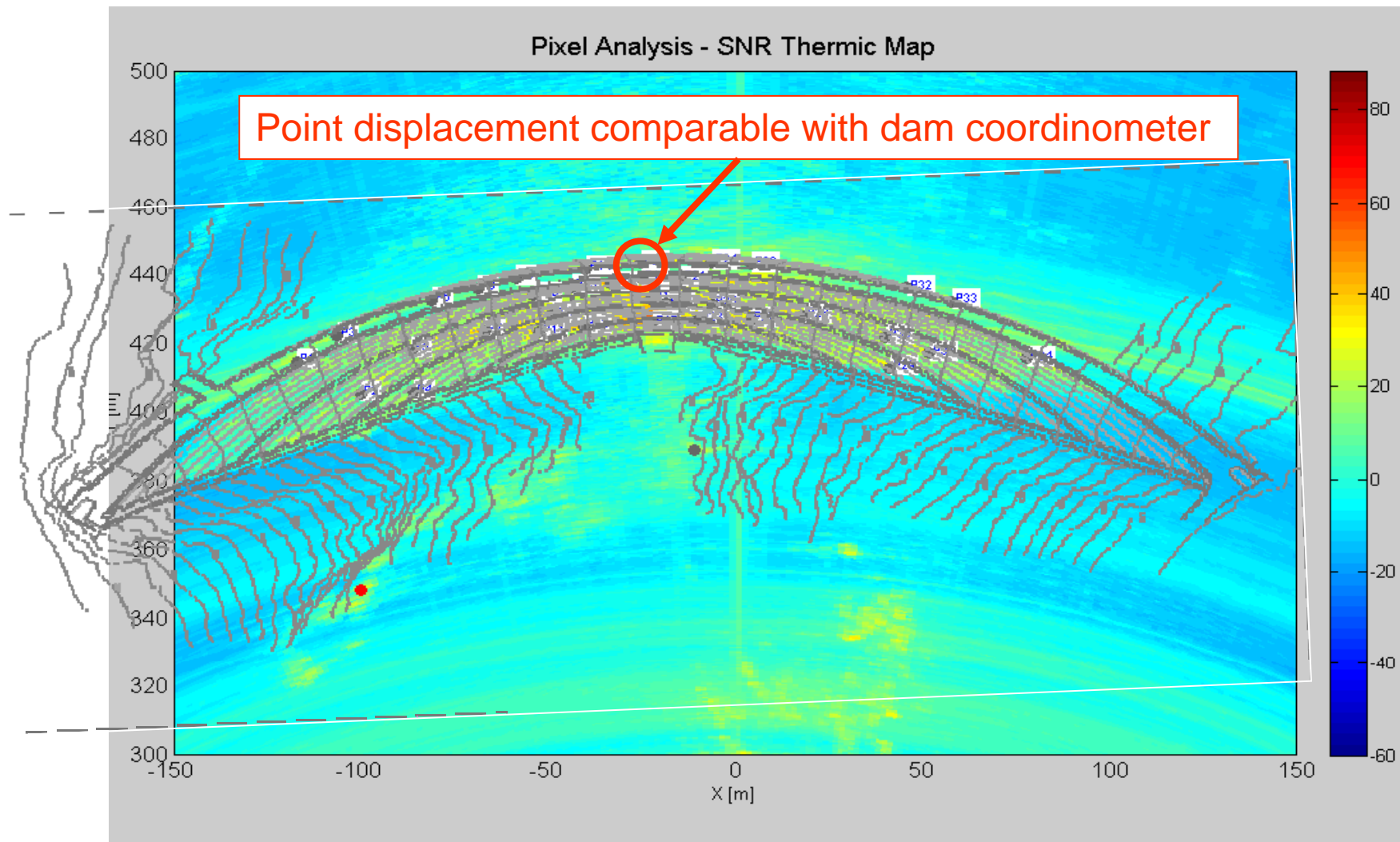


IBIS-L: monitoraggio dighe

Selected pixel L.O.S. displacement – 5 pixel belonging to the dam crown

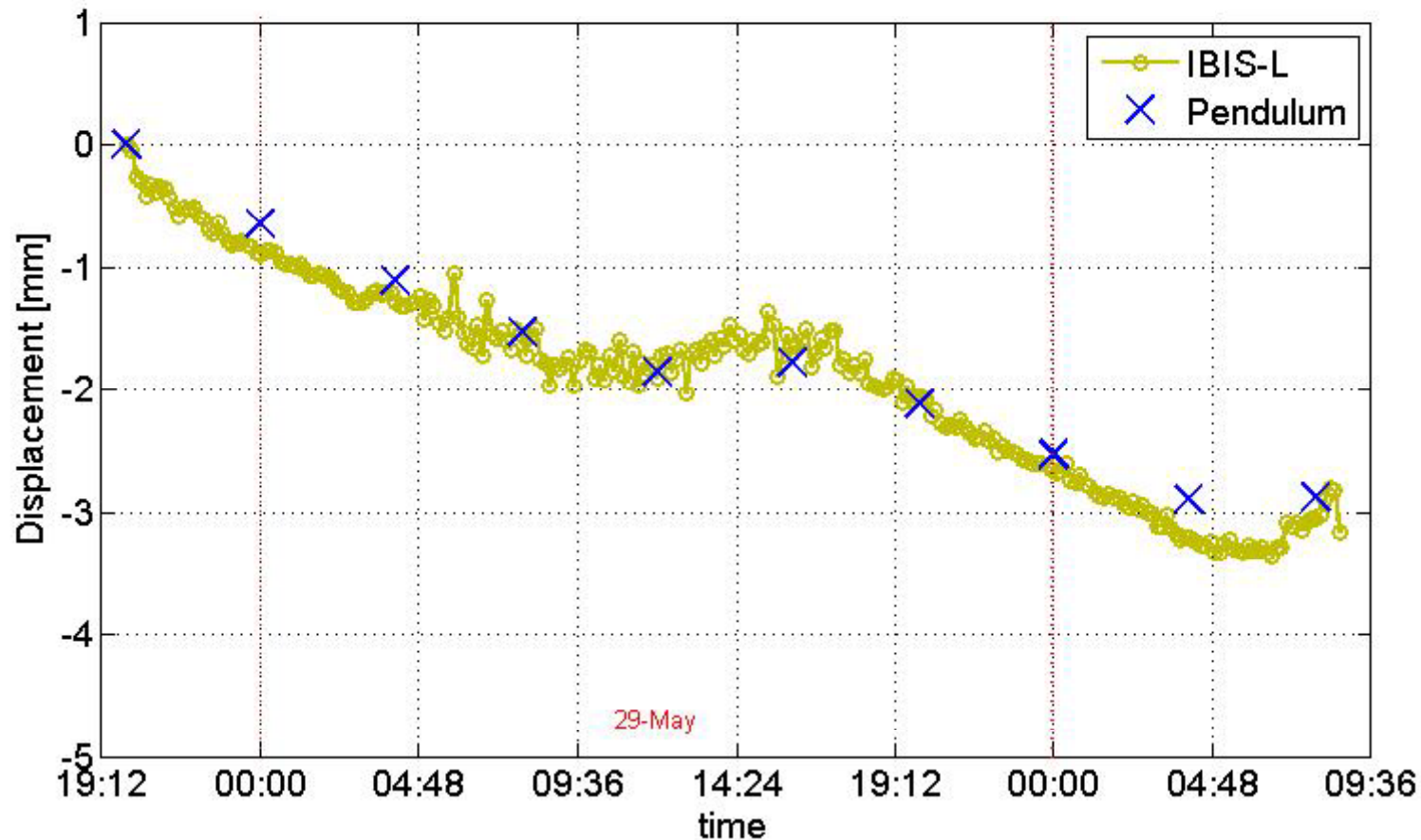


IBIS-L: monitoraggio dighe



IBIS-L: monitoraggio dighe

Crowning point displacement comparison between
IBIS-L and coordinometer measure



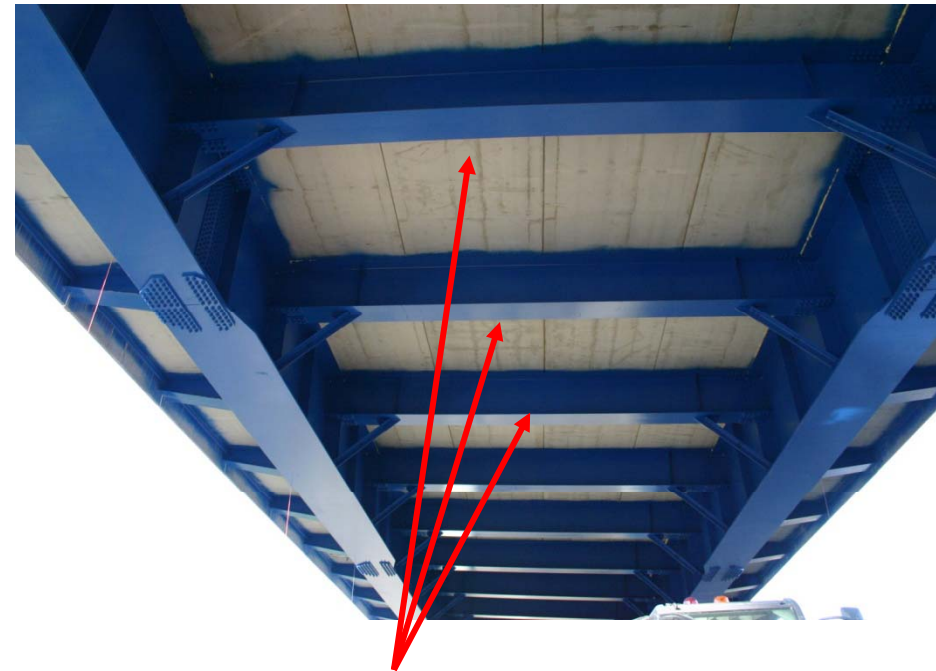
IBIS-L sampling interval: 9min

Pendulum sampling interval: 4hours

IBIS-S: collaudi statici di ponti



Viaducts crossing Forlanini Avenue
(Milan, Italy)

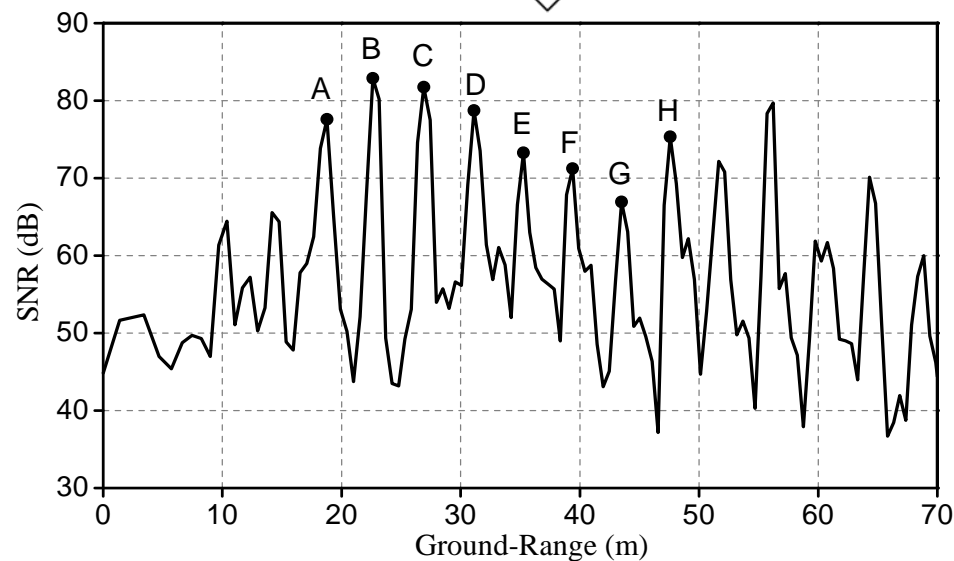
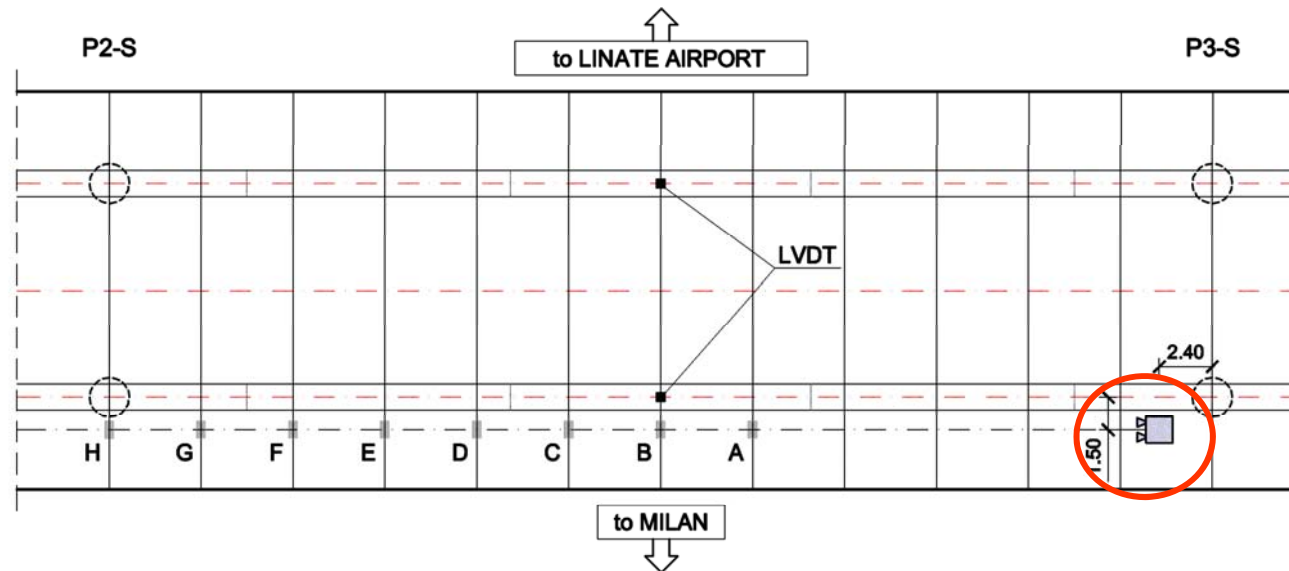


Bridge beams are good reflecting points

Static monitoring of a new bridge:

**Determination of displacement of the
bridge during a static load test**

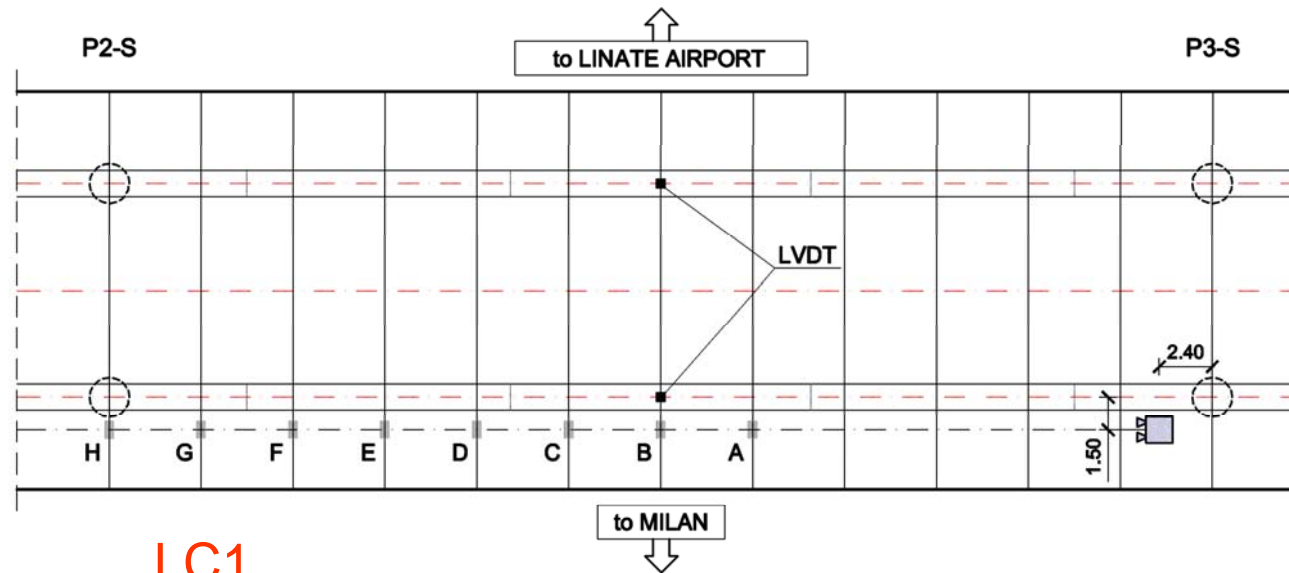
IBIS-S: collaudi statici di ponti



IBIS-S
installation

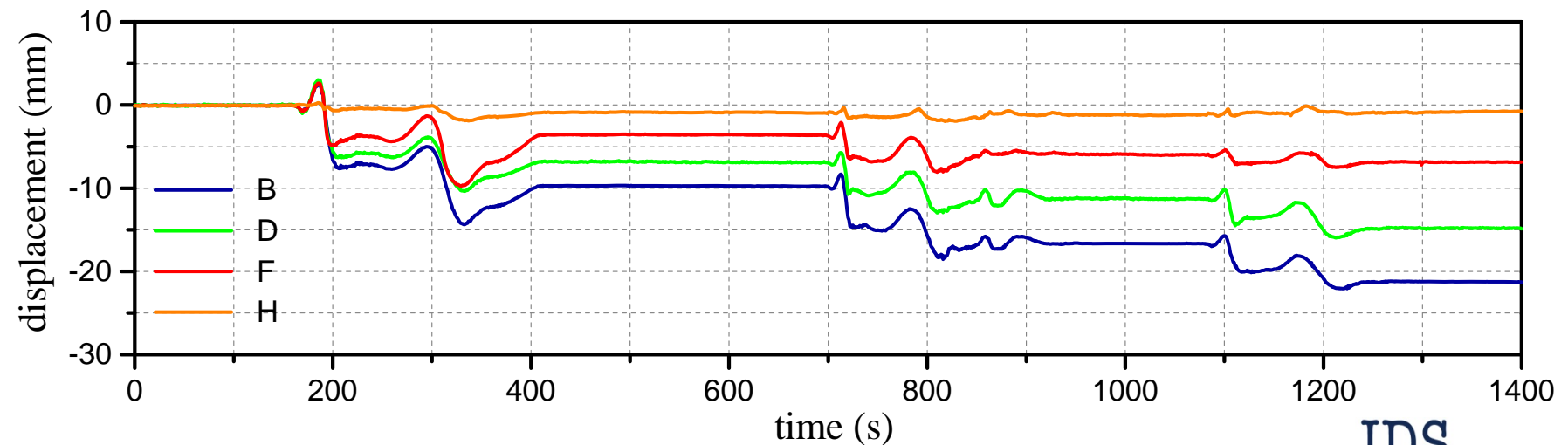
Range profile of
P2-S – P3-S span

IBIS-S: collaudi statici di ponti

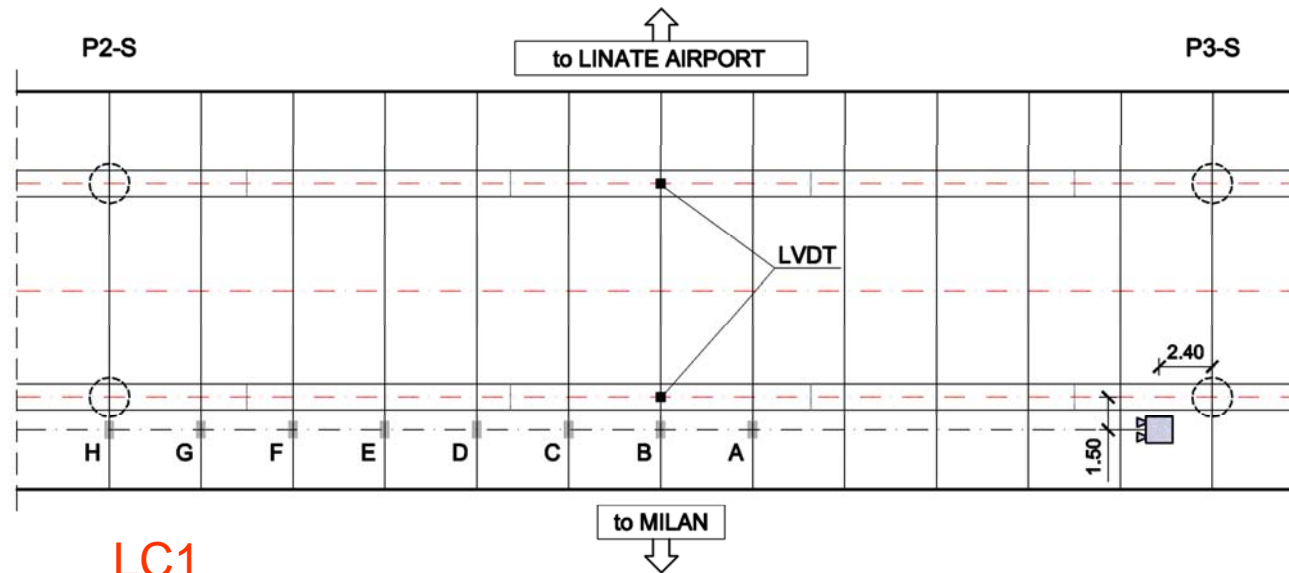


LC1

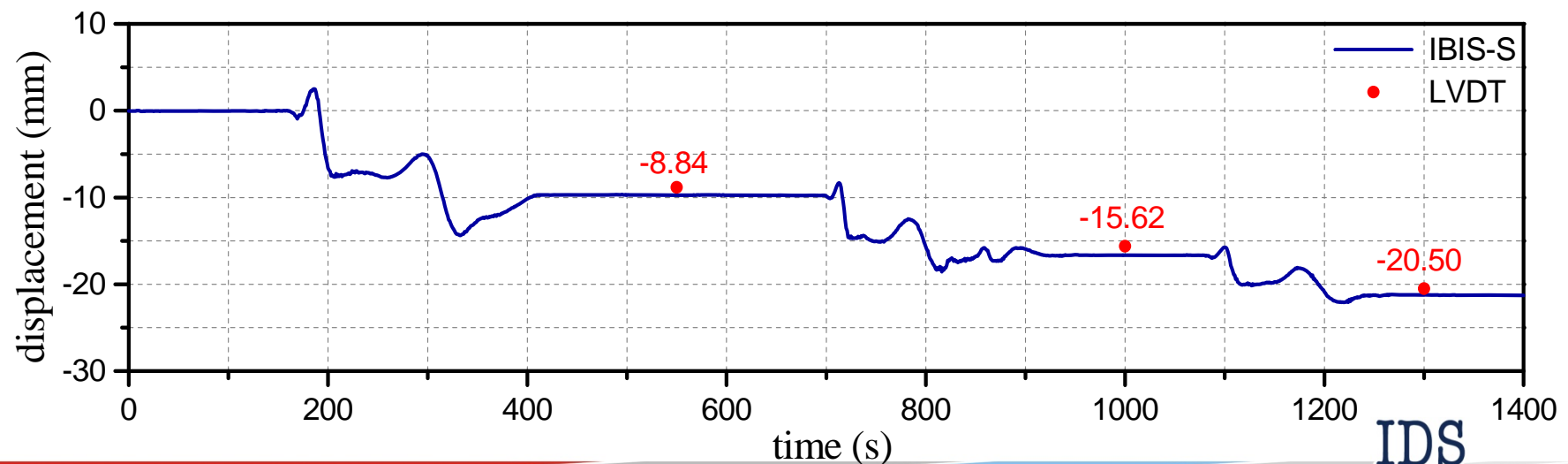
LVDT



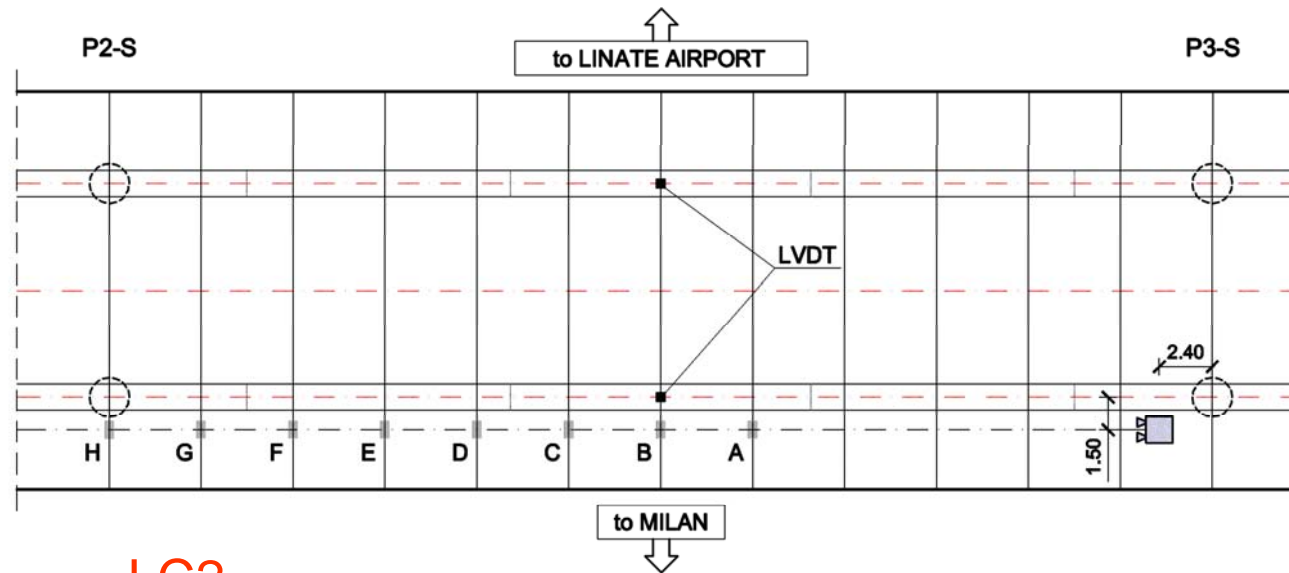
IBIS-S: collaudi statici di ponti



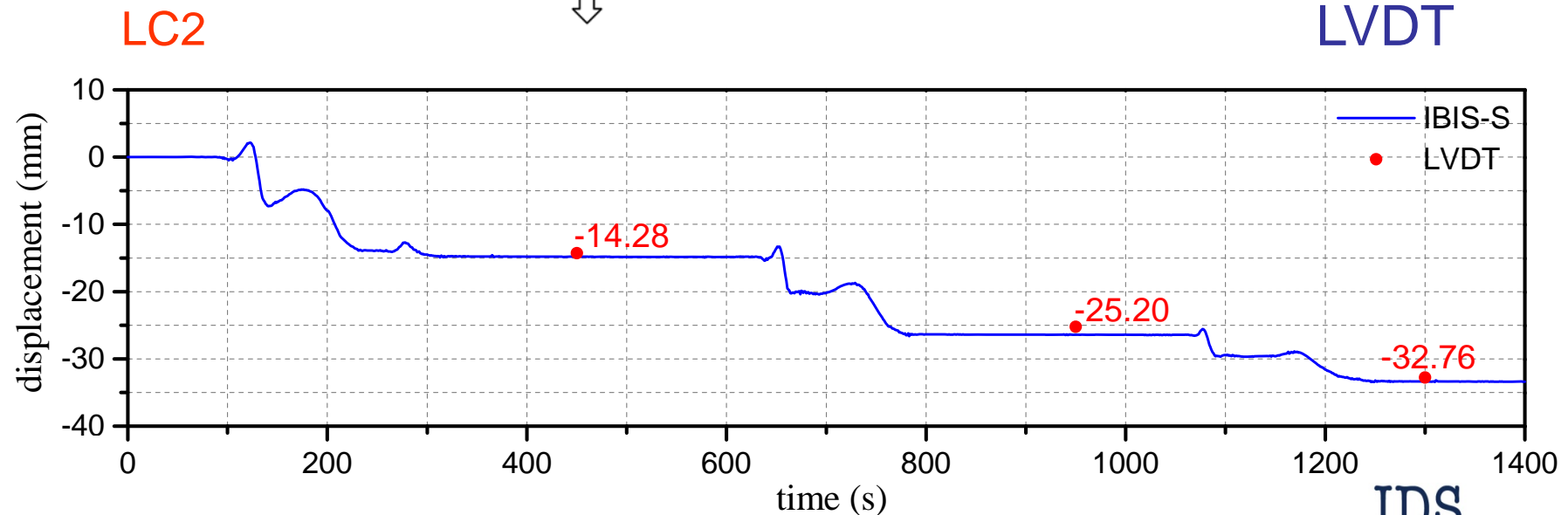
LVDT



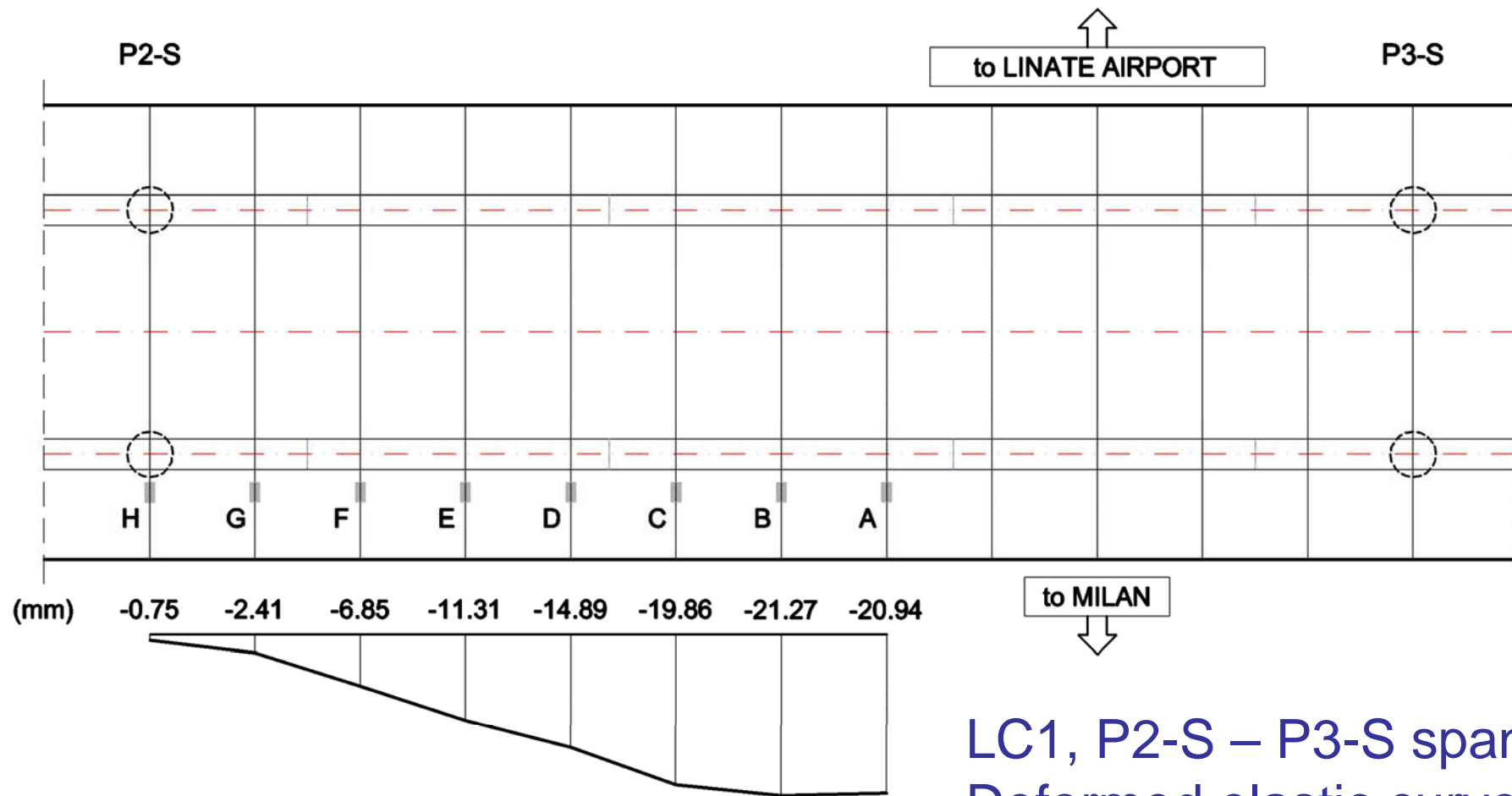
IBIS-S: collaudi statici di ponti



LVDT



IBIS-S: collaudi statici di ponti



LC1, P2-S – P3-S span:
Deformed elastic curve
provided by IBIS-S



NUOVE TECNOLOGIE RADAR
COLLAUDO. MONITORAGGIO E
INDAGINI NON INVASIVE PER MANUFATTI

 **POLITECNICO DI MILANO**

IDS
INGEGNERIA DEI SISTEMI S.p.A.



Vibration Measurement by Radar Techniques: a Review

Carmelo Gentile

Politecnico di Milano, Dept. of Structural Engineering



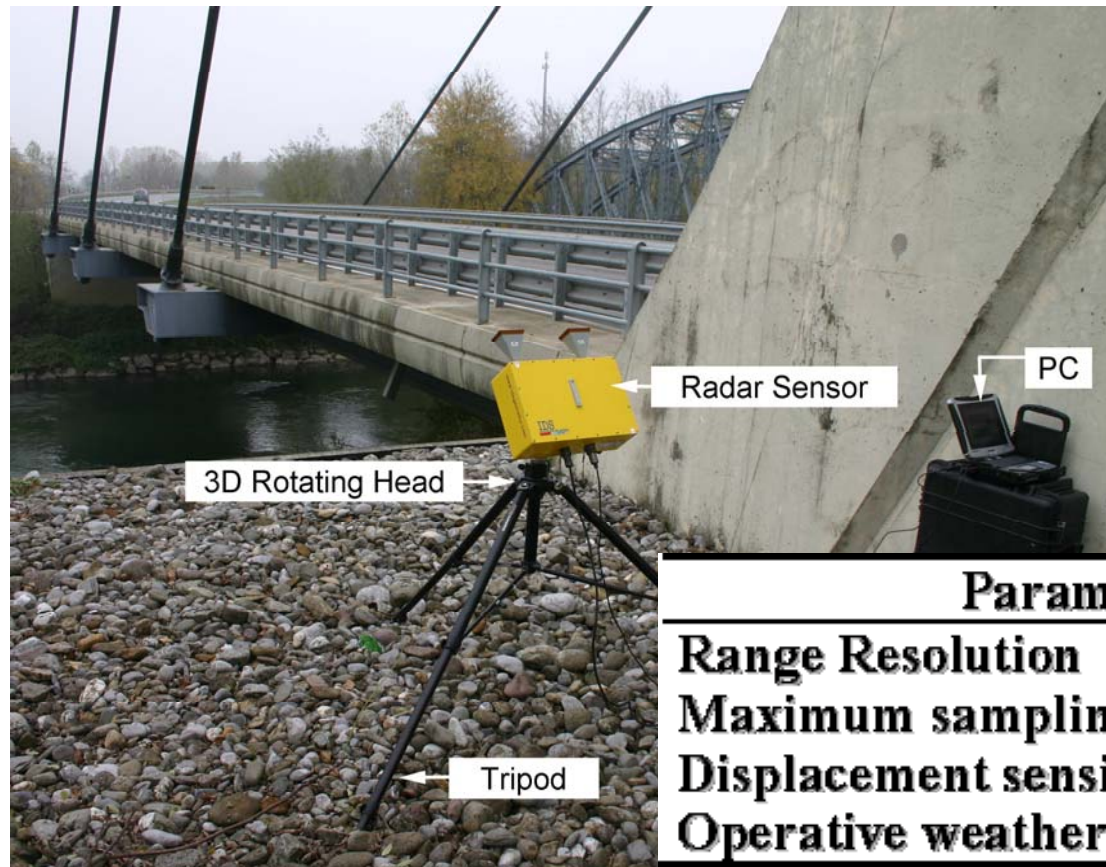
- ❑ **The Radar-based measurement technique**
 - Technical characteristics of the radar sensor
 - Background of radar techniques
 - Potential issues
- ❑ **Laboratory test**
- ❑ **On-site test**
- ❑ **Dynamic test (AVT) of a r.c. bridge**
- ❑ **Dynamic (AVT) of a steel-composite bridge**
- ❑ **Dynamic measurement on stay cables**
 - Cable-stayed bridge over the Oglio river
 - Cable-stayed bridge over the Adda river
 - Cable-stayed bridge in Porto Marghera
- ❑ **Dynamic test of Muge guyed mast**



Description of the radar sensor

3

Industrially engineered microwave interferometer, designed for the non contact measurement of displacement time-histories on civil engineering structures



IBIS-S:
**Image By Interferometric
Survey of Structures**

Parameter	
Range Resolution	0.50 m
Maximum sampling frequency	200.00 Hz
Displacement sensitivity	0.02 mm
Operative weather condition	All

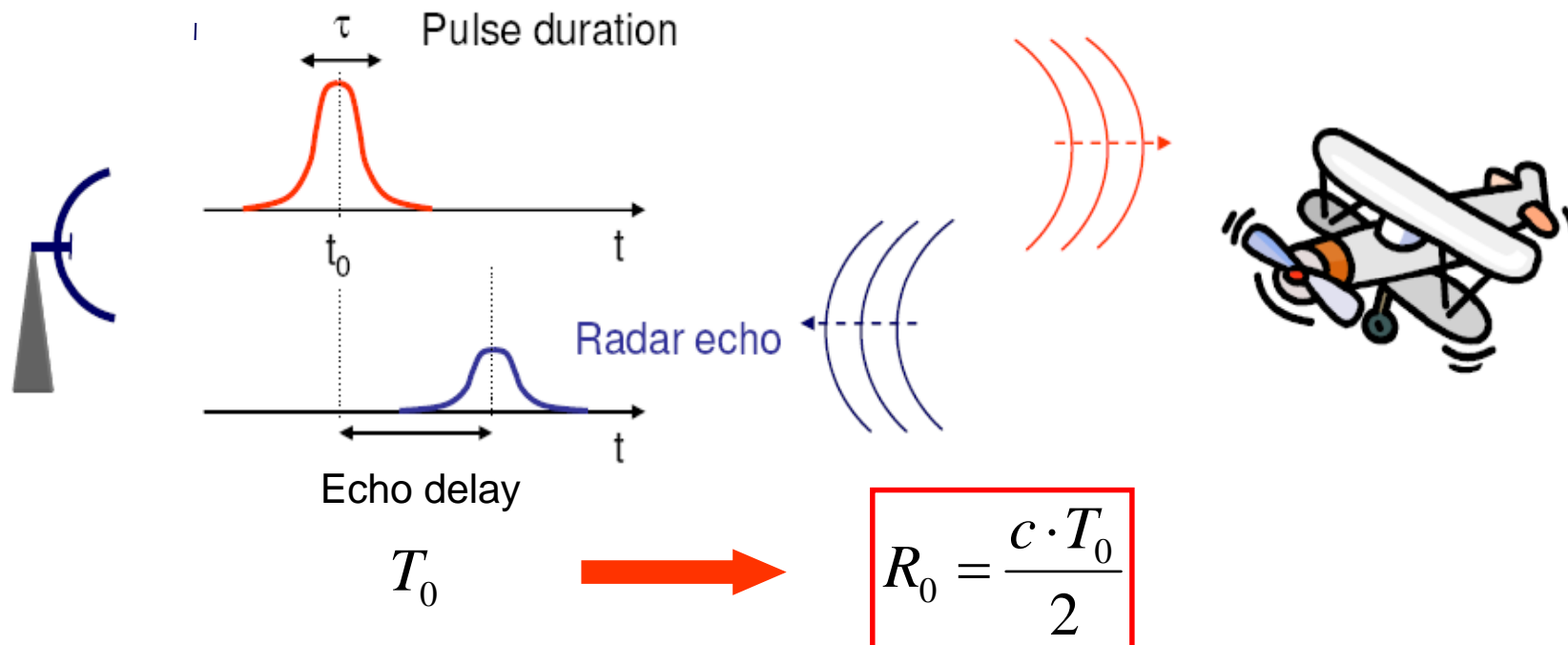


Background of radar techniques (1)

4

RADAR = **RA**dio **D**etection **A**nd **R**anging

The most peculiar and important characteristic of a conventional radar is its ability to determine the range (i.e. the distance) by measuring the time for the radar signal to propagate to the target and back



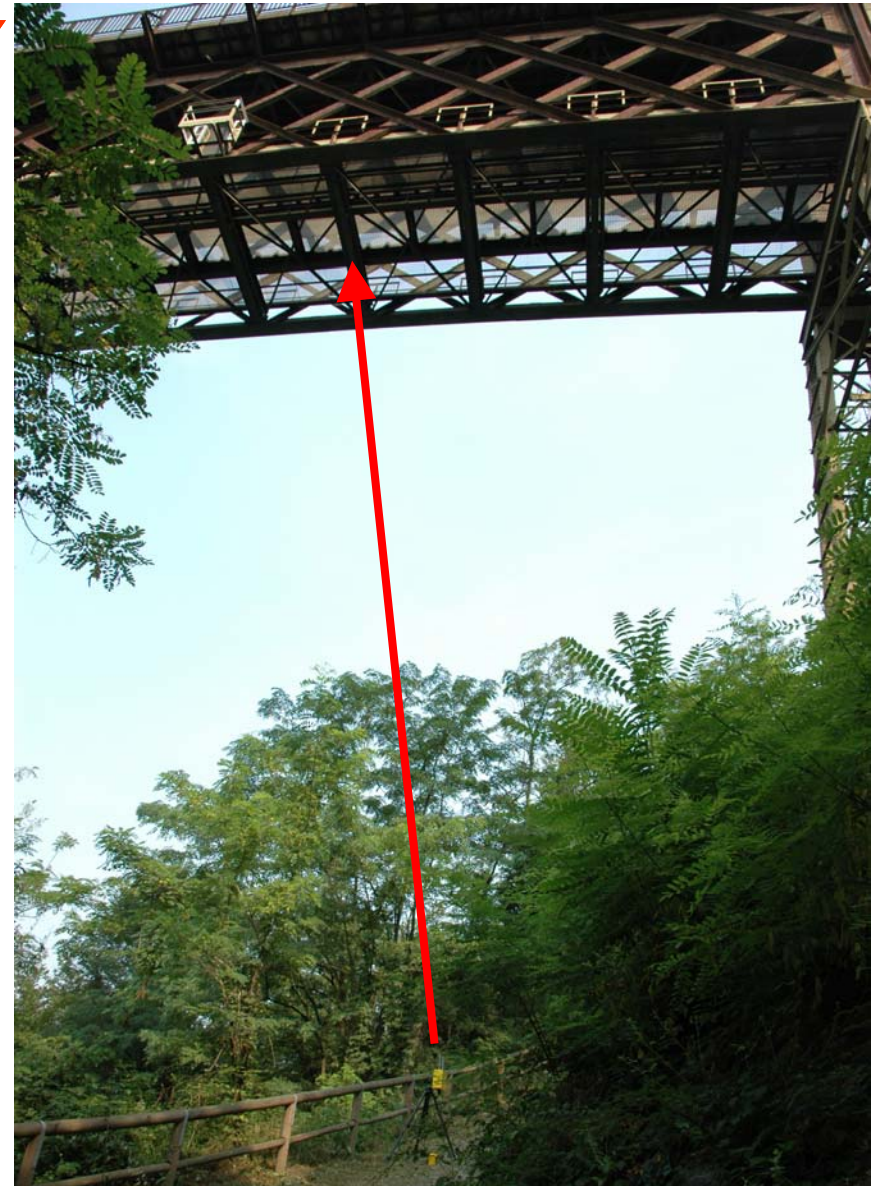
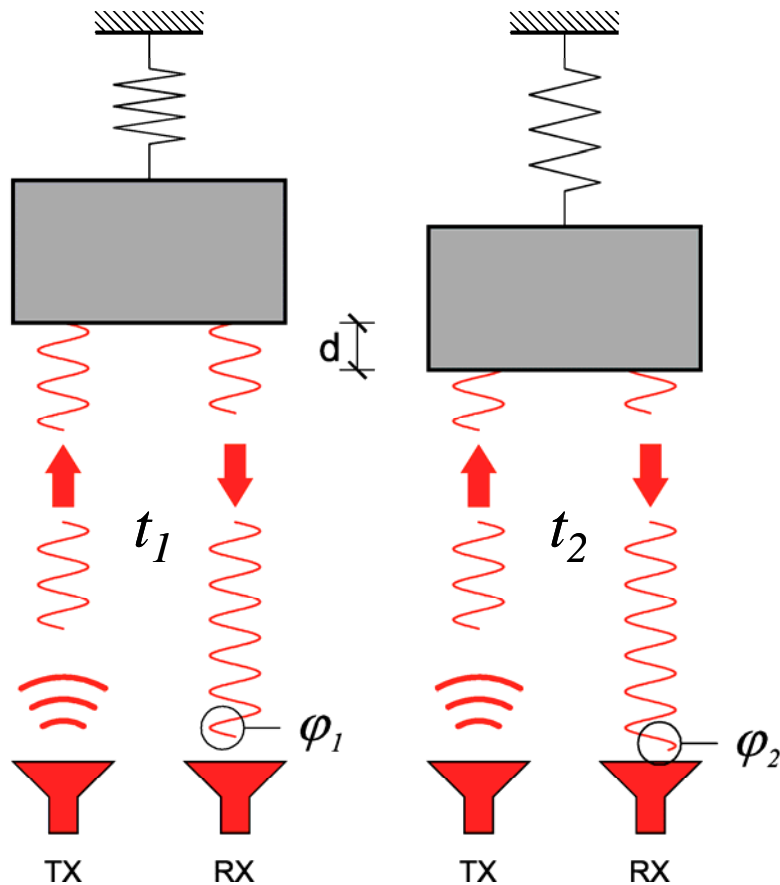


Background of radar techniques (2)

5

MICROWAVE INTERFEROMETRY

$$d = -\frac{\lambda}{4\pi}(\varphi_2 - \varphi_1)$$

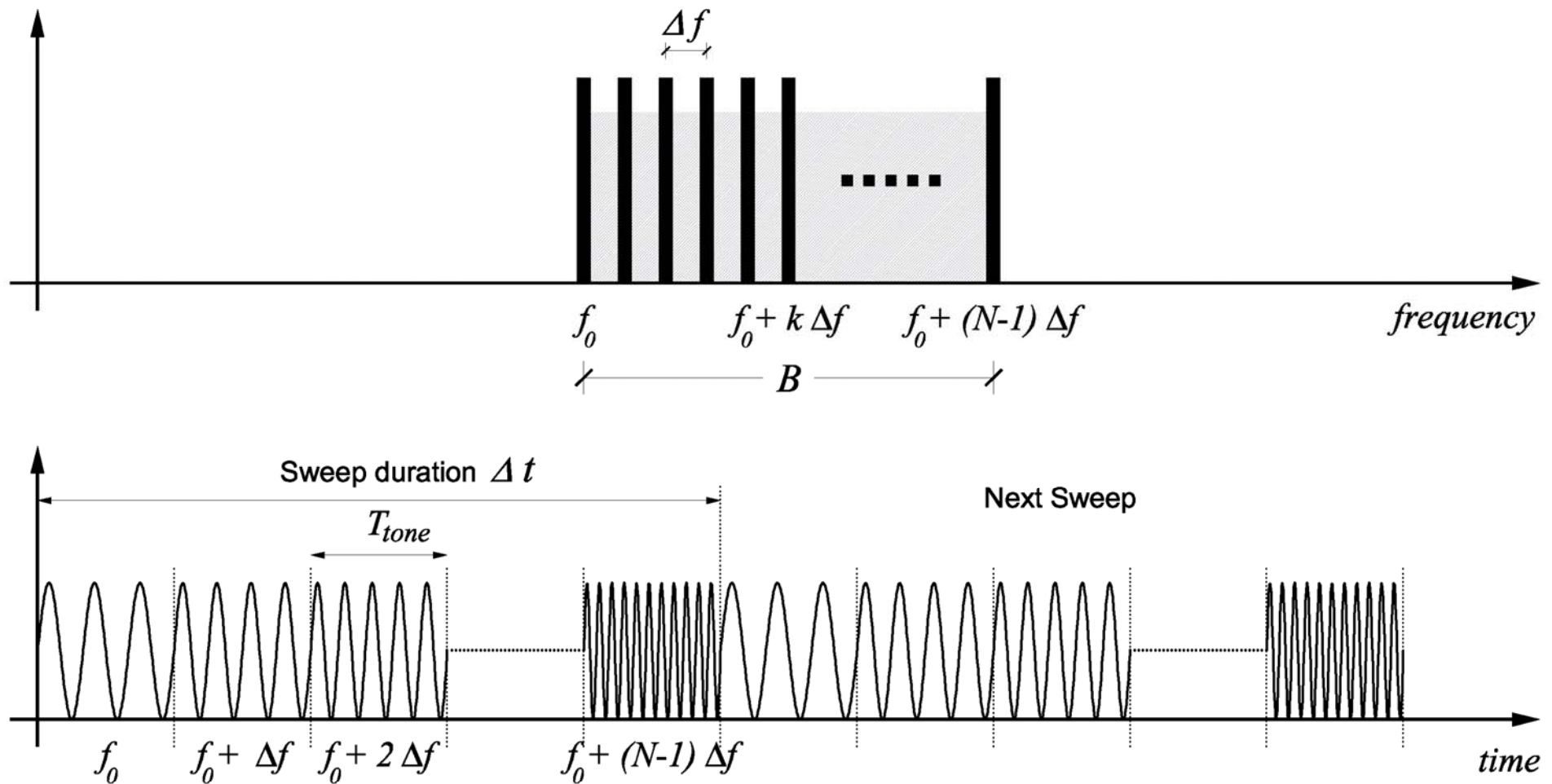




Background of radar techniques (3)

6

STEPPED FREQUENCY CONTINUOUS WAVEFORM





Background of radar techniques (4)

7

Main ideas of the microwave-based measurement of deflections:

- a) to employ a radar to take coherent and consecutive *images* of the investigated structure, with each image being a distance map of the intensity of radar echoes coming from the reflecting targets detected on the structure;
- b) to compute the displacement of each target from the phase difference between two consecutive images (the phase difference is proportional to the displacement)

Main information simultaneously provided by the radar technique:

Position and displacement of the target points, placed at different distances from the radar, that are characterized by a good electromagnetic reflectivity

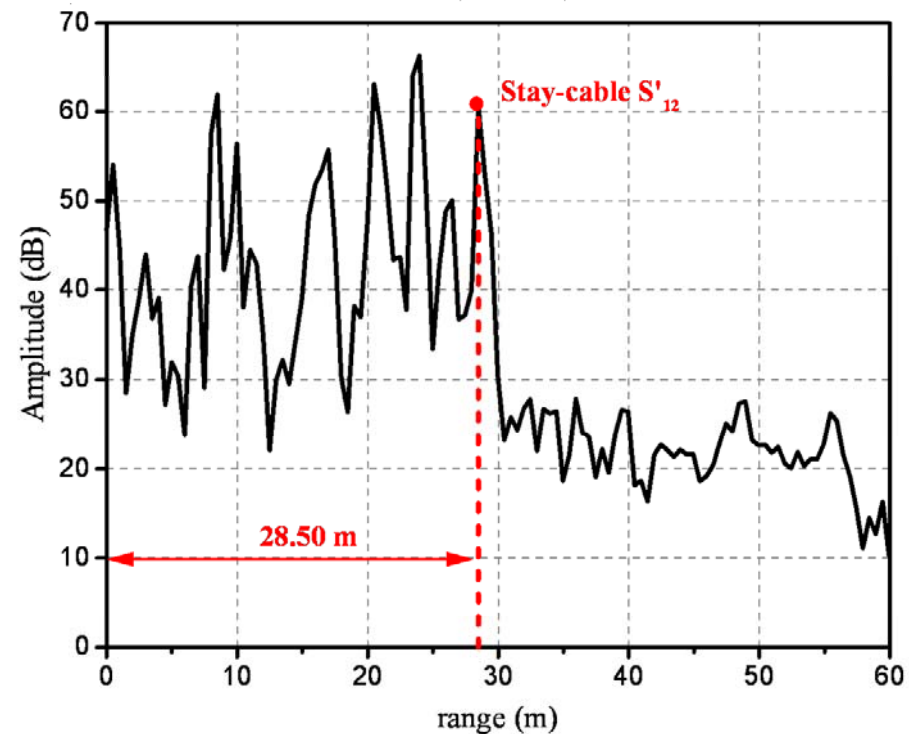
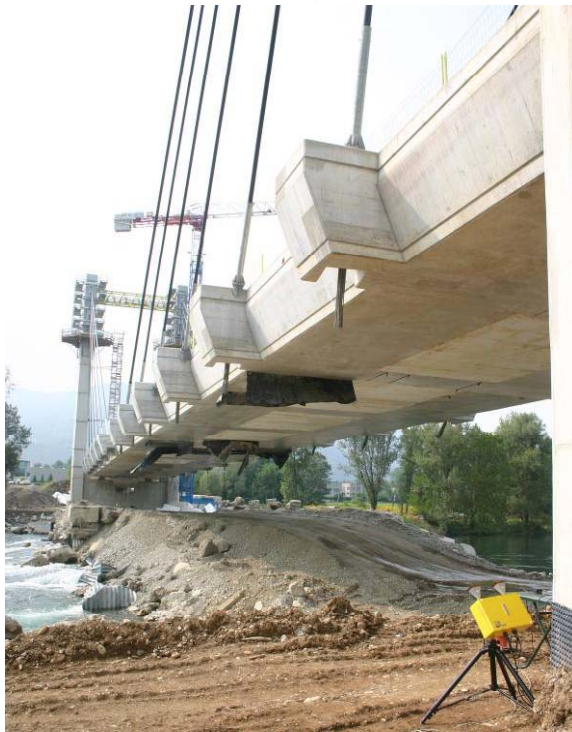
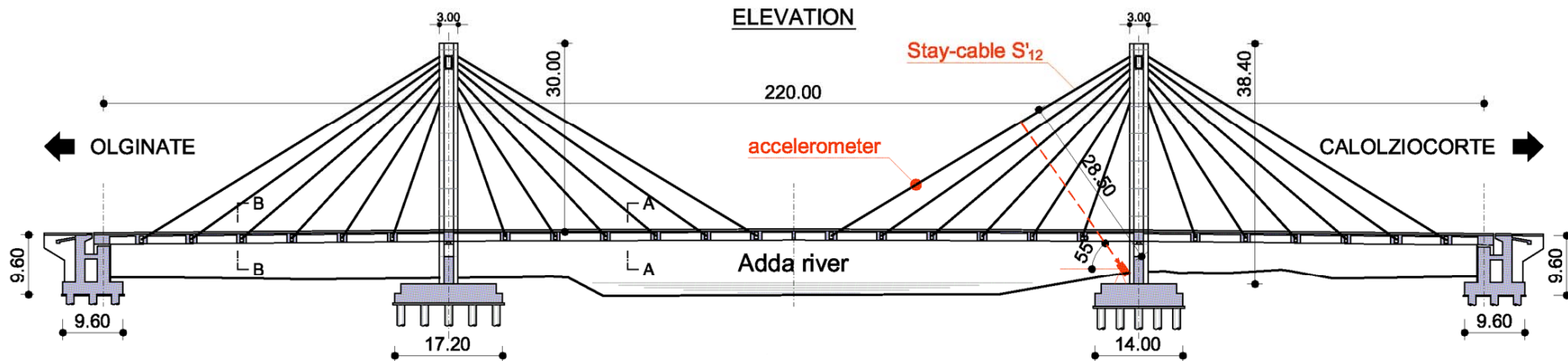
Potential issues:

1D imaging, Displacement in line-of-sight only



Background of radar techniques (5)

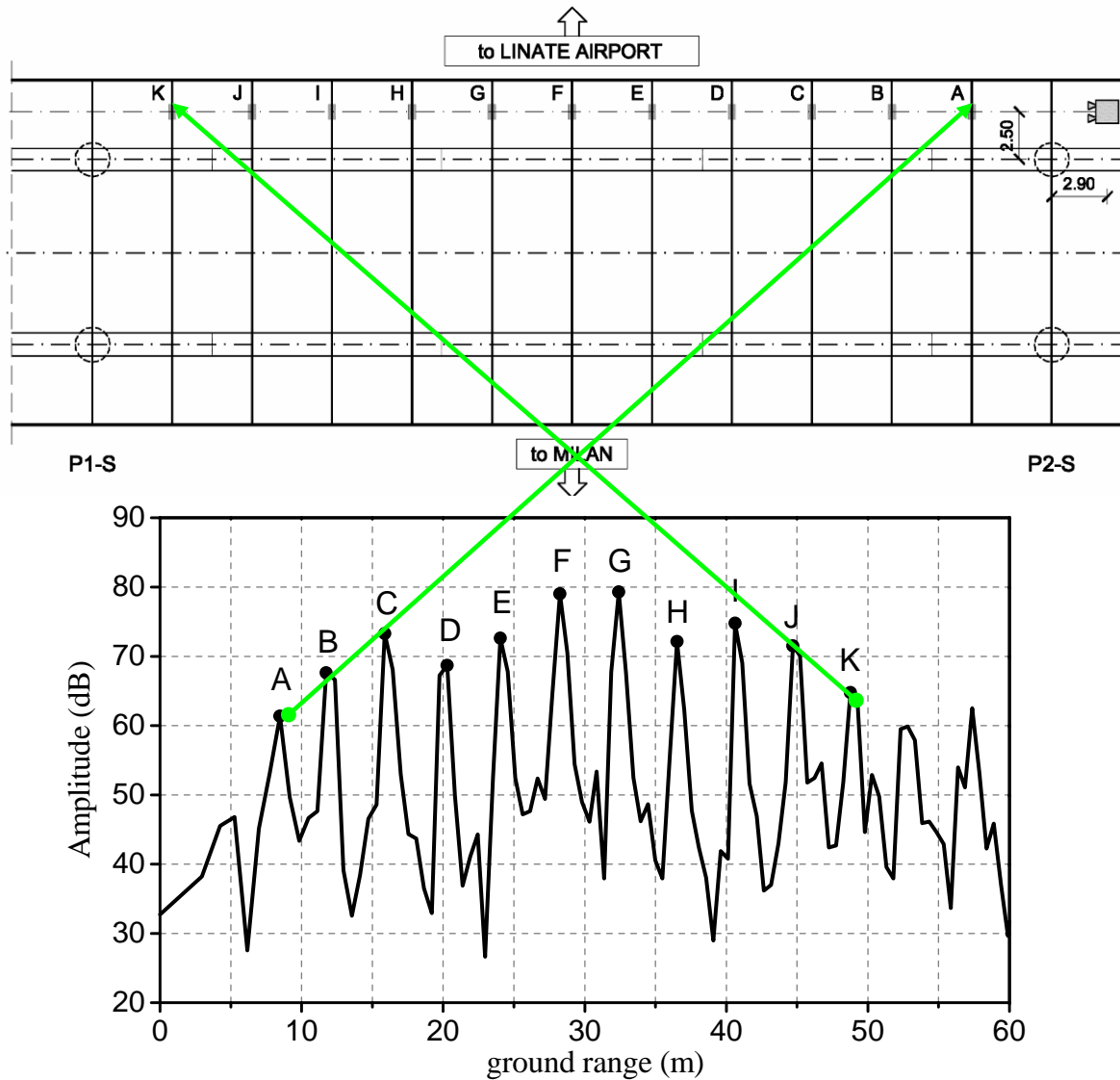
8





Background of radar techniques (6)

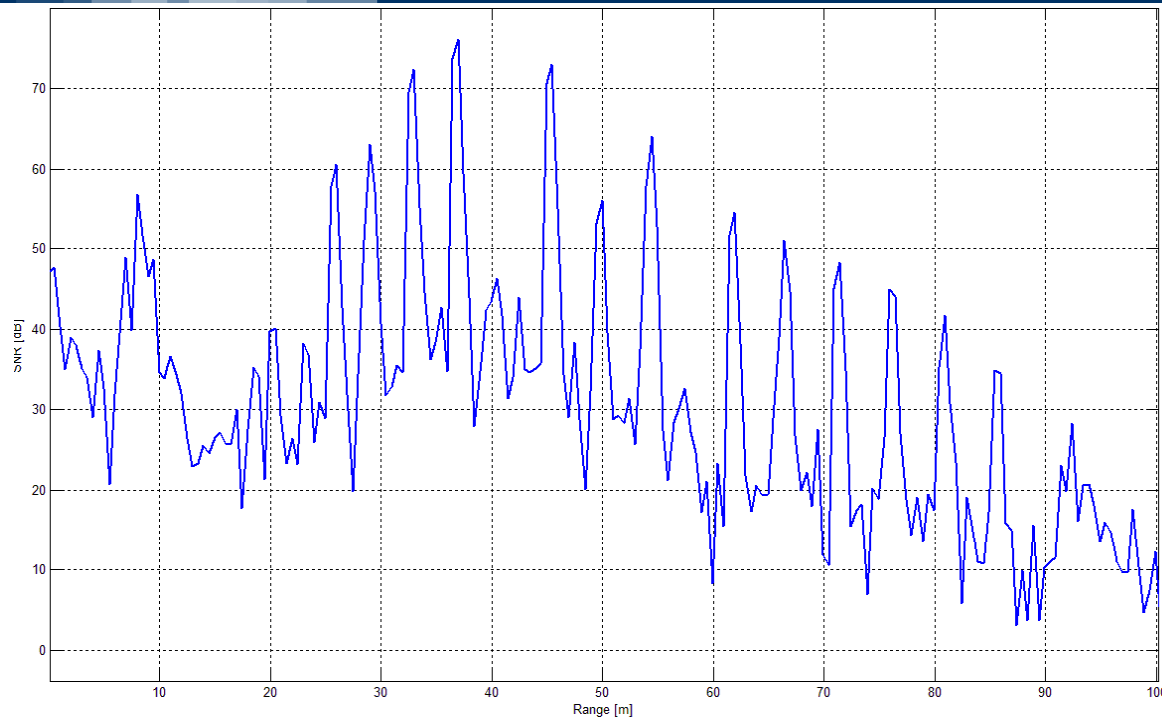
9





Background of radar techniques (7)

10





Stepped Frequency – Continuous Wave



SF-CW radar cannot distinguish two targets having the same distance from the equipment



Careful positioning of the sensor





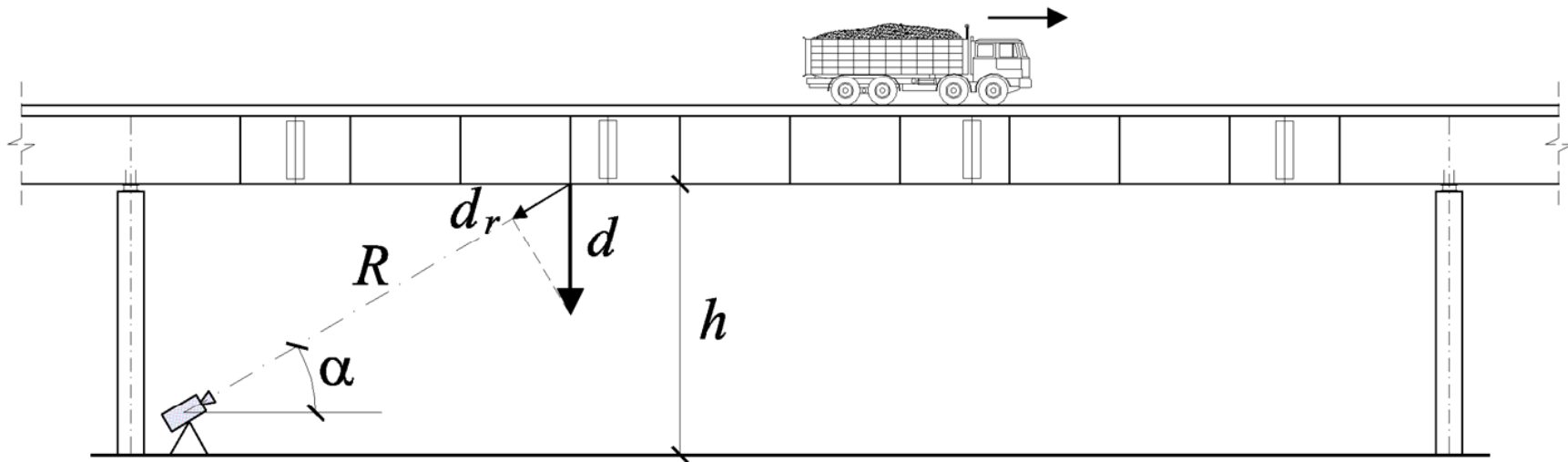
Interferometry



Interferometry provides the radial displacement



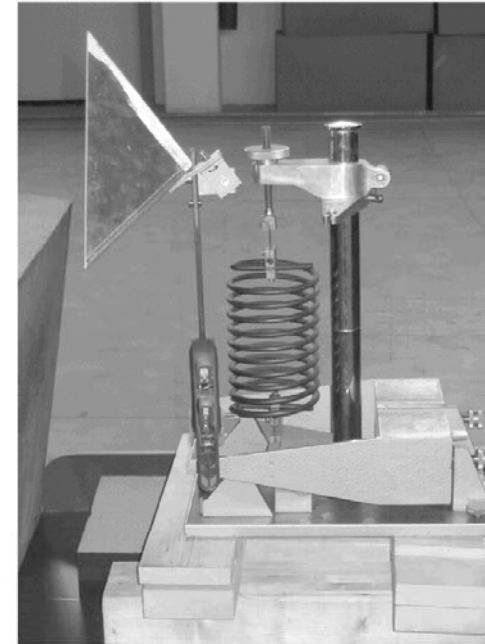
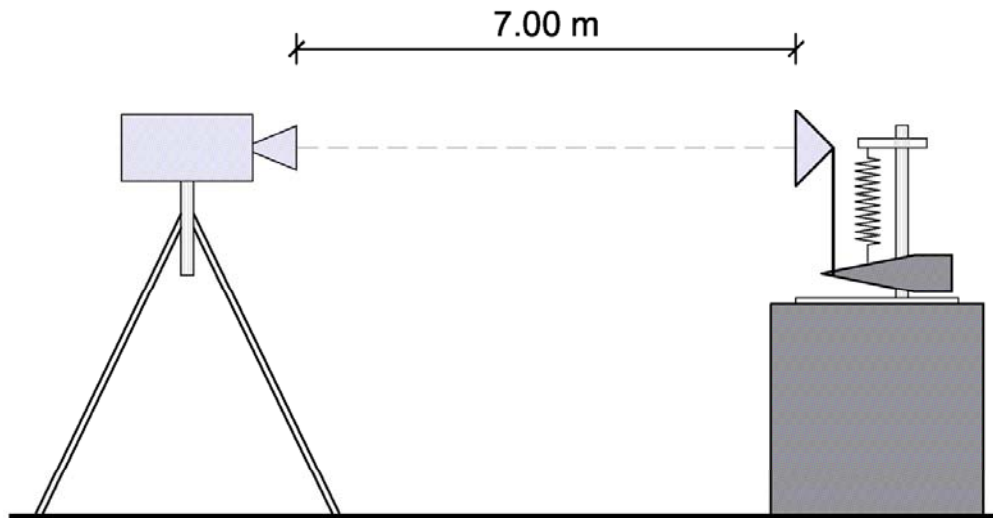
The evaluation of actual displacements requires the knowledge of the direction of motion



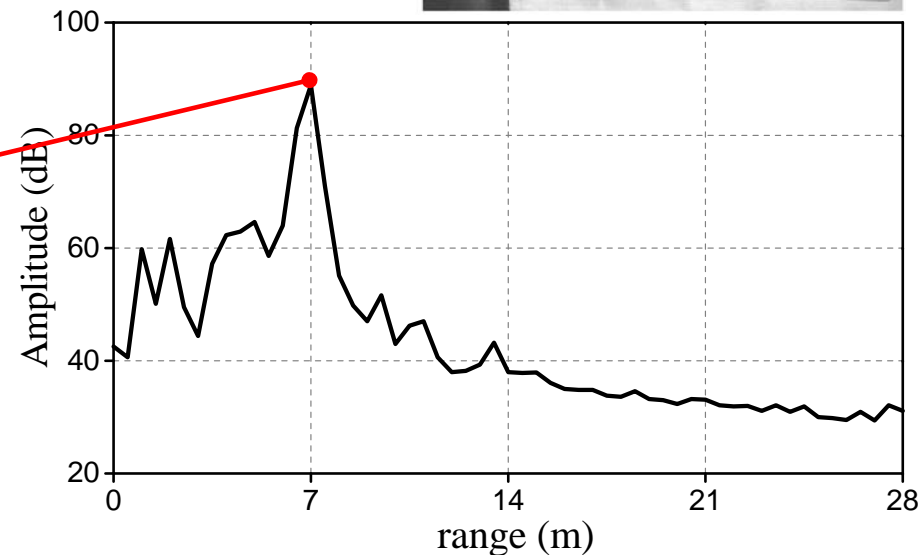


Laboratory test (1)

13



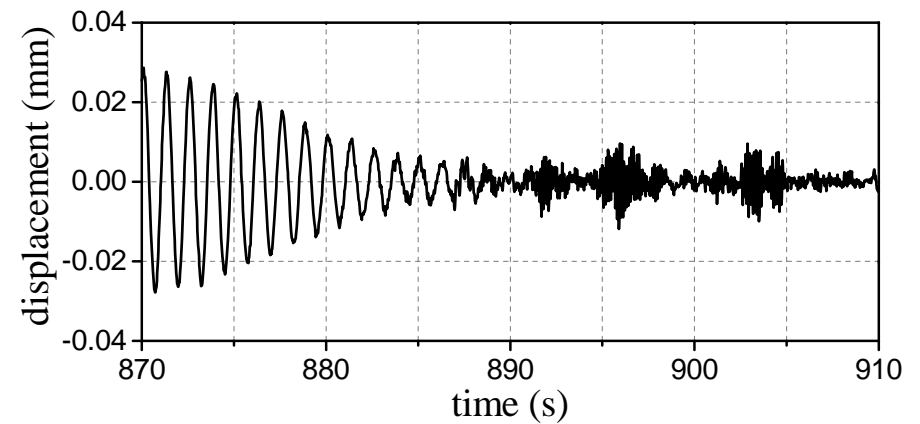
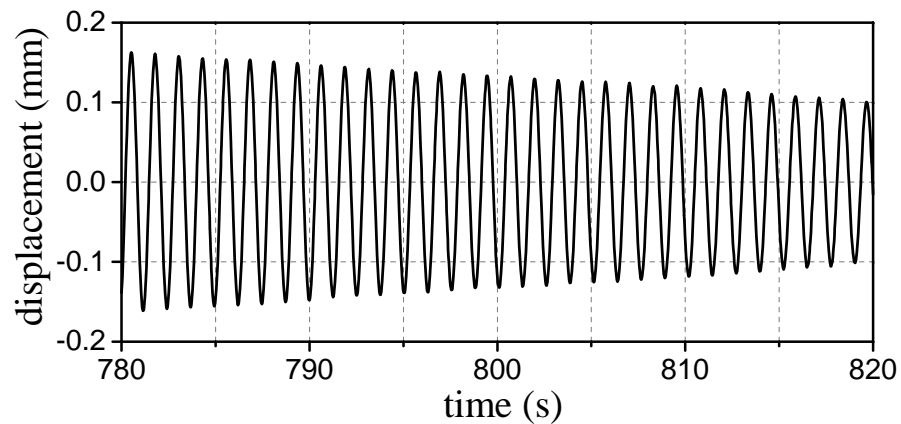
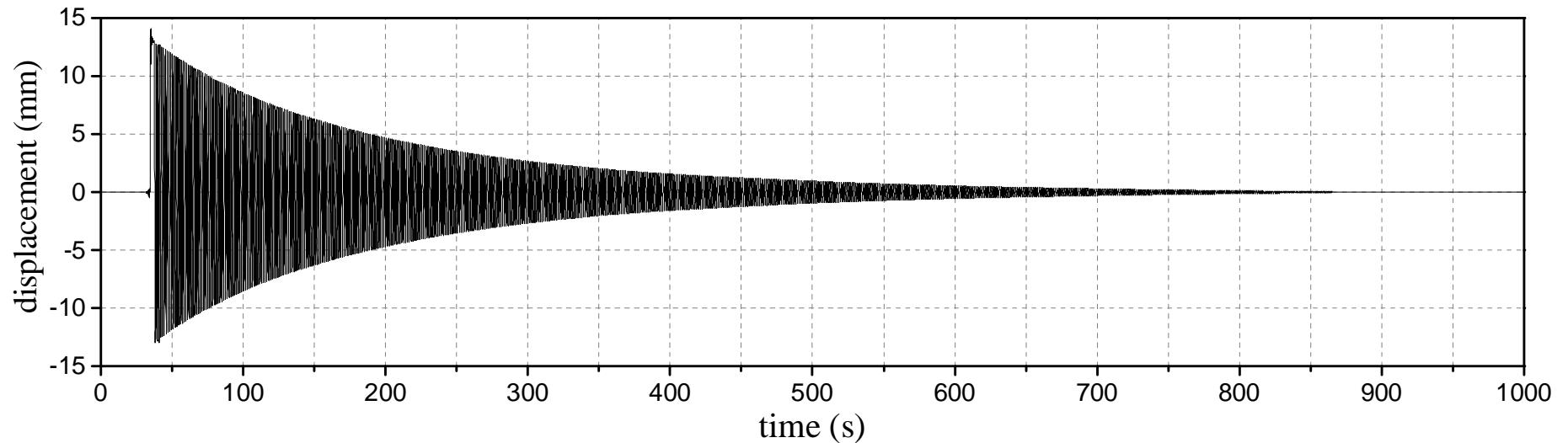
Dominant peak at a range of 7.0 m, correctly identifying the position of the s.d.o.f. system





Laboratory test (2)

14

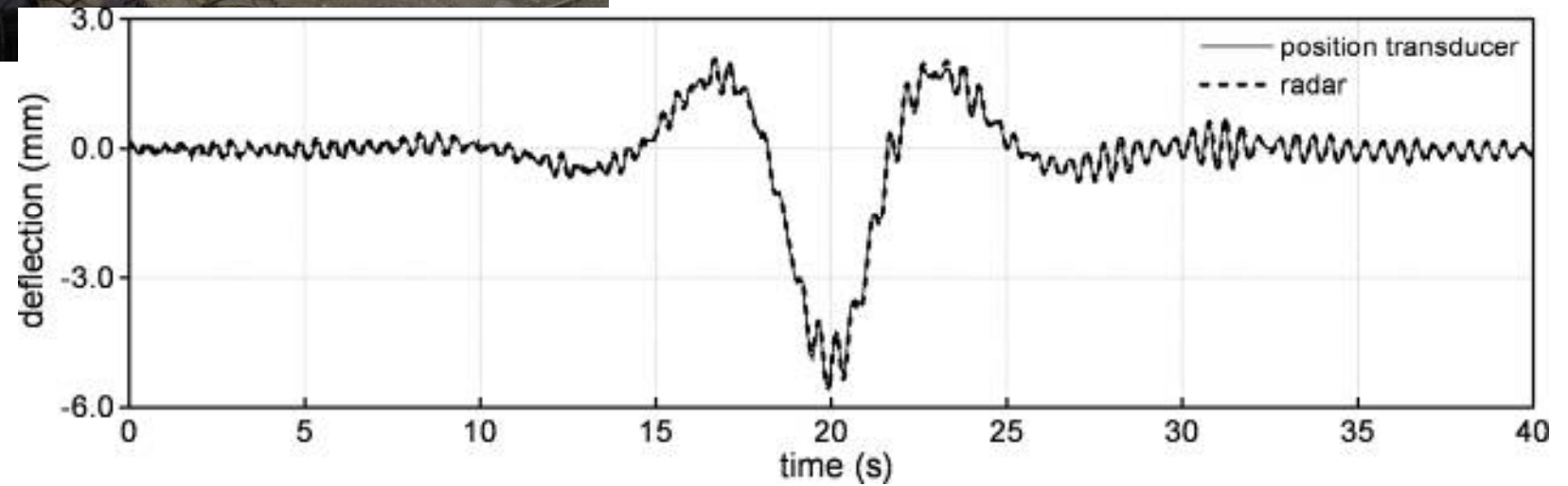


Displacement resolution better than 0.02 mm



On-site test

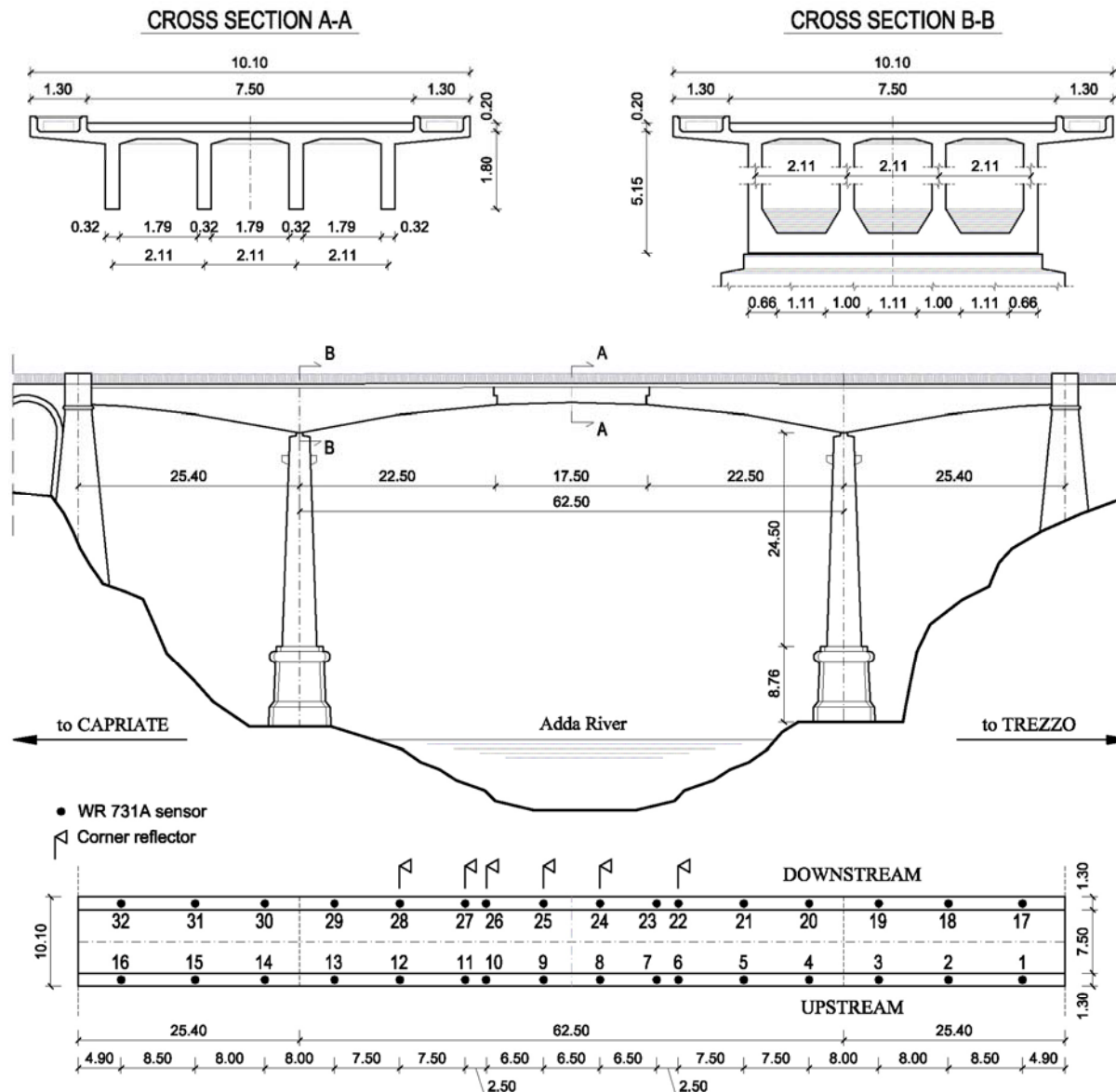
15





Dynamic test (AVT) of a r.c. bridge (1)

16

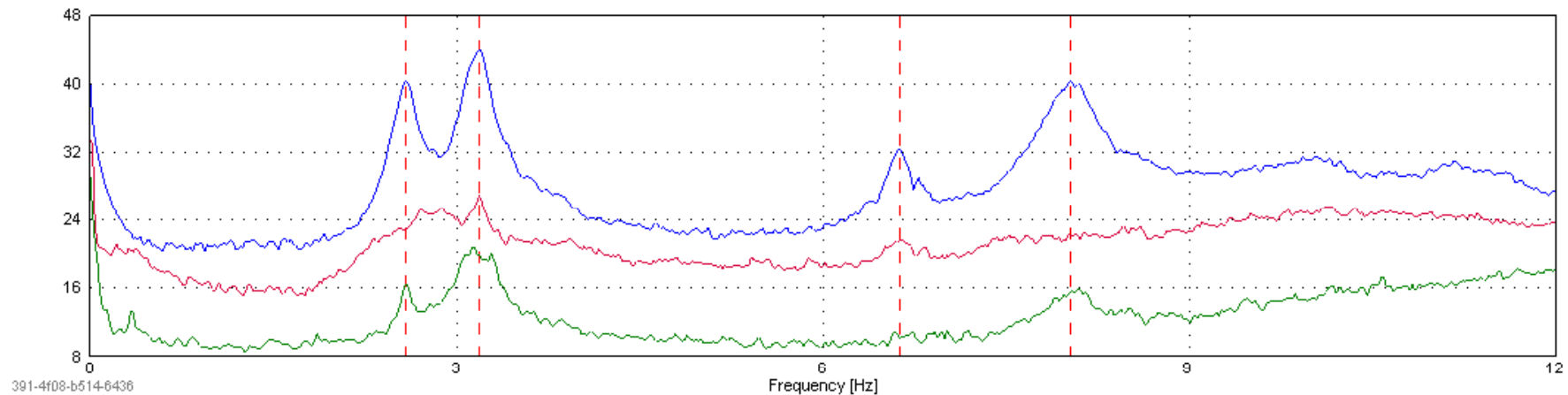




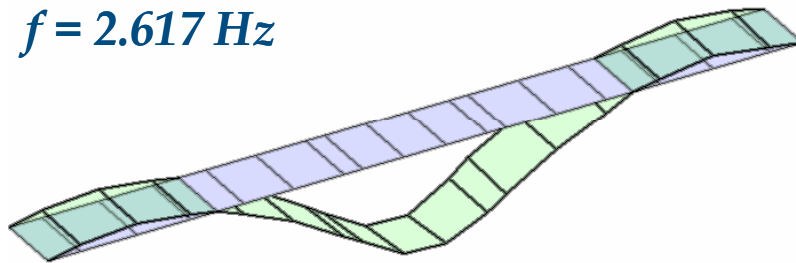
Dynamic test (AVT) of a r.c. bridge (2)

17

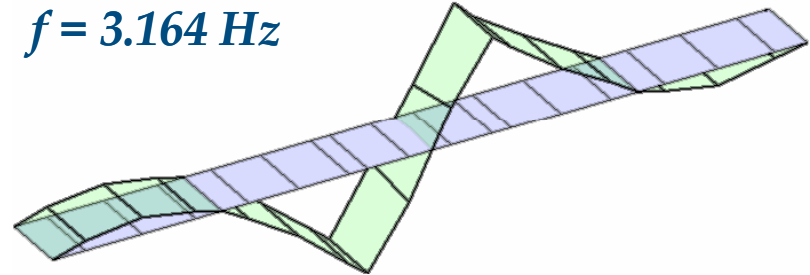
Dynamic behaviour of the bridge (WR 731A accelerometers)



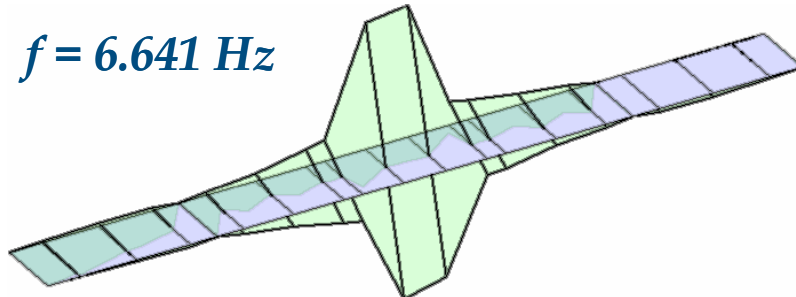
$f = 2.617 \text{ Hz}$



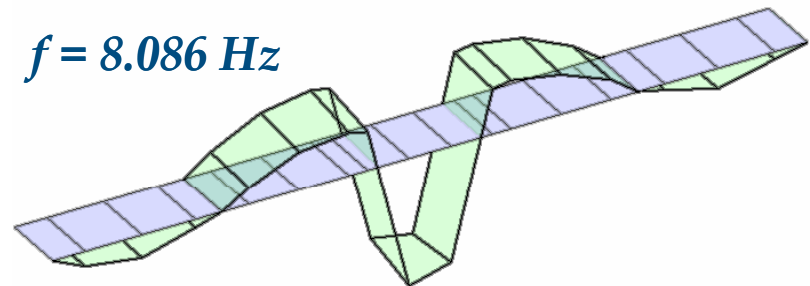
$f = 3.164 \text{ Hz}$



$f = 6.641 \text{ Hz}$



$f = 8.086 \text{ Hz}$

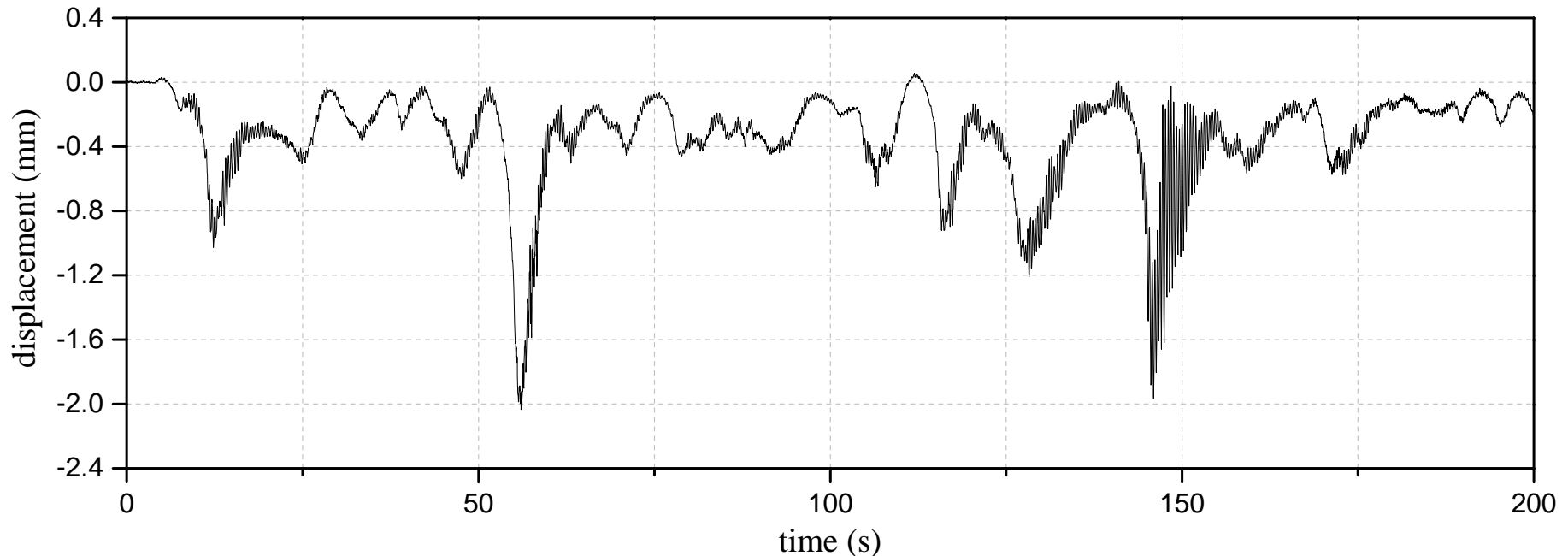




Dynamic test (AVT) of a r.c. bridge (3)

18

Typical displacement obtained by the IBIS-S sensor at TP25

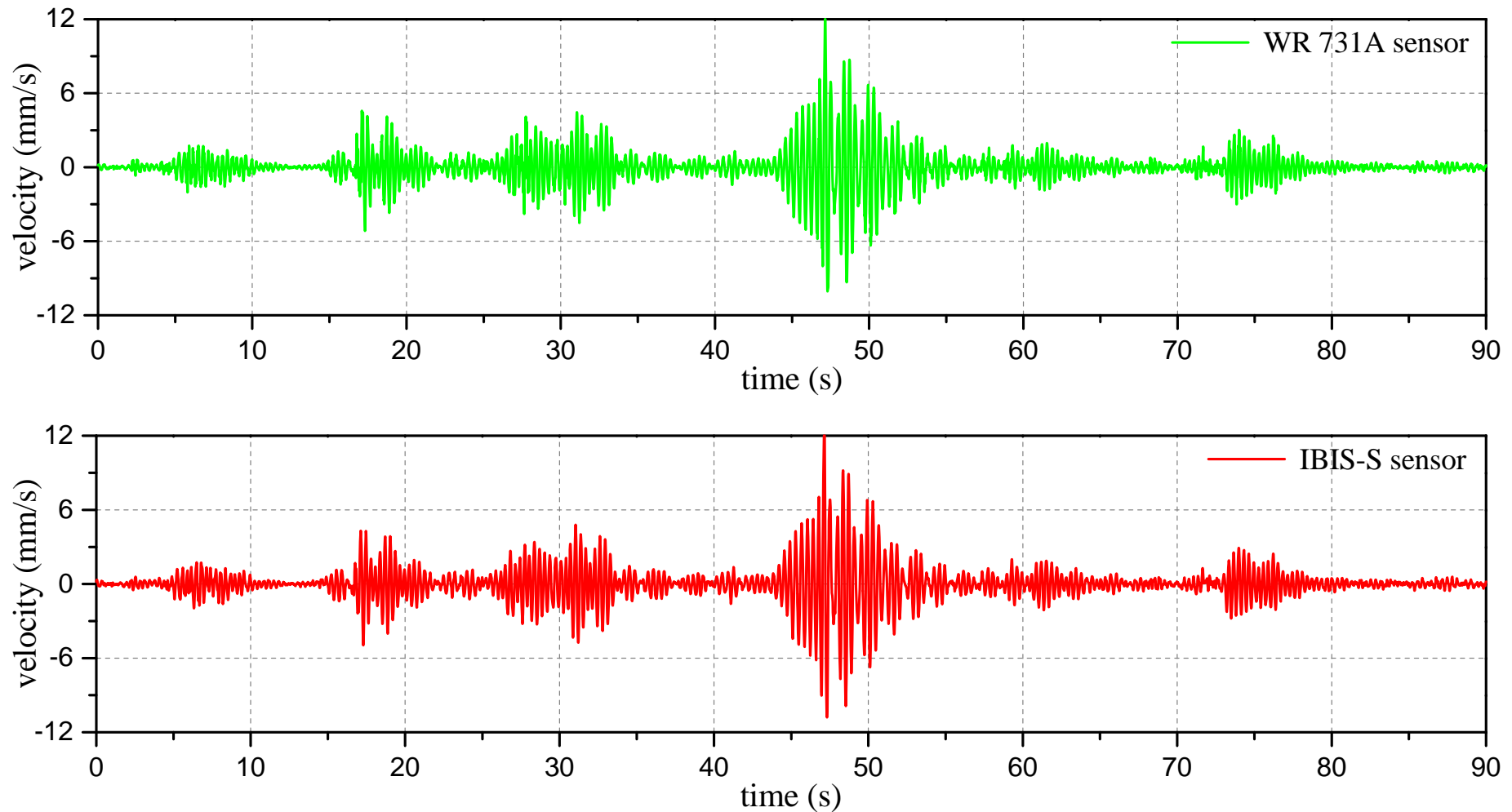


Displacements are very similar to what expected, based on well-known theoretical models: peculiarly, when the moving load is in the neighbourhood of the test point, the signal is composed by the superposition of one peak and damped harmonic functions



Dynamic test (AVT) of a r.c. bridge (4)

19



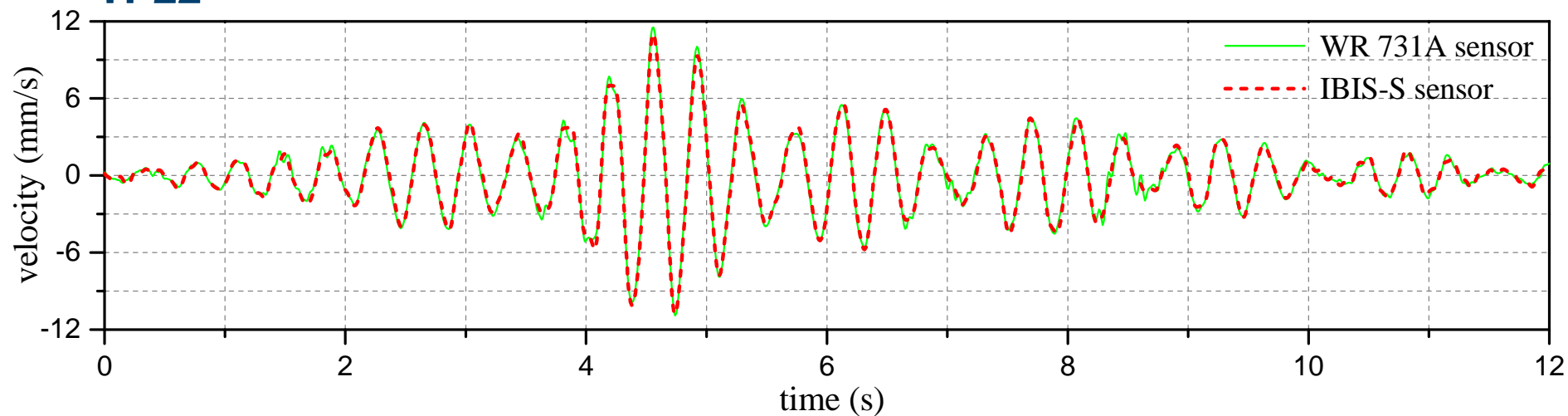
**Typical velocity signal recorded at TP26 by
WR 731A sensor and IBIS-S sensor**



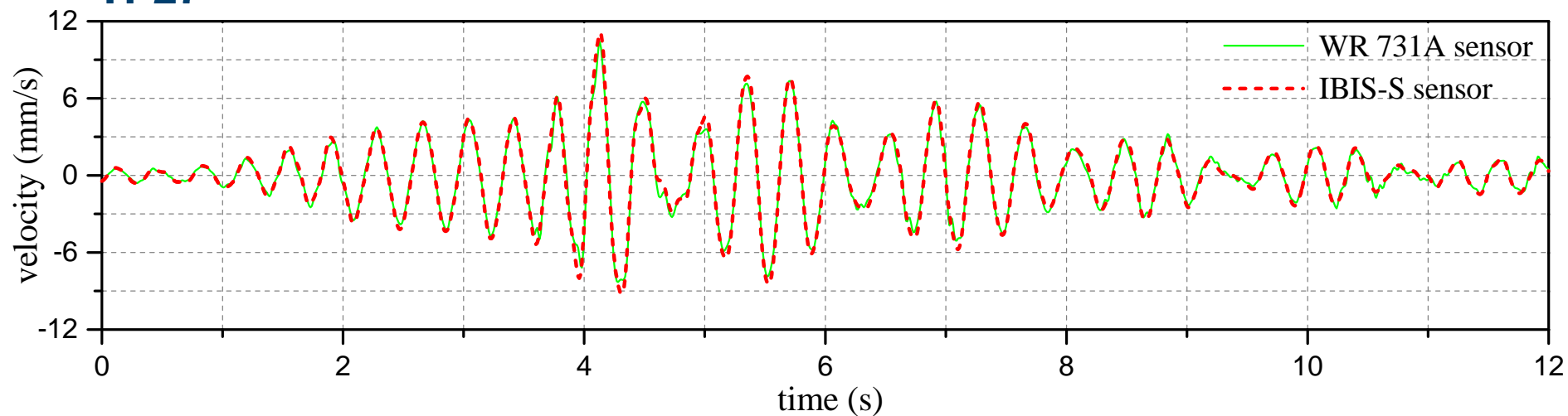
Dynamic test (AVT) of a r.c. bridge (5)

20

TP22



TP27

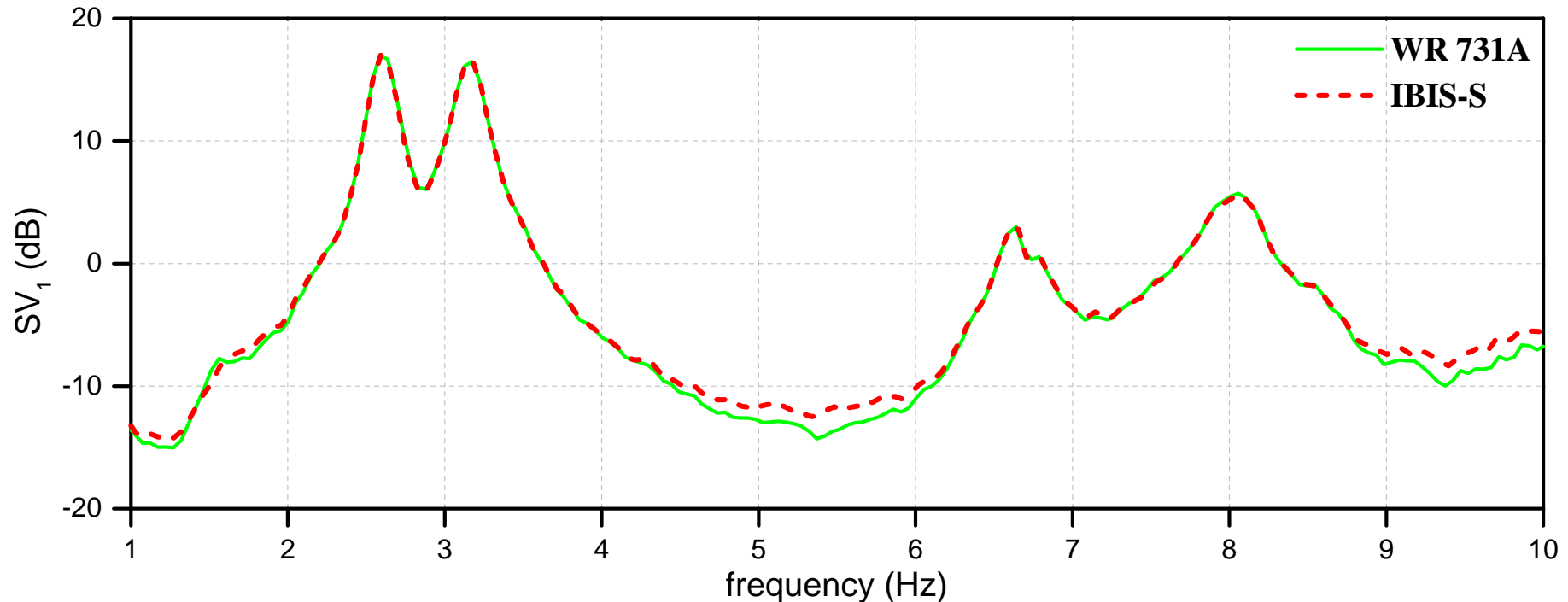




Dynamic test (AVT) of a r.c. bridge (6)

21

$T = 3000s$

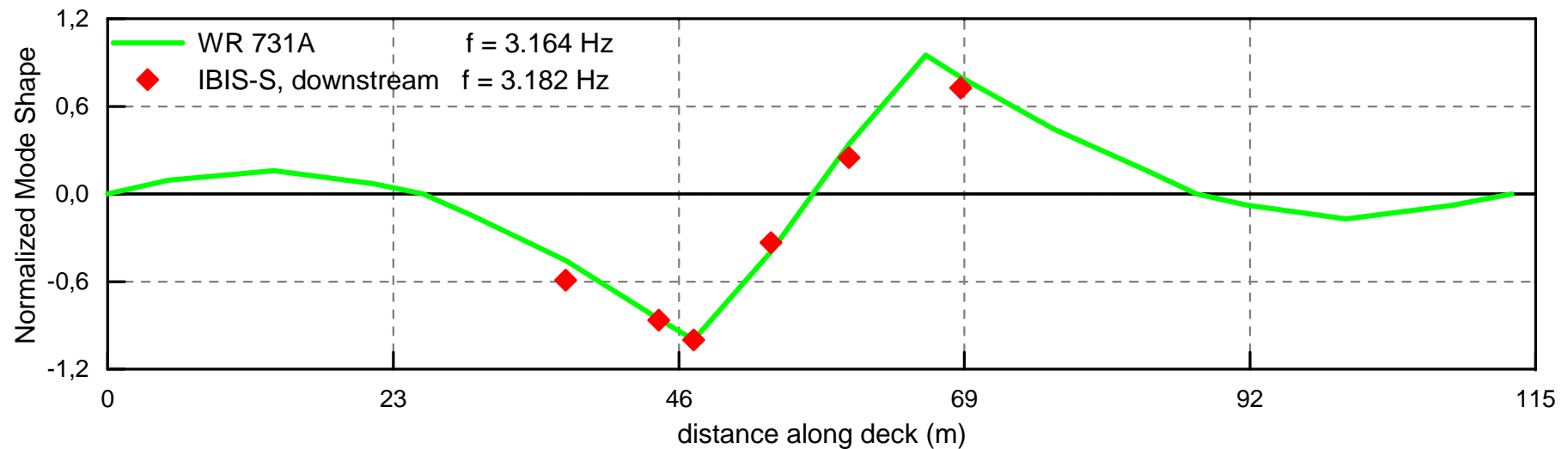
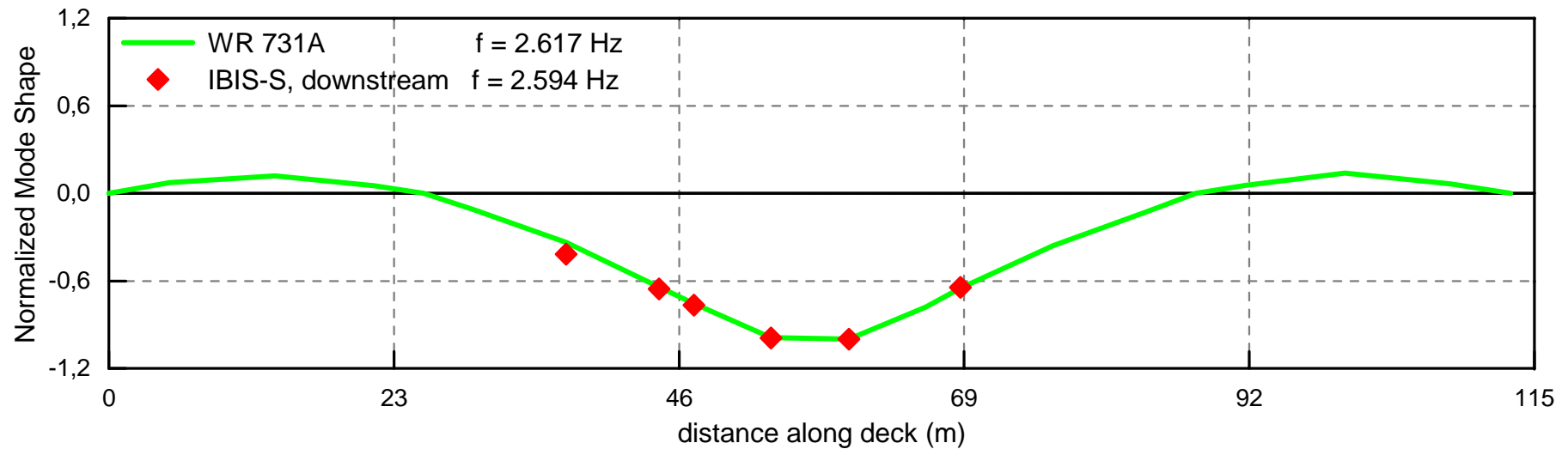


- *The radar signals describe the important dynamic characteristics of the bridge as well as the signals recorded by the conventional sensors;*
- *The main differences between radar and conventional signals are conceivably related to different S/N ratios.*



Dynamic test (AVT) of a r.c. bridge (7)

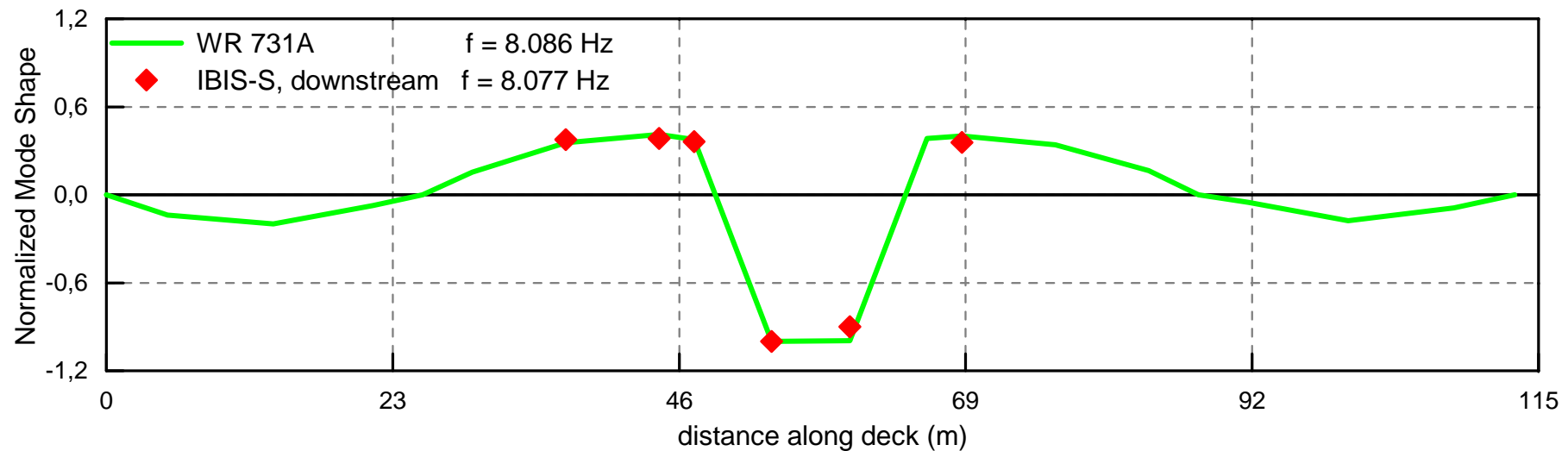
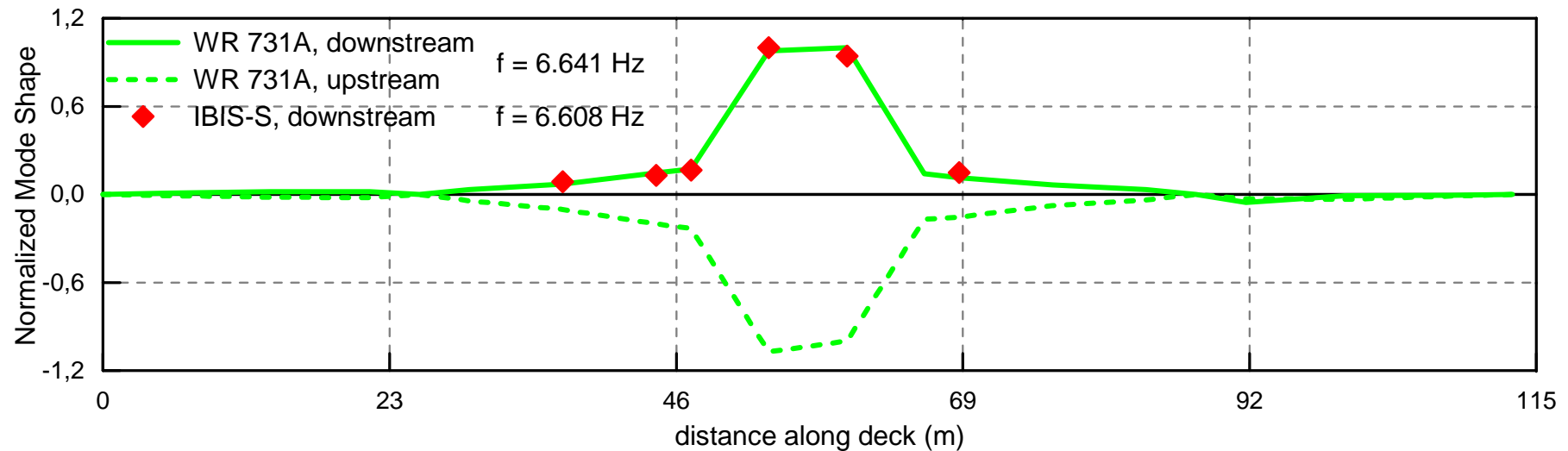
22





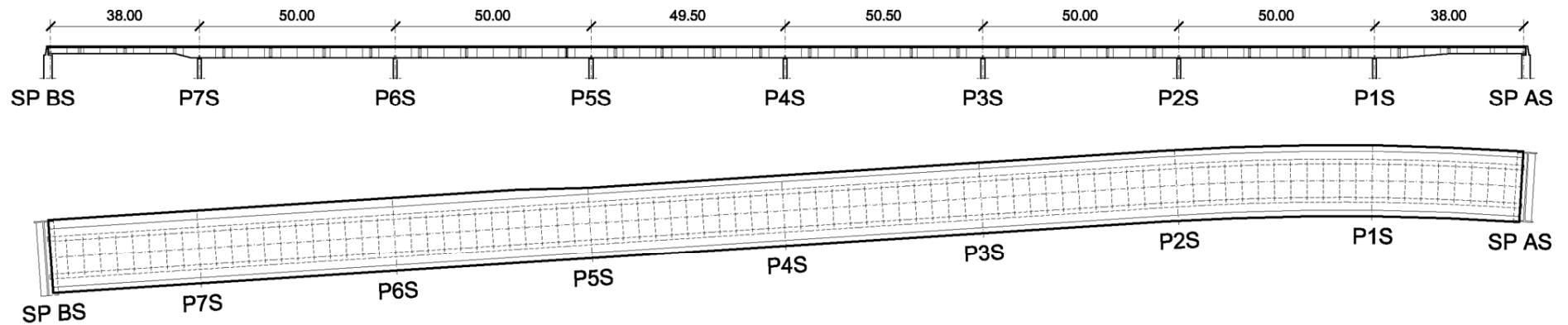
Dynamic test (AVT) of a r.c. bridge (8)

23





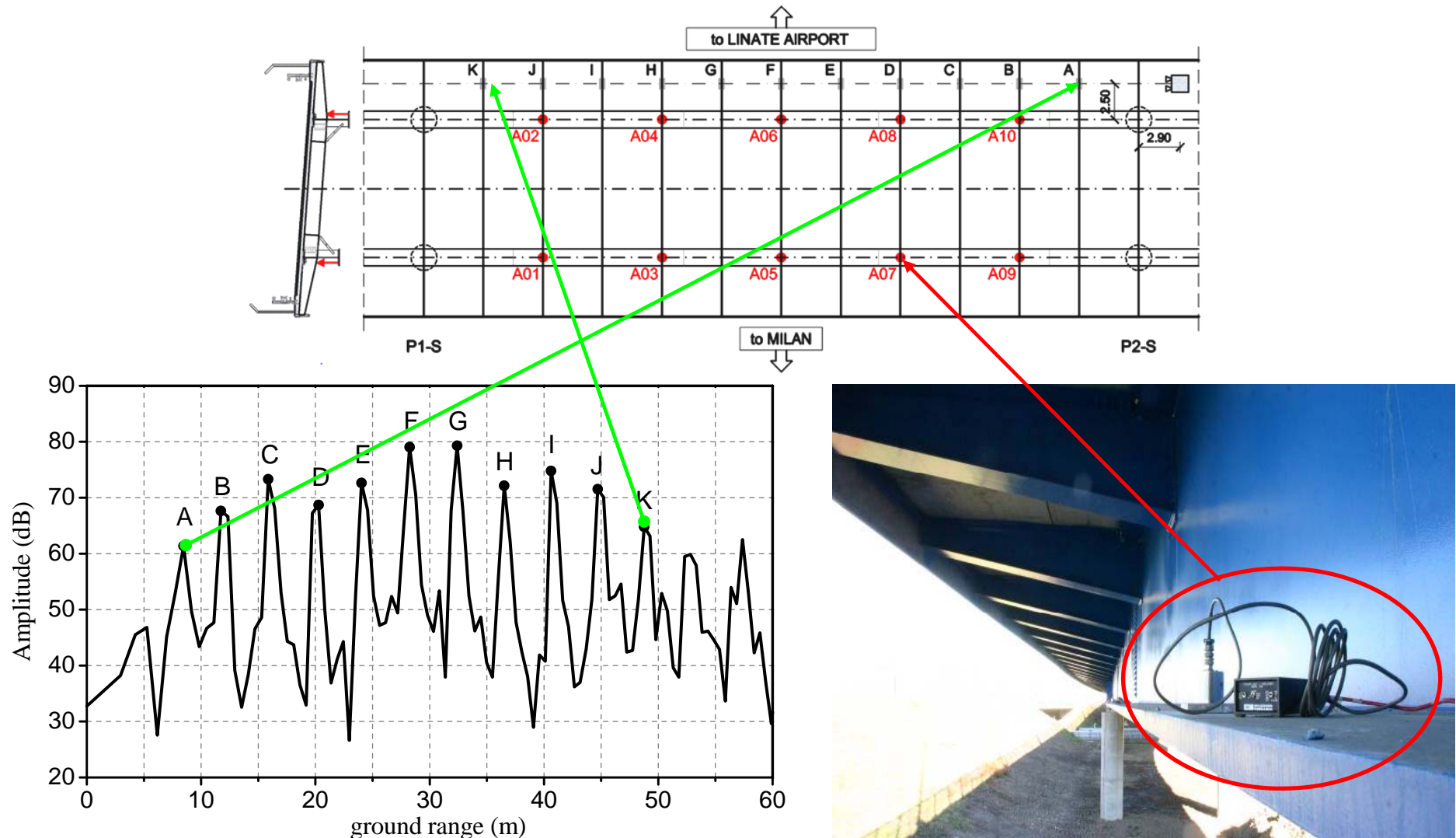
Dynamic test of a steel-composite bridge (1)²⁴





Dynamic test of a steel-composite bridge (2)²⁵

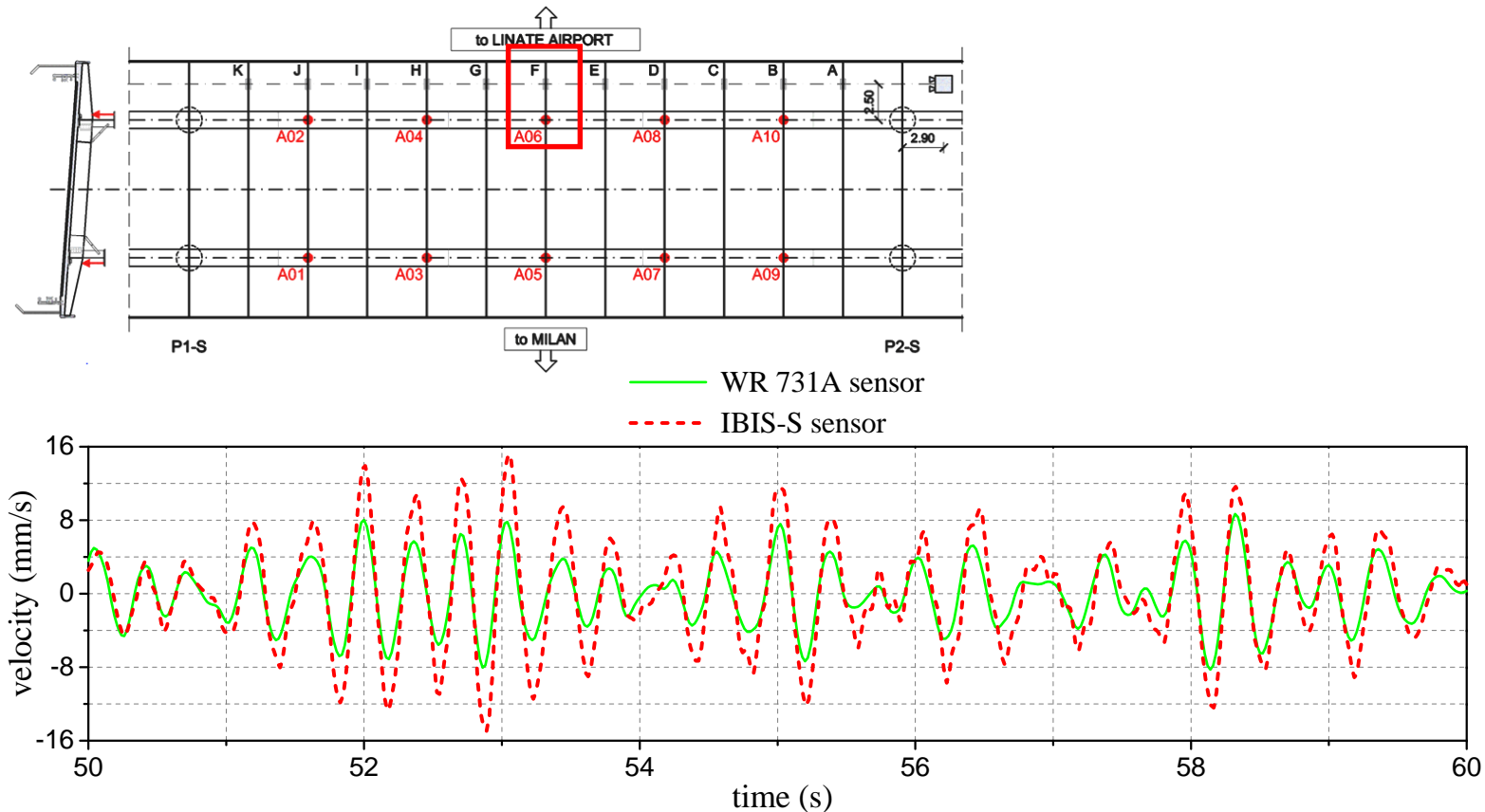
Experimental procedures:





Dynamic test of a steel-composite bridge (3)²⁶

Results obtained from the radar sensor: velocity time-series

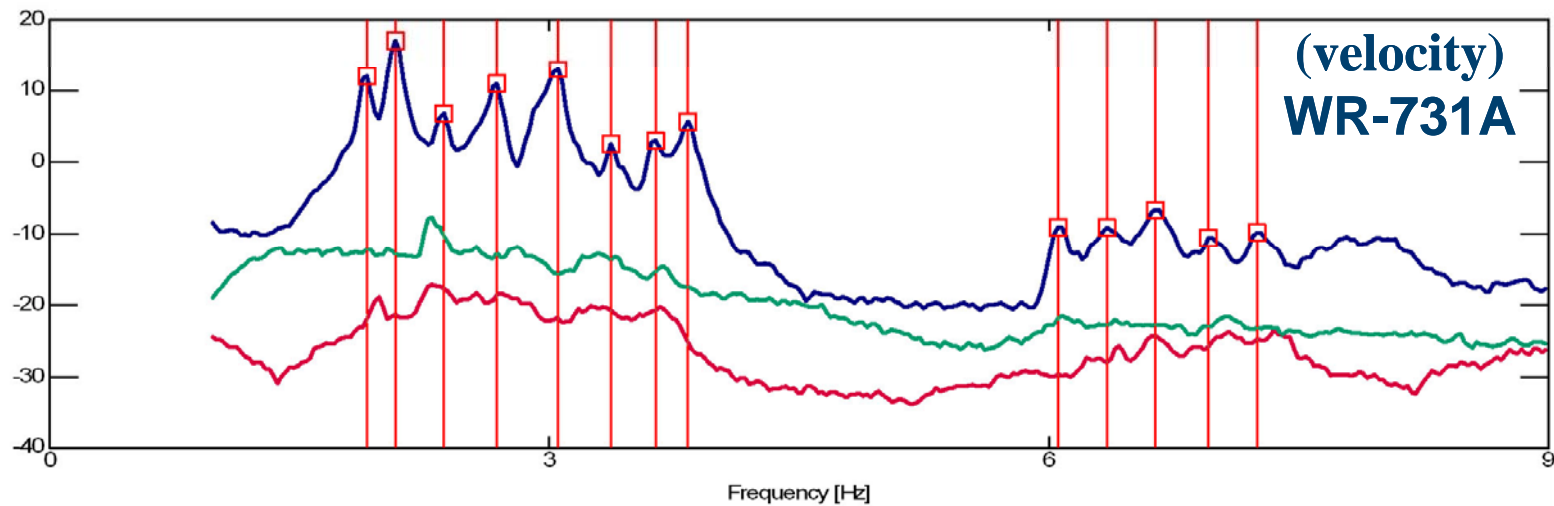


Differently from the Capriate bridge, the time-histories obtained from the radar and from conventional sensors refer to close but different points.

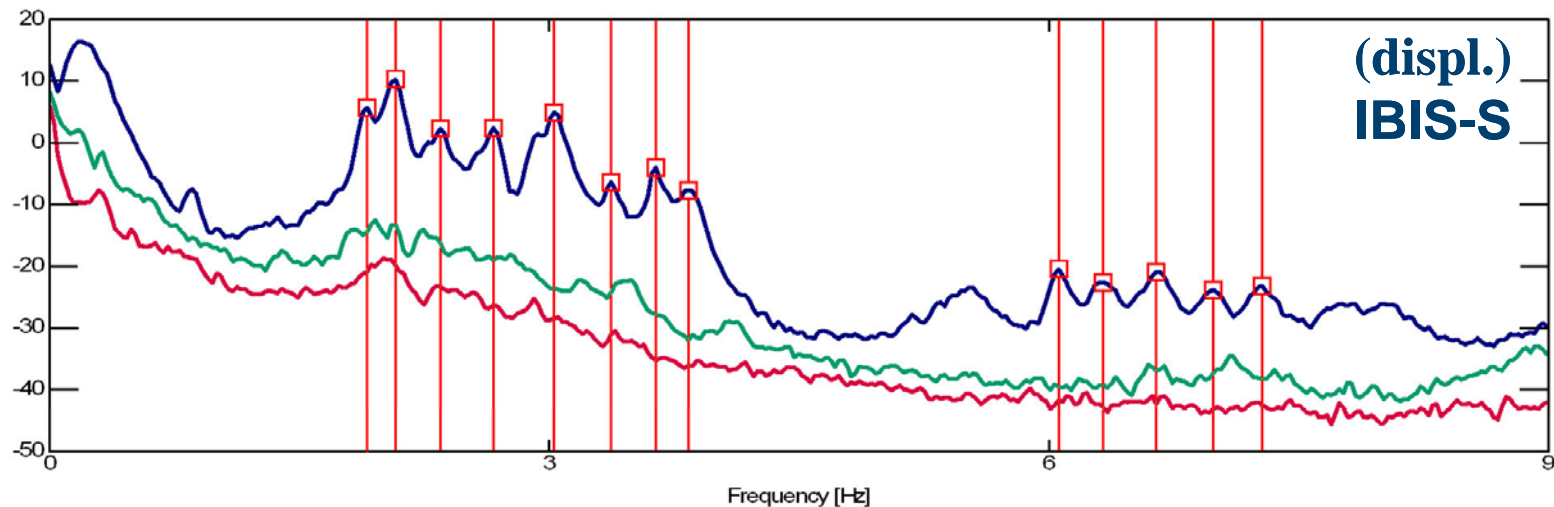


Dynamic test of a steel-composite bridge (4)²⁷

Results obtained from the radar sensor: natural frequencies



$T = 2260$ s





Dynamic test of a steel-composite bridge (5)²⁸

Results obtained from the radar sensor: modal parameters

Mode Identifier	f (Hz)		MAC	Mode Identifier	f (Hz)		MAC
	WR-731A	IBIS-S			WR-731A	IBIS-S	
B ₁	1.904	1.905	0.996	B ₇	3.833	3.835	0.998
B ₂	2.075	2.076	0.992	T ₂	6.055	6.058	0.994
B ₃	2.368	2.345	0.989	B ₈	6.348	6.327	0.989
B ₄	2.686	2.663	0.997	B ₉	6.641	6.645	0.985
B ₅	3.052	3.029	0.998	B ₁₀	6.982	6.987	0.976
B ₆	3.369	3.371	0.995	T ₃	7.251	7.280	0.984
T ₁	3.638	3.640	0.995		—	—	—

- *The natural frequencies identified from radar signals are practically equal to those identified from conventional sensors;*
- *The mode shapes exhibit excellent correlation (MAC very close to 1) as well, provided that the modal deflections were properly normalized.*

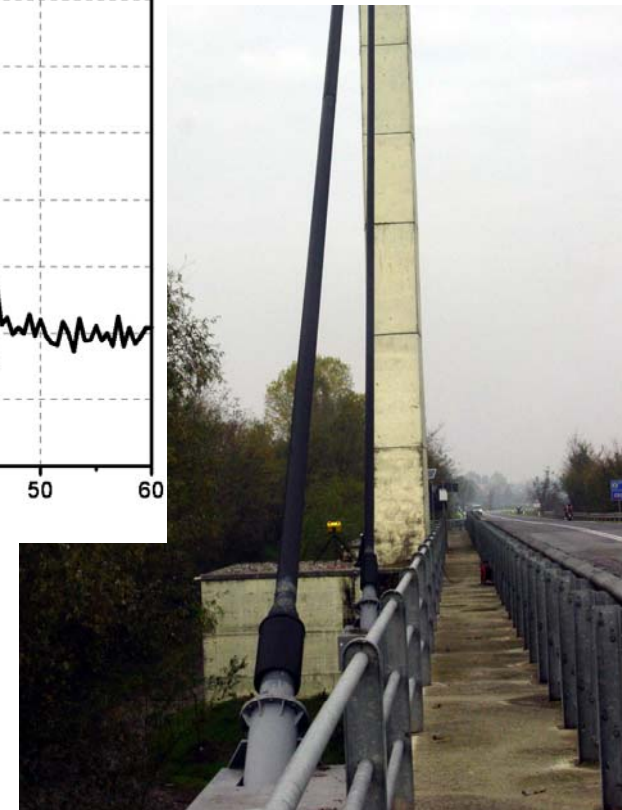
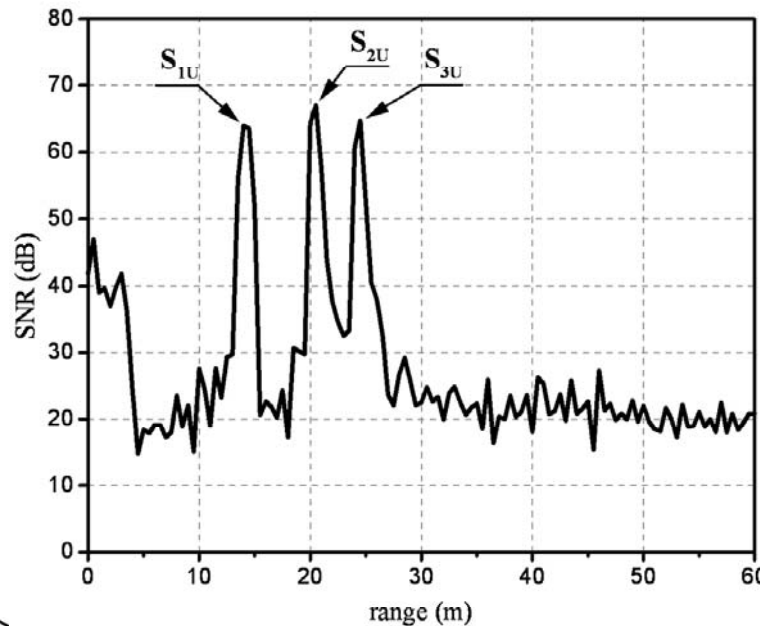
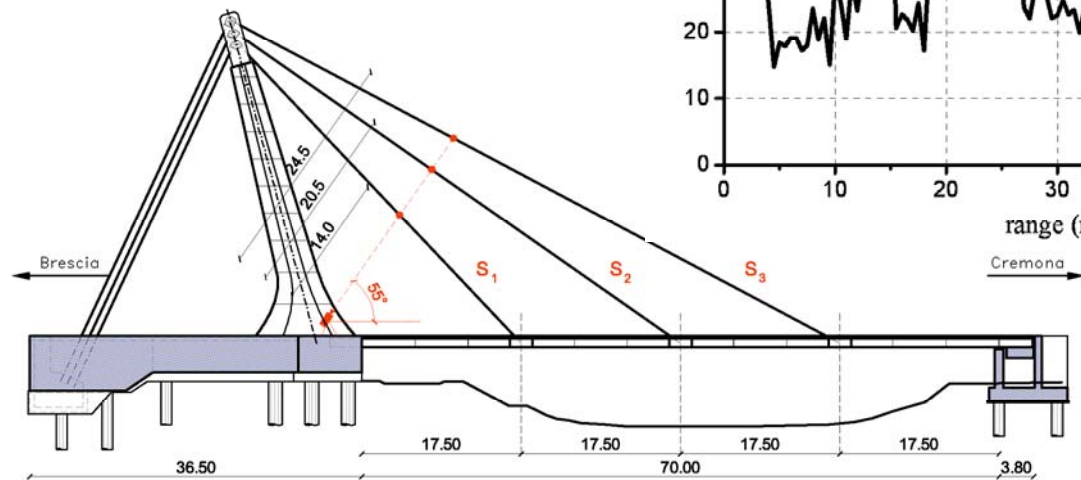


Dynamic measurements on stay cables (1)

29

The typical position of the sensor is inclined upward; hence, the only targets encountered along the path of the electromagnetic waves are the stays itself so that 1-D imaging capability is perfectly adequate to the test scenario

Upstream Side



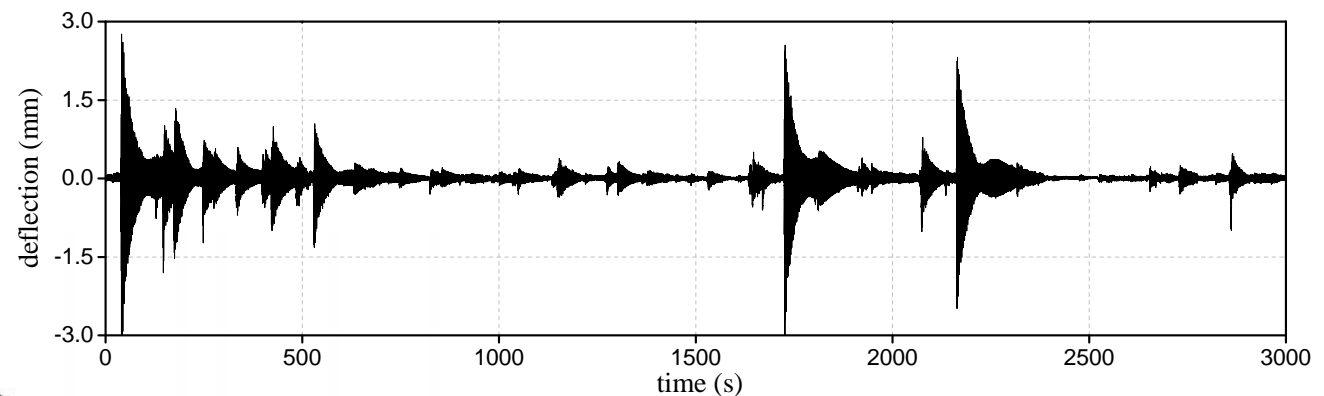


Dynamic measurements on stay cables (2)

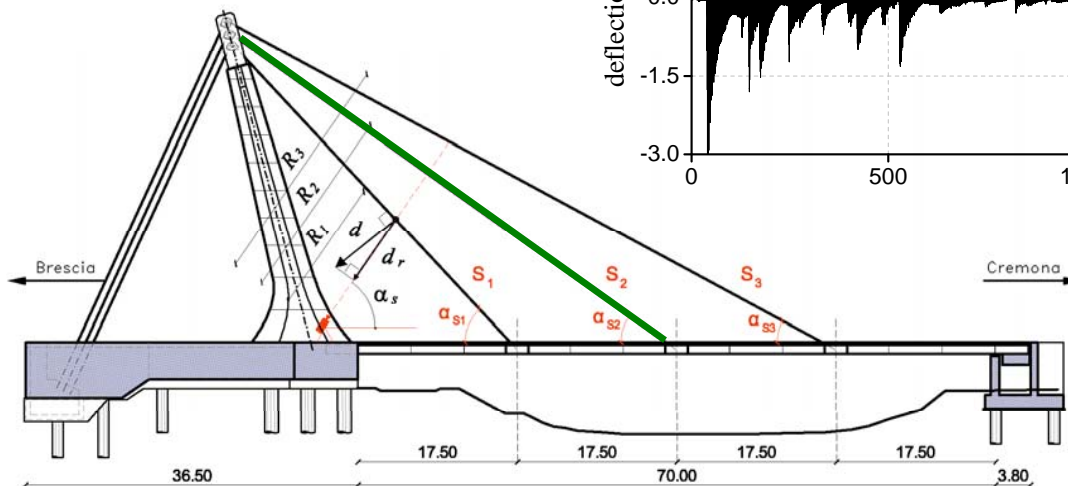
30

By assuming that the in-plane motion of the cable is orthogonal to its axis, the actual deflection d of the cable is easily evaluated from the knowledge of the radial deflection d_r , the slope of the cable α_c and the inclination of the sensor α_s :

$$d = \frac{d_r}{\cos[\pi/2 - (\alpha_c + \alpha_s)]}$$



Stay cable S_{2U}



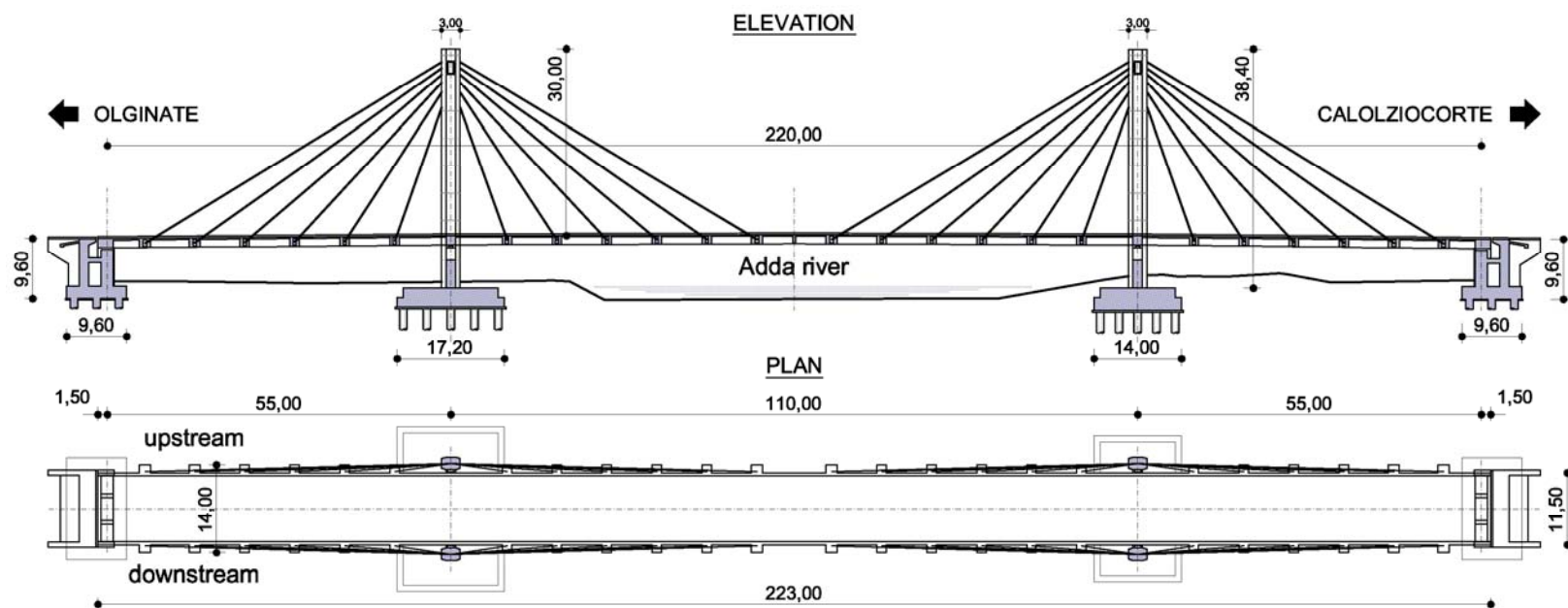


Dynamic measurements on stay cables

Cable-stayed bridge over the Adda river

31

(1)



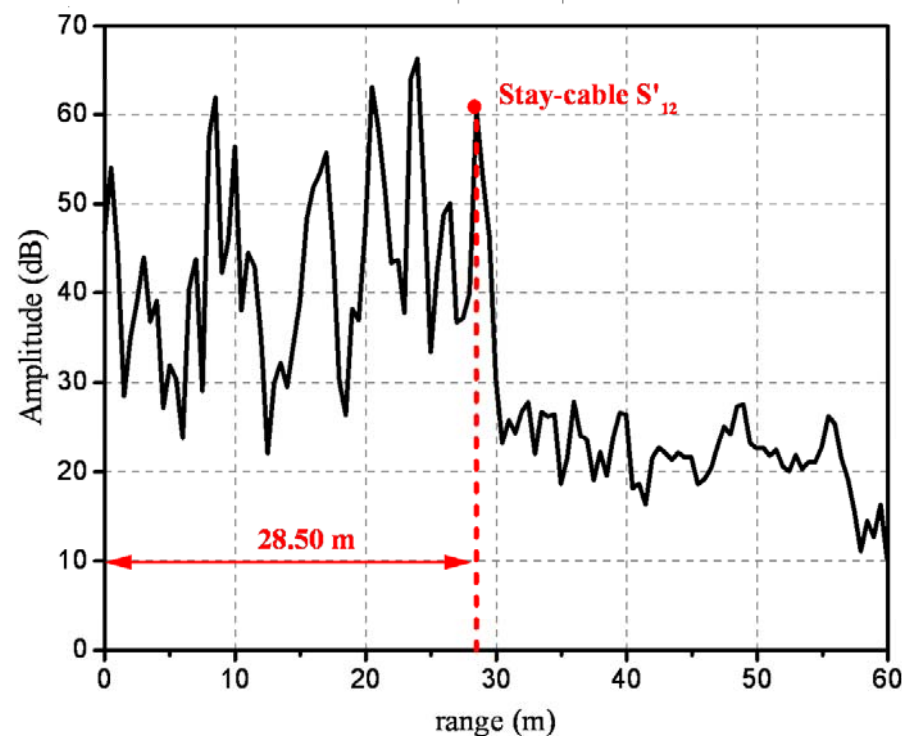
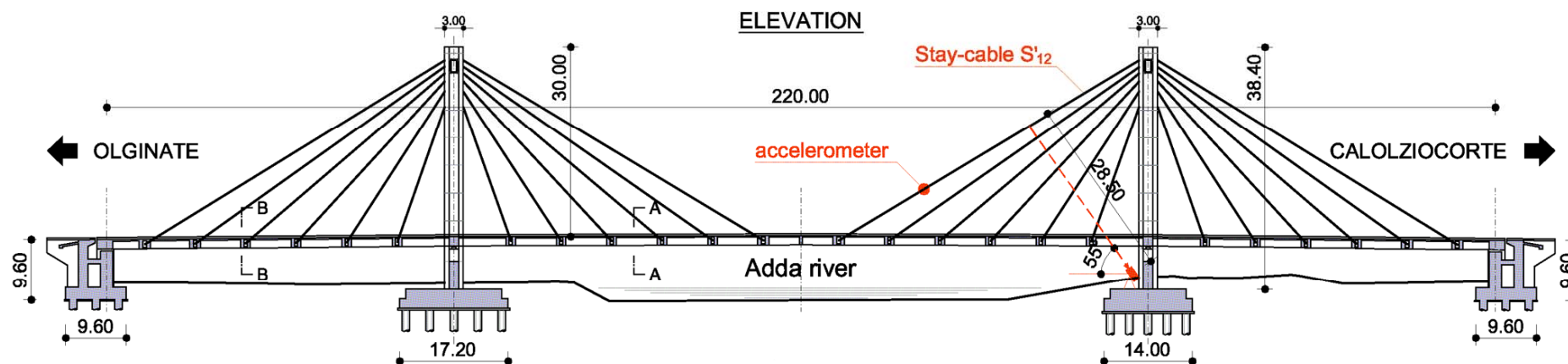


Dynamic measurements on stay cables

Cable-stayed bridge over the Adda river

32

(2)





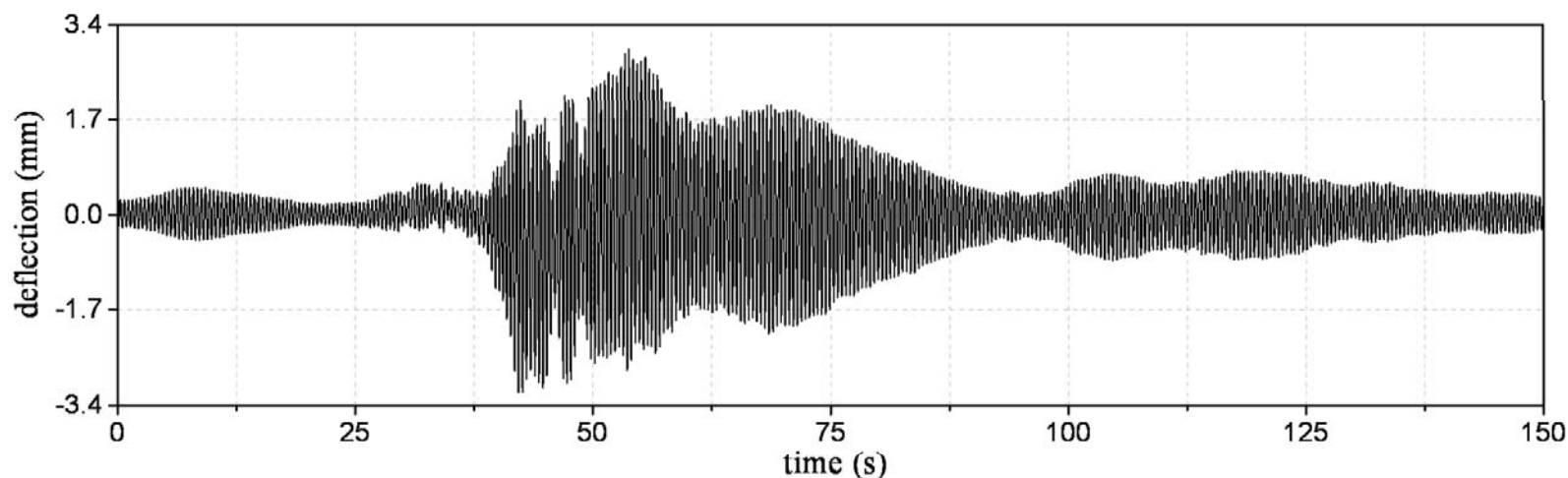
Dynamic measurements on stay cables

Cable-stayed bridge over the Adda river

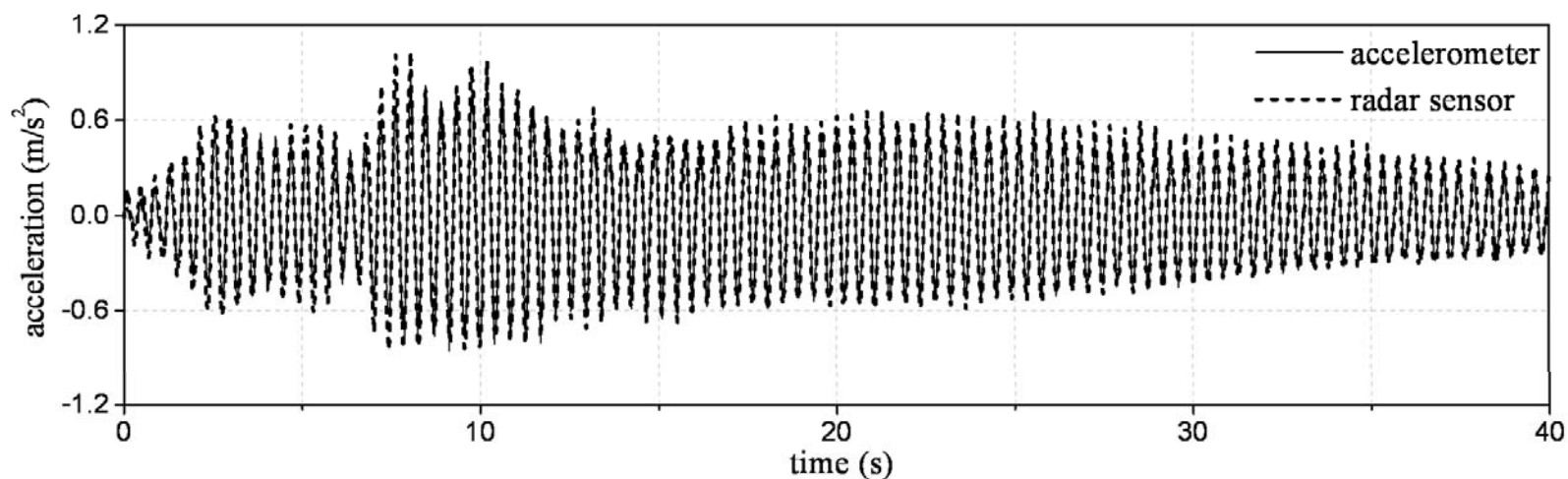
33

(3)

Typical deflection time-history



Acceleration time-histories obtained from accelerometer and radar sensor



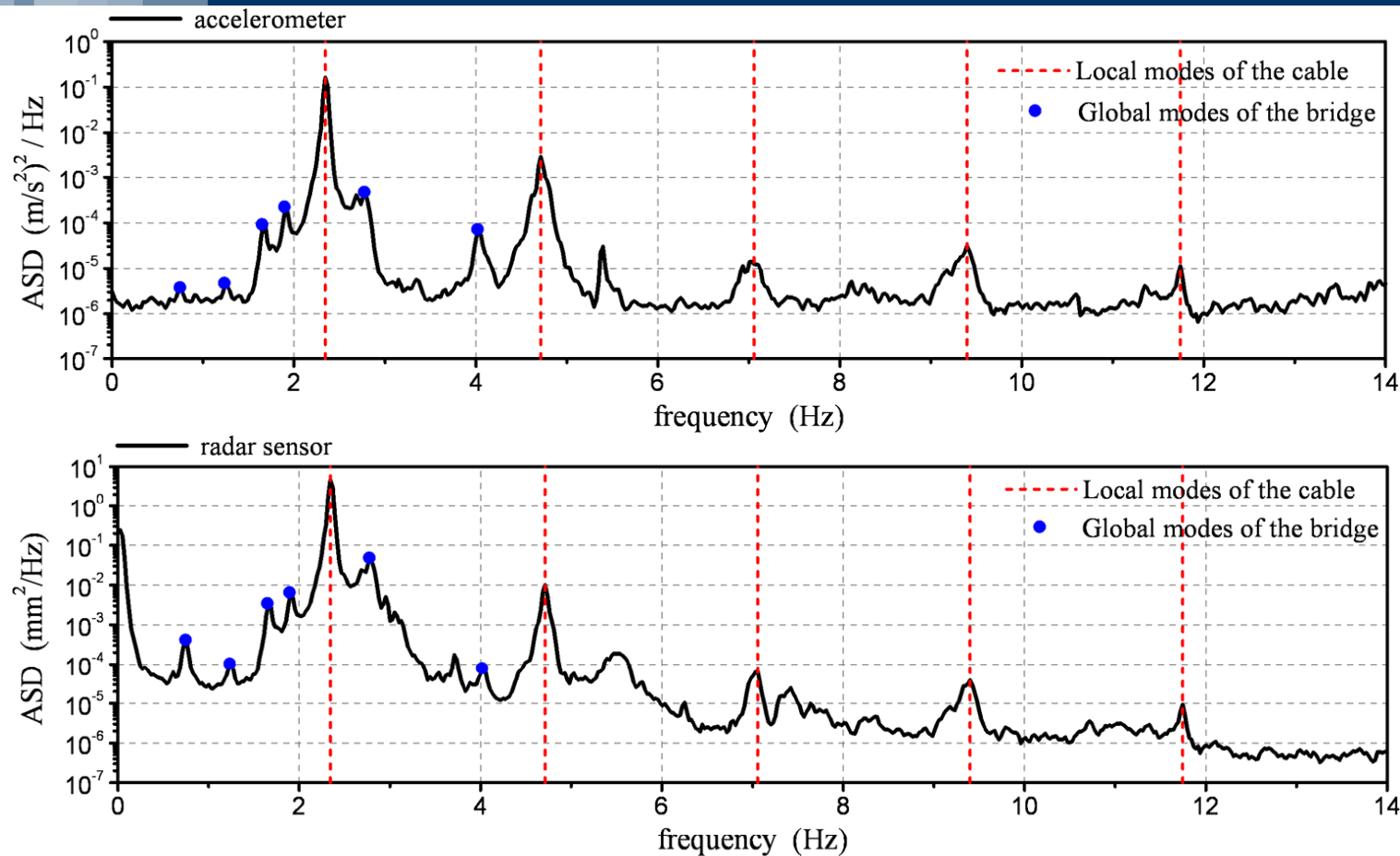


Dynamic measurements on stay cables

Cable-stayed bridge over the Adda river

34

(4)



- Excellent agreement in terms of local natural frequencies of the cable (red dashed lines) and in terms of global natural frequencies of the bridge (blue dots), as well

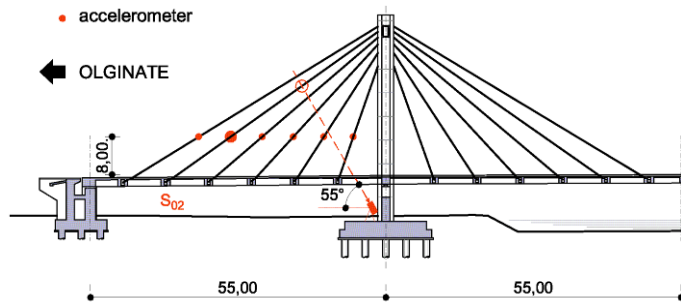


Dynamic measurements on stay cables

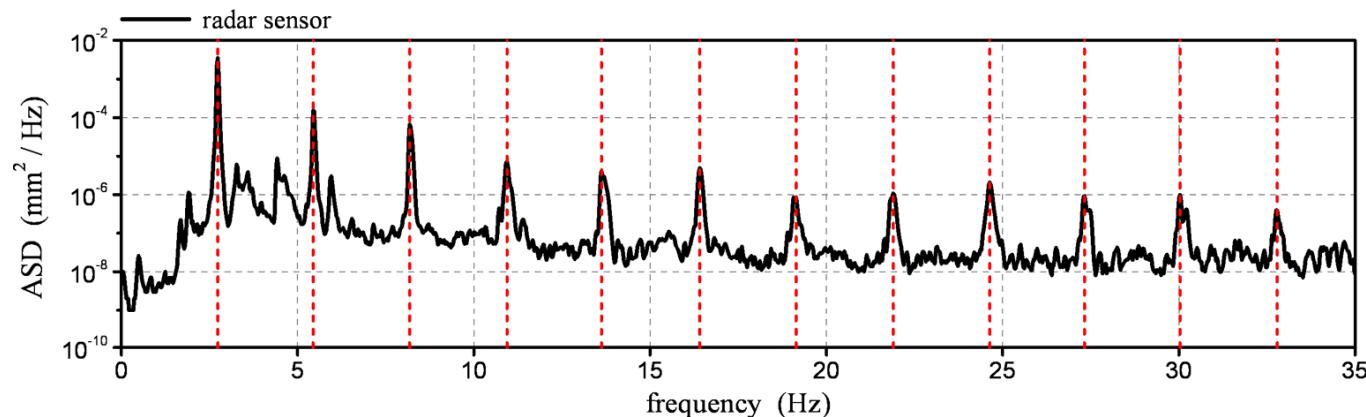
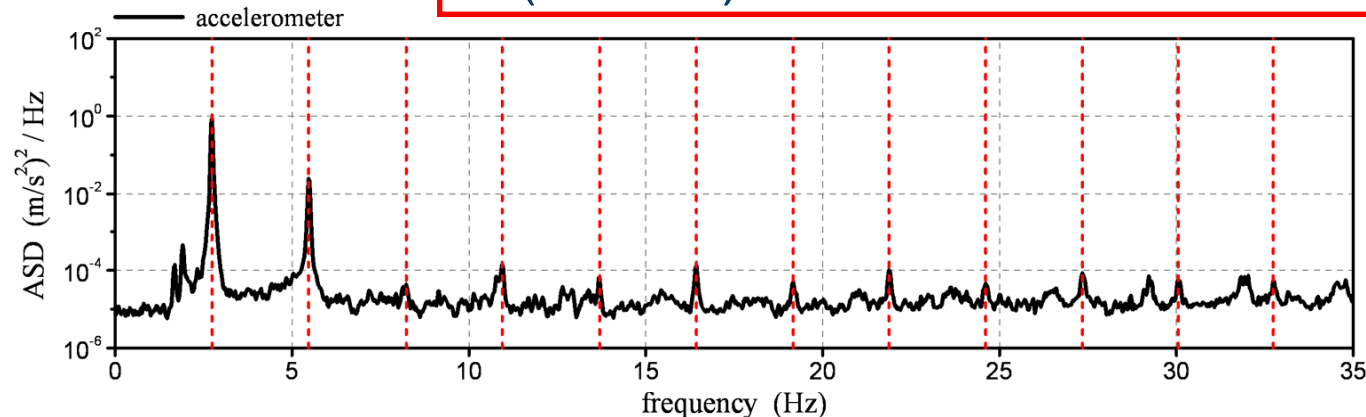
Cable-stayed bridge over the Adda river

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(5)



- Large number of local modes identified;
- The peaks related to the cable natural frequencies are much more evident in the ASD of radar data in the high-frequency range (7-35 Hz)





Dynamic measurements on stay cables

Cable-stayed bridge over the Adda river

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(6)



Cable tensions obtained from accelerometer and radar measurements

Cable	Sensor	$T(f_1)$ (kN)	$T(f_2)$ (kN)	$T(f_3)$ (kN)	$T(f_4)$ (kN)	$T(f_5)$ (kN)	Average (kN)	$T_{\text{Load Cell}}$ (kN)
S'_{12}	Accelerometer	2679	2707	2660	2693	2690	2686	2694
	Radar sensor	2679	2707	2679	2693	2690	2689	
S_{02}	Accelerometer	2788	2789	2805	2789	2798	2794	2855
	Radar sensor	2788	2789	2772	2789	2778	2783	

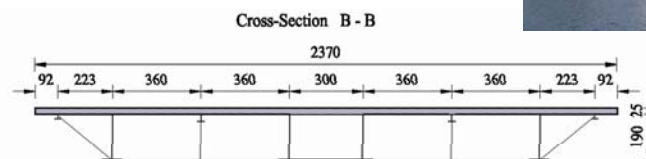
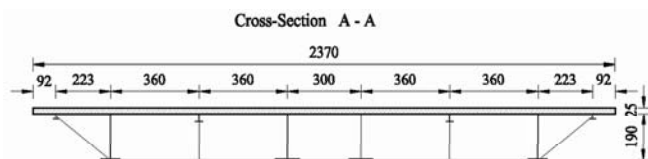
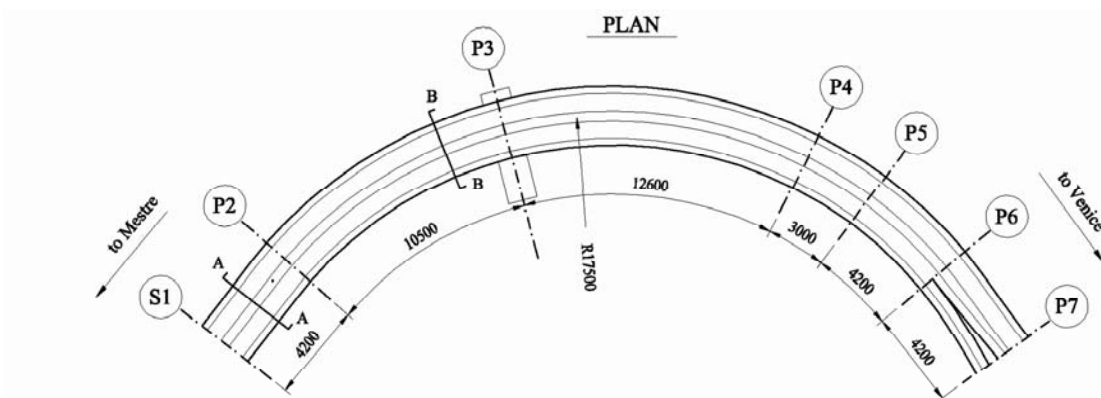
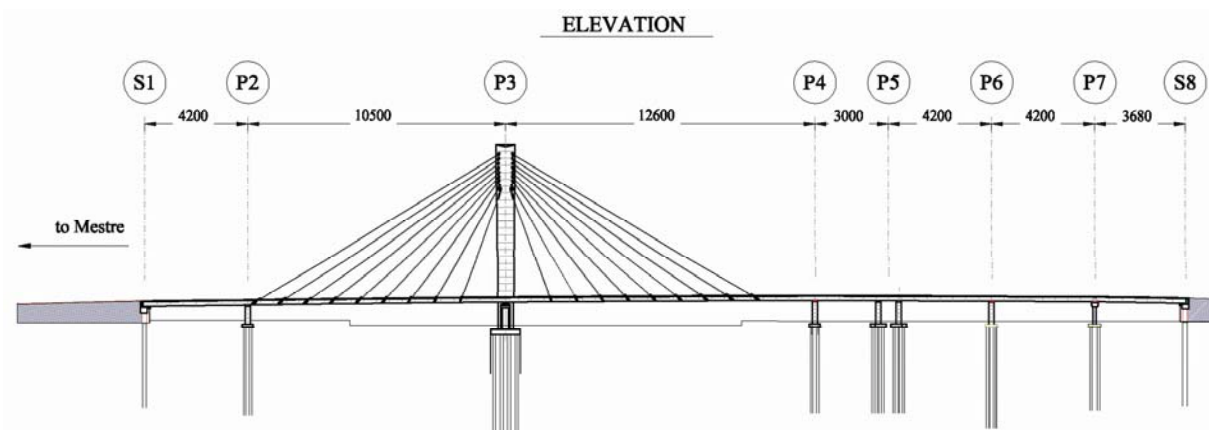


Dynamic measurements on stay cables

Cable-stayed bridge in Porto Marghera

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(1)



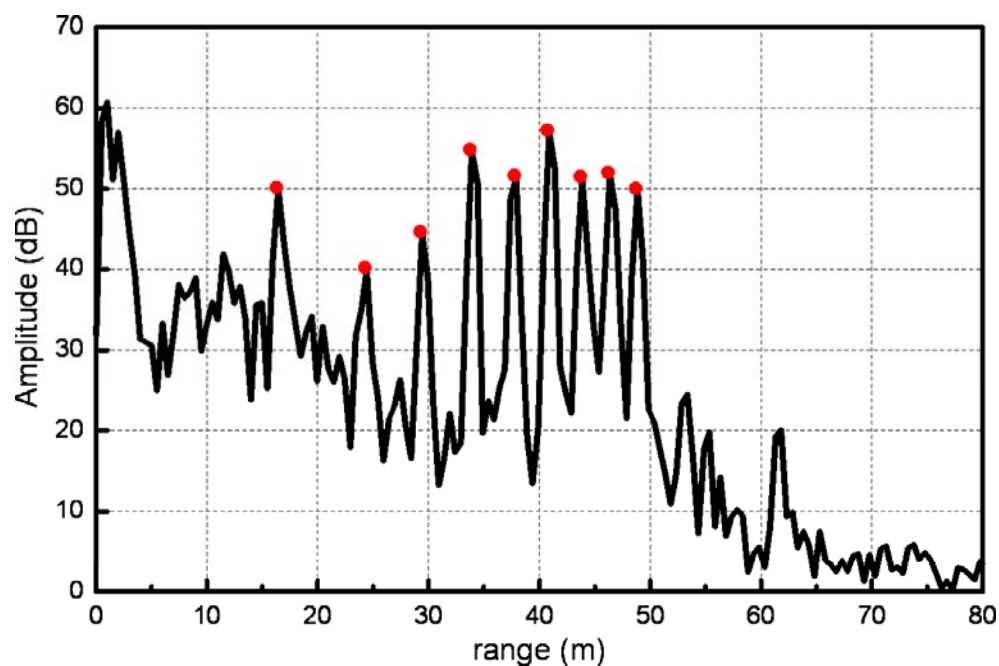
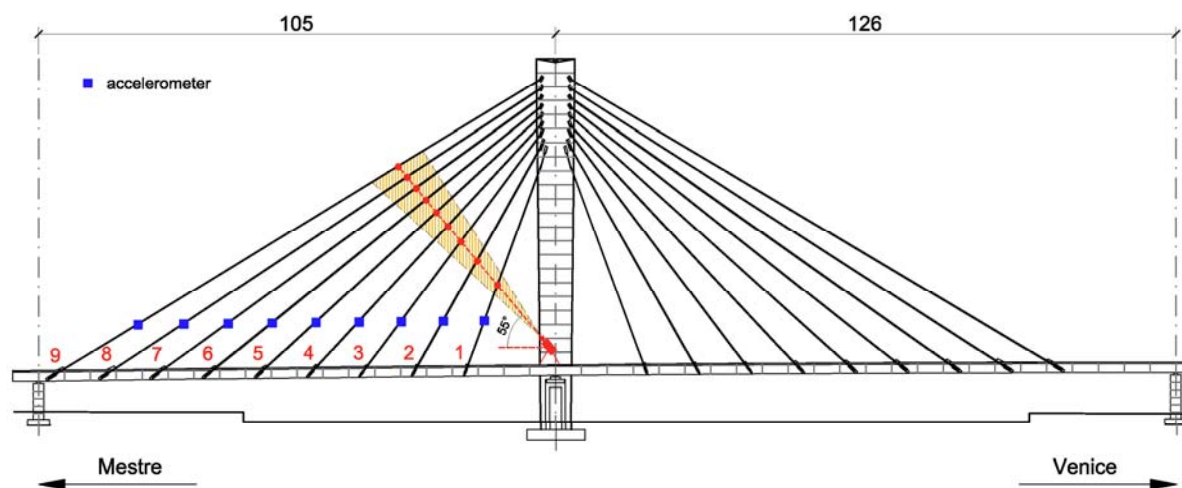


Dynamic measurements on stay cables

Cable-stayed bridge in Porto Marghera

38

(2)





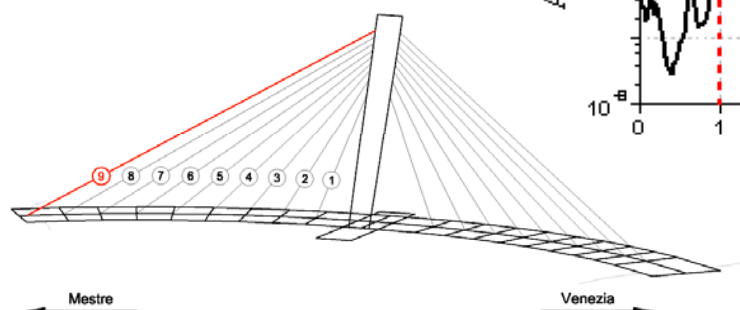
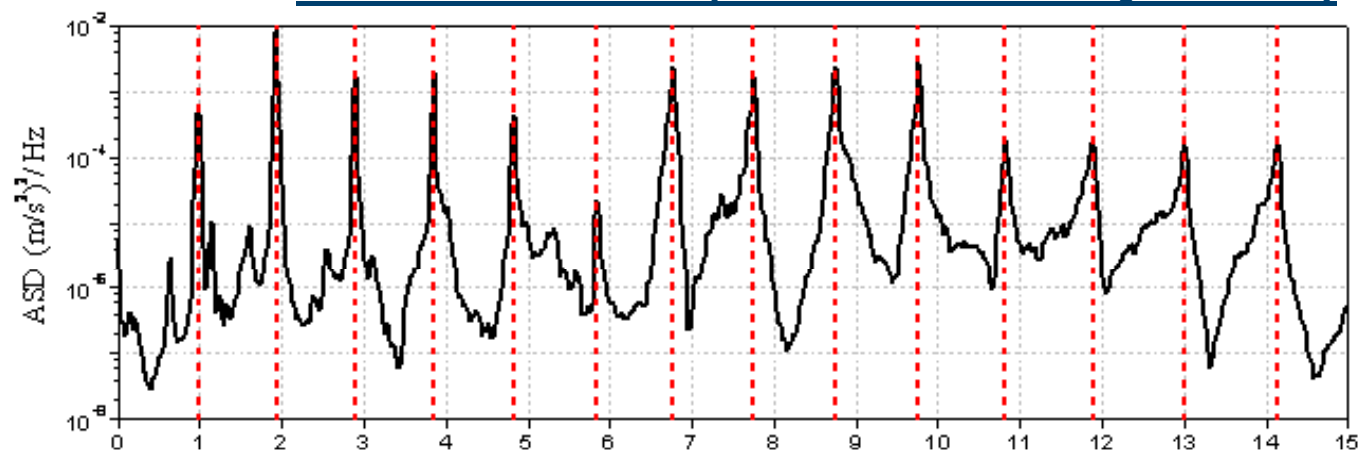
Dynamic measurements on stay cables

Cable-stayed bridge in Porto Marghera

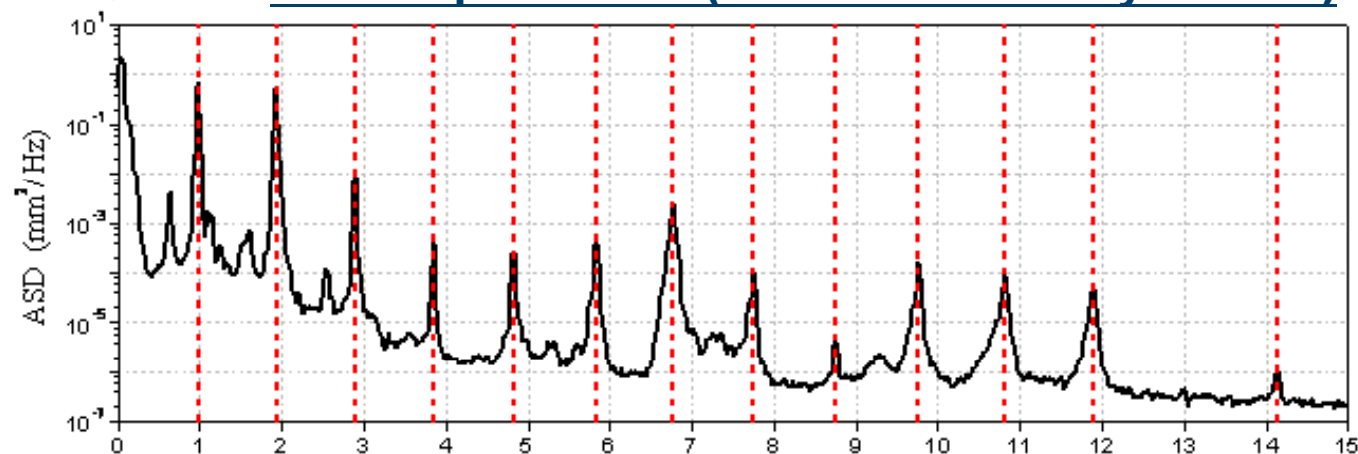
39

(3)

ASD acceleration (Mestre Side – Stay cable 9)



ASD displacement (Mestre Side – Stay cable 9)





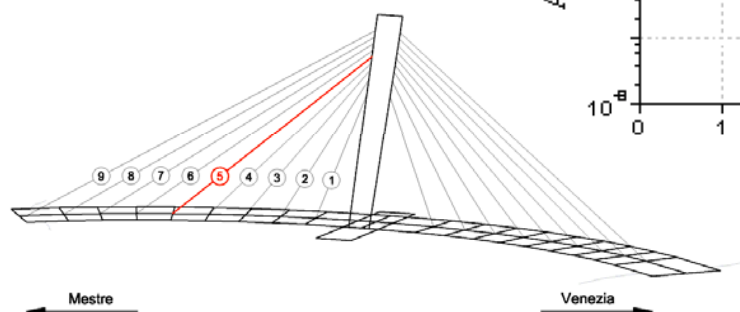
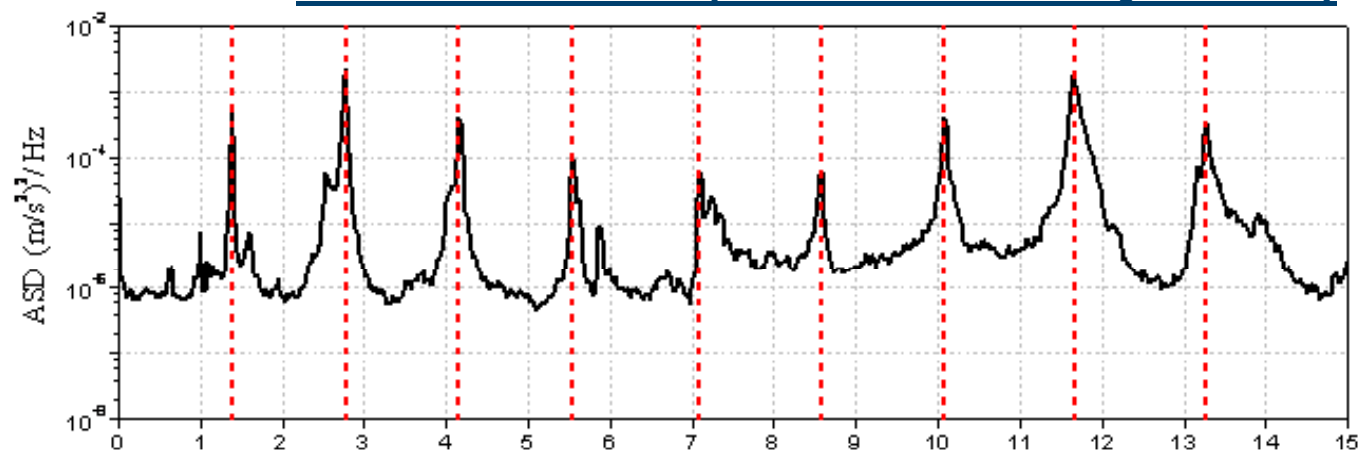
Dynamic measurements on stay cables

Cable-stayed bridge in Porto Marghera

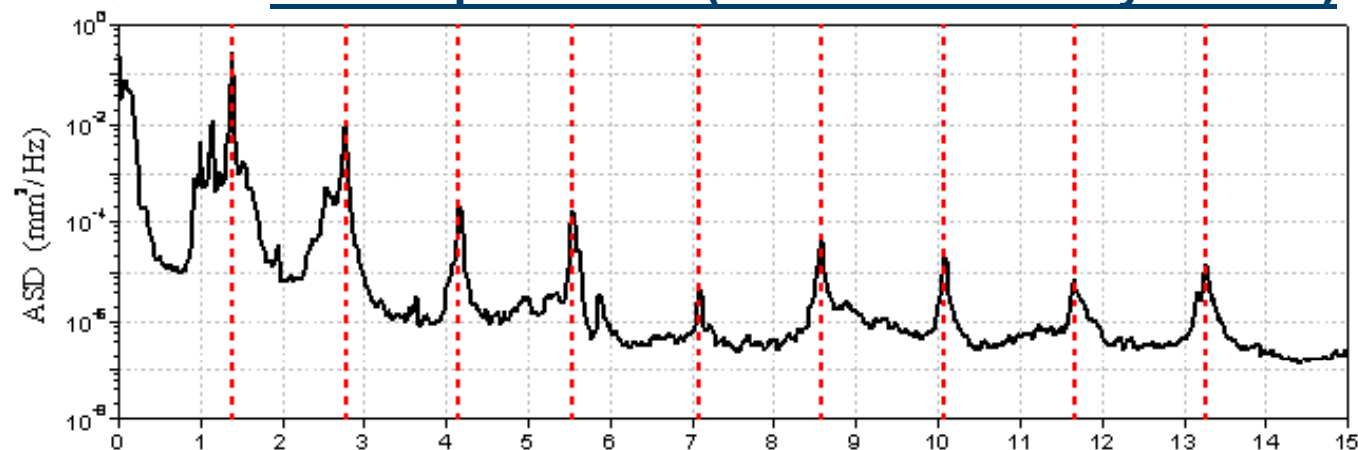
40

(4)

ASD acceleration (Mestre Side – Stay cable 5)



ASD displacement (Mestre Side – Stay cable 5)



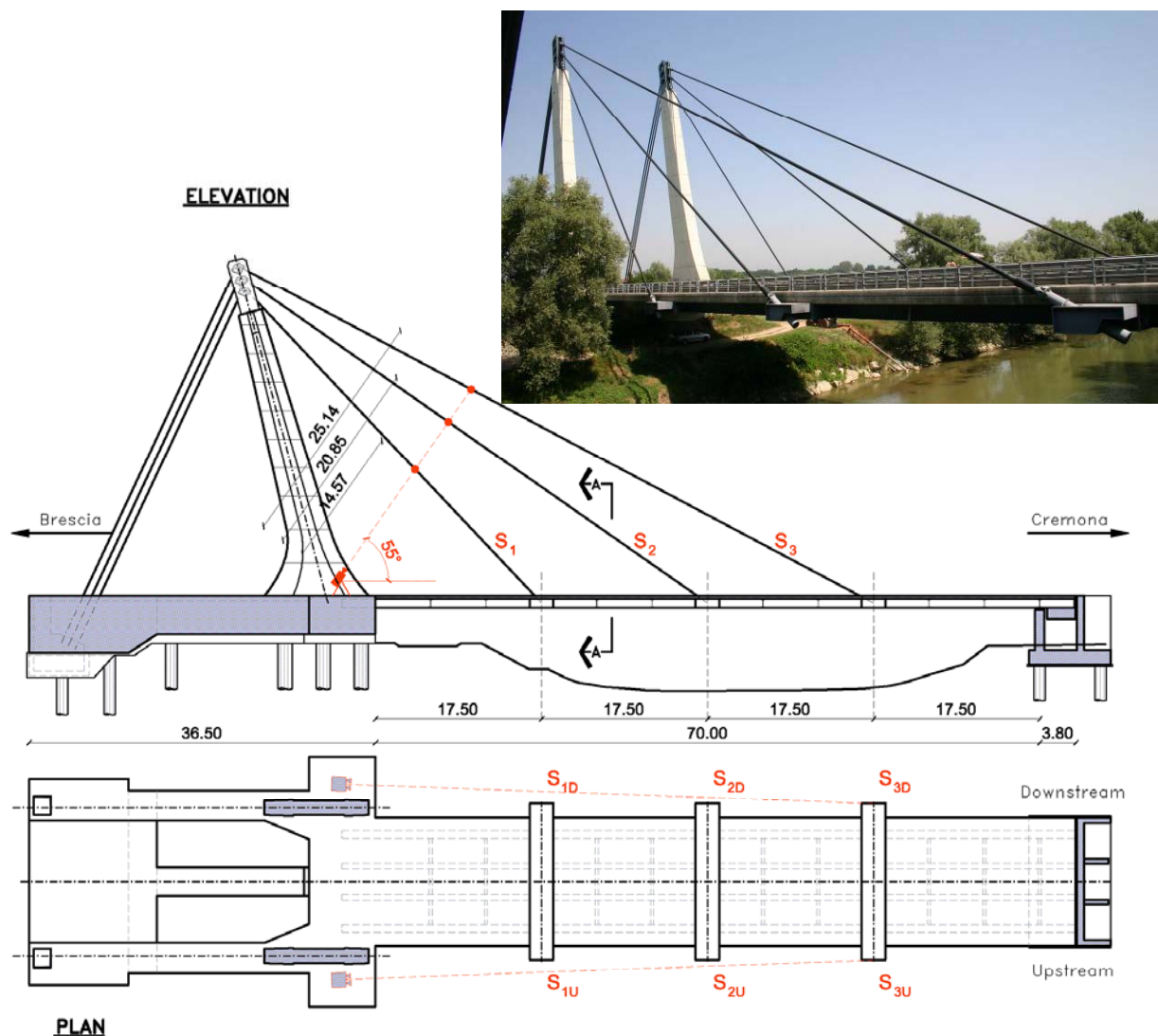


Dynamic measurements on stay cables

Cable-stayed bridge over the Oglio river

41

(1)



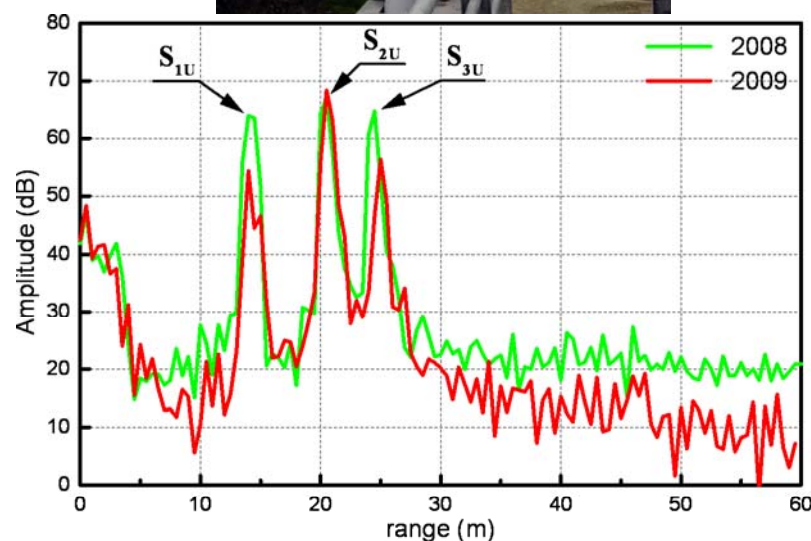


Dynamic measurements on stay cables

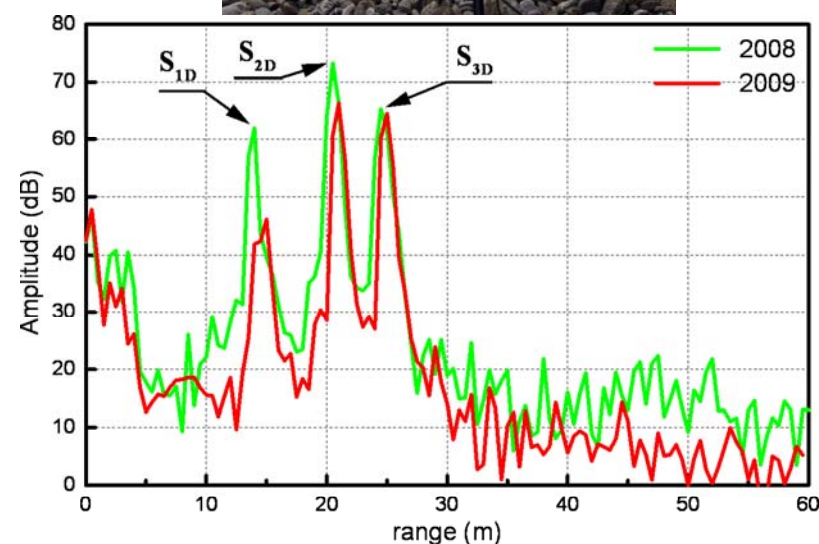
Cable-stayed bridge over the Oglio river

42

(2)



Upstream Side



Downstream Side



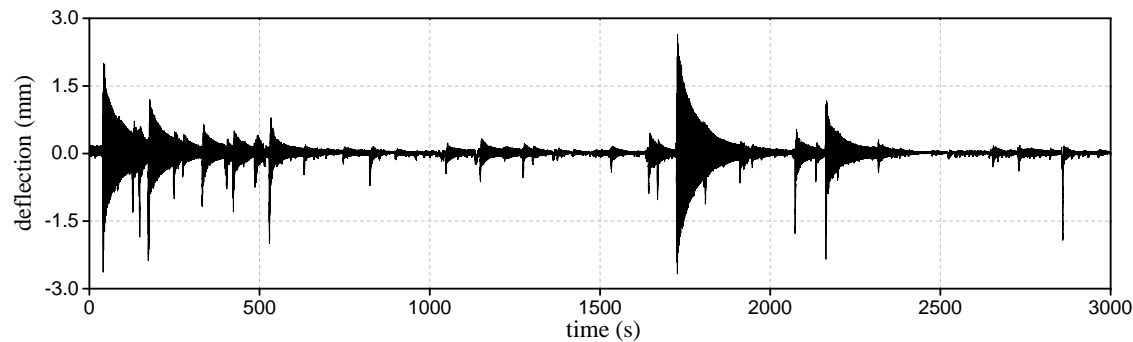
Dynamic measurements on stay cables

Cable-stayed bridge over the Oglio river

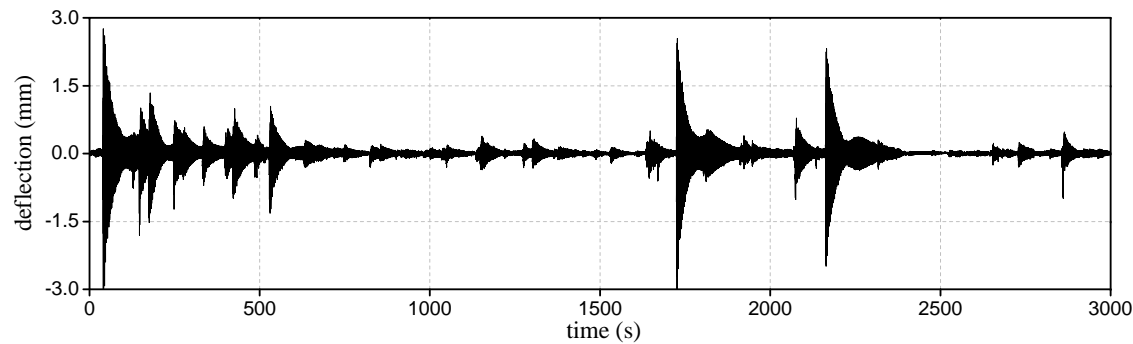
43

(3)

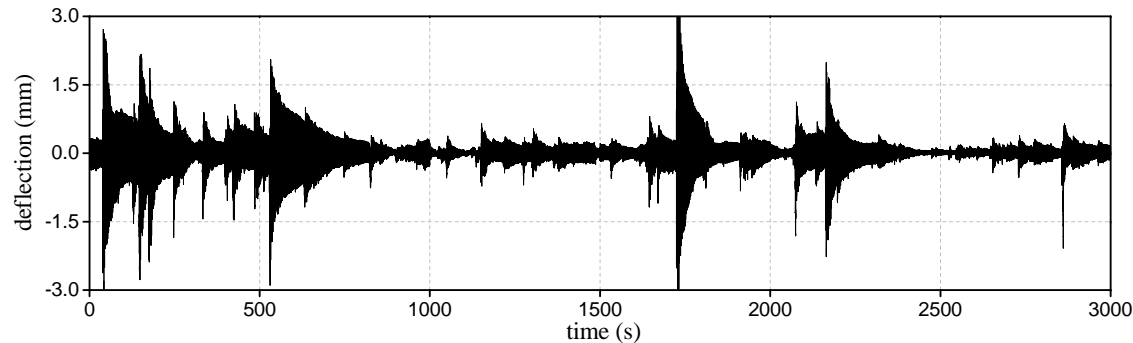
Deflection time-histories of upstream forestays



Stay cable S_{1U}



Stay cable S_{2U}



Stay cable S_{3U}



Dynamic measurements on stay cables

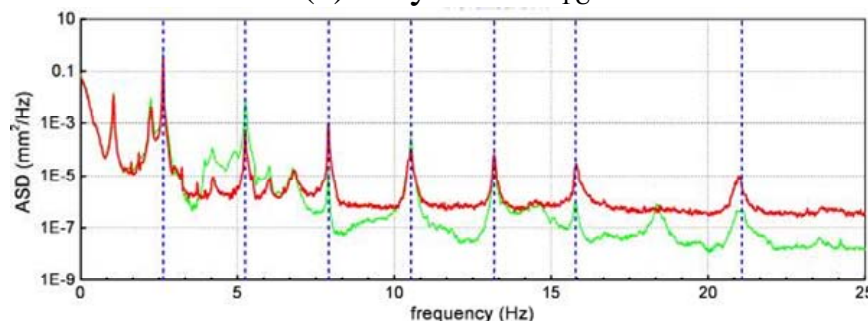
Cable-stayed bridge over the Oglio river

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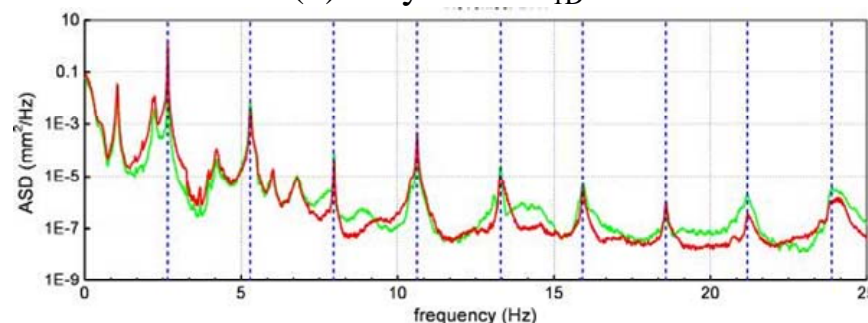
(4)

— November 2008
— November 2009

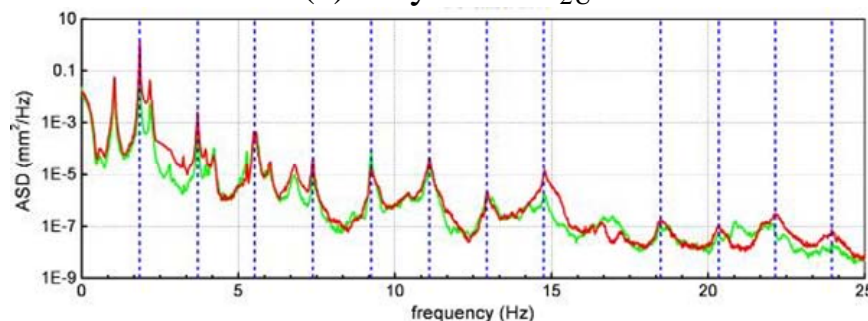
(a) Stay cable S_{1U}



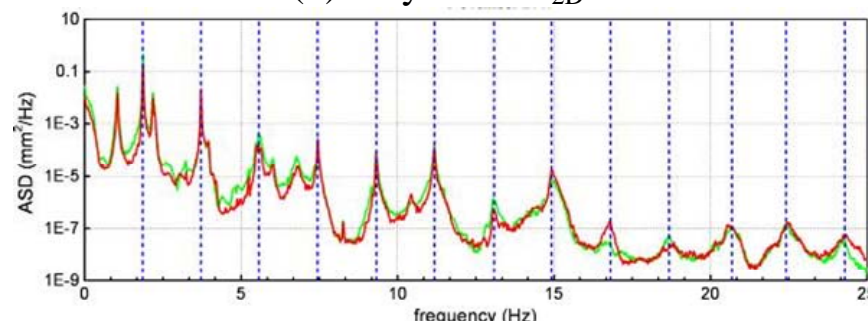
(b) Stay cable S_{1D}



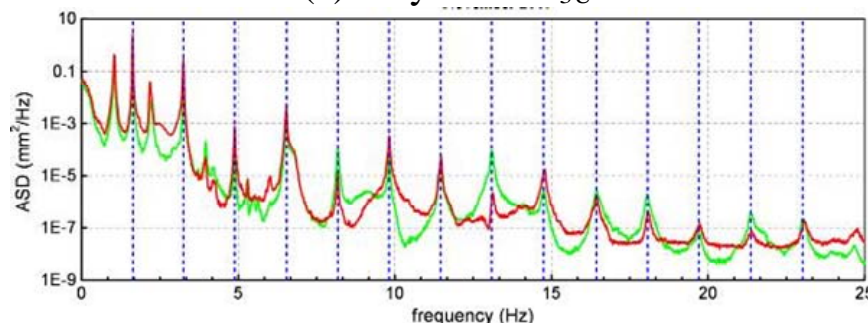
(c) Stay cable S_{2U}



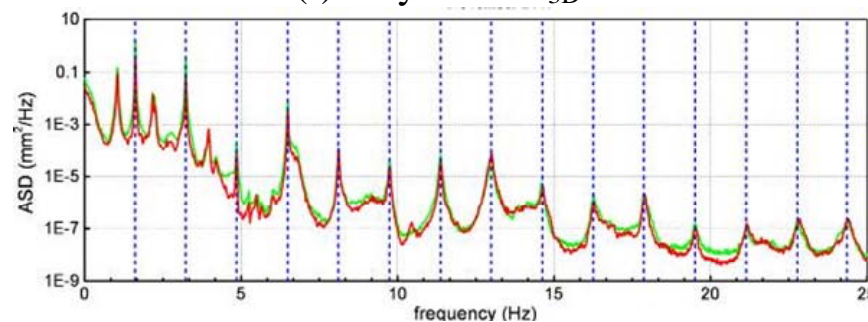
(d) Stay cable S_{2D}



(e) Stay cable S_{3U}



(f) Stay cable S_{3D}





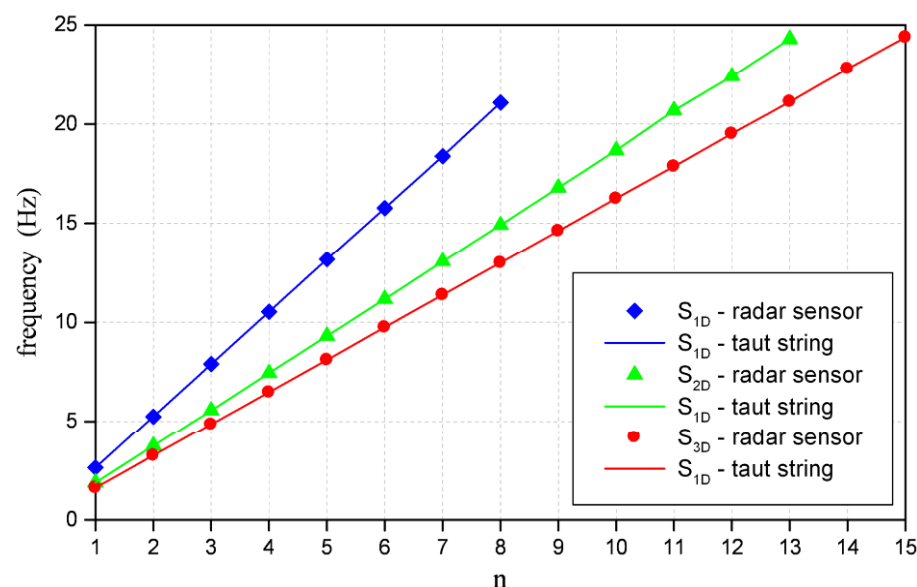
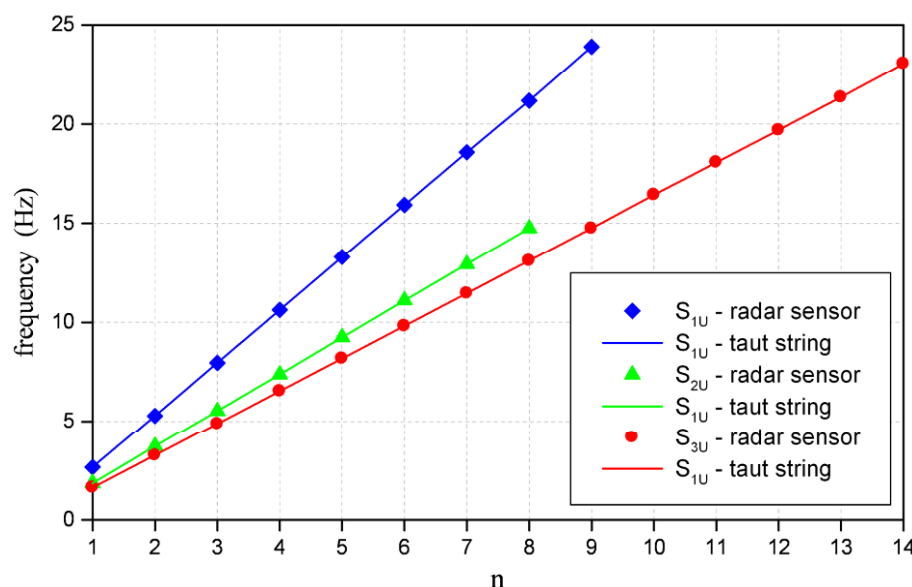
Dynamic measurements on stay cables

Cable-stayed bridge over the Oglio river

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(5)

Experimental and taut-string based natural frequencies of the stay cables

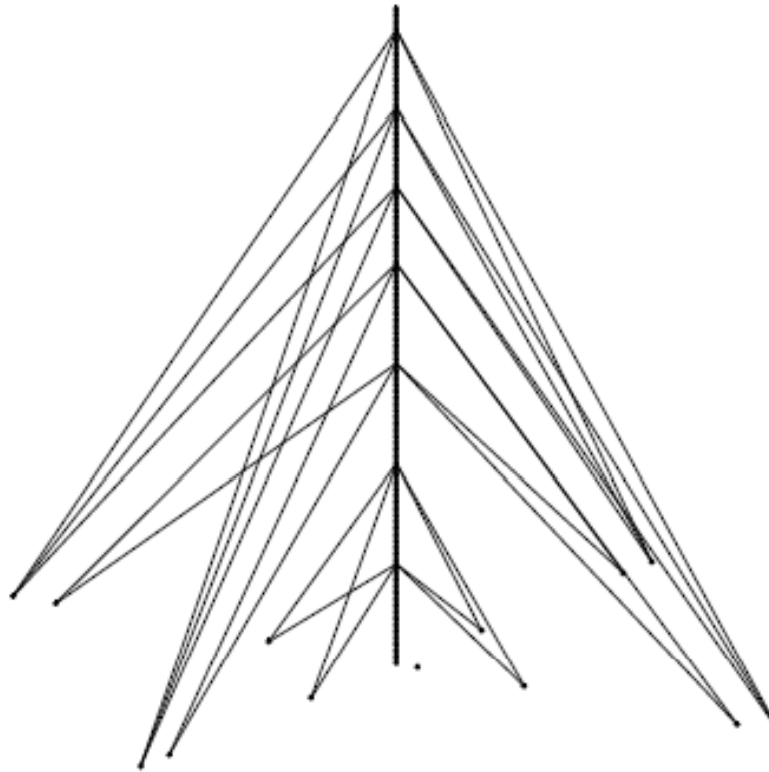


Stay cable	$T(f_1)$ (kN)	$T(f_2)$ (kN)	$T(f_3)$ (kN)	$T(f_4)$ (kN)	$T(f_5)$ (kN)	$T(f_6)$ (kN)	$T(f_7)$ (kN)	Average (kN)
S_{1U}	2704	2692	2712	2716	2722	2716	2715	2711
S_{1D}	2655	2654	2671	2670	2674	2662	2657	2663
S_{2U}	2923	2943	2924	2924	2939	2945	2936	2933
S_{2D}	3003	2982	2949	2982	2986	2982	2995	2983
S_{3U}	4054	4052	4073	4098	4113	4113	4120	4089
S_{3D}	3990	3997	4031	4037	4039	4062	4063	4031



Muge guyed mast (1)

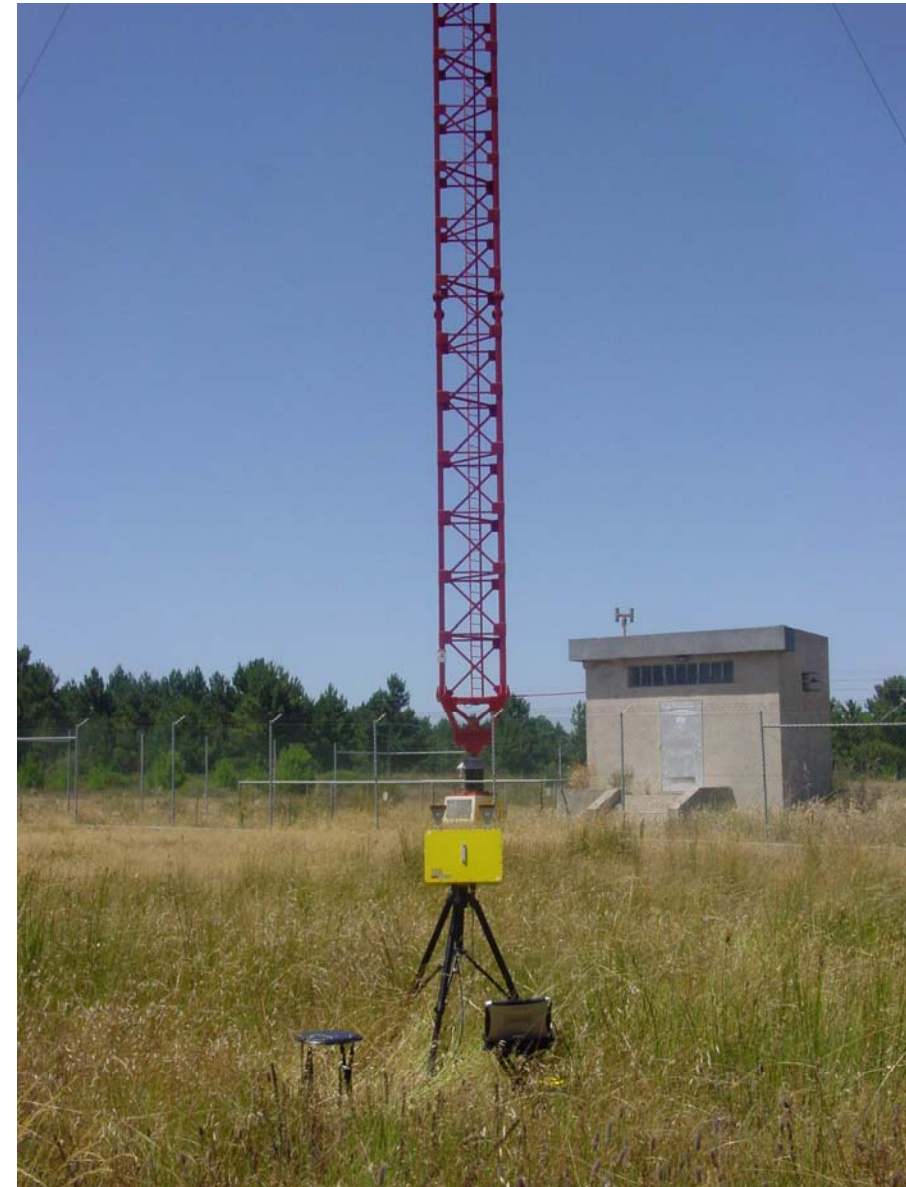
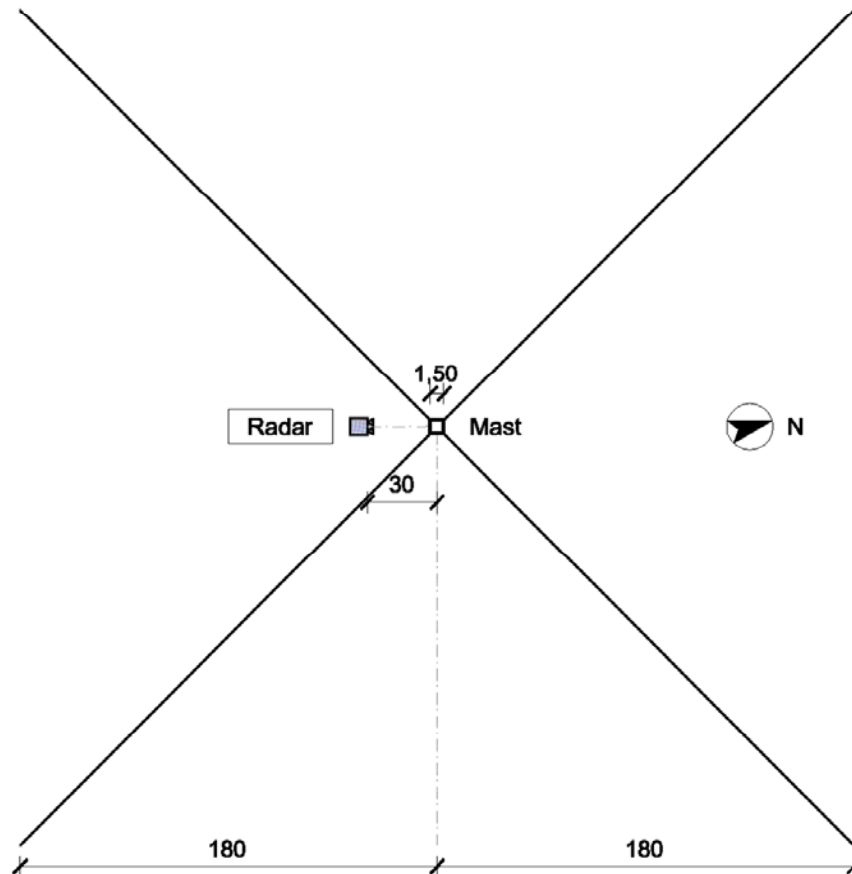
46





Muge guyed mast (2)

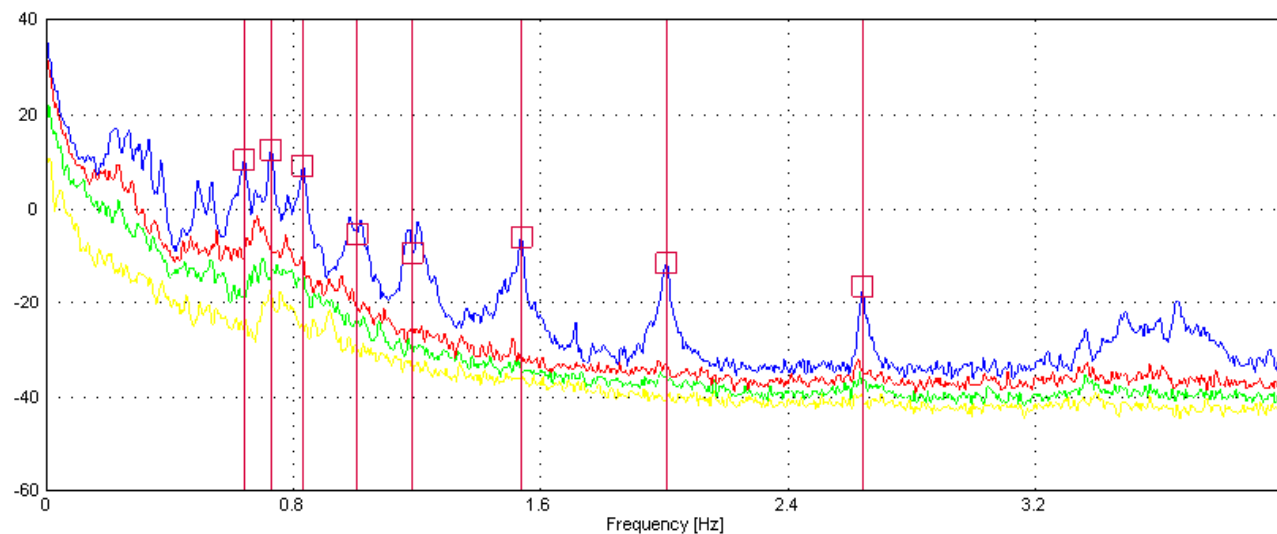
47



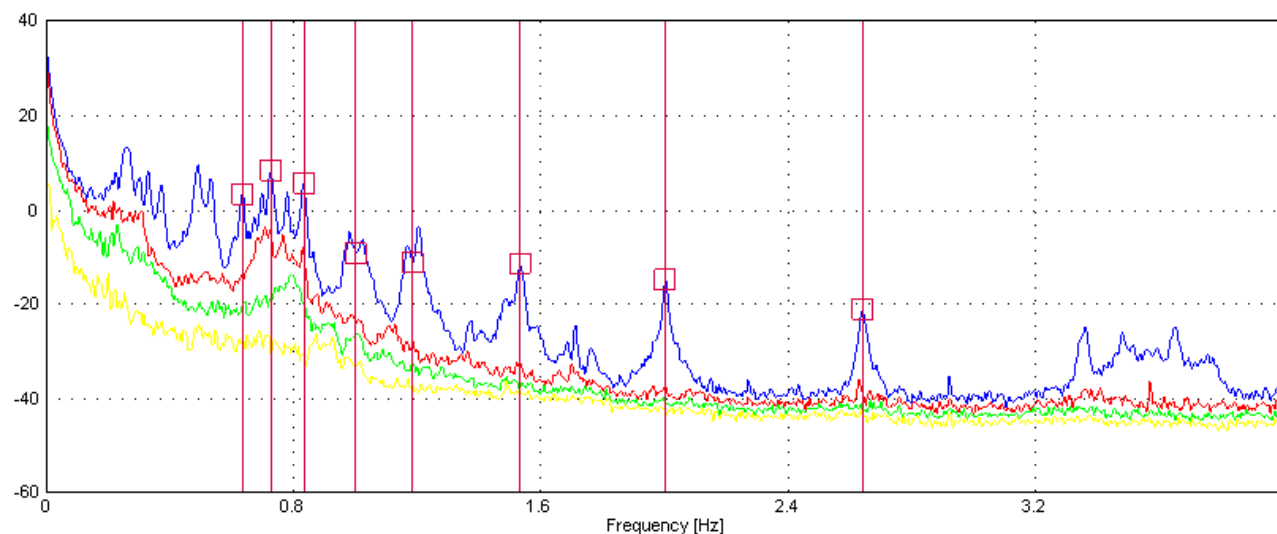


Muge guyed mast (3)

48



$T = 1800$ s

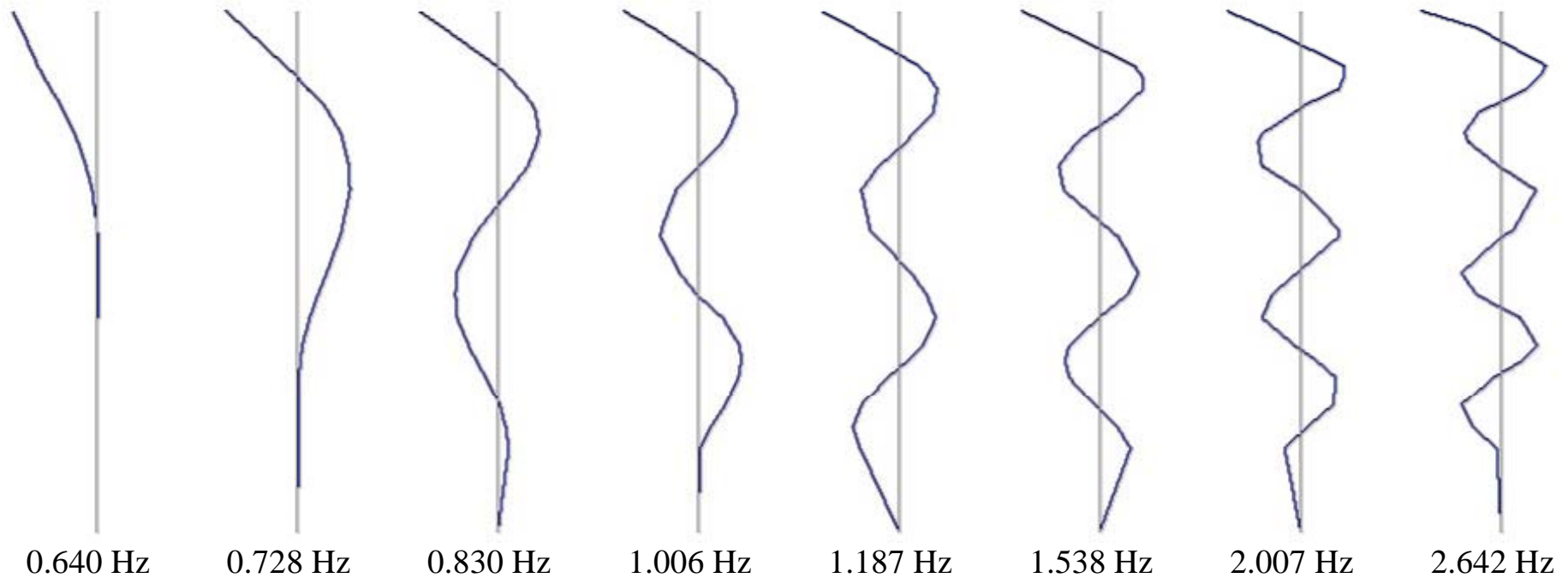


$T = 3600$ s



Muge guyed mast (4)

49





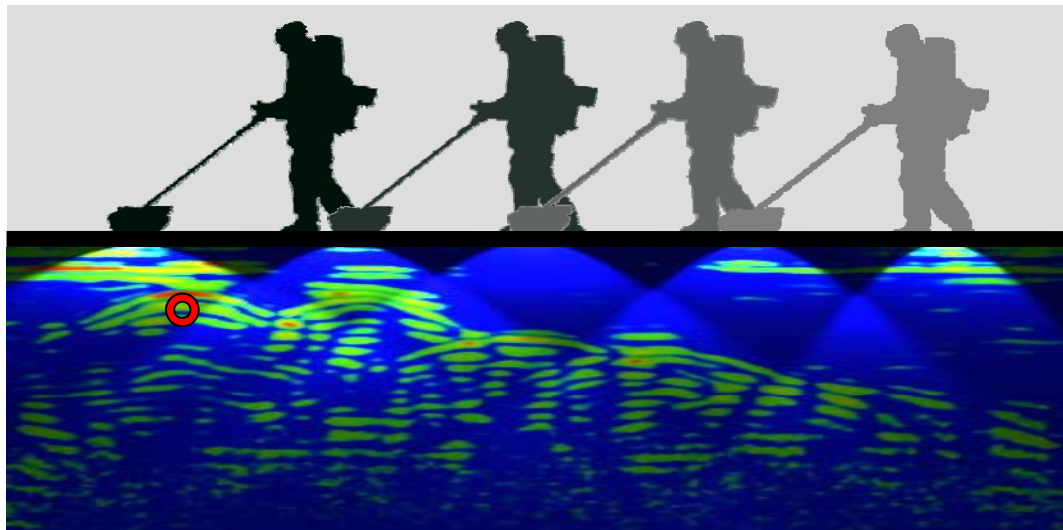
CONCLUSIONS

50

... to be continued

GeoRadar Division

Innovative radar technology for engineering, environment and security





IDS Ingegneria dei Sistemi S.p.A.

- founded in 1980
- about 380 employees
- core expertise in Applied Electromagnetics, Radar Systems, System Engineering

The offices:

- Headquarter in Pisa - Montacchiello
- GeoRadar office in Pisa - Montacchiello
- Branch office in Rome
- Subsidiary in Brisbane (IDS-Australasia)
- Subsidiary in Southampton (IDS-UK)
- Subsidiary in Sao Paulo (IDS-Brazil)
- Subsidiary in Montreal (IDS-North America)



Organization



IDS UK | IDS Brazil | IDS North America | IDS Australasia

Local offices across the world provide expertise, services and 24/7 support for industries with time, quality and cost critical requirements. Highly trained agents and distributors worldwide extend the IDS network over 40 countries.

Customers



Naval Division



Aeronautical Division



Aeronavigation Division



Georadar Division

IDS Laboratories

Computer Science & Information Technology Lab.

**EM Design
Framework
Lab.**

**Avionics
Lab.**

**RADAR
Systems Lab.**

**Air Navigation
Systems Lab.**

**Signatures
Technologies
Lab.**

Measurements & Trials Lab.

Naval Division

Mission

*To provide Navies and Industries with
an **innovative design capability**
aimed at optimizing ship EM
performances and signature control.*

That means:

**Maximizing mission
success probability**



Aeronautical Division

Mission

To support governmental authorities and aeronautic industry with product and services aimed at improving design process' efficiency, especially in conceiveng stealth aircrafts .

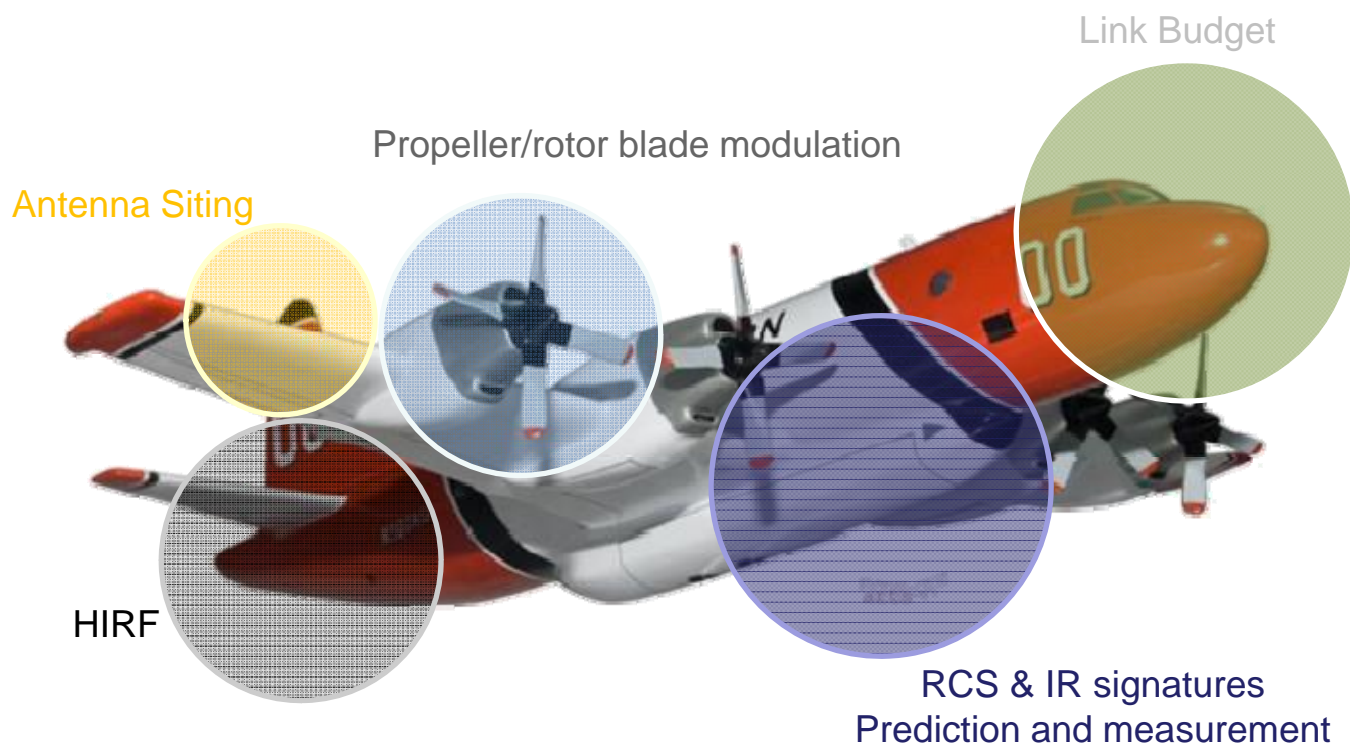
To provide also flight control systems and avionics design services for fixed/rotary wing platforms and UAVs.



Aeronautical Division

Analysis and EM design

EM design means to deal with the following matters:



*A **different approach** in the design phase, integrating EM simulation and innovative prediction tools ensure the attainment of the **desired performances**.*

Aeronautical Division

Main programs



Air Navigation Division

Mission, product

Delivering systems and performing services for the air transport market segment and specifically targeted to Air Navigation Service Providers and Aviation Authorities (Civil, Military)

Systems are mainly **built and maintained in house** with minor off-the-shelf components from third party providers

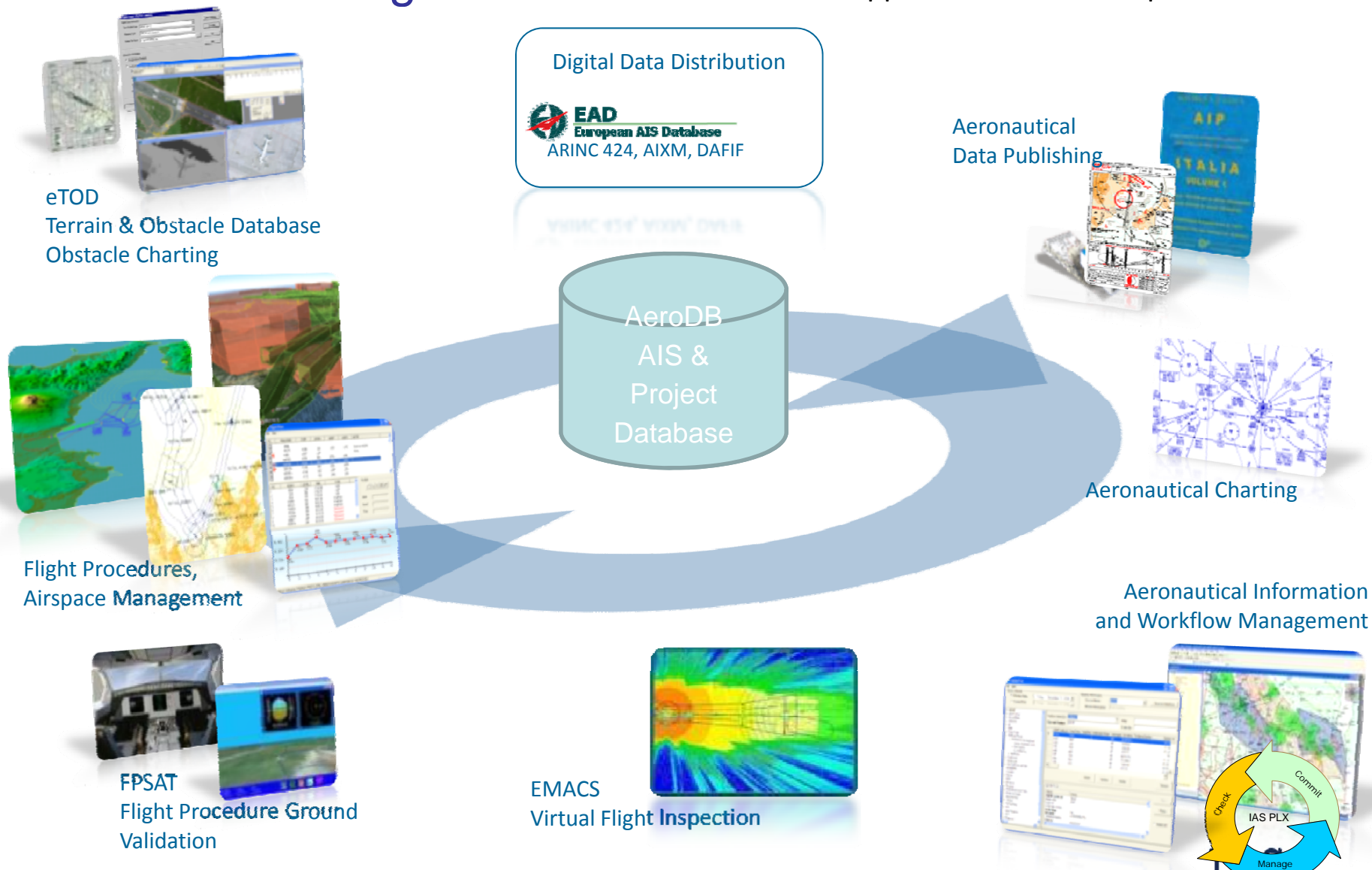
Operating worldwide through and with the four IDS subsidiaries and through a number of dealers/partners

IDS Aeronavigation Systems are now installed in about **30 countries** for a total of **40 accounts**

“..IDS has the largest installed base of any supplier in the field, including four of the five most influential operators in air navigation. Customers, including all the organisations represented here and more, range from large standard setting ANSPs on four continents to specialist service providers...”

Airnavigation Division

Flexible approach for an “enterprise” solution

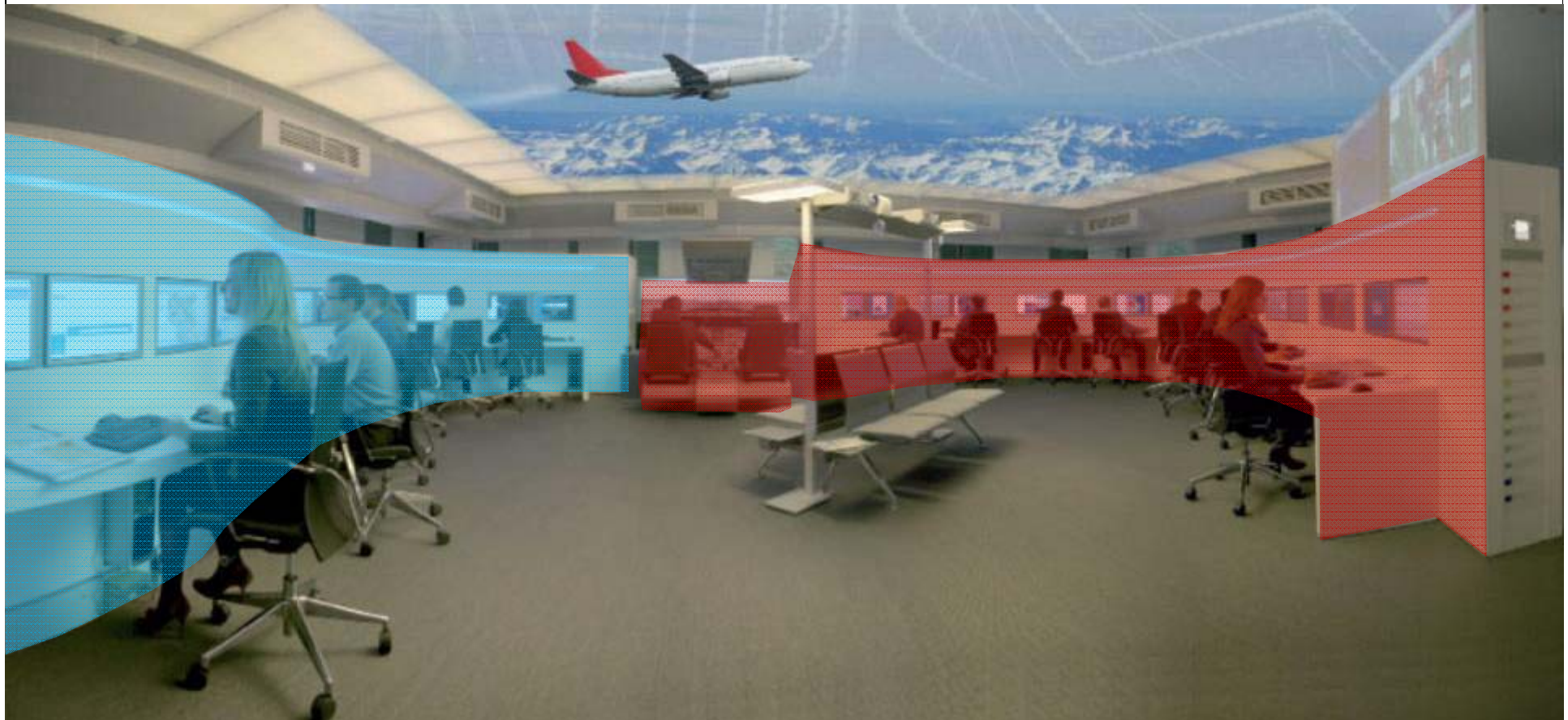


Airnavigation Division

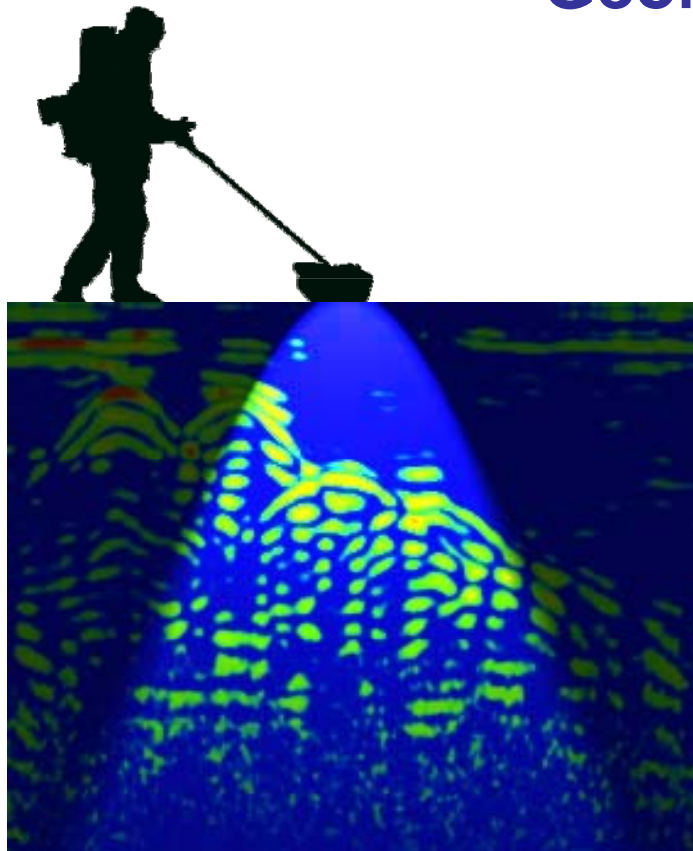
Operational testing room

AIS Production Systems
(Information Management and Data Distribution)

Engineering Systems
(Design and Validation)



Georadar Division



*To transfer IDS competencies in the radar field and system engineering to “low power” **radar systems for engineering, environmental and security applications***

Pursuing the product excellence through the creation of application-specific, innovative products, able to bring valuable benefits to the user

IDS GeoRadar facts

- ***Leader in Multi-frequency, Multi-channel Ground Penetrating Radar Systems***

- IDS began to study GPR technology since 1991 in connection with the need of Telecom Italia of improving the capabilities of mapping subsoil Utilities



- IDS was the first to introduce in GPR market the **multi-frequency, multi-channel array** systems, dramatically improving utilities detection performance
- Since 1999 IDS began the worldwide commercialization of GPR products
- IDS is now one of the key players in GPR market, with a continuously growing market share

- ***Innovative radar interferometry technology for the Earth Environment***

- In 2007 IDS introduces IBIS on the market, the first Ground-Based interferometric SAR

Current worldwide dealers of commercial radar products



Product Lines

Ground Penetrating Radar (GPR):

*Innovative, application-specific products
for geo-applications*



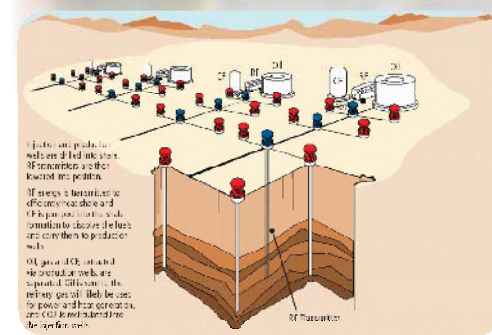
Interferometric Radar:

*A new approach, through radar
interferometric technology, for monitoring
ground and structure displacements*



Solutions:

*Provide high-level, specialized solutions
and services, based on the Division
technology and know-how*



Product Overview by Application



Utilities



Transportations



Civil and Structures



Geology and Environment



**Archaeology and
Cultural Heritage**



Forensic and Security



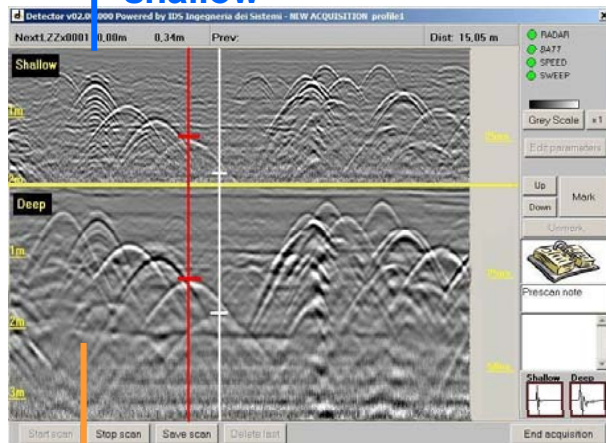
Utilities Detection and Mapping

Detector Duo:

real-time
detection of
pipes



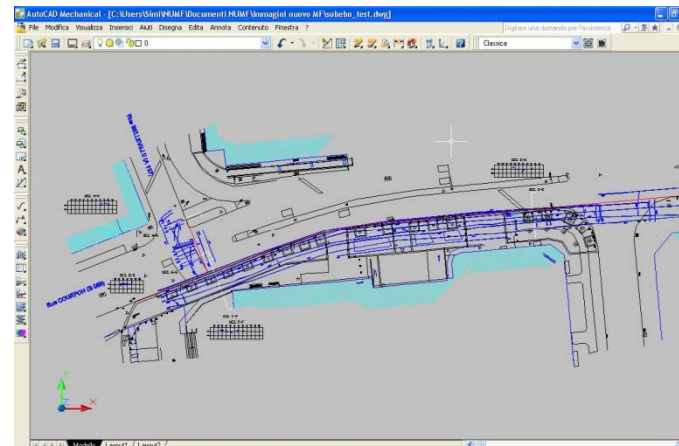
shallow



deep

RIS MF Hi-Mod:

Utilities
mapping on all
zones





Utilities Detection and Mapping

Stream: massive arrays for the fast mapping of utilities

Stream EM:

**Vehicle towed
array for
extensive road
utility mapping**

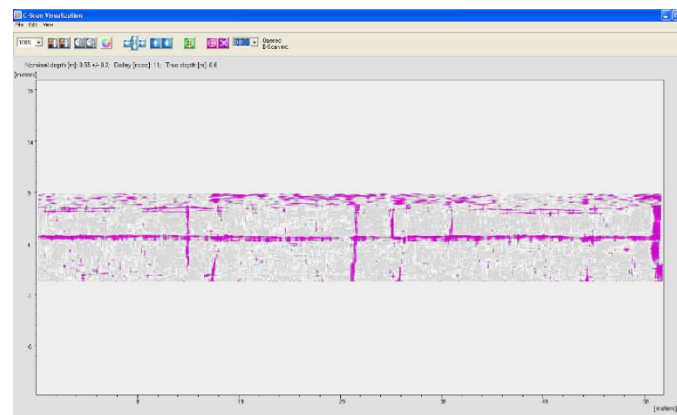


**Underground road
mapping obtained by
simple vehicle
passages, up to 15
km/h**



Stream MT:

**Fast utility
mapping for
Mini-Trenching
applications**



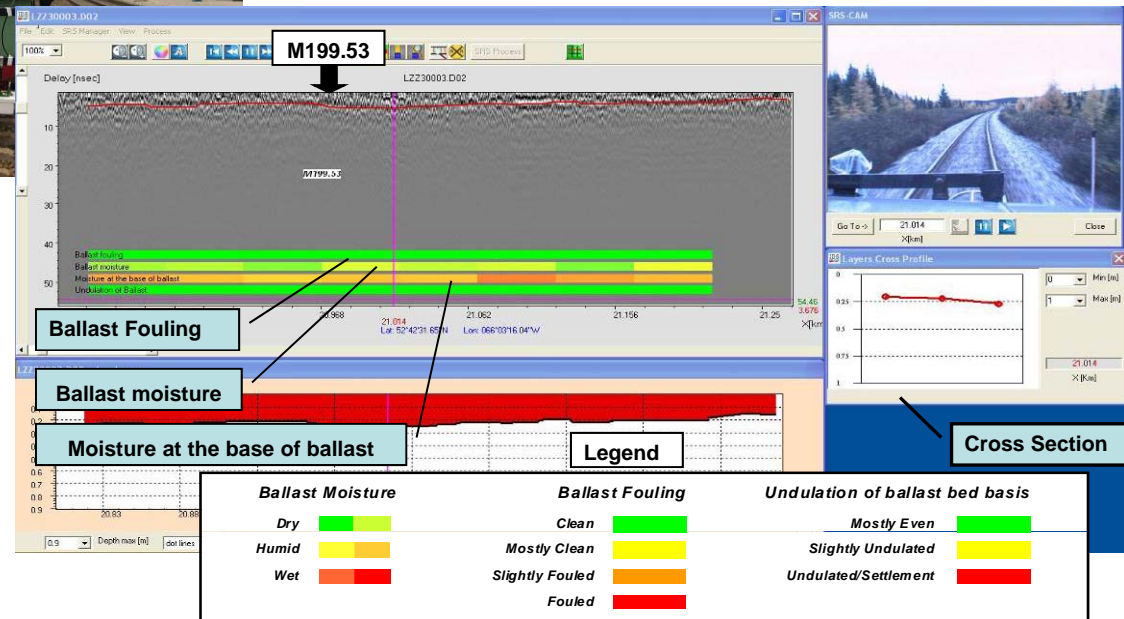
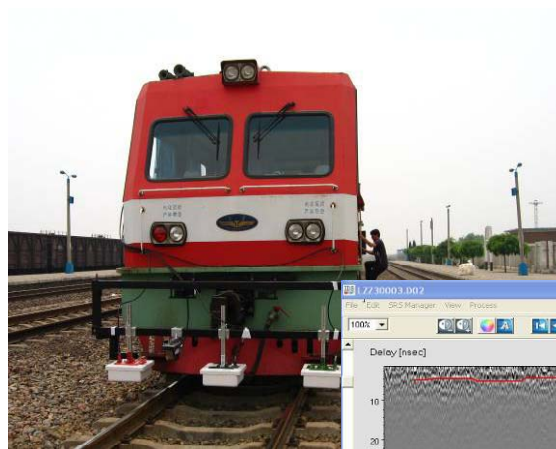
**Mapping by
single,
longitudinal
passage
along the
trench line**



Railway Engineering

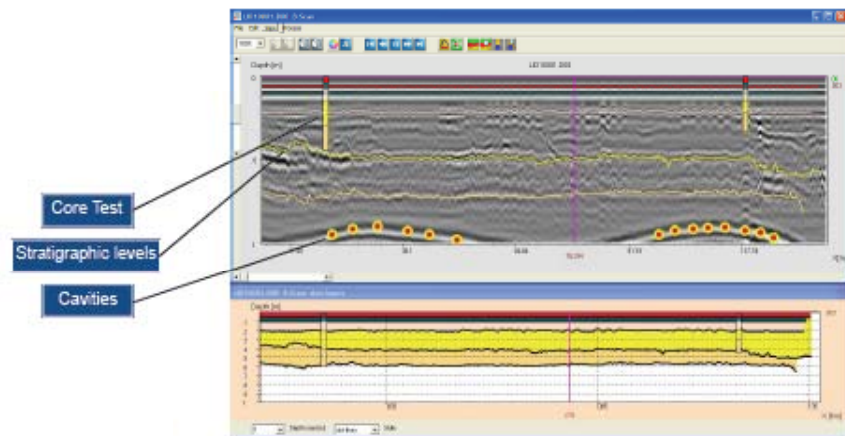
**SafeRailSystem
(SRS):**

**Continuous
mapping of
railway ballast
status**





Road Engineering



Imaging of the
different levels of the
road, with cores and
cavities



RIS Hi-Pave:

The fastest and
most flexible
solution for road
assessment
surveys



Civil and Structure Engineering

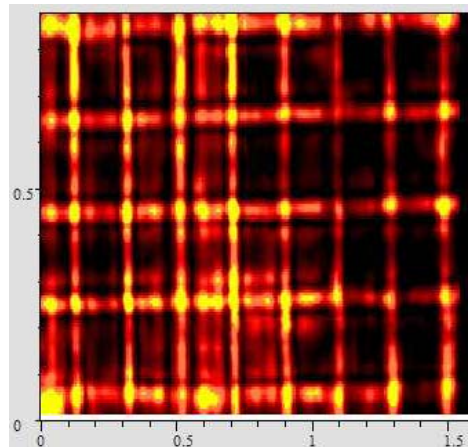
RIS Aladdin:

Analysis of the
internal status of
structures



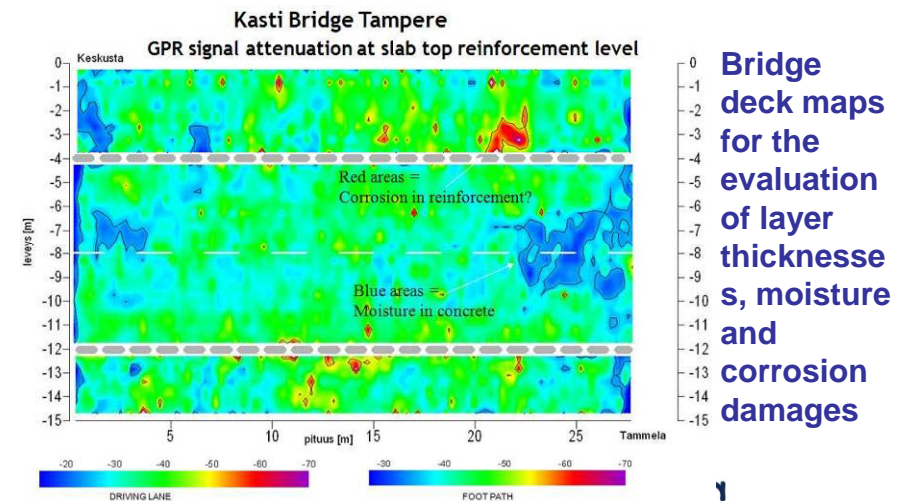
Depth: 0.10m

Imaging of concrete
rebar and internal
structures



RIS Hi-BrigHT:

Array for bridge
deck survey





Civil and Structure Engineering:

Interferometric Radar: IDS is currently the only one world manufacturer of radar technology for structural displacement applications

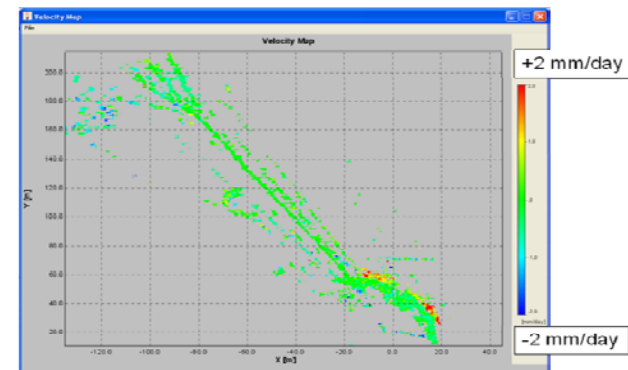
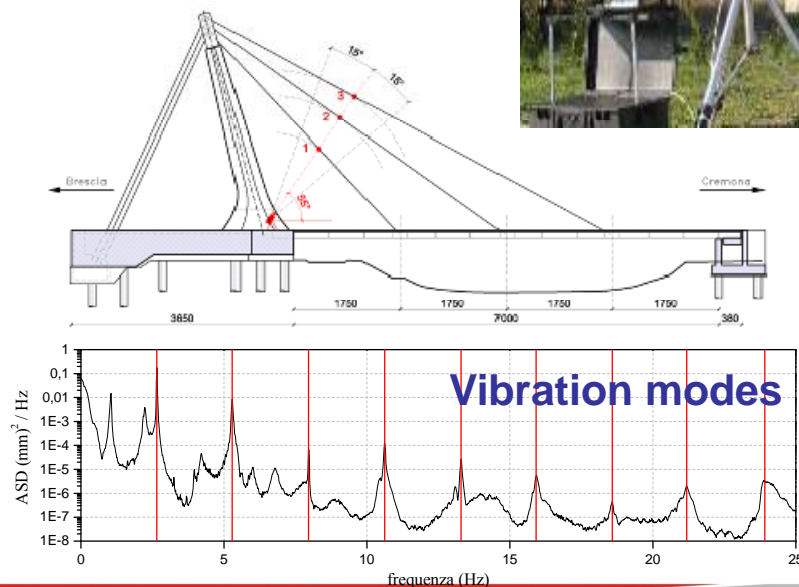
IBIS-S:

Dynamic and static monitoring of bridges and linear structures



IBIS-L:

Static monitoring of large structures



Dam displacements



Geology and Environment



Stream-X:

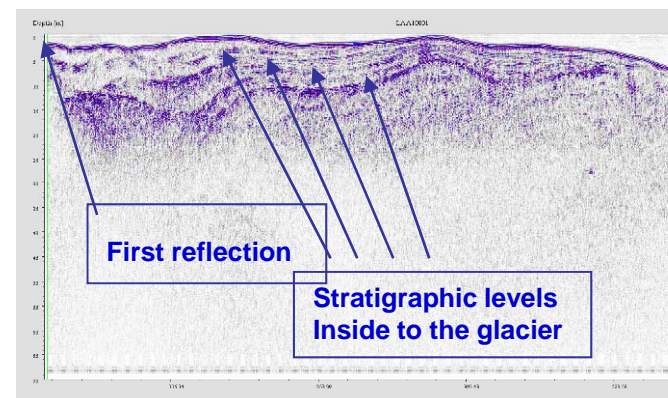
**Fast environment
survey and clearance
of large areas**



RIS ONE-PLUS:

**Flexible and
complete
solutions for
geology**

Tomographic maps showing
archeological structures in
large areas





Geology and Environment

IBIS-M, a dedicated configuration to enter into the Mining Market

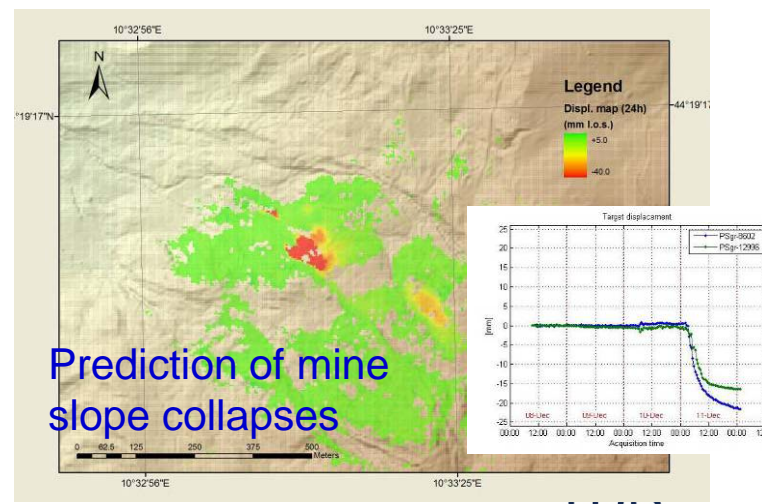
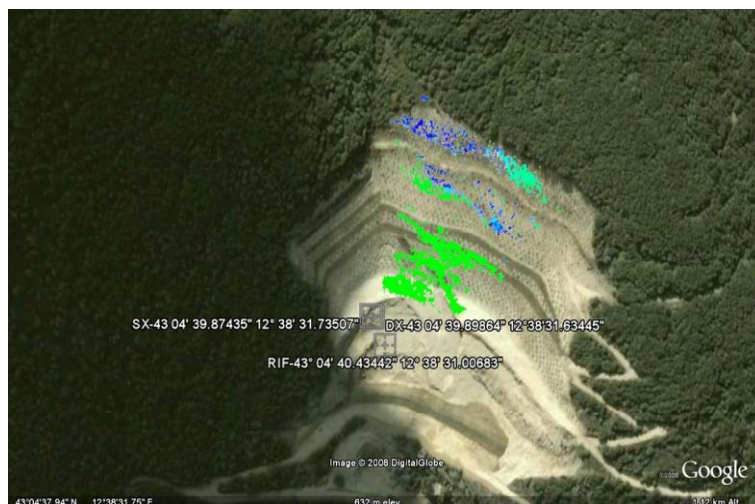
IBIS-L:
Monitoring of
landslides



IBIS-M:
Early
Warning for
mine slope
instabilities



Slope
displacement
map
overimposed
on a Google
picture





Forensic and Public Security

Sila system:

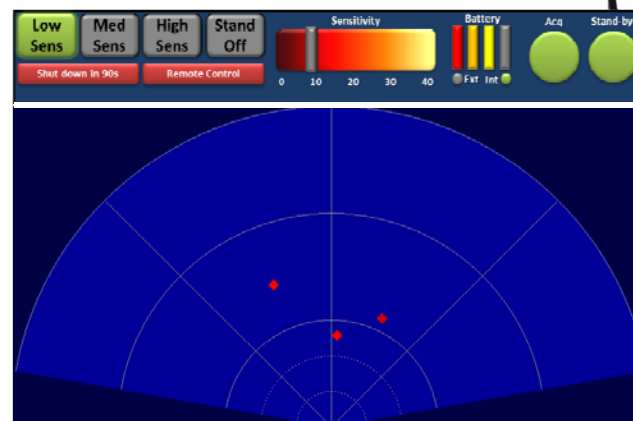
Location of
cavities,
tunnels, buried
bodies



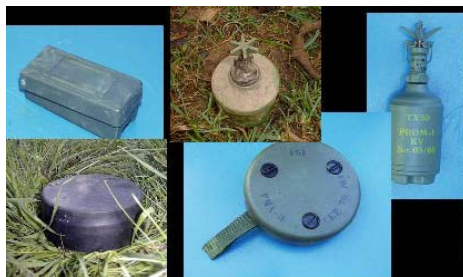
TWR

(Through
Wall Radar):

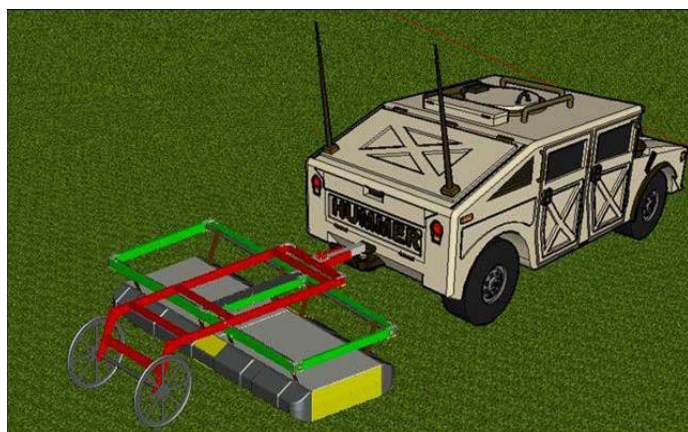
(under
development)



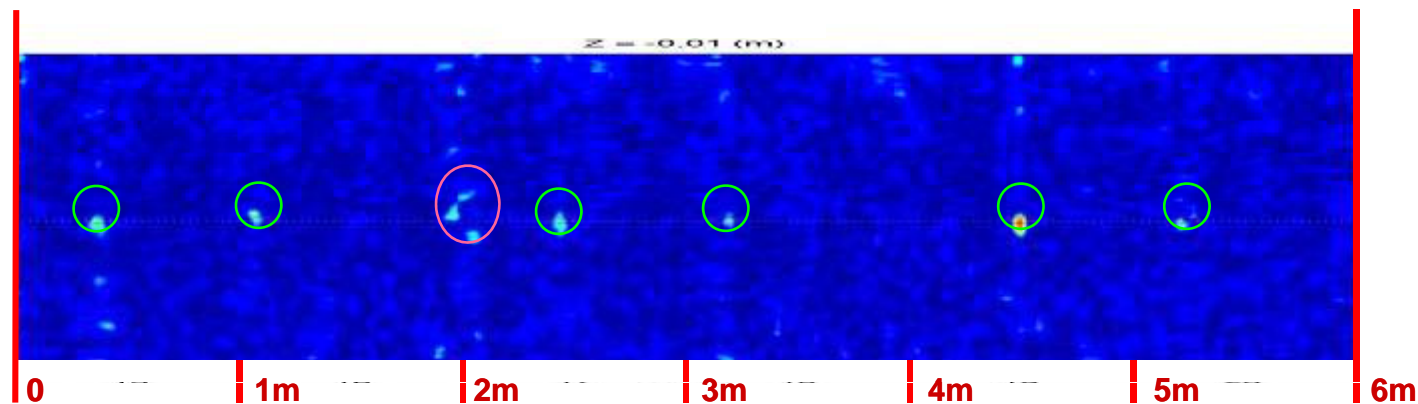
Location of
people
behind
walls



IED/UXO/mine detection



Configuration proposed for IED (Improvised Explosive Device), UXO (Unexploded Ordnance) and mine detection (under development)



Focalised GPR data at shallow depth



UTILITIES DETECTION AND MAPPING

SPECIALIZED SOLUTIONS FOR EACH APPLICATION



UTILITY DETECTION AND
MAPPING

Real Time
Detection

DETECTOR
DUO

Add on for
PIT TEST



Detection and
Mapping

RIS MF Hi-Mod



Mapping for
Trencher

EXPLORER



New Product for
extensive utilities
mapping

STREAM



Detector Duo

A dual frequency antenna radar for detecting metallic and non-metallic pipes.

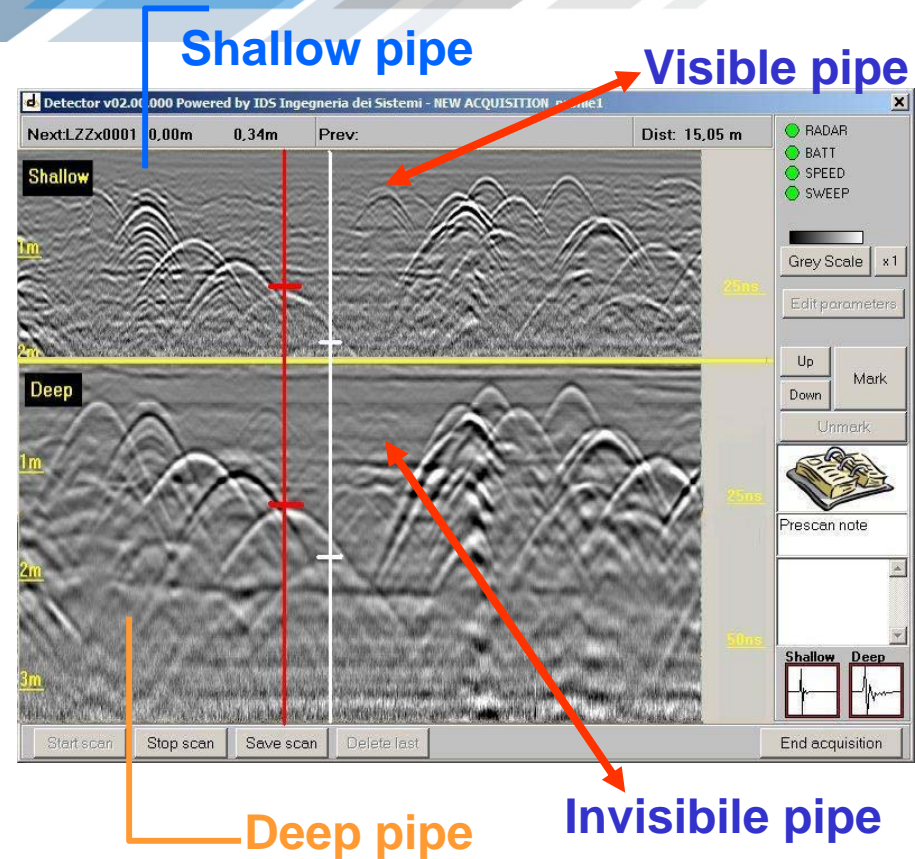
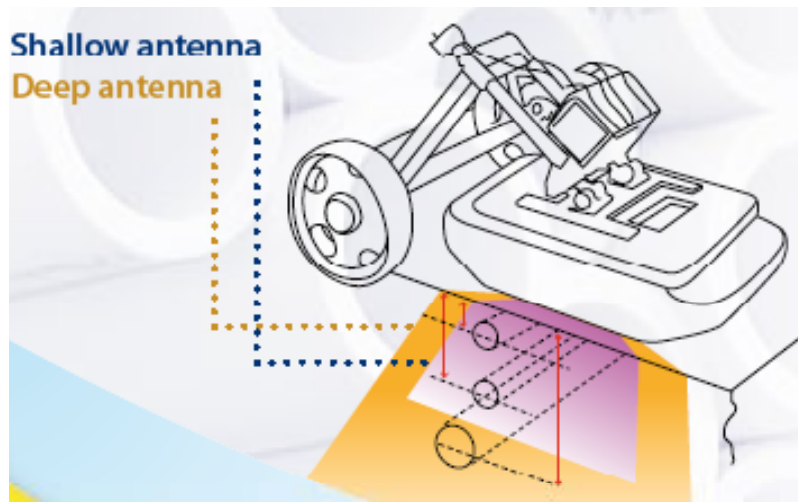


Collapsible trolley, easy to transport and assembly.



Innovative Features

- Deep and Shallow antennas in one compact box (250 – 700 MHz)
- Antenna footprint: 60x37 cm
- Real time display of deep and shallow channels in the same screen



- Highest performance with simultaneous display of deep and shallow pipes
- Highest productivity with a single scan
- Only 30 minutes training required






RIS MF Hi-Mod

The only end-to-end “industrial” solution for **accurate utility mapping**

- 4 dual frequency antennas (200 MHz and 600 MHz)
- 2 m wide Antenna Array for 3D mapping
- Modular design suited to urban environment and narrow passages
- High productivity post-processing SW
- CAD/GIS automatic rendering
- Data Base for rational storage of large quantities of data

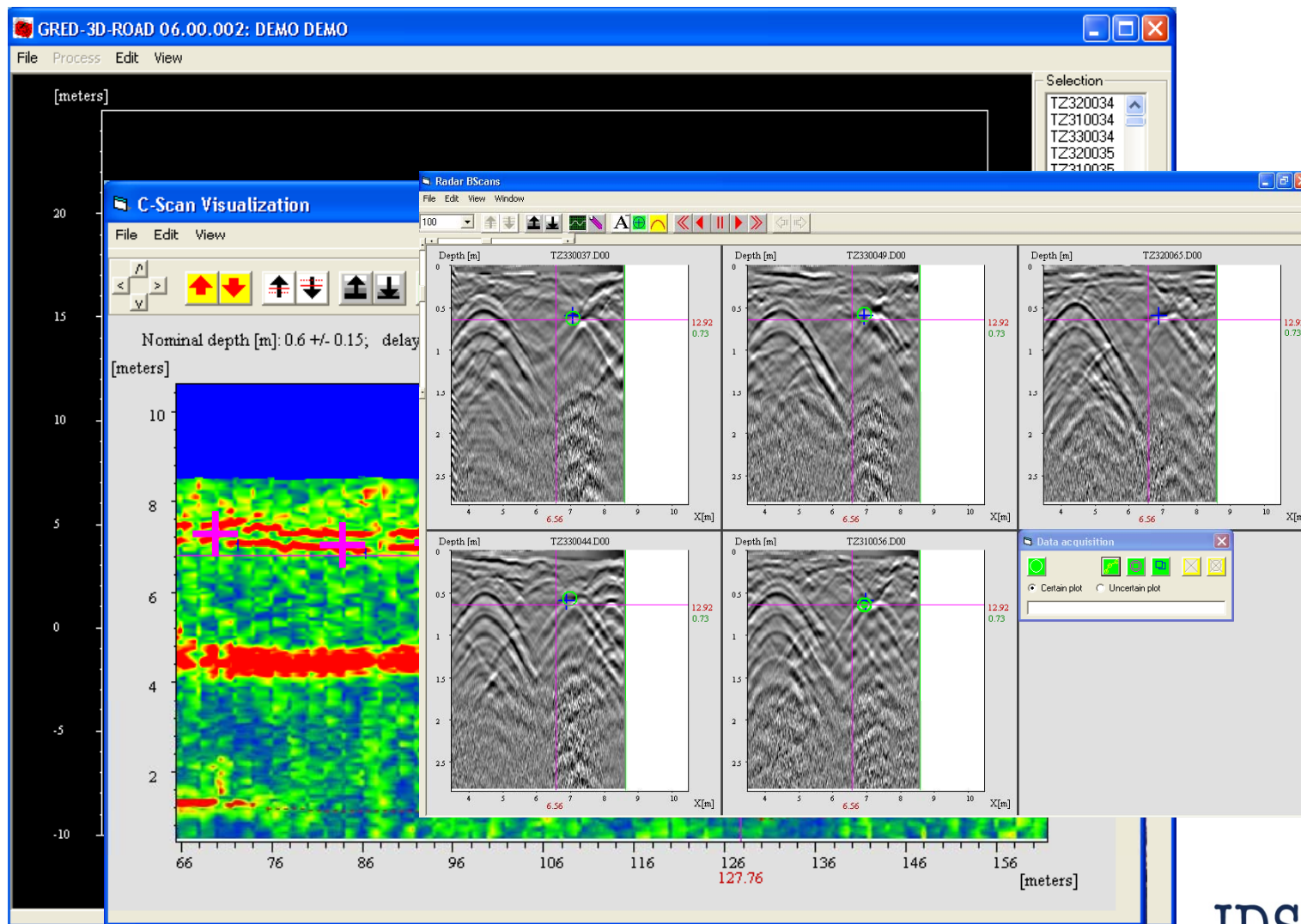


MODULAR COMPOSITION and UPGRADABILITY

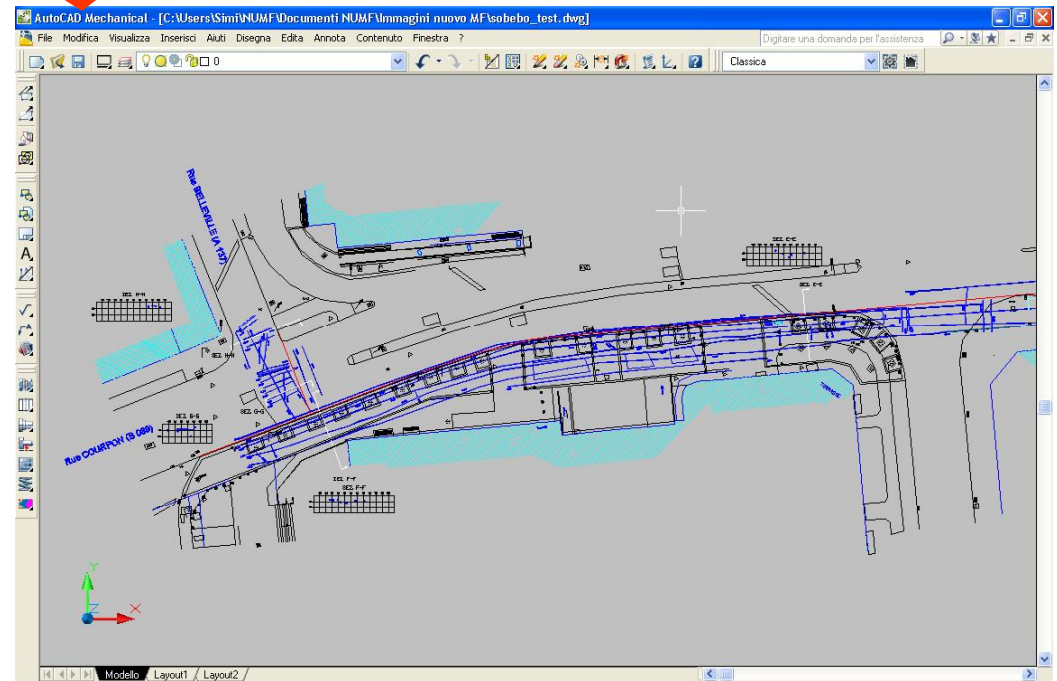
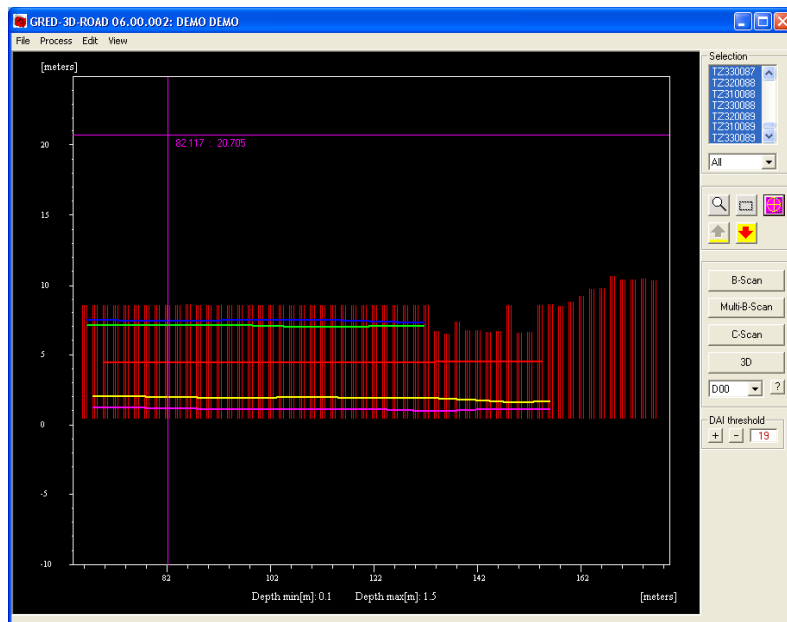
CONFIGURATION MODEL	ANTENNAS	PICTURE	UPGRADABILITY
BASIC RIS MF Hi-Mod #1	1		
INTERMEDIATE RIS MF Hi-Mod #2 or RIS MF Hi-Mod #3	2 or 3	 	
FULL RIS MF Hi-Mod #4	4		

GREED 3D UTILITIES: POST PROCESSING SOFTWARE

Automatic target detection



GRED 3D UTILITIES: POST PROCESSING SOFTWARE



Export data to CAD

STREAM family

IDS innovative solutions for “*massive array*” radar



Stream-EM



Stream-X



Stream-MT

STREAM philosophy and user BENEFITS:

“Making possible what was only a dream”

- Stream is a new family of products based on arrays of large numbers of antennas (20-50; “massive arrays”) with unique features, such as:
 - High acquisition speed
 - Multi-frequency or multi-polarization
 - Dense sampling
 - Highly reconfigurable
 - Modular architectures
- User benefits:
 - High field productivity (avoiding many scans, transversal scans etc.)
 - No need to block traffic in road surveys
 - High quality of data
 - Adaptable to other applications with suitable kits (archaeology, environment)
- **Sets new standards in utility mapping accuracy and productivity**

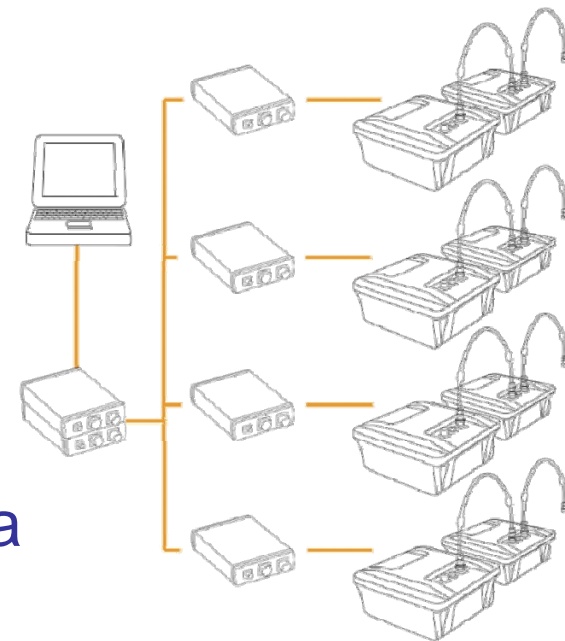
The core of *STREAM* technology

- The new DAD Fast Wave control unit:
 - High acquisition speed
 - High number of antenna channels (“massive arrays”)
 - “Networking” of up to 4 DAD’s for driving multiple arrays
- Antenna technology:
 - Antenna arrays specifically designed (not just the collocation of standard antennas)
 - Compact antennas enabling the construction of very dense arrays
 - Ability to put together antenna at different frequencies or polarization
 - Large bandwidth and efficiency giving high data quality

FAST WAVE : the new DAD control unit

New DAD FastWave unique features:

- 6 times faster than the previous DAD K2
- The fastest control unit on the market:
 - 4760 scan/sec @128 samples
 - 2 channels acquired simultaneously
- Chain connection:
 - Antenna elements connected in “cascade”
- Multiple DAD can be synchronized in a “network of DAD’s”



The **STREAM** family for **utilities mapping**

The STREAM family includes currently the following solutions:

- **STREAM-EM**: the solution for extensive **utility mapping**
- **STREAM-MT**: the solution supporting **micro and minitrenching**

STREAM-EM

IDS INNOVATIVE SOLUTION FOR EXTENSIVE UTILITY MAPPING



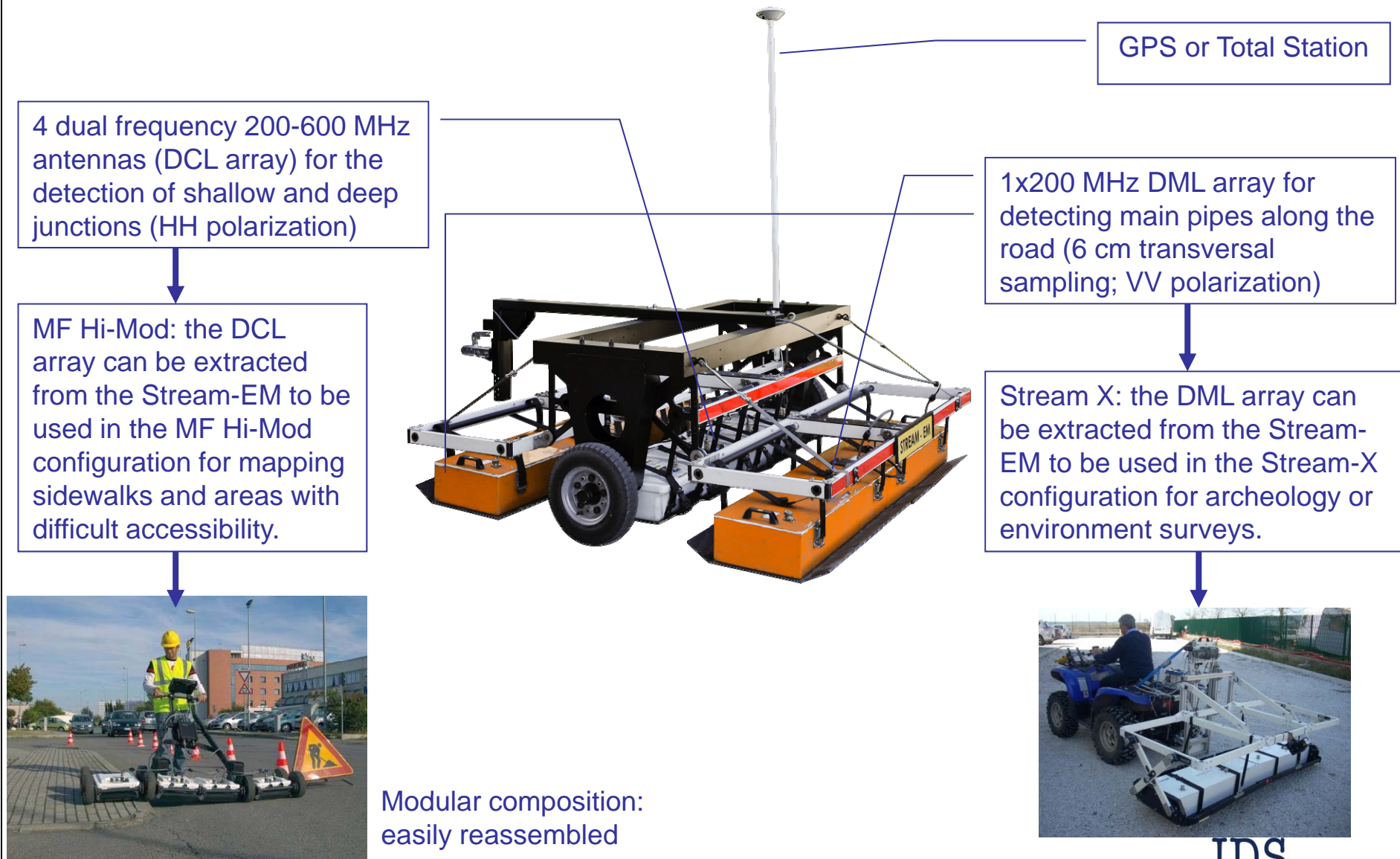
STREAM-EM: main benefits

- GPR solution towed by a vehicle (speed > 15 Km/h).
- Data collection in longitudinal direction (without the need of moving the array in the transversal directions) but detection of utilities and connections.
- High productivity
- High modular structure
- High detection capability
- Avoid blocking the road traffic
- Exploit the same advanced processing feature of RIS MF Hi-Mod
- Possibility of different kind of towing frames



Stream EM System: complete configuration with 3 array of antennas

STREAM-EM: modularity and array architectures



STREAM-EM: Trolley easily collapsible

- Stream-EM trolley permit to adjust the distance of each array module from the soil
- DML 1 and DML 2 antennas can be collapsed up to 90° to reduce the overall dimension of the trolley
- Stream-EM trolley can be connected to any car or van with drag-hook
- The collapsed trolley can be easily stored in the van for transportation

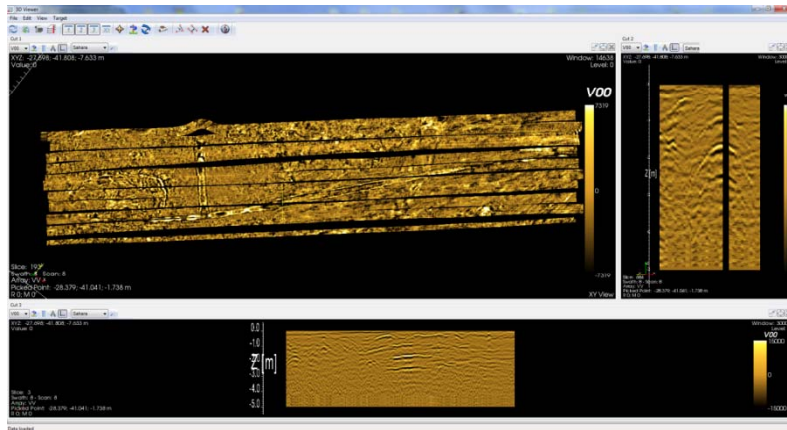


STREAM-EM: Work Flow

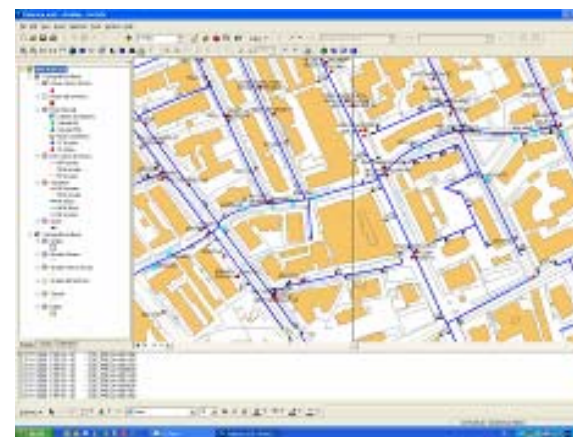
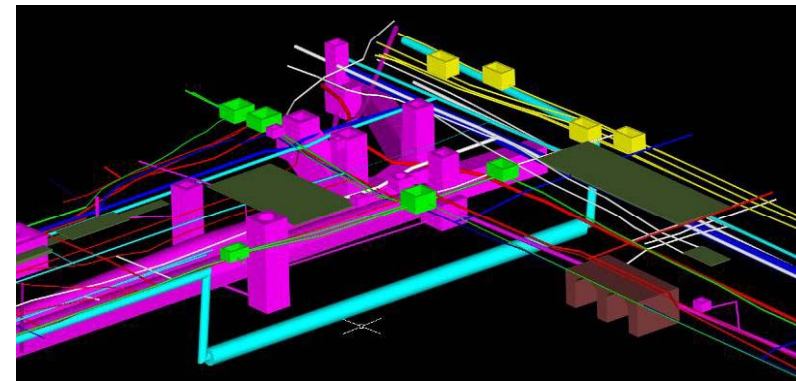
1. Data acquisition



2. Data processing (office)



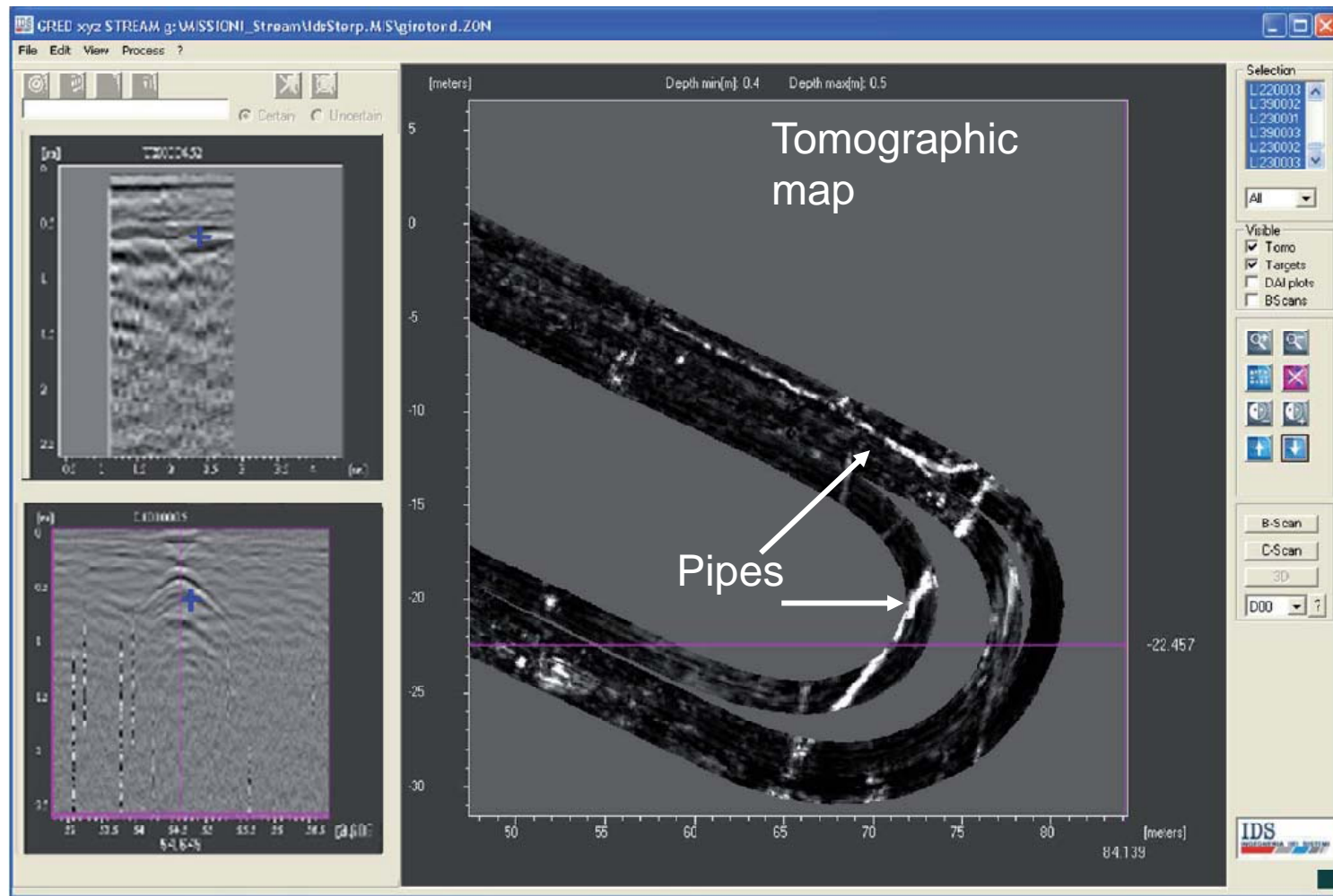
3. 3D view of the utility network in CAD/GIS environment



GED 3D Utilities STREAM: the post processing software

Transversal
map

Longitudinal
map



STREAM-MT:

dedicated solution for Mini/Micro Trenching technology

- Micro and Mini trenching is a new installation technology, alternative to the traditional excavation and No-Dig solutions, offering lower costs and lower environmental impact. This new technology is mainly suitable for the following new installations:

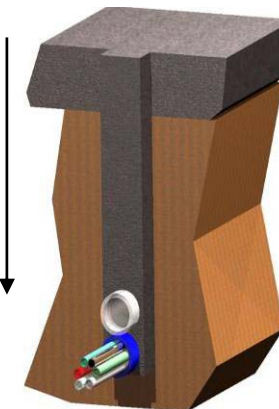
- TLC cables
- Public illuminations
- Video surveillance
- Traffic lights cables.



5 up to 30 cm



30-40 cm

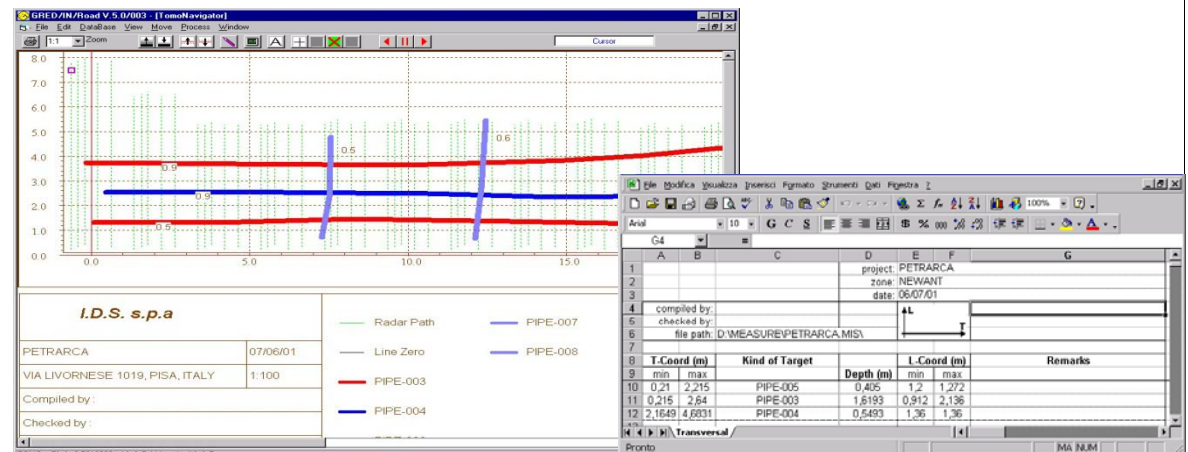


STREAM-MT: main benefits

- Data collection only with longitudinal scans: no need of transversal scans
- With only one scan you can detect all the main pipe and connections
- High detection capability: very shallow pipes and cables thanks to the unmatched data density and the double polarization.
- High resolution capability: 1 GHz array of antenna
- Compact and easy to move in narrow area
- Processing software allowing an efficient representation of the end results

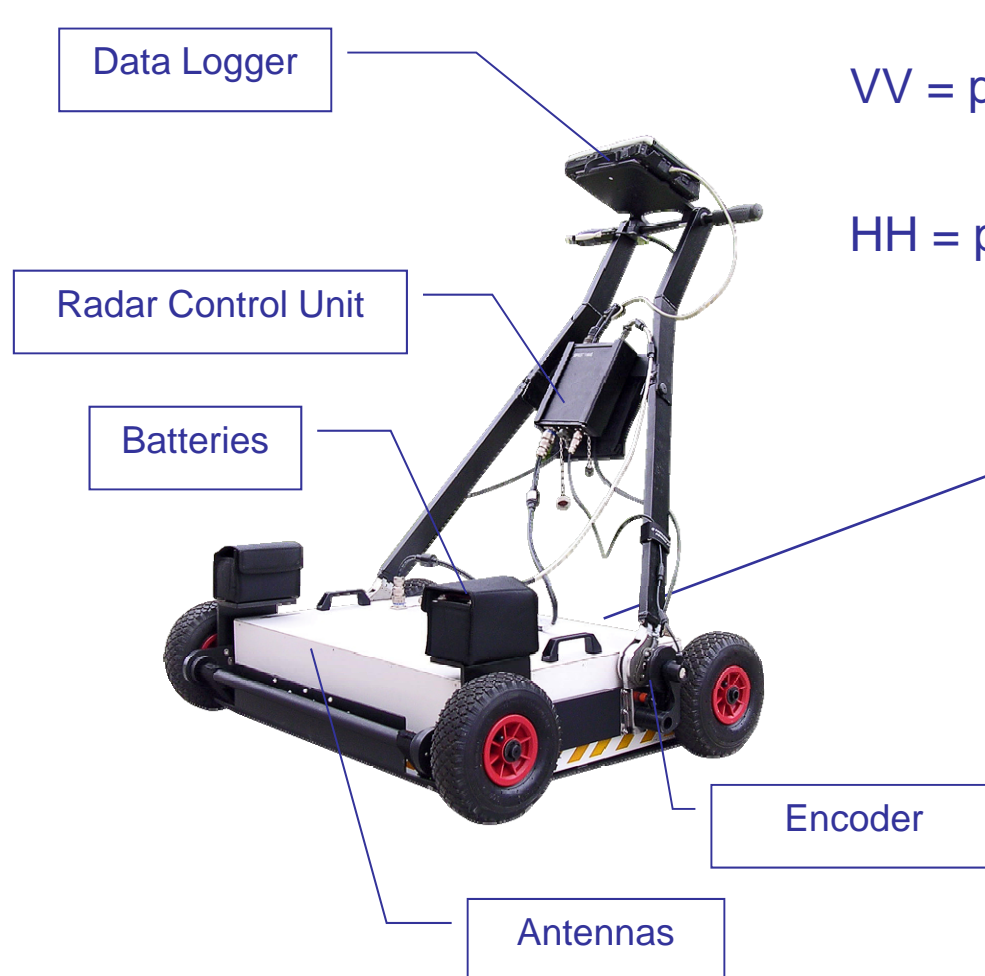


Stream MT: acquisition unit



GRED ROAD: end results including a schematic 2D map and an excel file with the position of the detected targets

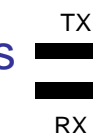
STREAM-MT: the system and array architectures



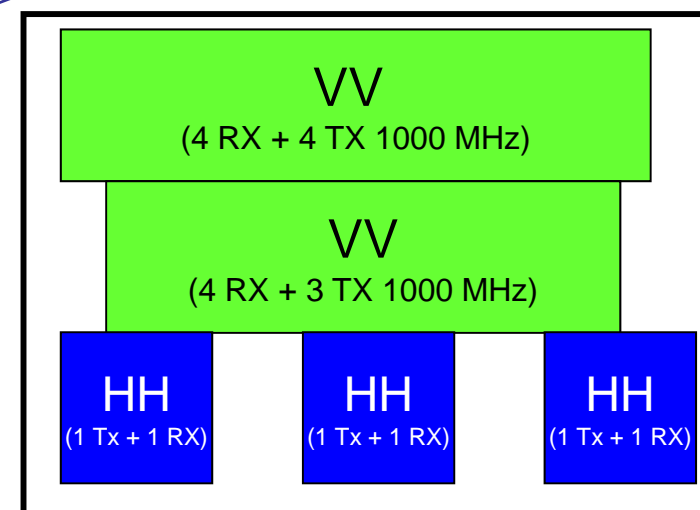
VV = polarization of the antenna modules



HH = polarization of the antenna modules



Antenna architecture

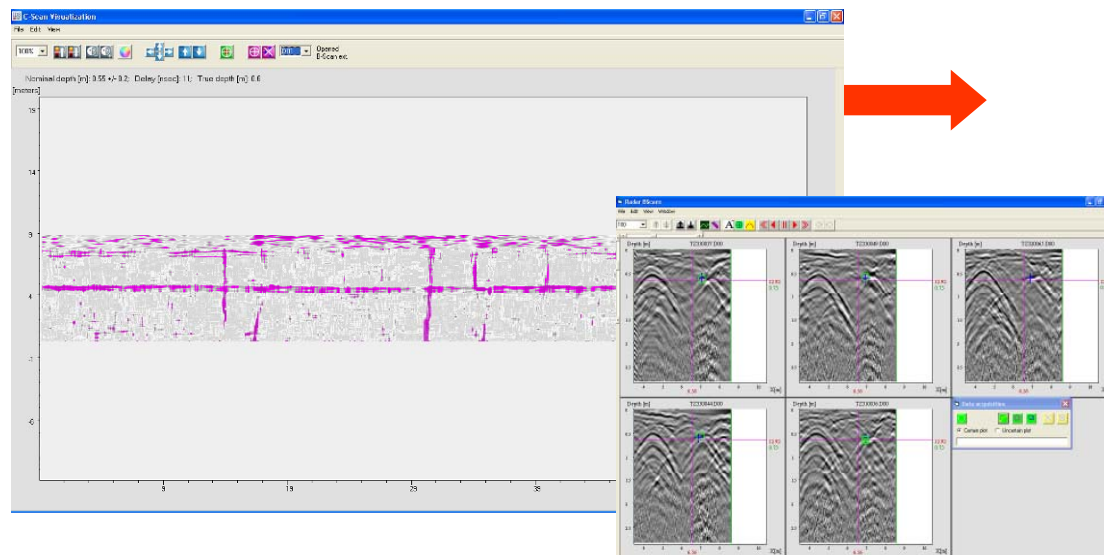


STREAM-MT: Work Flow

1. Data acquisition

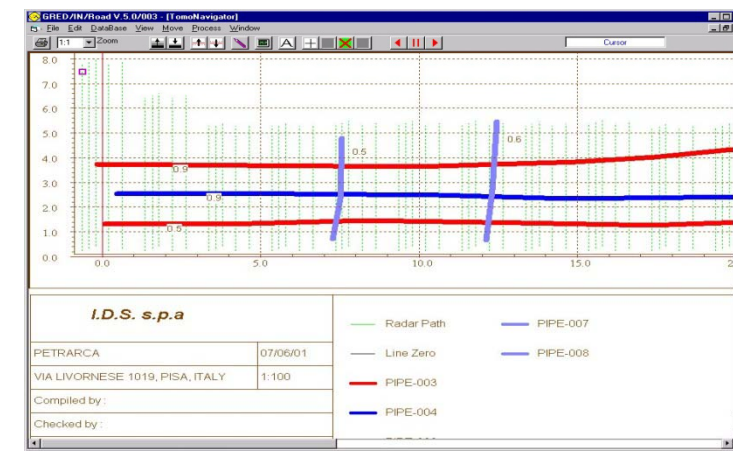


2. Data processing (office)



3. End results includes a schematic table of the pipes position and a 2D schematic map

File Modifica Visualizza Inserisci Formati Strumenti Dati Finestra ?											





CIVIL ENGINEERING

RIS Hi-BrigHT

Bridge High Resolution Tomography

IDS SPECIFIC RADAR SOLUTION

FOR BRIDGE DECK SURVEY



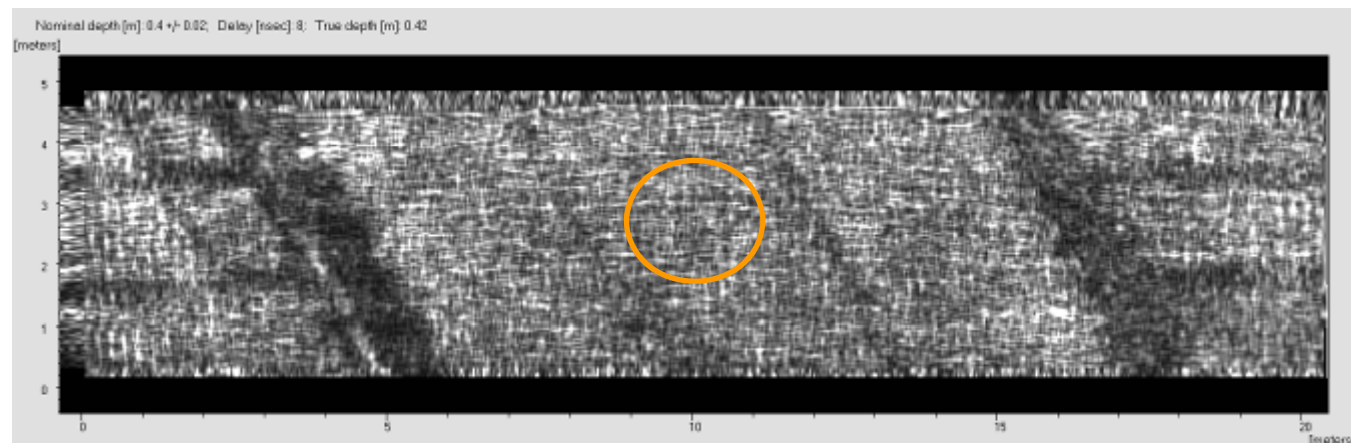
RIS Hi-BrigHT: Features



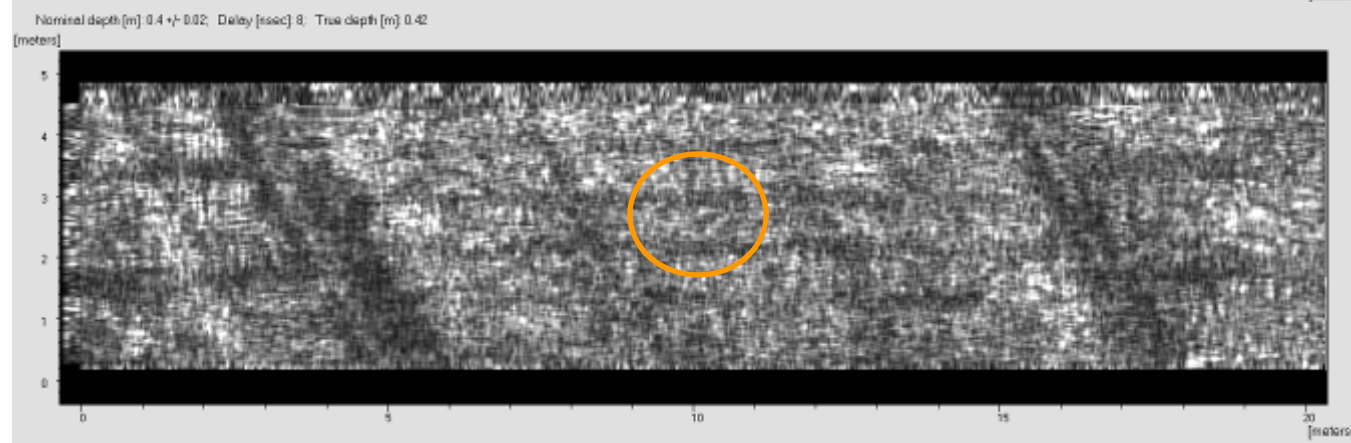
- High Bandwidth: >2 GHz → best resolution of defects
- 16 antennas array → permitting 3D Tomography and saving acquisition time
- Double polarisation: 8 antennas in VV polarisation + 8 antennas in HH → providing more information on defects
- High manoeuvrability: compact and lightweight design → easing and speeding data collection

RIS Hi-BrigHT: tomography

**Tomography: HH
Polarization**



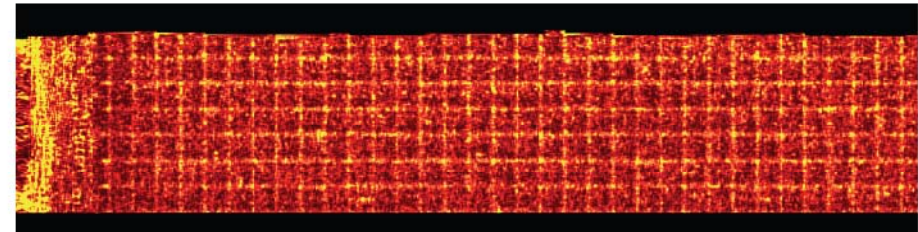
**Tomography: VV
Polarization**



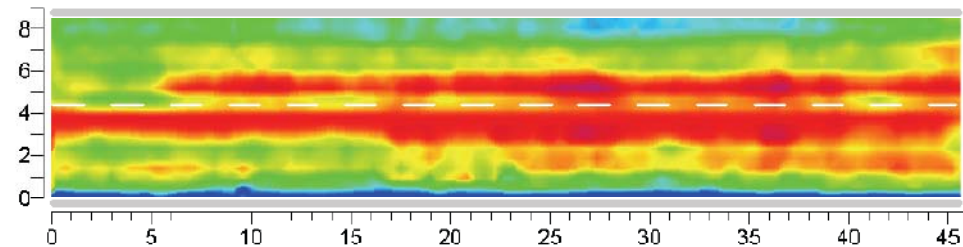
RIS Hi-BrigHT: processing



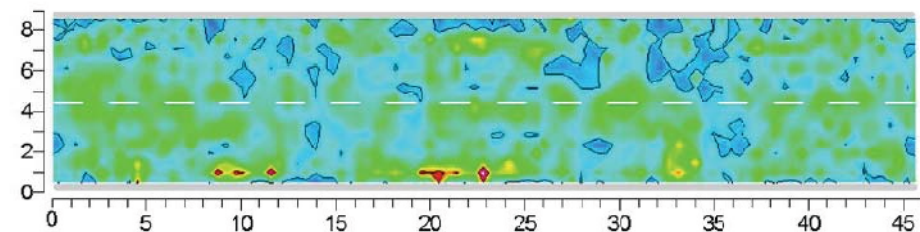
- RIS Hi-BrigHT uses the new BridgeDoctor processing software by Roadscanners, a processing and interpretation tool dedicated to bridge analyses, featuring:
- 3D tomographic view
 - Map of pavement and concrete thicknesses
 - Map of moisture deteriorated zones
 - Map and depth of reinforcement bars



Tomographic view of the reinforced cover.



Map of pavement thickness.



Identification of moisture zones. Blue spots locate moisture in concrete.

ALADDIN

an advanced radar based sensor for
Non-Destructive structural analysis

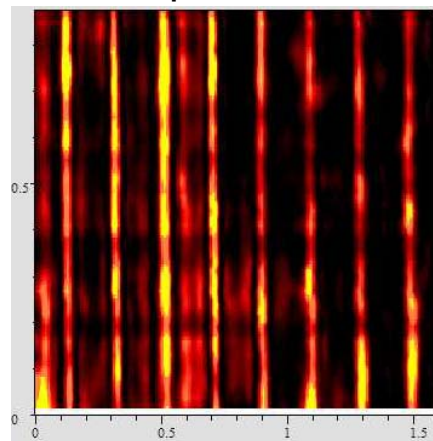


Civil engineering & Cultural heritage applications

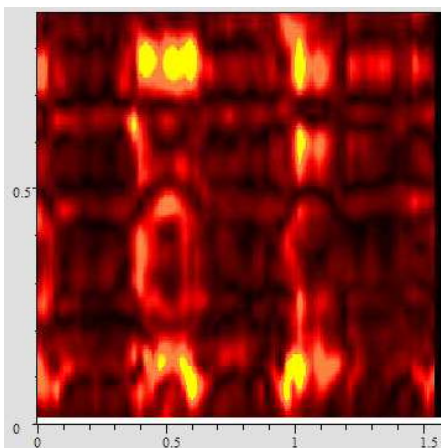
- 3D imaging of shallow and deep rebars in concrete;
- Inspection of concrete for location of voids;
- Inspection of concrete thickness, integrity;
- 3D imaging of pre-tension and post-tension cables;
- Inspection and analysis of old structures and monuments;
- Inspection of walls and floors for the location of pipes, objects, caches, etc..

Standard Products

Depth: 0.10m



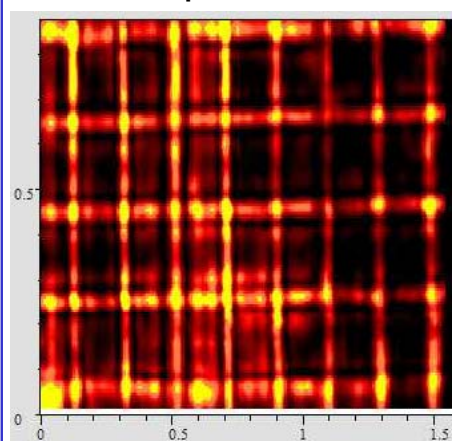
Depth: 0.40m



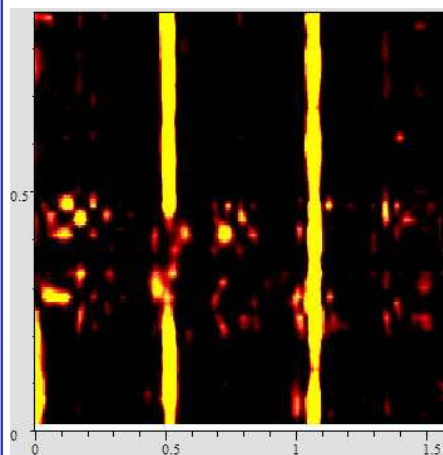
The standard antenna can read the shallow targets (rebars), but is not able to reveal the lower structures

ALADDIN

Depth: 0.10m

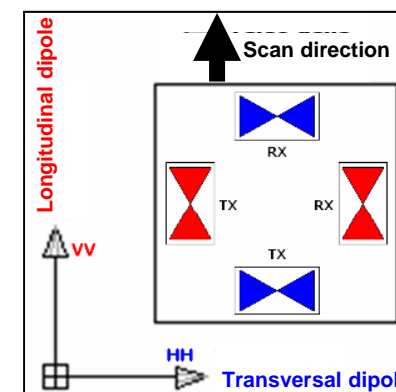


Depth: 0.40m



Instead, the FULL-POLAR antenna is able to identify both targets (shallow and deep) in just one scan.

The **SPECIAL FULL-POLAR** high-frequency (2 GHz) antenna combined with the **patented Pad Survey Guide (PSG)** permit joint orthogonally polarized scans to be acquired in a single pass, detecting shallow and deep structures and halving acquisition time compared to standard methods.





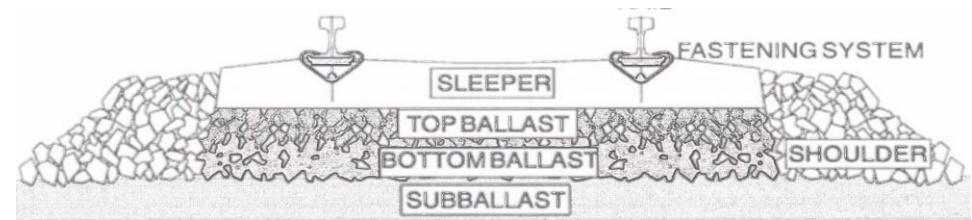
RAILWAY ENGINEERING



Track bed inspection by
high speed radar

Expectations from the end-user

- Continuous Mapping of Ballast Thickness
- Locating Areas with Insufficient Bearing Capacity (e.g. Ballast Pockets)
- Differentiation Between Clean and Fouled Ballast
- Detection of Sections with Drainage Problems



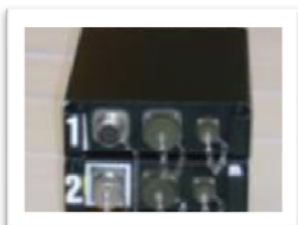
Data Acquisition Unit



Data Logger / Pc
(Panasonic CF30)



Qty2:
DAD MCh Fastwave



Qty1:
Synchro Unit



SRS 400 MHz antennas

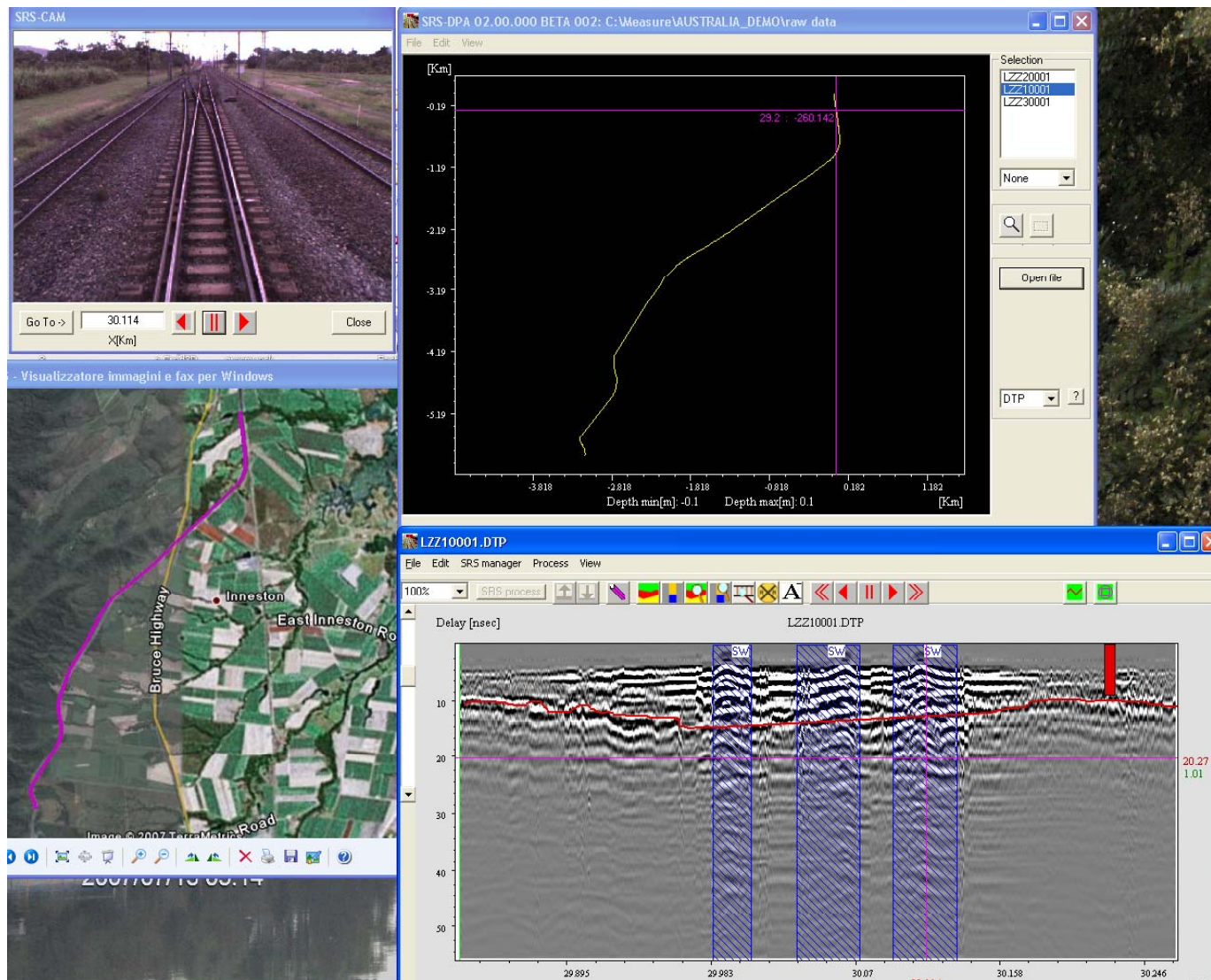


Doppler Encoder

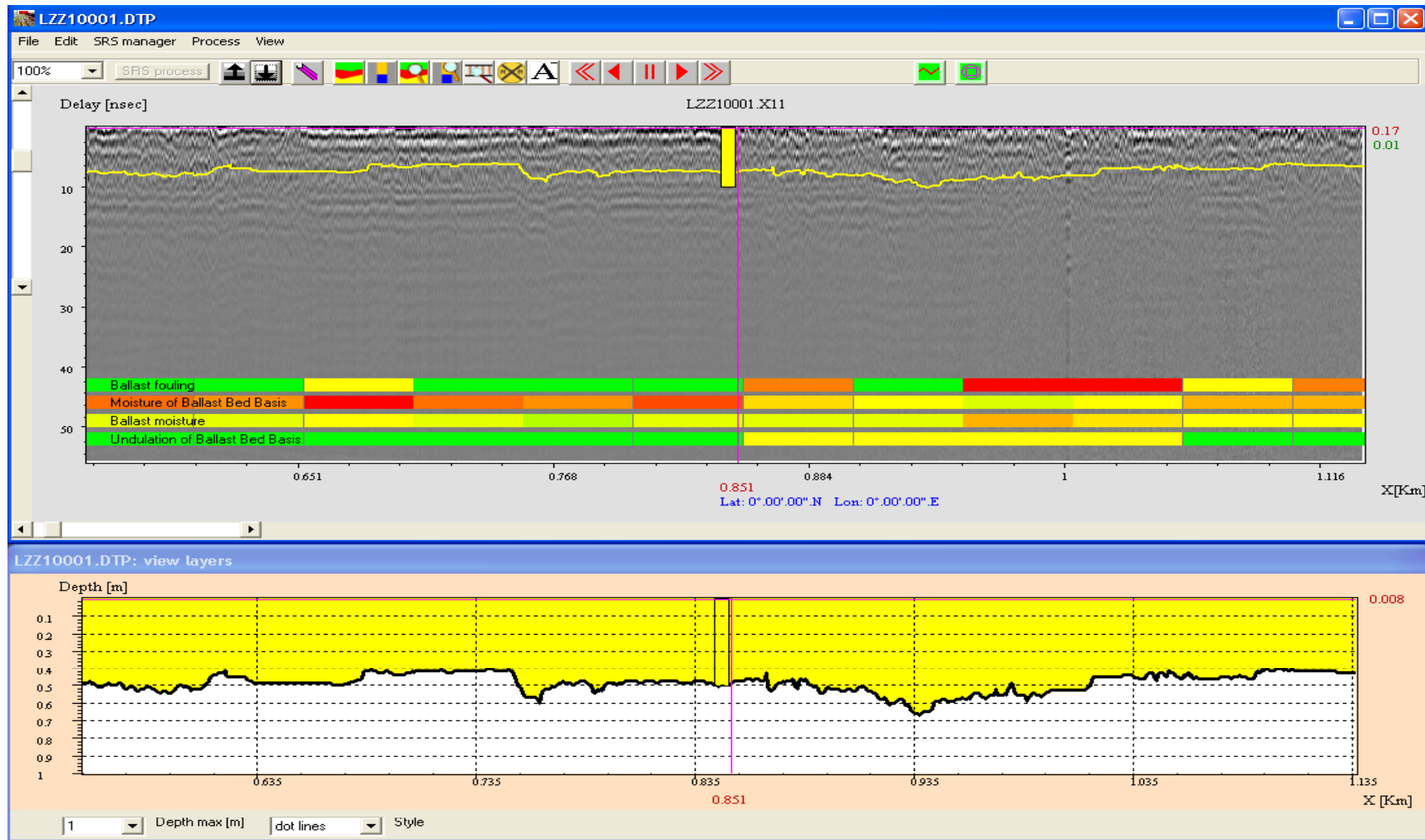
Data Acquisition Unit: unmatched features

- Interleaved multiplexing (up to 4 antennas ran simultaneously)
- Very fast collection speed
 - ❖ 150 Km/h @ 12 cm sampling step (512 samples per trace)
 - ❖ 190 Km/h @ 12 cm sampling step (384 samples per trace)
 - ❖ > 300 Km/h @ 60 cm sampling step (512 samples per trace)
- Video frame from the USB camera captured and stored at user-defined step (typ. 20 m)
- GPS information stored with radar data at user-defined step (typ. 20 m)
- Unlimited length of the collected profile for avoiding stop on tracks (data are automatically stored every 10 Km and reformatted at the end of the survey)

Data Analysis Software: data selection



Automatic analysis of ballast





ROAD ENGINEERING

RIS Hi-Pave: architectures

DAD MCh Fastwave



Data Logger



GPS antenna + Video Camera (option)



Dedicated encoder fixed on the car wheel



Horn antenna 1000 MHz



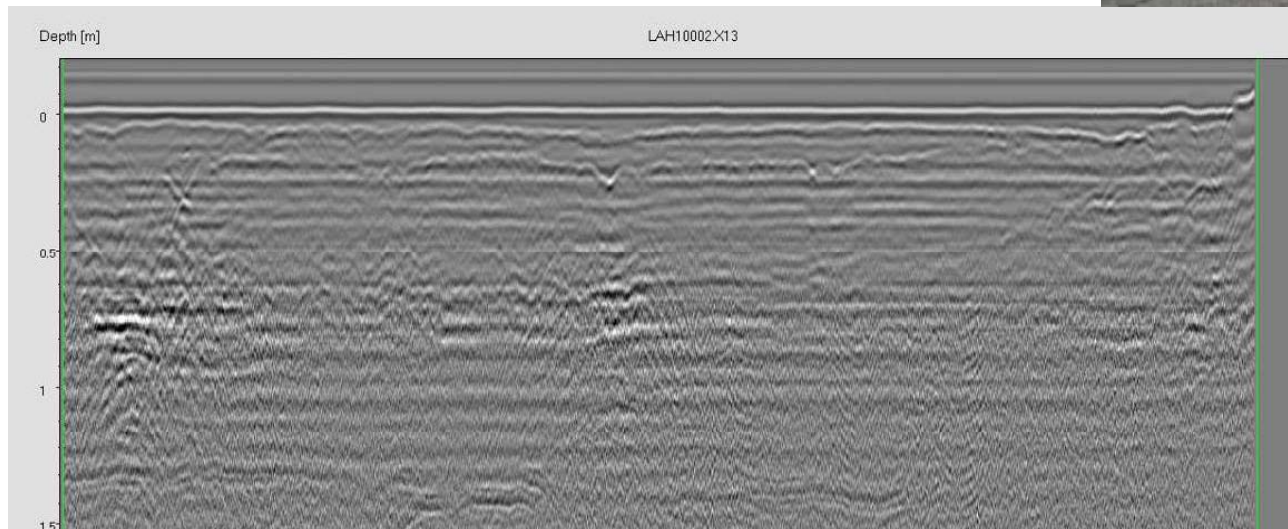
Mechanical Kit for can be connected to any car or van with drag-hook



RIS Hi-Pave: available Horn antennas

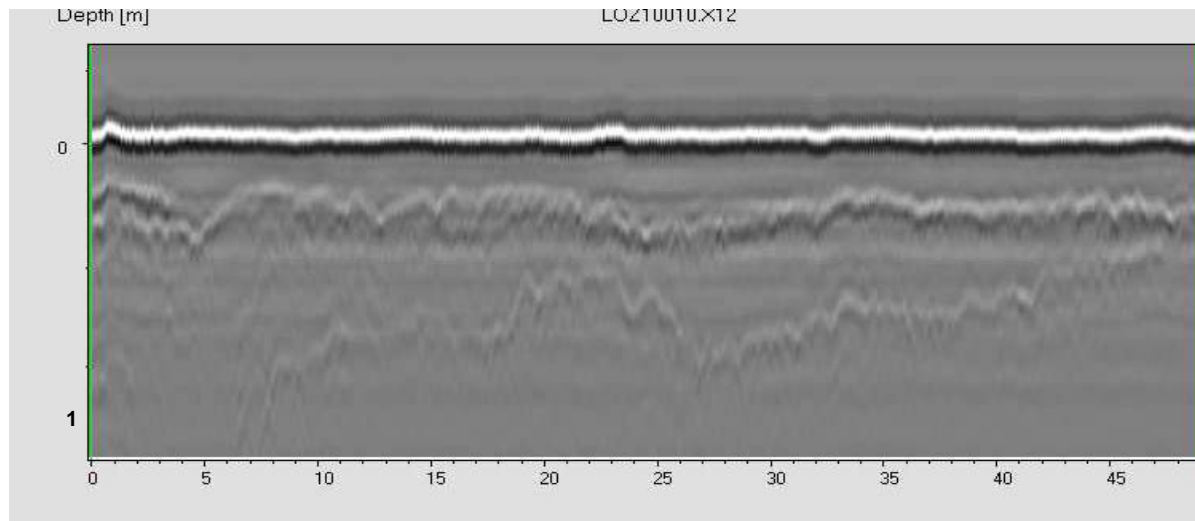
IDS Horn antennas :

- TR 1000 (1000 MHz)
- TR2000 (2000 MHz)

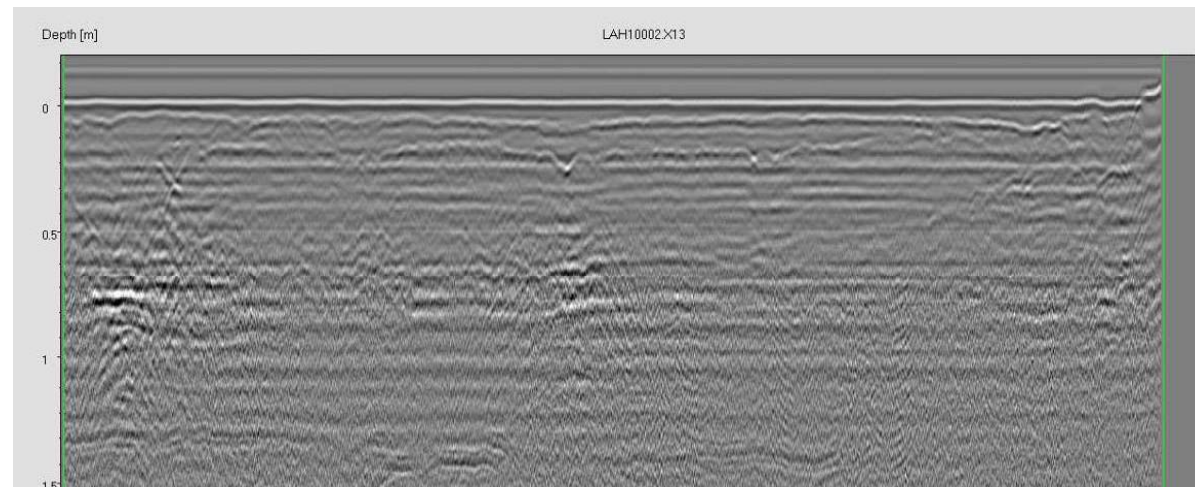


Radar map with 1000 MHz
Horn antenna.

Horn antennas: radar maps



Radar map with 2000 MHz
Horn antenna.



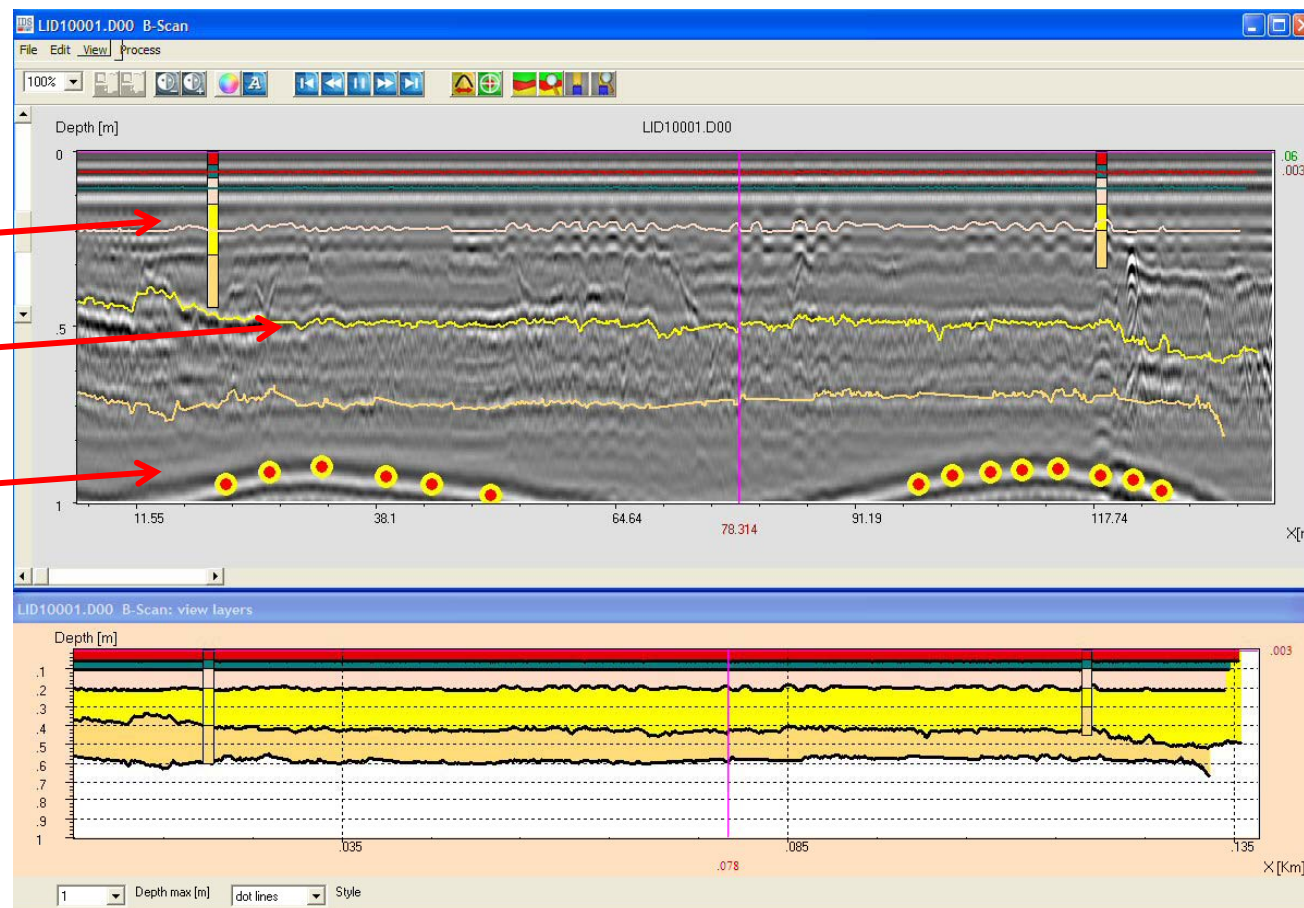
Radar map with 1000 MHz
Horn antenna.

RIS Hi-Pave: data analysis software for asphalt layers

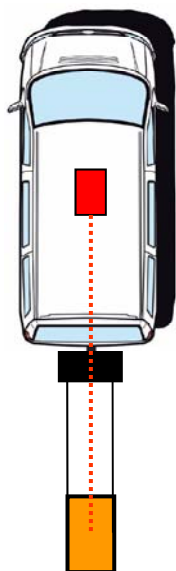
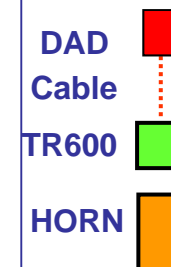
Core test

Stratigraphic levels

Cavities



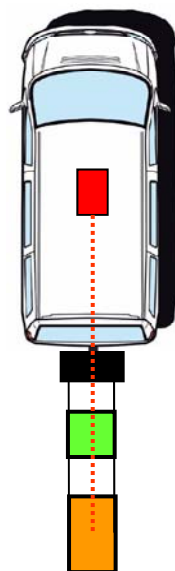
RIS Hi-Pave: possible configurations



RIS Hi-Pave HR1

The single-antenna, entry-level configuration for road and runaway pavement evaluation:

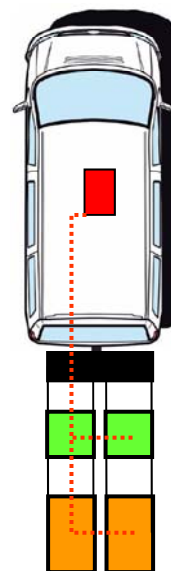
- 1 DAD FastWave control unit
- 1 HR2000 antenna (2 GHz horn) for road survey or 1 HR1000 antenna (1 GHz horn) for runaway survey



RIS Hi-Pave HT2

The double-antenna configuration for complete road and runaway evaluation (pavement, grade, subgrade):

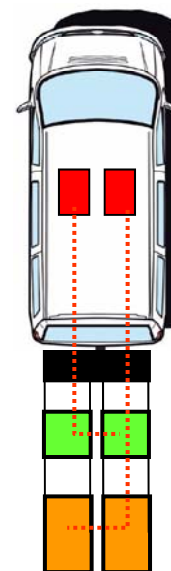
- 1 DAD FastWave control unit
- 1 HR2000 antenna (2 GHz horn) for road pavement survey or 1 HR1000 antenna (1 GHz horn) for runaway survey
- 1 TR600 antenna (600 MHz) for grade and subgrade evaluations



RIS Hi-Pave HT4

The four-antenna configuration for complete and wide road and runaway evaluation:

- 1 DAD FastWave control unit
- 2 HR2000 antennas (2 GHz horn) for road survey
- 2 HR1000 antenna (1 GHz horn) for runaway survey
- 2 TR600 antennas (600 MHz) for grade and subgrade evaluations



**RIS Hi-Pave HT4 HS
or
RIS Hi-Pave HT2 HS**

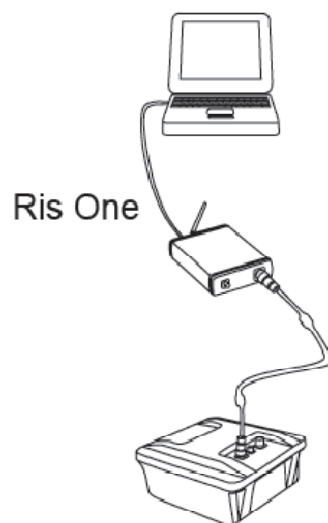
The same as the HT4 or HT2 configuration but with 2 synchronised DAD control units for maximum speed (over 200 Km/h) or very dense sampling (5 cm. at 125 km/h)



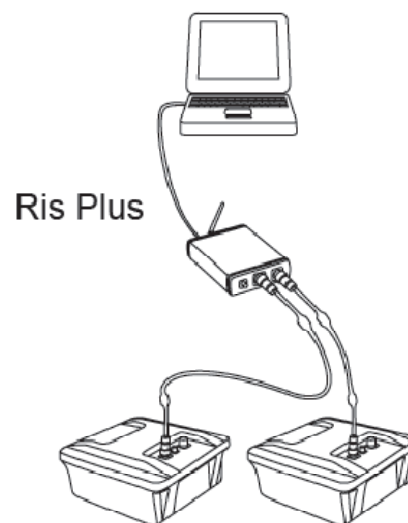
Geology and Environment

RIS One and RIS Plus:

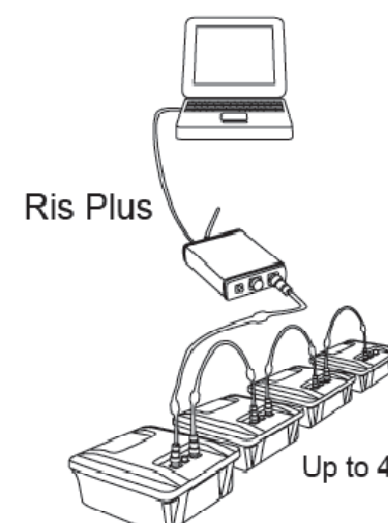
a comprehensive set of products covering the needs of geology and environment applications



Single channel configuration (also available with 1 dual frequency antenna)



Multi-channel configuration with two single frequency antennas



Multi-channels configuration comprising a chain connection with up to 4 dual frequency antennas

IDS available antennas

TPOLOGY	MODEL	FREQUENCY (MHz)	WEIGHT (Kg)	DIMENSIONS (Cm)
UNSHIELDED	TR 25	25	18	400x120x55
	TR 40	40	18	274x120x55
SHIELDED	TR 80	80	23	140x70x30
	TR 100	100	23	140x70x30
	TR 200	200	6	43x37x20
	TR 400	400	5.5	43x37x20
	TR 600 H	600	5.5	43x37x20
	TR 600 V	600	3	20x26x20
	TR 900	900	3	20x26x20
	TR HF	2000	1.3	13x12x8
BOREHOLE	BH 150	150	1	160; Ø 40
	BH 300	300	1.5	100; Ø 40
HORN ANTENNAS	HR 1000	1000	7	51x46x23
	HR 2000	2000	7	51x46x23

TPOLOGY	MODEL	FREQUENCY (MHz)	WEIGHT (Kg)	DIMENSIONS (Cm)
DUAL FREQUENCY ANTENNAS	DUAL F (200-600) Fastwave	1 x 200	6	43x37x20
		1 x 600		
	DUAL F (400-900) Fastwave	1 x 400	6	43x37x20
		1 x 900		
	TR-AL	1 x 600	5	43x37x20
		1 x 2000		
SPECIAL HF ANTENNAS	HIRESS	4 x 2000	3	45x15x17
	FULL POLAR	2 x 2000	1.5	12x12x18
ANTENNA ARRAY	DML 200	200	32	98x37x18
	DML 600	600	30	98x37x18

Main features:

- Wide number of model at different frequency
- Compact and lightweight
- Better performances

21 models available

Low-frequency antennas for deep surveys



25 MHz antenna

- Unshielded 25 MHz and 40 MHz antennas.

Single Tx/Rx module with replaceable antenna modules



80/100 MHz antenna

- Shielded 80 MHz and 100 MHz antennas.

Separated Tx and Rx modules for bistatic and CMP investigations

BOREHOLE antennas for deep surveys



Available models/frequency antennas :

- BA150 MHz,
- BA 300 MHz
- BA 1000 MHz (prototype)
- Borehole antenna cable (40 m) (BAC 4000)
- Antenna Type: Unshielded Dipole
- Nominal Frequency: 150 or 300 MHz
- Operation Mode: Single hole reflection, Cross-hole tomography
- Length: 1.6 or 1.0 meter
- Diameter: 40 mm
- Weight: 1.5 Kg
- Water-proof: up to 5 bar

STREAM-X: the massive array solution for archaeology and environment survey



Stream-X towed by quad



Stream-X dragged by hand

STREAM-X: main benefits

- GPR solution towed by a vehicle (speed > **15** Km/h).
- Suitable for working on rough terrain
- Can be dragged by hand or towed by a vehicle
- Positioning: survey wheel, GPS or Total station
- High productivity: 1 hectare/hour
- High detection capability thanks to the following data spacing:
 - up 12 cm @200 MHz
 - up to 4 cm @ 600 MHz
- Higher investigation depth thanks to the high stacking factor and high performance low frequency antennas
- Real time Navigator for a fast and complete area coverage
- Dedicated post processing software with automated transfer to CAD/GIS



Stream X System: complete configuration with an array of 200 or 600 MHz antennas

STREAM-X: modularity and array architectures

1x200 MHz DML array for detecting main target underground (12 cm transversal sampling; VV polarization)

GPS or Total Station

Radar Control Unit

Electric motor

Cart to be towed by a van or a quad



Stream X: the DML array can be dragged by hand for archeology or environment surveys.

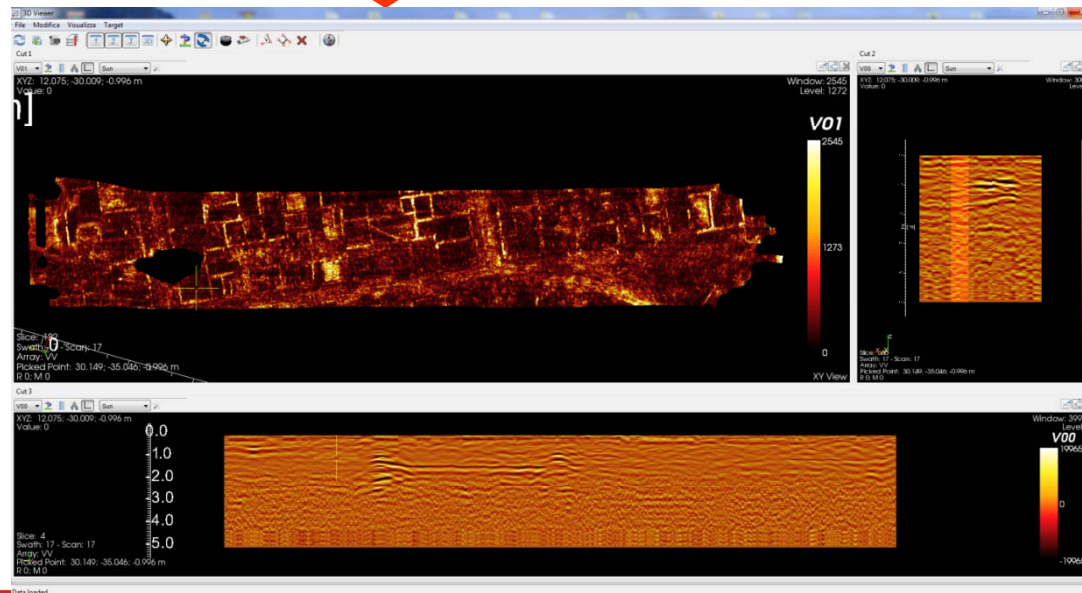


STREAM-X: Work Flow

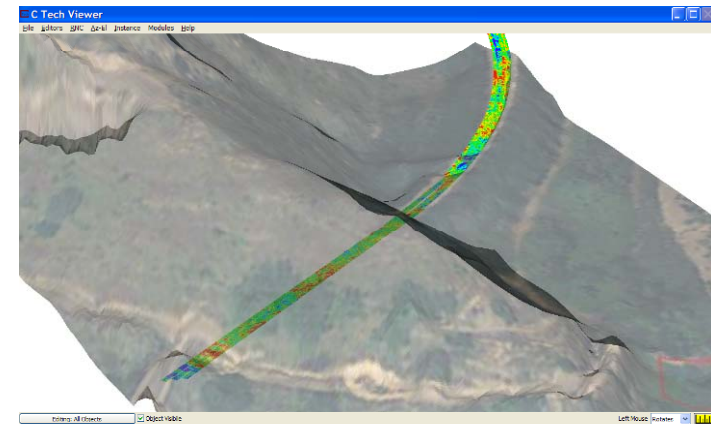
1. Data acquisition



2. Data processing (office)



3. 3D view in CAD/GIS environment



Forensic & Security

FoRad System

Forensic Solutions

Radar technology is exploited
for public security & law enforcement applications
to locate tunnels, weapons, caches and hidden persons
composed by
a specialized **Surface Penetrating Radar**
and
an innovative **TWR Detector**

Available Configurations

Sila System

Forensic Radar



Shallow
Antenna
(HF)

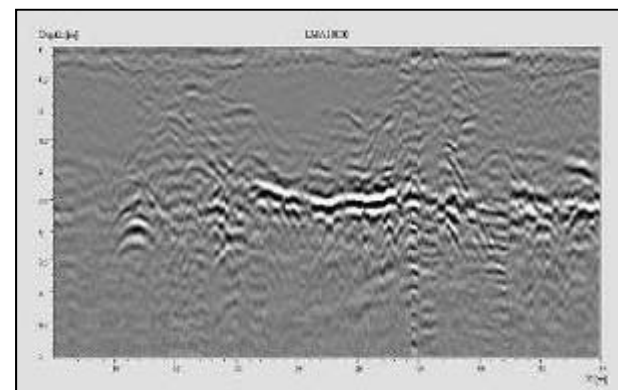
Medium-Deep
Antenna
(MF-LF)

Sila - MF/LF

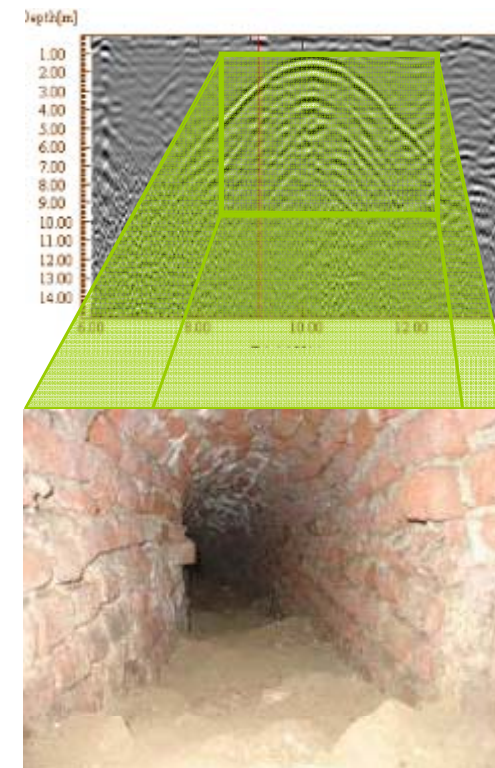
200/600 MHz Antennas
for subsoil investigations

Fast Surveys & deeper
investigations

Locates tunnels, caches
and cavities where people
and weapons are
supposed to be hiding

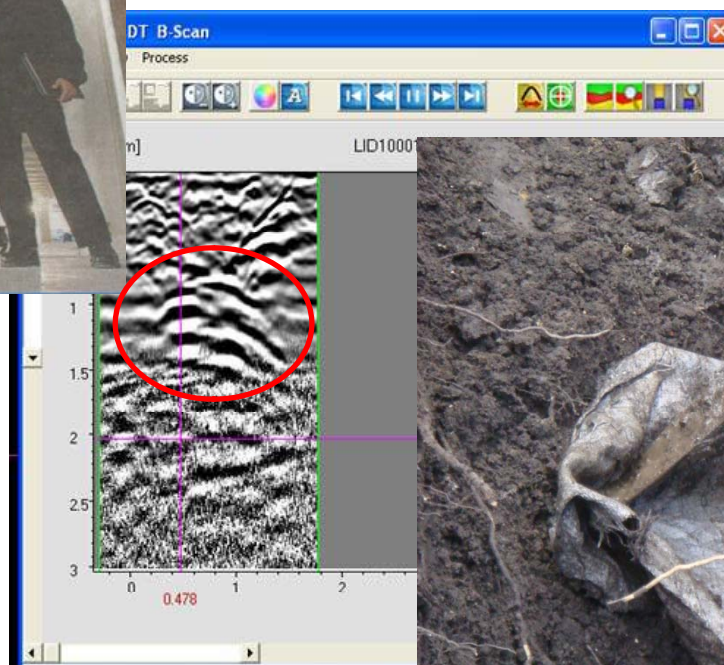


Sila - MF/LF



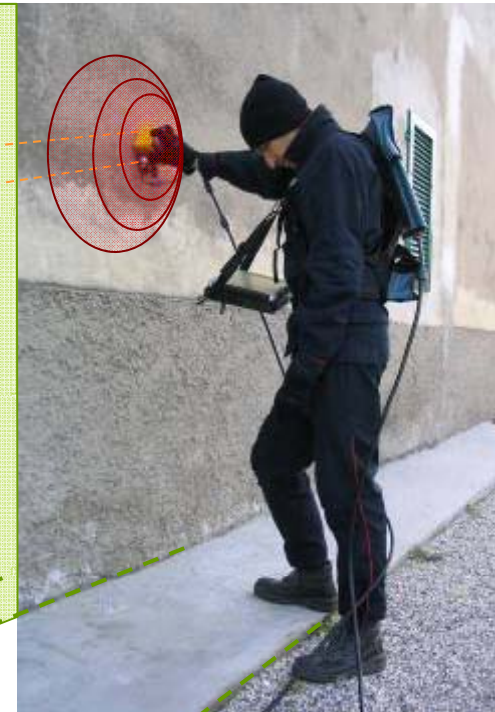
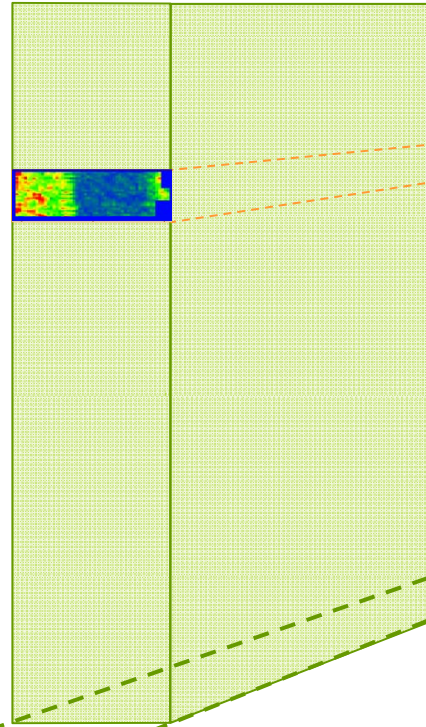
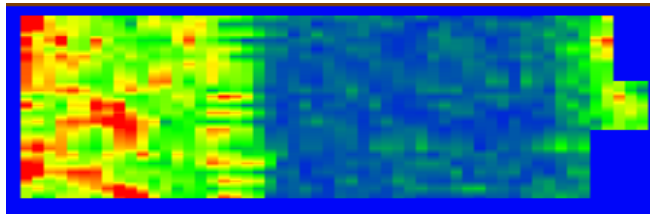
Quickly reveals buried constructions, buildings and booties by the use of 200 MHz antenna (low frequency)

Sila – MF/LF



Carabinieri research and discover of
buried bodies, thanks to Sila system

Sila-HF



2 GHz antennas for wall and floor investigations

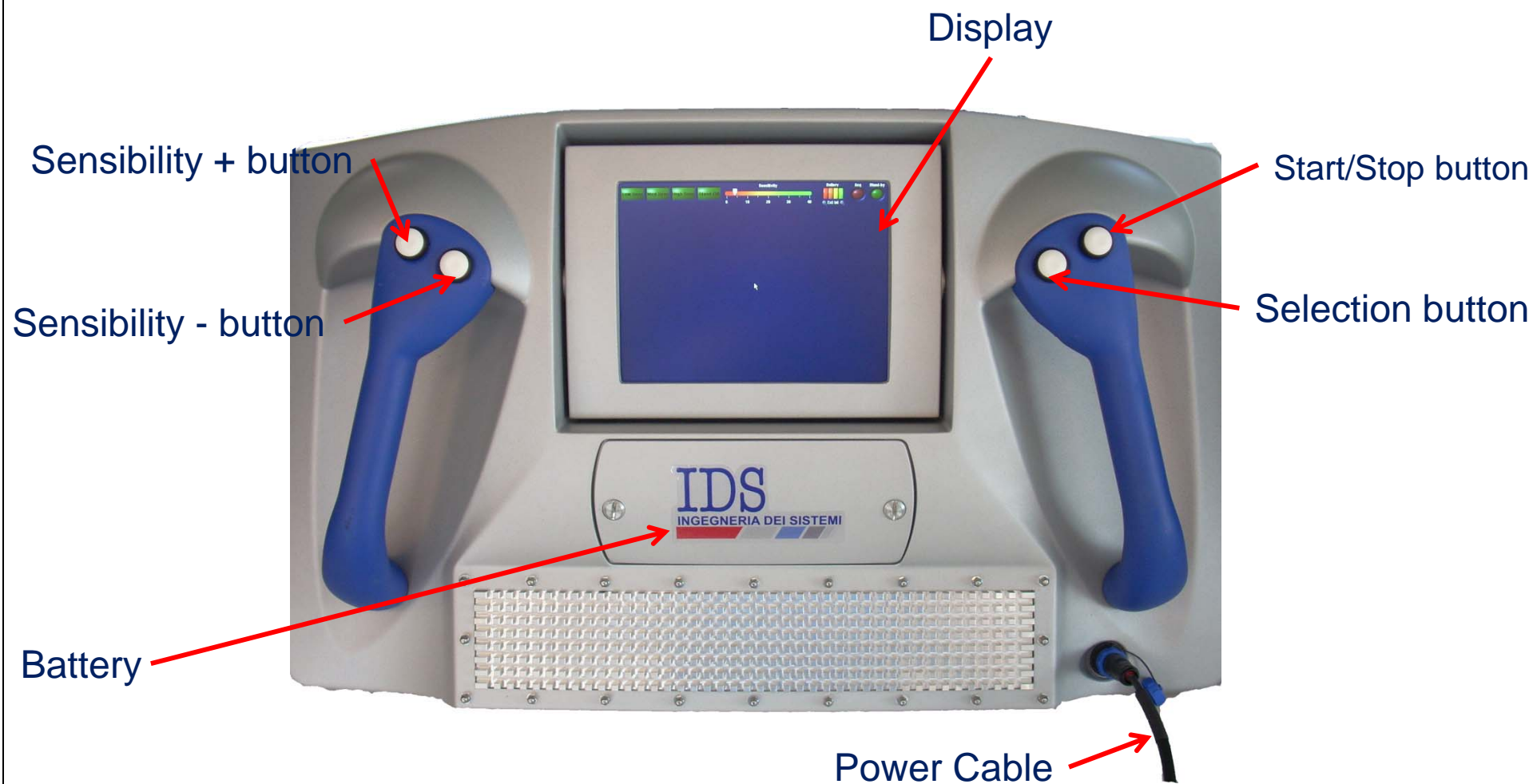
IDS TWR

IDS Through Wall Radar device for ISR missions

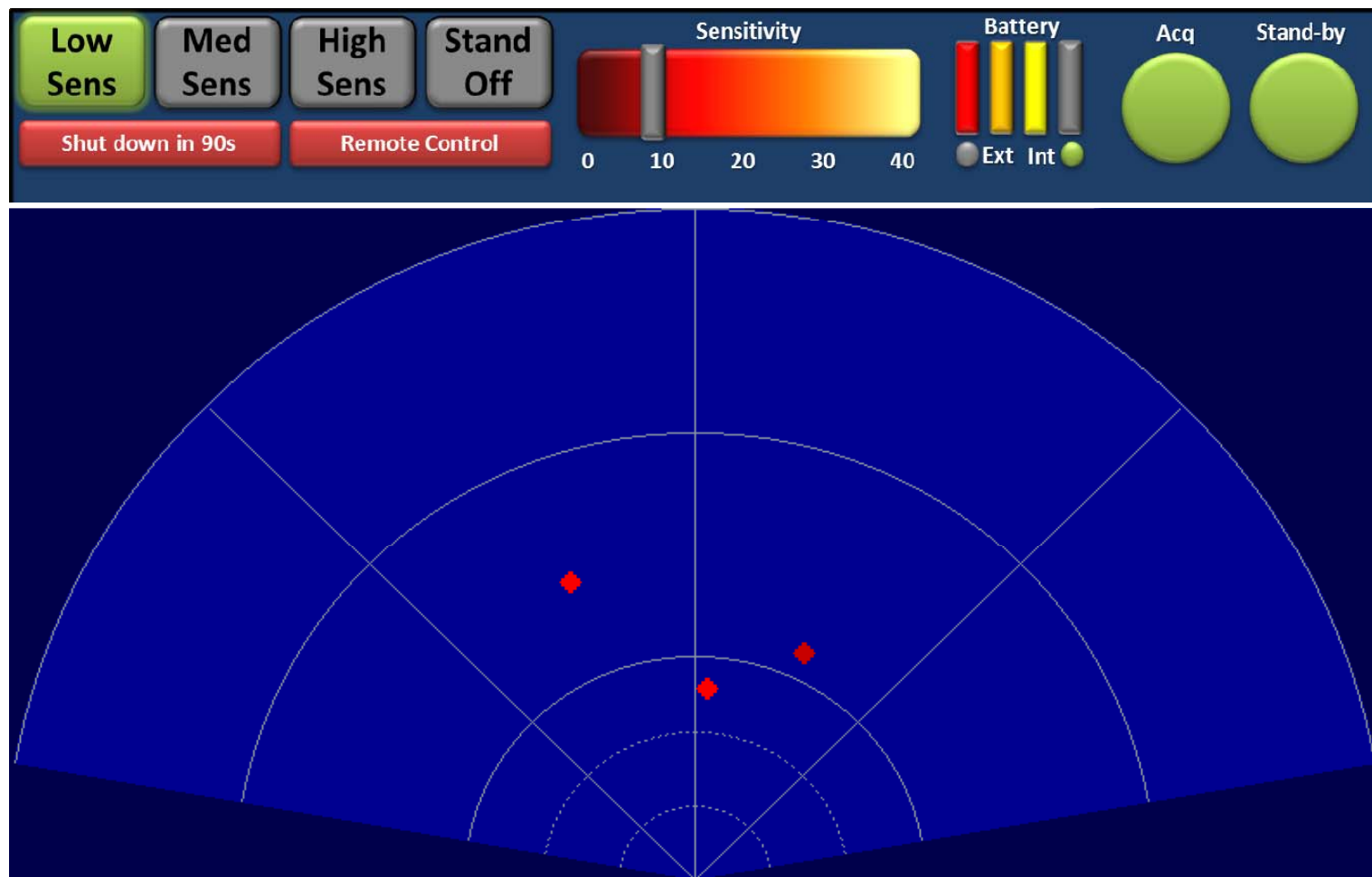
(Intelligence, Surveillance & Reconnaissance)



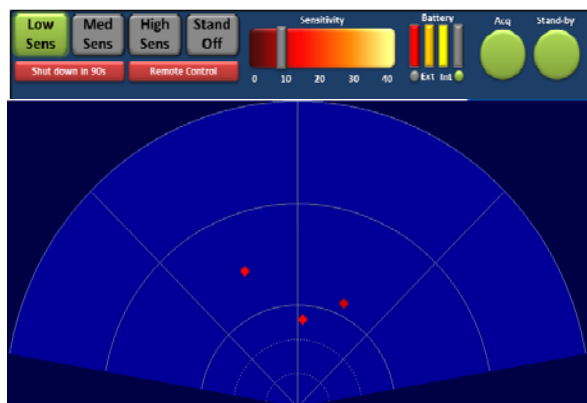
IDS TWR- Composition



IDS TWR - Handheld Through the Wall Radar



IDS TWR- Handheld Through the Wall Radar



Technical Features

Frequency: 2 GHz to 2,5 GHz

Display mode: 2D plain view, 1.5D (range with time history)

Display type: Colour, tilt-able, ultra bright

Weight: 5,5 Kg

Size: 60x32x12 cm

Ultra light materials: carbon & glass fibre

Survey Range: 15m (depending on obstacle type)

walking person > 12 m

standing, still breathing >3 m

Data Processing: Real time, 47 frame/sec

Wireless connection: available

Power Supply: battery 15 V or power line

Batteries operating time: Rechargeable batteries < 4hours

IDS TWR- Handheld Through the Wall Radar

Main Features:

- High sensibility: Breathing and heart beat detection capability
- Compact and lightweight for tactical operations
- User friendly: 2D imaging capability for intuitive image interpretation
- Detection through different types of wall: concrete, full-bricks, empty-bricks, stone, adobe, wood
- Friendly HMI: controls directly available by the handles

IBIS

Image by Interferometric Survey

A comprehensive family of ground-based Radar Interferometers for the measurement of displacements and vibrations



IBIS: ground-based interferometric radars

IDS present the IBIS family:

an innovative range of advanced “geodetic” instruments based on ground-based radar interferometry aimed at providing accurate measurement of movements over wide areas.

IBIS products have been designed to address the specific needs of the civil engineering, geotechnical and mining markets

This revolutionary approach provides the IBIS users with accurate remote measurements without requiring any contact with the target and in almost all weather conditions.

IBIS product range

PRODUCTS



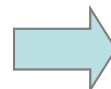
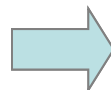
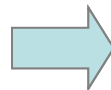
IBIS - L



IBIS - M



IBIS - S



APPLICATIONS



LANDSLIDE & DAM MONITORING



SLOPE STABILITY IN MINING



STRUCTURE MOVEMENTS

IBIS-S: system & application fields



IBIS-S

BRIDGE TESTING



CULTURAL HERITAGES



INDUSTRIAL FACILITIES

IBIS-L: system & application fields



IBIS-L



LANDSLIDE MONITORING



DAM MONITORING



**GROUND SETTLEMENTS
MONITORING**

IBIS-M: system & application field



IBIS-M



**SLOPE MOVEMENT MONITORING
WITHIn OPEN PITS MINES**

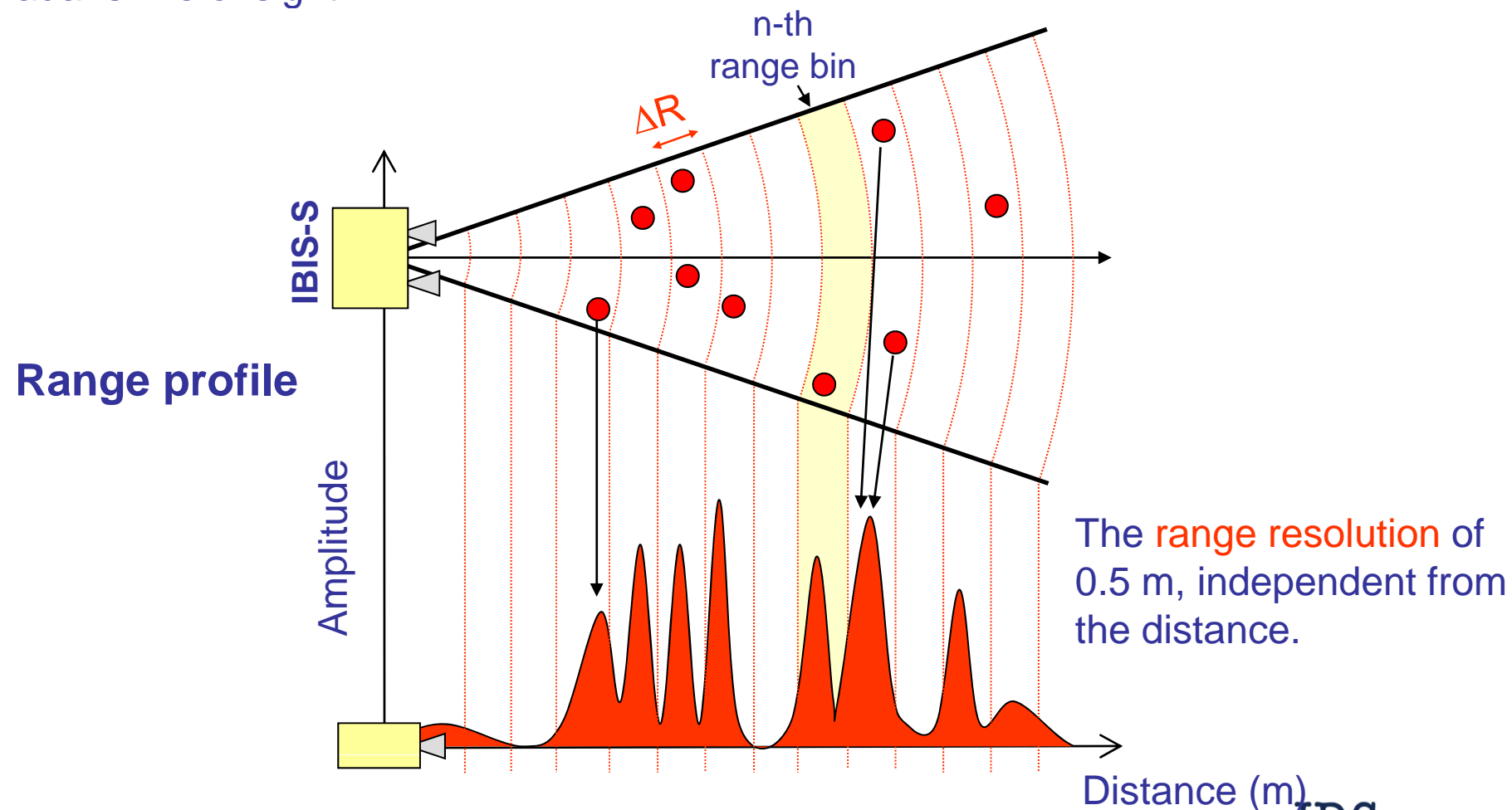
Techniques behind the IBIS systems

The IBIS products are based on four well-known radar techniques:

1. **Stepped-Frequency Continuous Wave (SF-CW)** technique resolves the scenario in the range direction, detecting the position in range of different targets placed along the radar's line of sight;
2. **Synthetic Aperture Radar (SAR)** allows to obtain 2D high-resolution radar images by adding to the range resolution (from the SF-CW), the cross-range angular resolution
3. **Interferometric technique**, computes the displacement of each pixels by comparing the phase information of the radar signal collected at different times.
4. **Persistent Scatterers** algorithm (PSInSAR) selects among the whole image the high quality pixels and estimates the atmospheric artefacts in an automatic and robust way

Stepped Frequency-Continuous Wave

The SFCW radar detects the position in range of different targets placed along the radar's line of sight

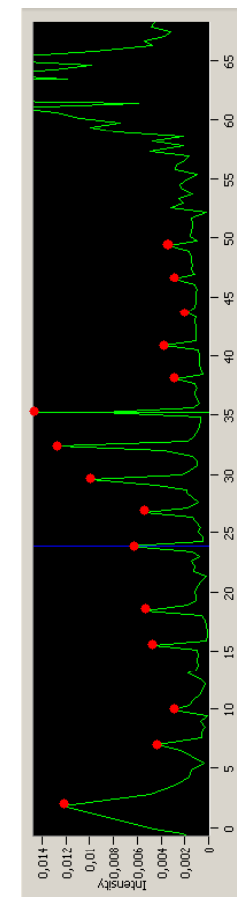
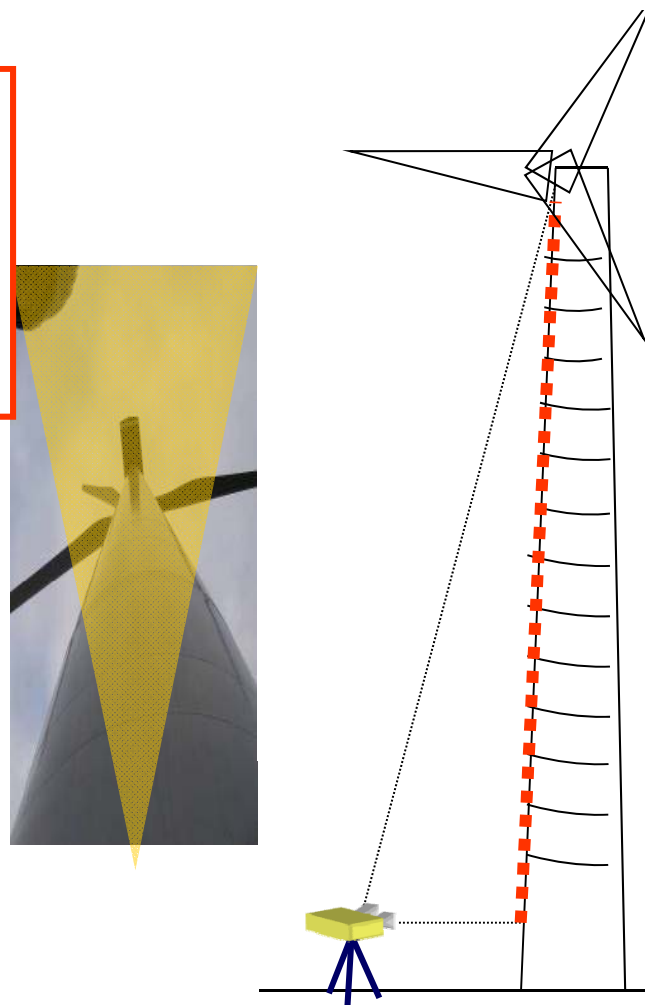


IBIS-S: 1-dimensional range profiles

Range Profile: one dimensional image with 0.5m range resolution



IBIS-S installed at the turbine pillar base (height 60m)



IBIS-L & IBIS-M: Synthetic Aperture Radar (SAR)

SAR technique enables the system to provide high cross range resolution exploiting the movement of the physical antenna along a straight trajectory (linear scanner)



Using 2 m rail
IBIS-L system obtains
4.38mrad (=0.25deg)
angle resolution

The SAR process of the data, collected during the movement of the sensor head on the 2 meter track, allows the IBIS-L and M systems to synthesize a 2m antenna whose azimuth beam width is:

$$\Delta\varphi = \frac{\lambda}{2 \cdot L} = 4.38 \text{ mrad}$$

IBIS-L & IBIS-M: SAR 2-dimensional images

The combination of SAR and SF-CW techniques allows the system to resolve the scenario into two dimensional pixels

Pixel dimension:

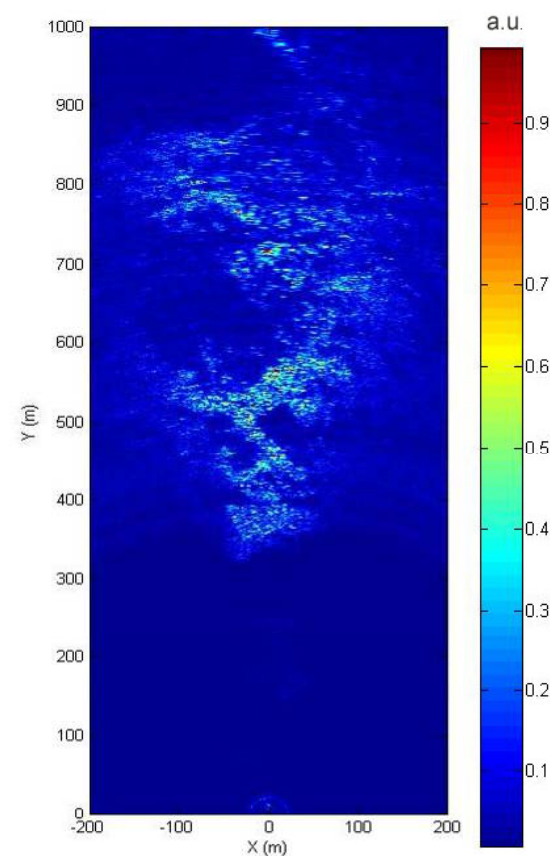
- 0.5m in range;
- 1.35m – 4.05m cross range for 300 - 900m range



Optical Image

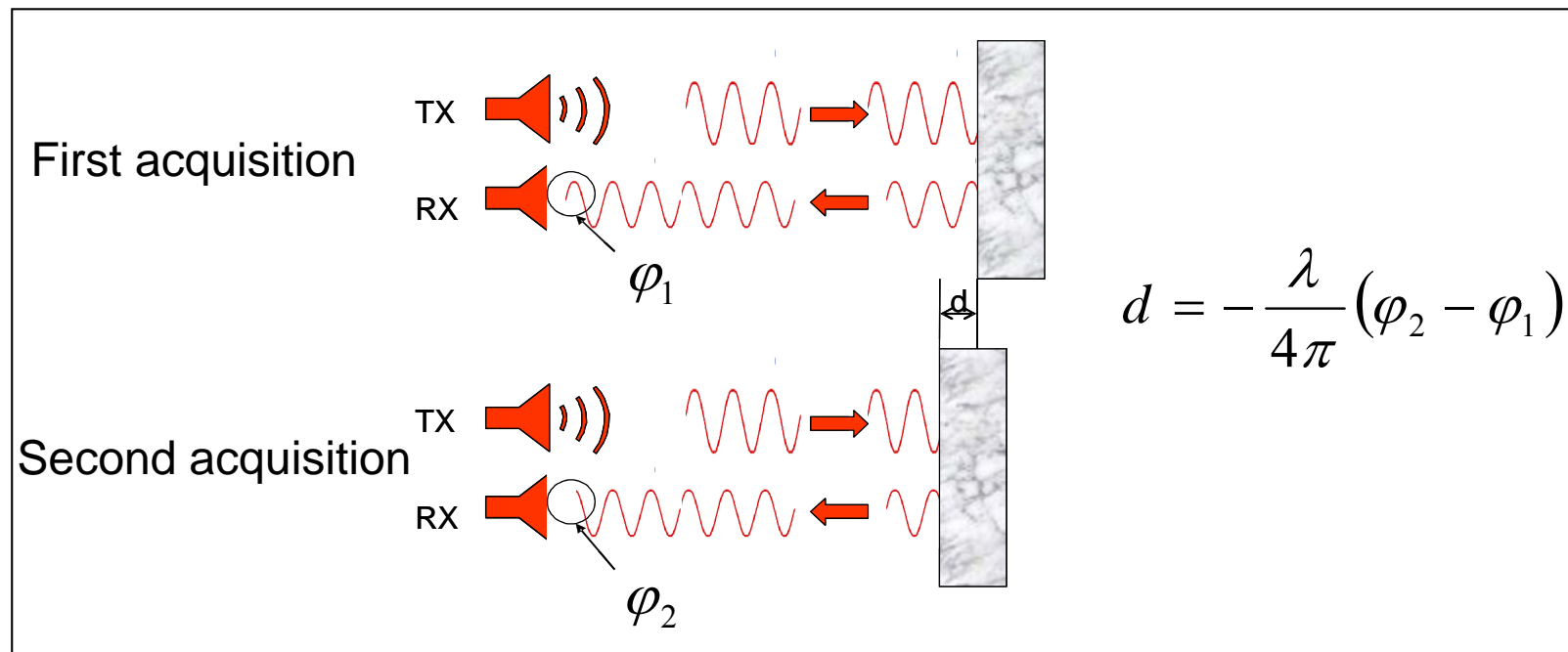


Power Map



Interferometric capability

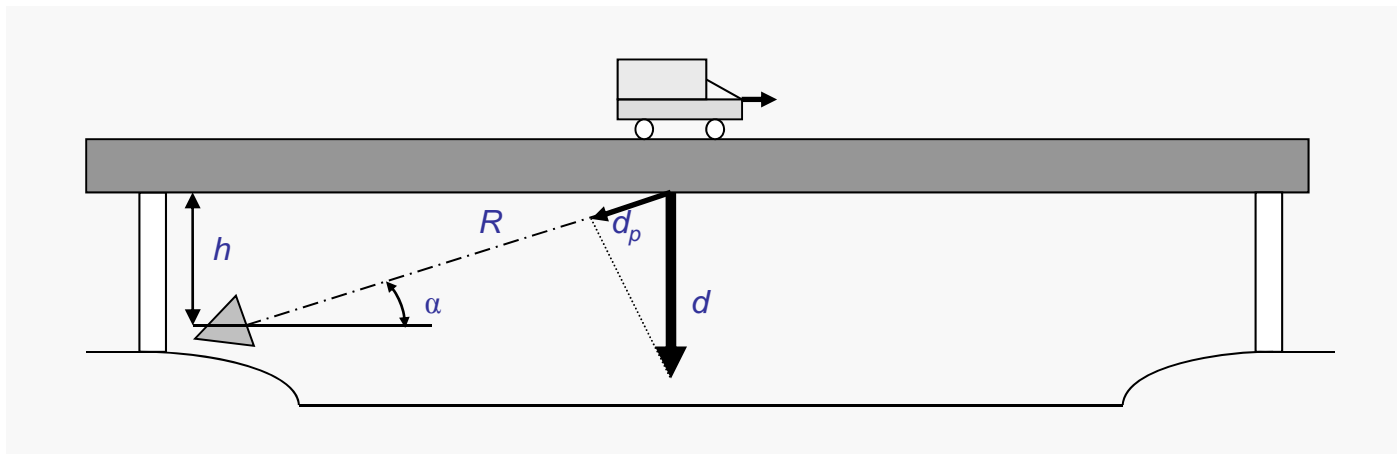
The **interferometric analysis** provides data on object displacement by comparing phase information, collected in different time periods, of reflected waves from the object, providing a measure of the displacement with an accuracy of less than 0.01mm (intrinsic radar accuracy in the order of 0.001 mm.)



Interferometric capability

The displacement is measured in the direction of the **line of sight** of the system.

To calculate the real displacement is needed to know the acquisition geometry



$$d = \frac{d_p}{\sin(\alpha)} \quad \Rightarrow \quad \sin(\alpha) = \frac{h}{R} \quad \Rightarrow \quad d = d_p \cdot \frac{R}{h}$$

The distance **R**
is measured
by IBIS-S

IBIS main advantages

The main advantages of the use of IBIS for monitoring are:

- possibility to carry out the survey **without accessing the land/structure** but installing the IBIS system in its proximity
- obtain **information from all the area** illuminated by the antenna beam: the radar measures the local displacement of the scenario by resolving it into pixels of a few square meters
- **high displacement measurement accuracy**, up to 1/10 mm
- **day-night** continuous operation
- **completely autonomous operation** not requiring human intervention
- **acquisition frequency** of the order minutes for IBIS-L, msec for IBIS-S

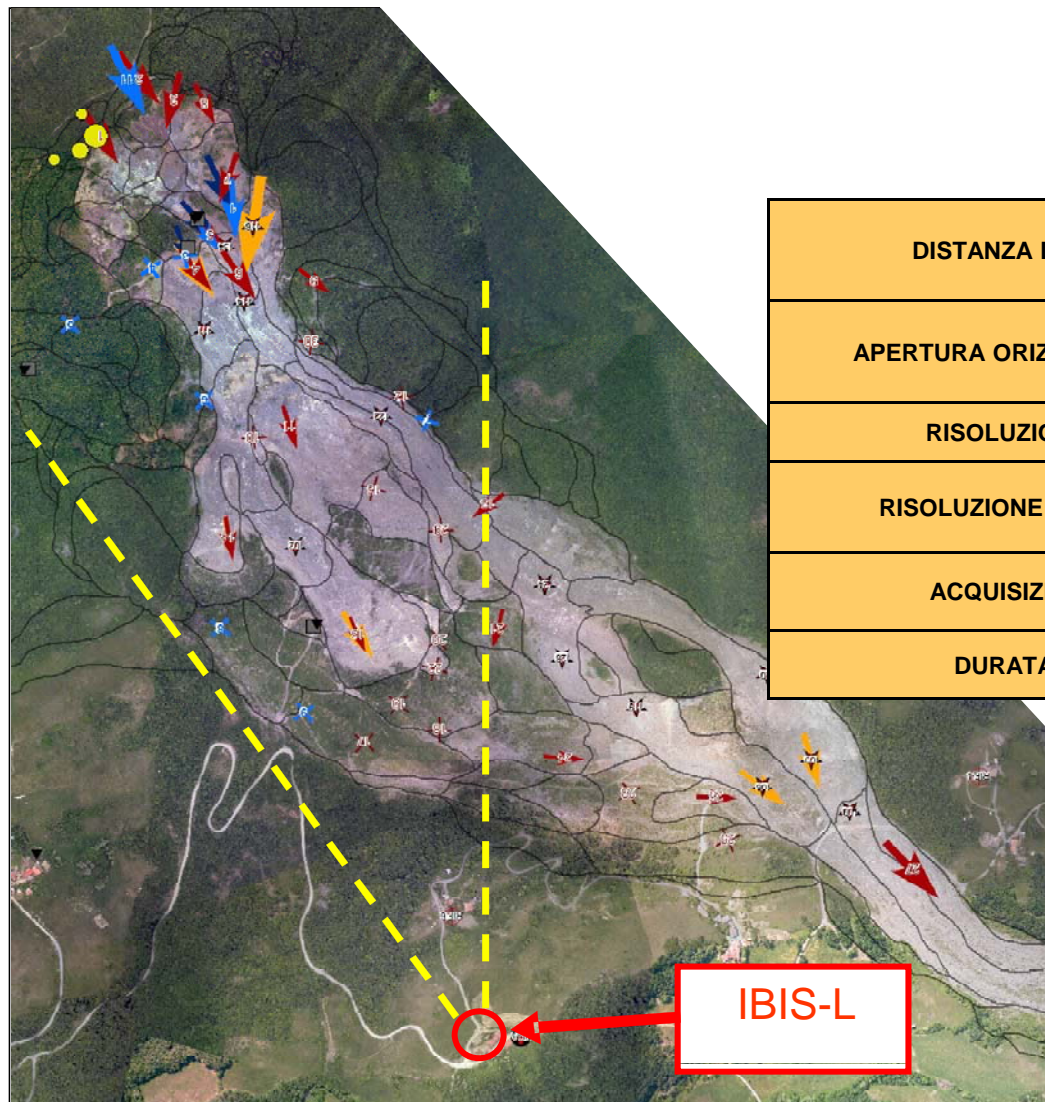
Landslide monitoring



Active earth slide evolving into
an earth flow in the lower part

Very fast movements (m/days)
during re-activation periods

Landslide monitoring

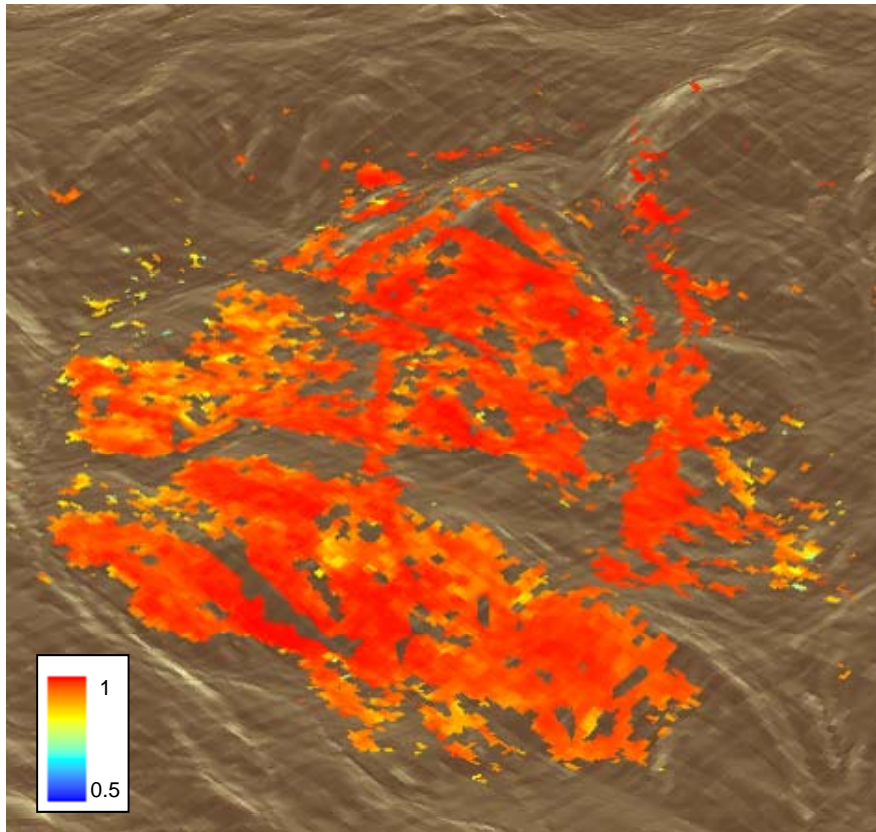


DISTANZA DAL VERSANTE	[m]	450-1300
APERTURA ORIZZONTALE ANTENNE	[gradi]	38
RISOLUZIONE IN RANGE	[m]	0.5
RISOLUZIONE IN CROSS-RANGE	[mrad]	4.5
ACQUISIZIONI PER ORA	-	9
DURATA SESSIONE	[ore]	24



IBIS-L System set-up

Landslide monitoring



Geocoded quality map

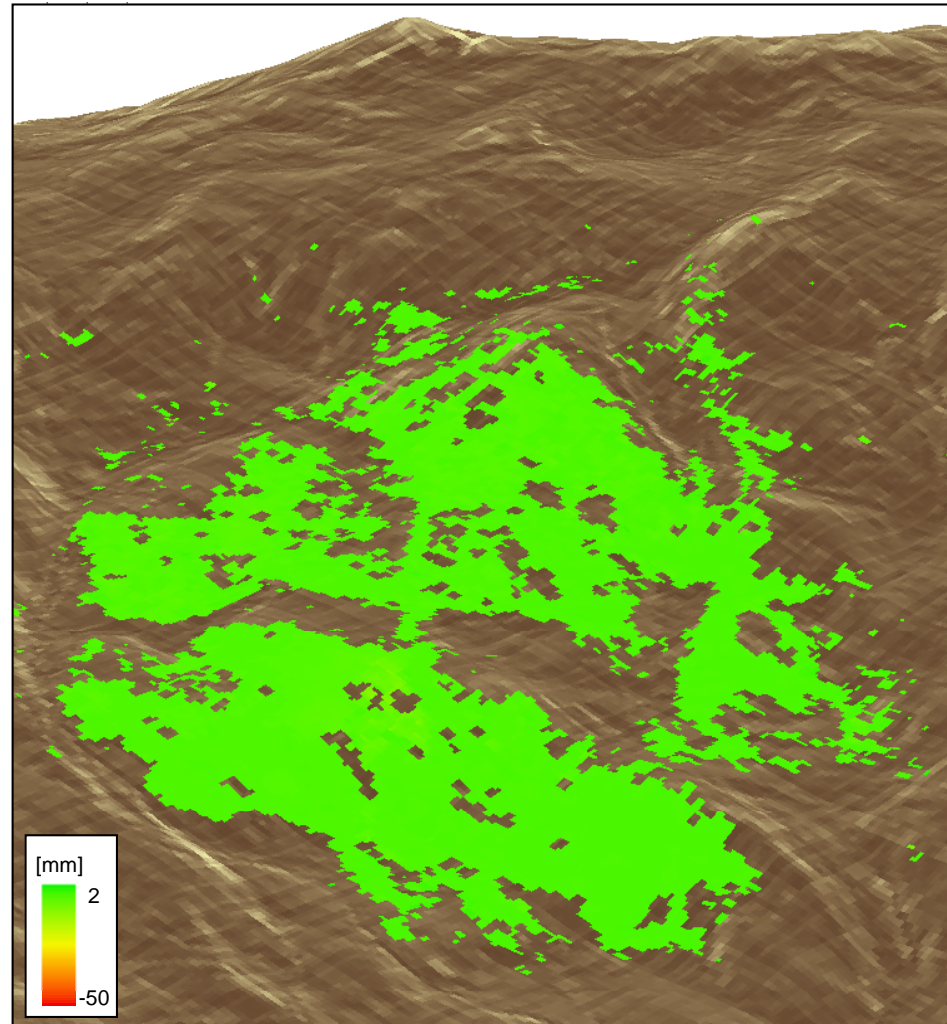


Picture taken from the radar location

More than 40.000 measurement points
are identified on the quality map

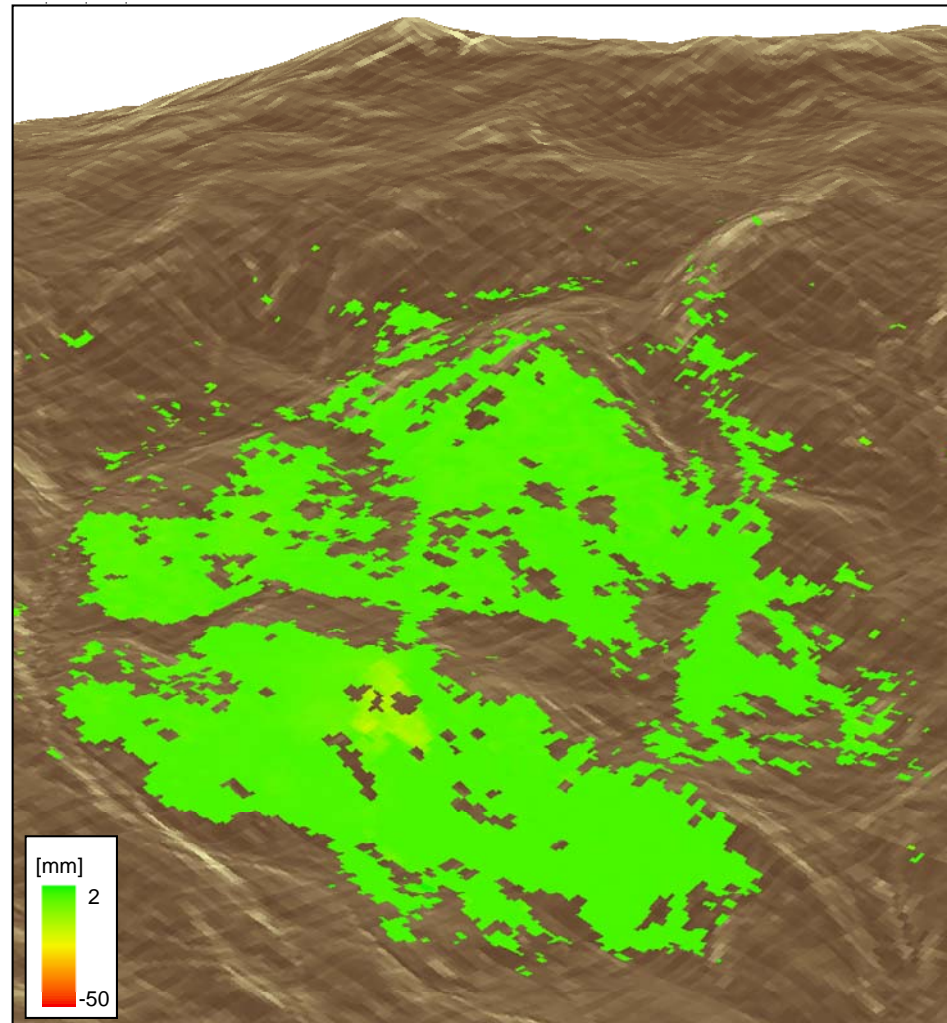
Geocoded cumulative displacement map (1 h)

Geocoded Line Of Sight Displacement Map



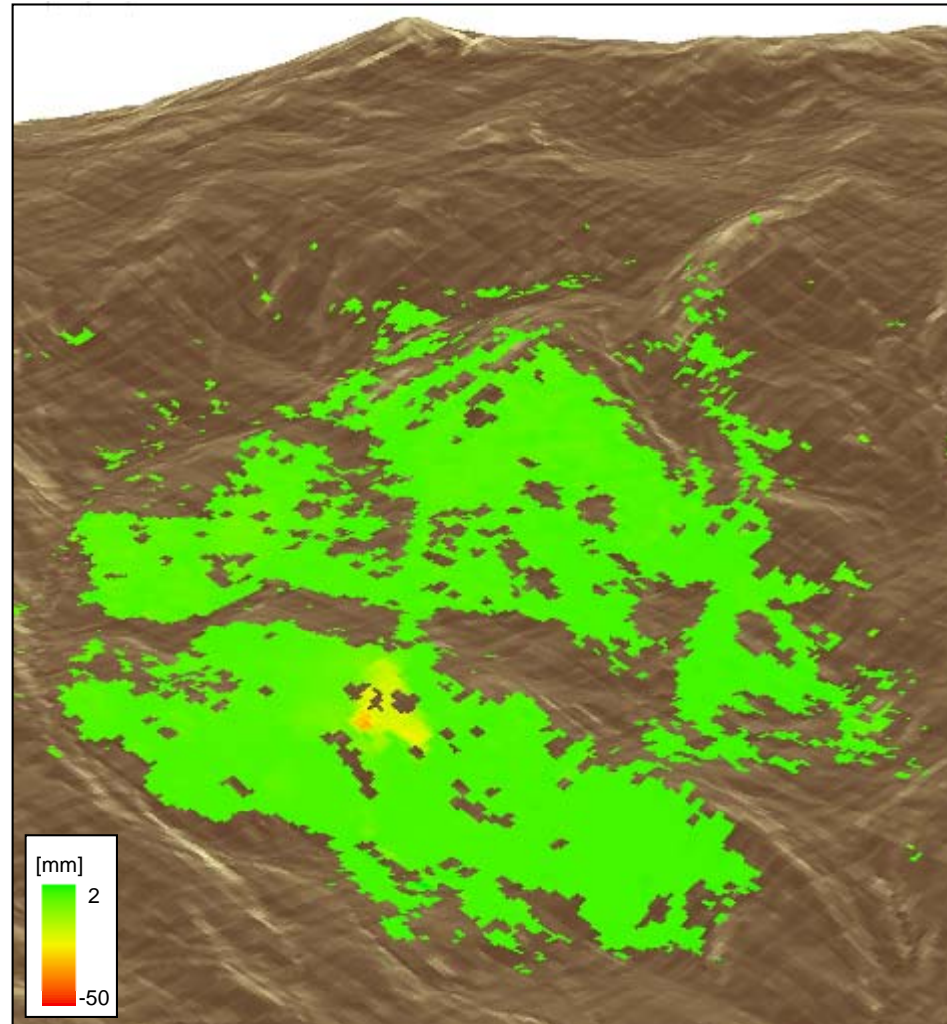
Geocoded cumulative displacement map (2 h)

Geocoded Line Of Sight Displacement Map



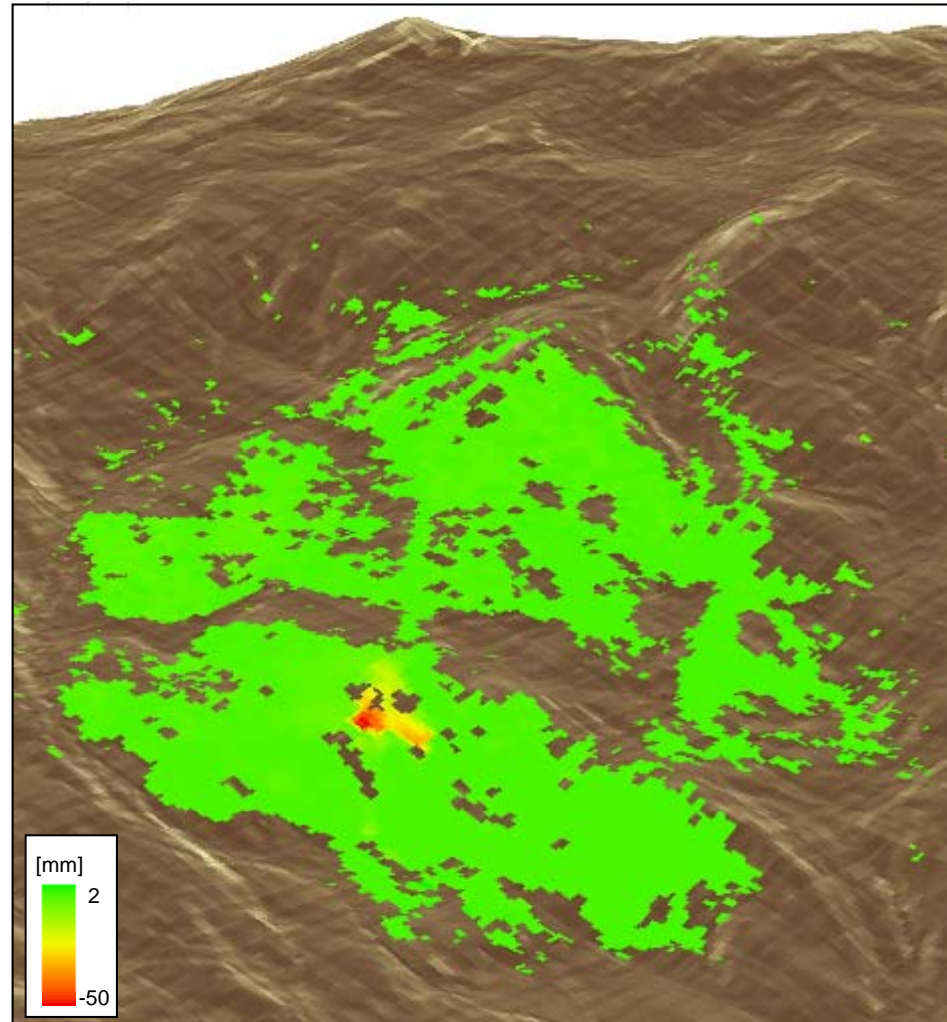
Geocoded cumulative displacement map (3 h)

Geocoded Line Of Sight Displacement Map



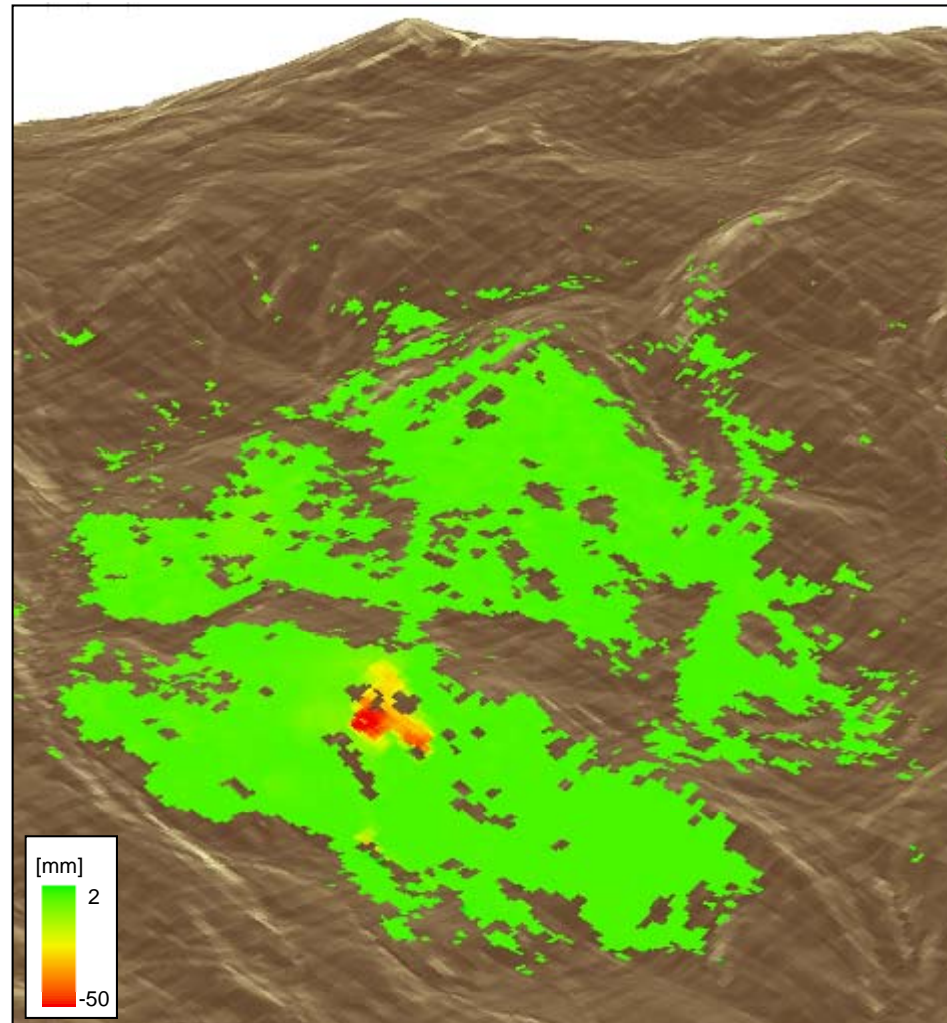
Geocoded cumulative displacement map (4 h)

Geocoded Line Of Sight Displacement Map



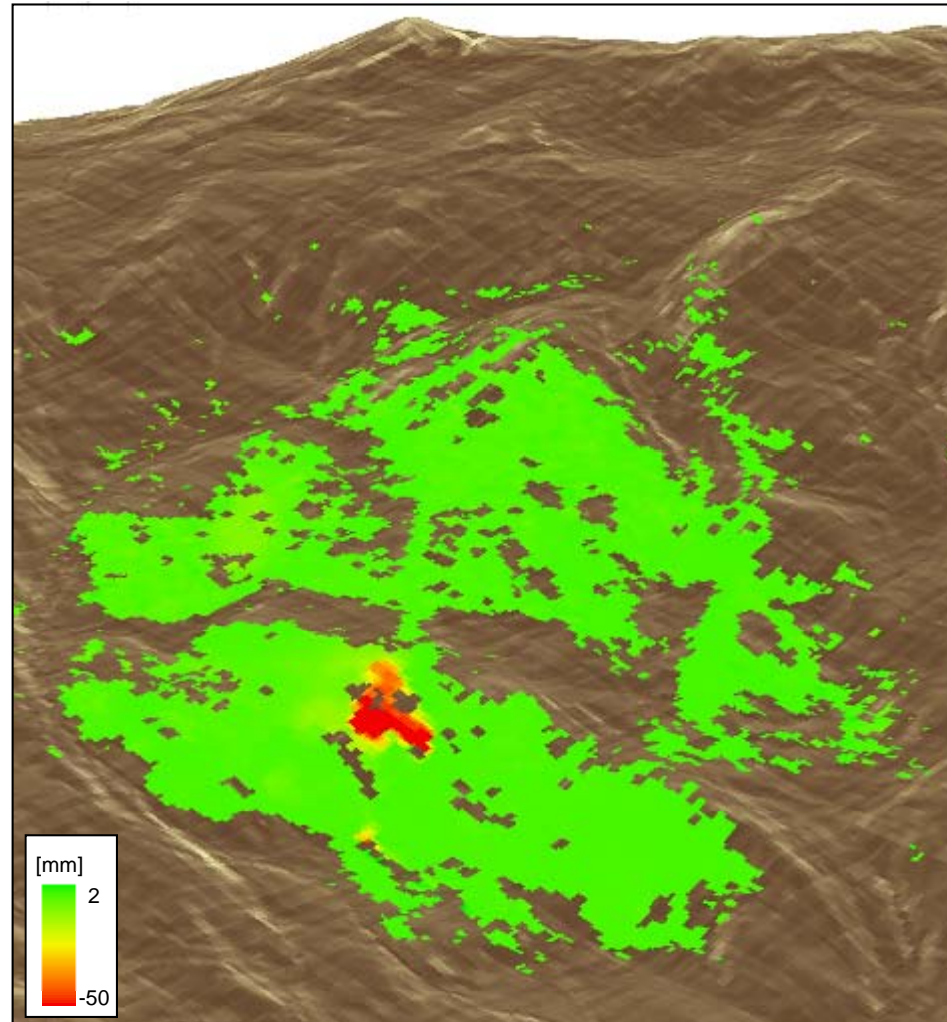
Geocoded cumulative displacement map (5 h)

Geocoded Line Of Sight Displacement Map



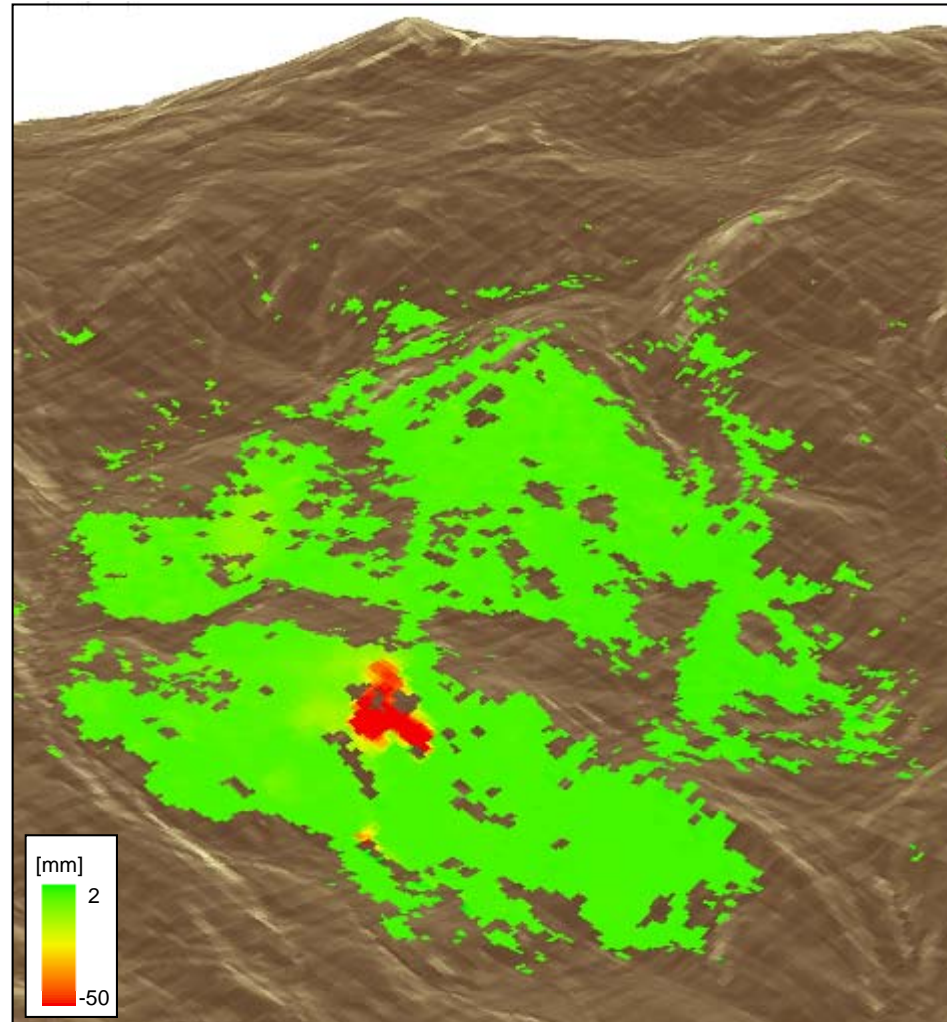
Geocoded cumulative displacement map (6 h)

Geocoded Line Of Sight Displacement Map



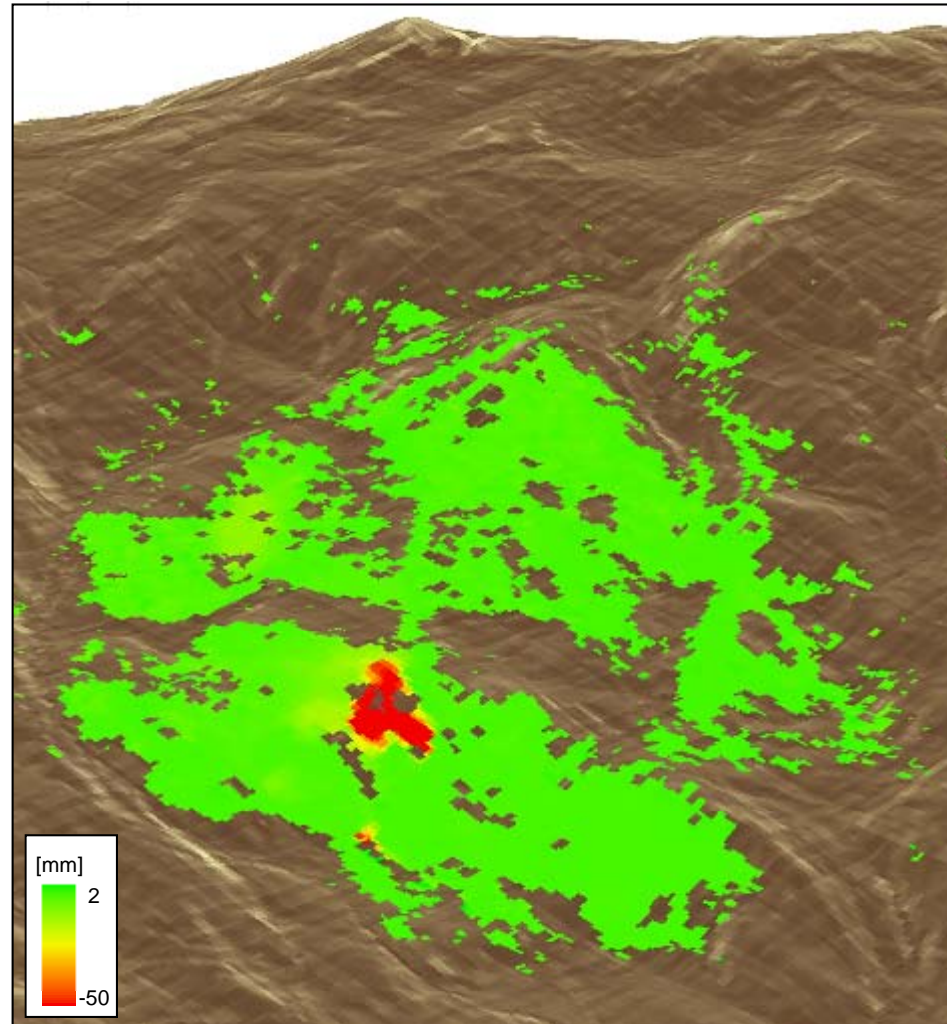
Geocoded cumulative displacement map (7 h)

Geocoded Line Of Sight Displacement Map



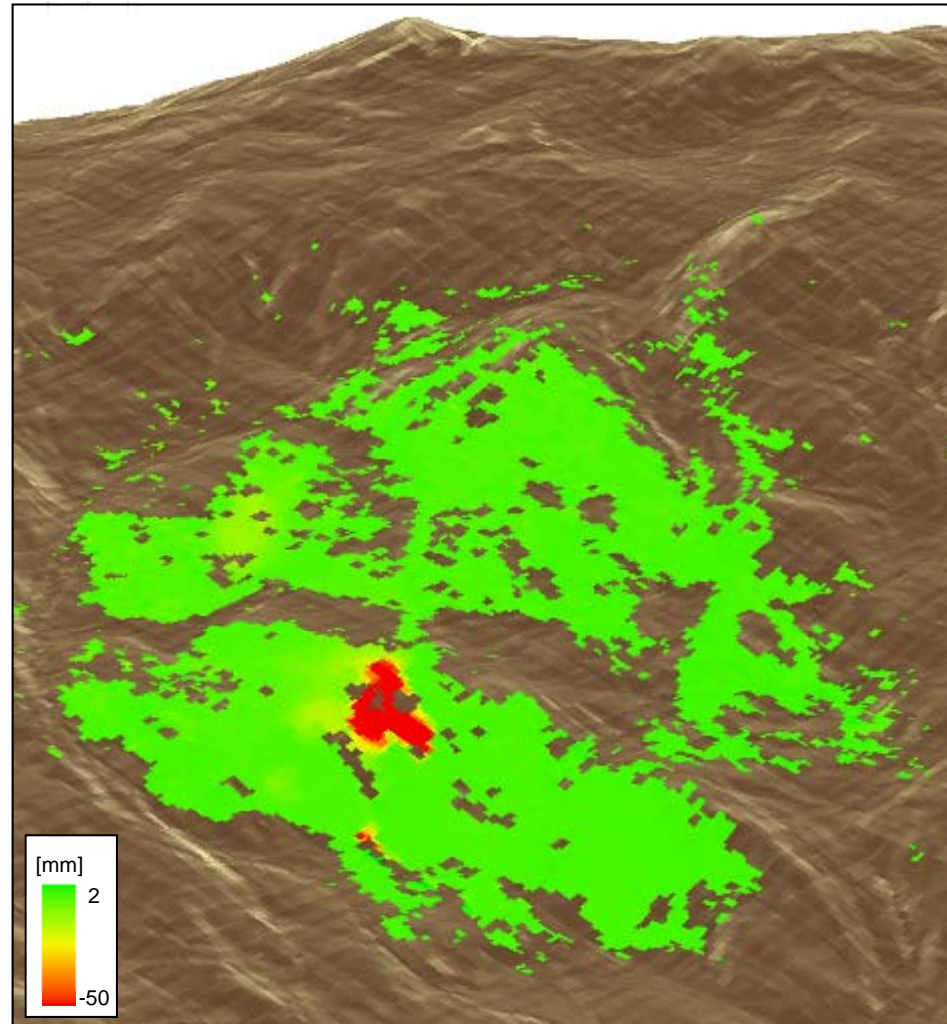
Geocoded cumulative displacement map (8 h)

Geocoded Line Of Sight Displacement Map



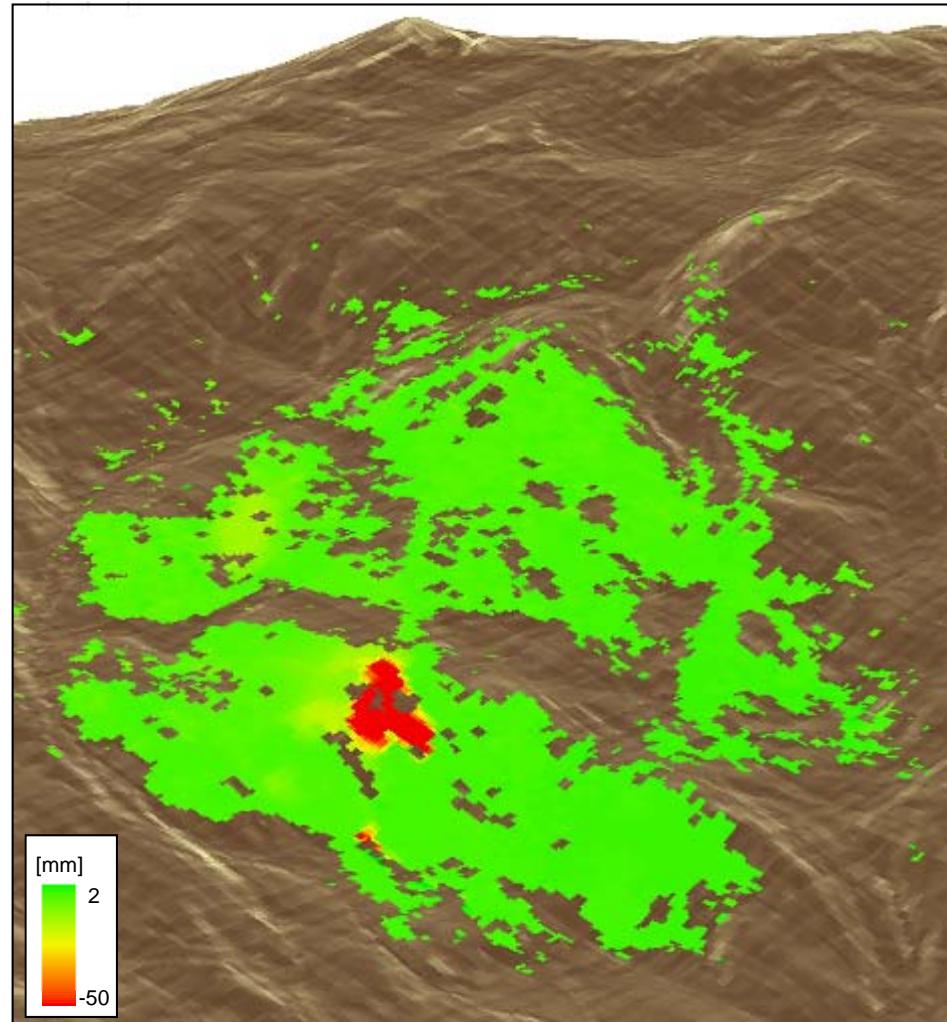
Geocoded cumulative displacement map (9 h)

Geocoded Line Of Sight Displacement Map



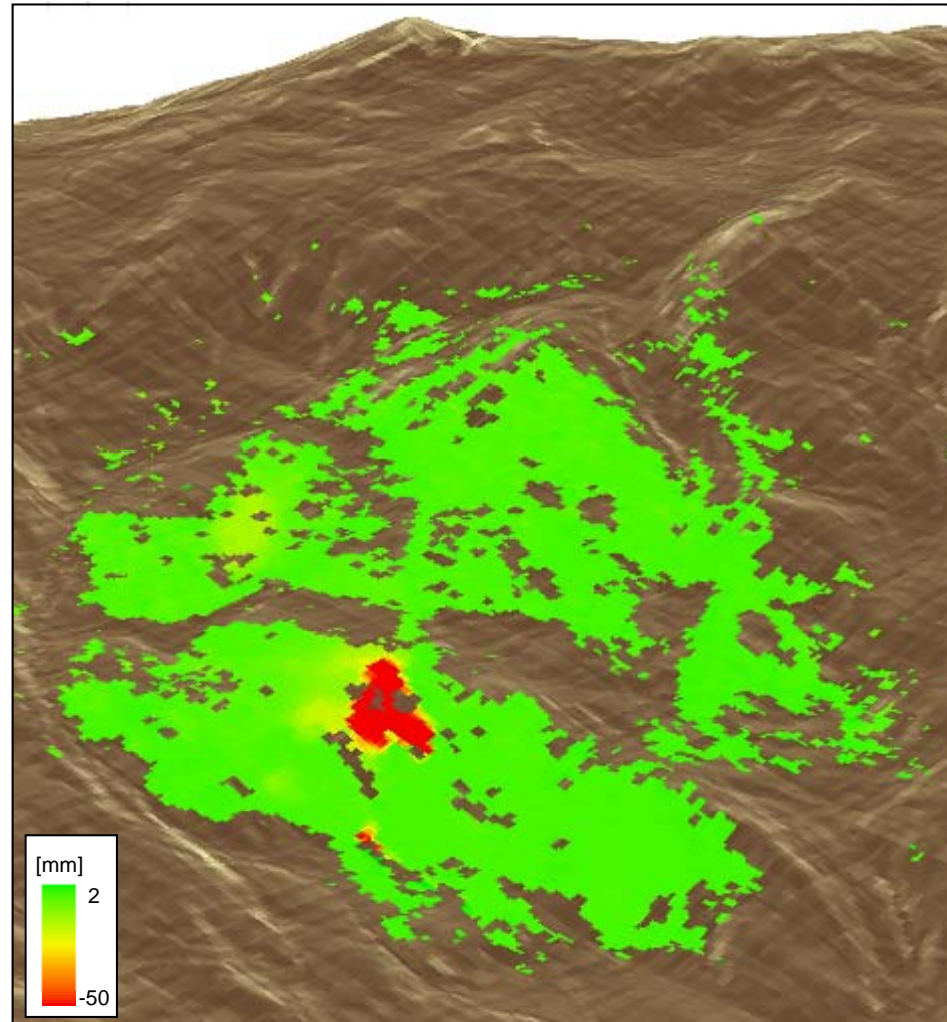
Geocoded cumulative displacement map (10 h)

Geocoded Line Of Sight Displacement Map



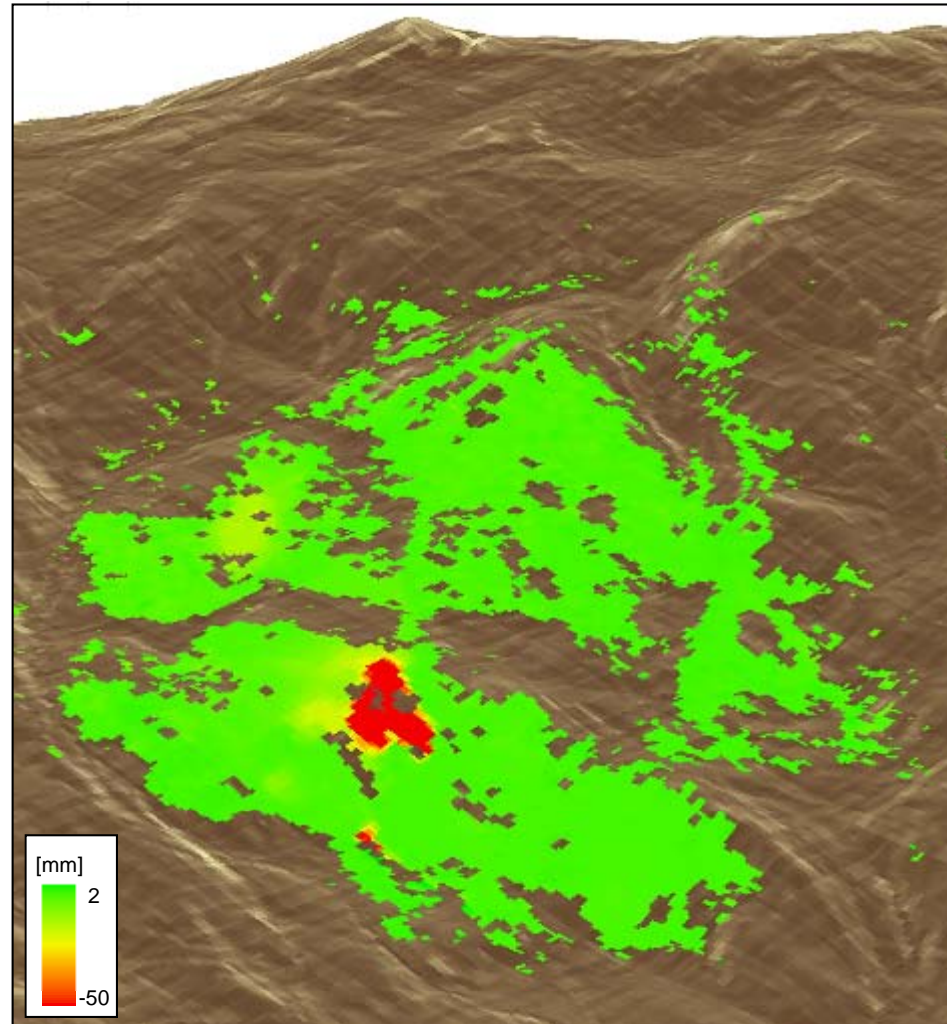
Geocoded cumulative displacement map (11 h)

Geocoded Line Of Sight Displacement Map



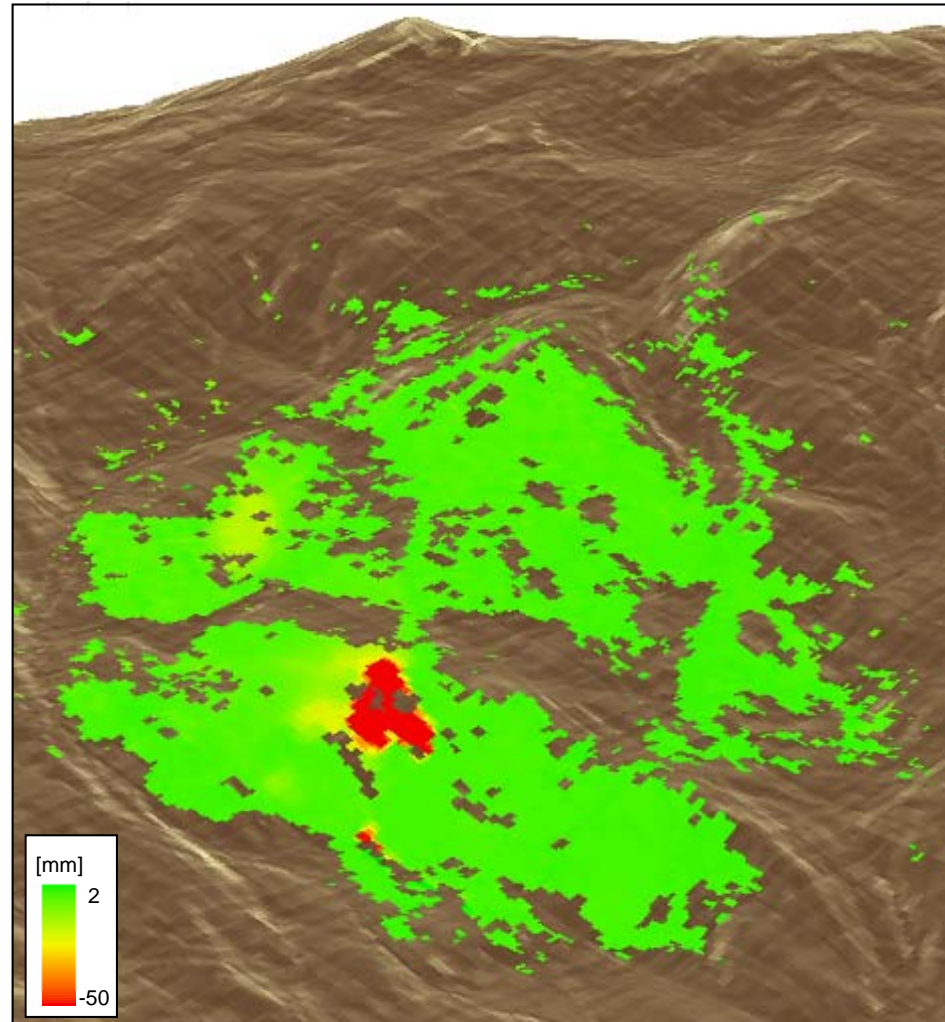
Geocoded cumulative displacement map (12 h)

Geocoded Line Of Sight Displacement Map



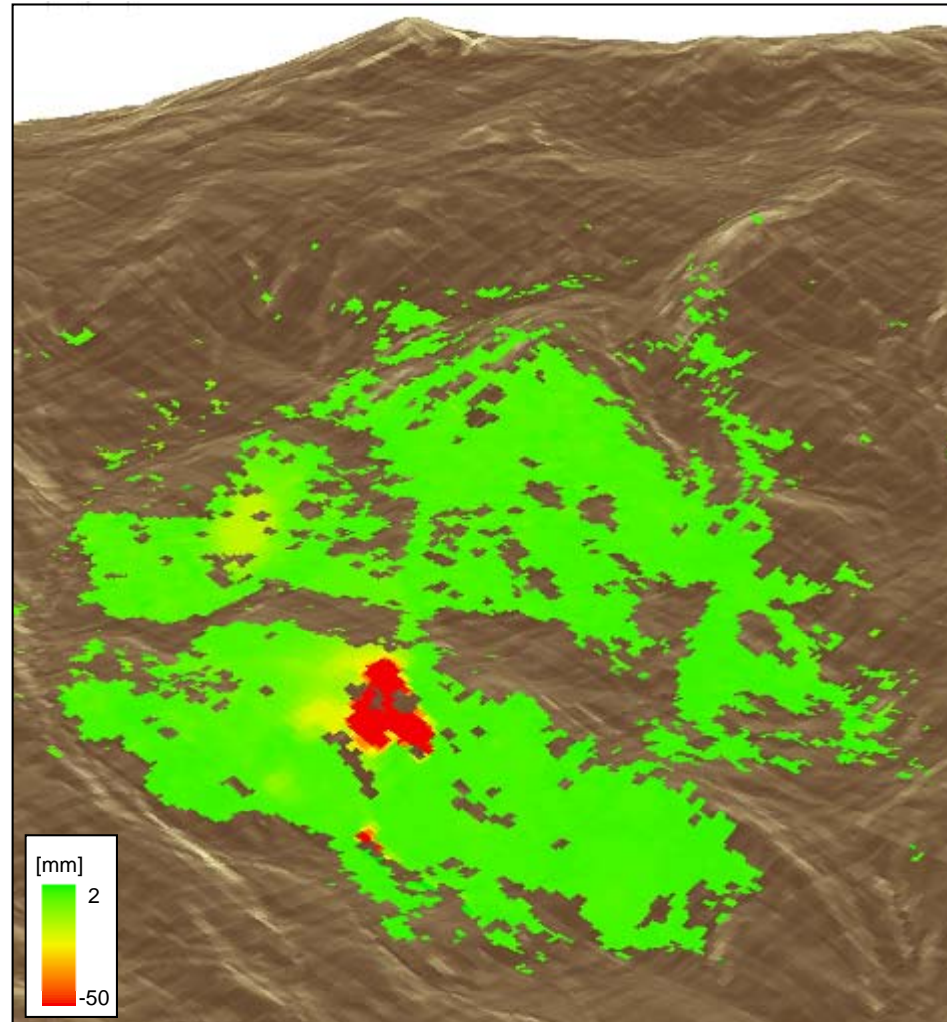
Geocoded cumulative displacement map (13 h)

Geocoded Line Of Sight Displacement Map



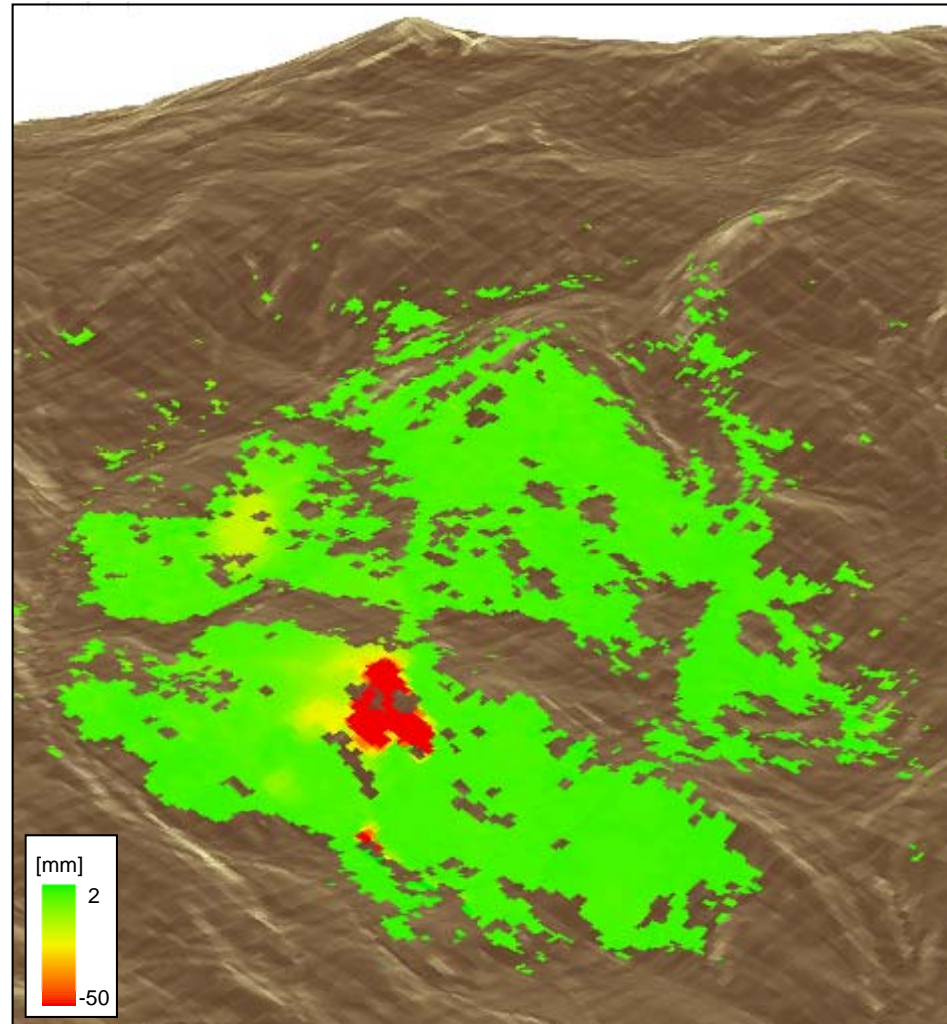
Geocoded cumulative displacement map (14 h)

Geocoded Line Of Sight Displacement Map



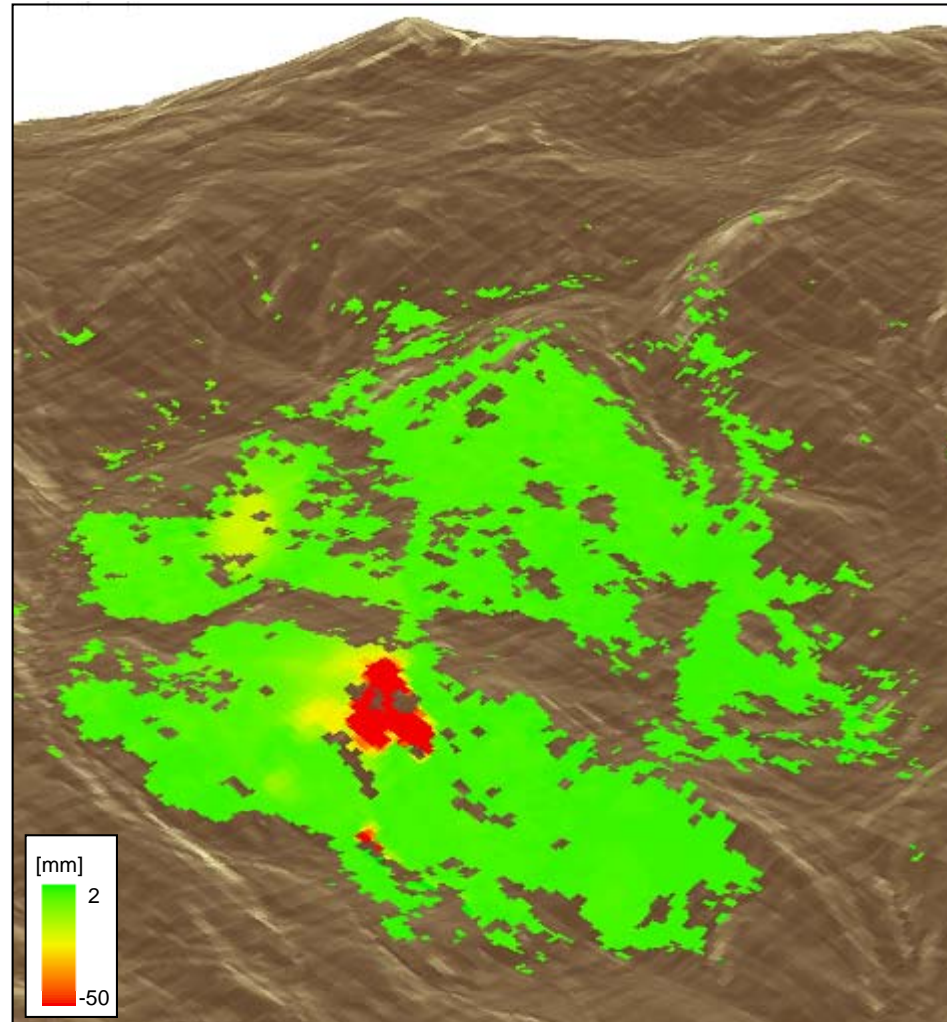
Geocoded cumulative displacement map (15 h)

Geocoded Line Of Sight Displacement Map



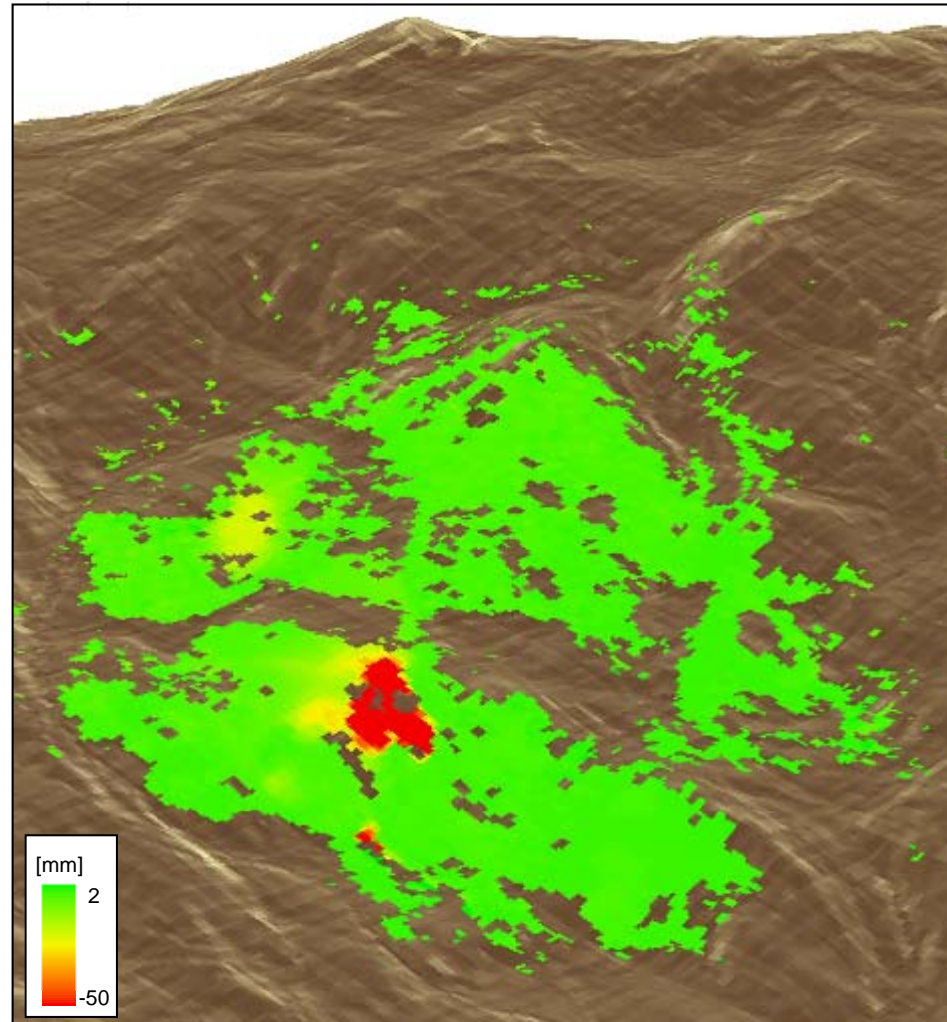
Geocoded cumulative displacement map (16 h)

Geocoded Line Of Sight Displacement Map



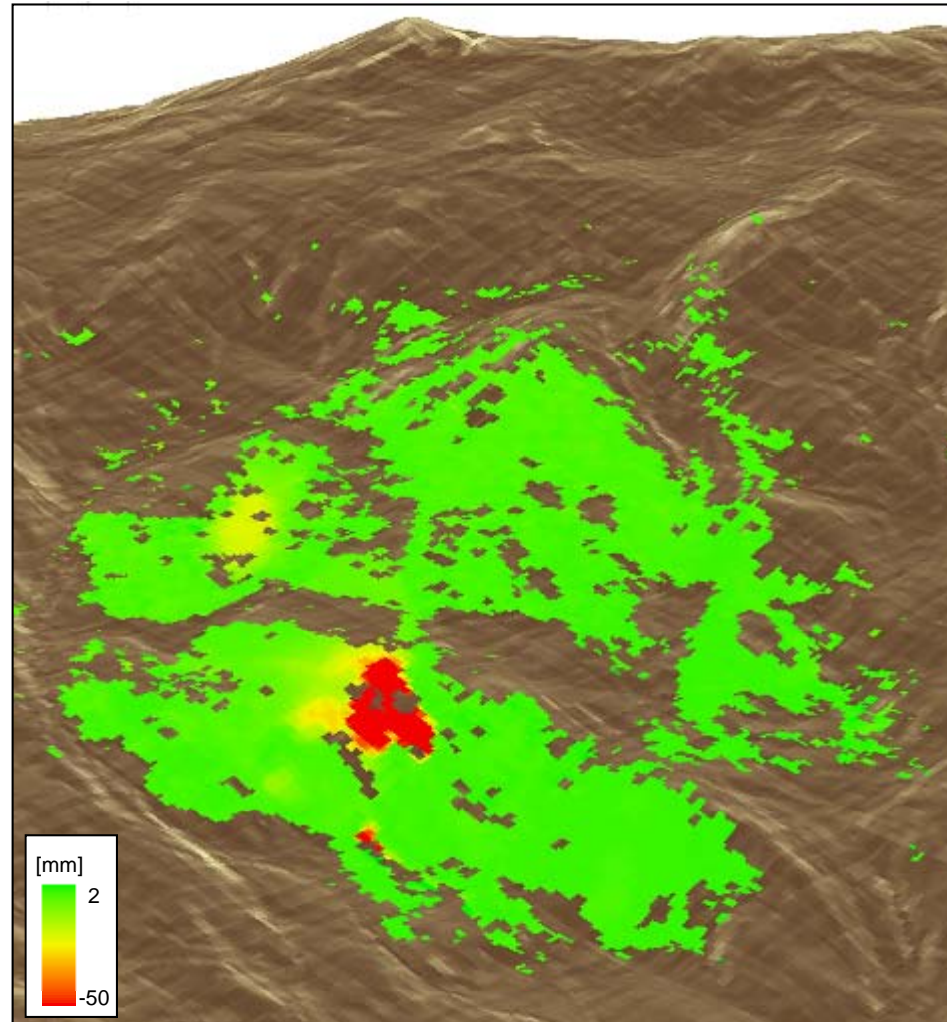
Geocoded cumulative displacement map (17 h)

Geocoded Line Of Sight Displacement Map



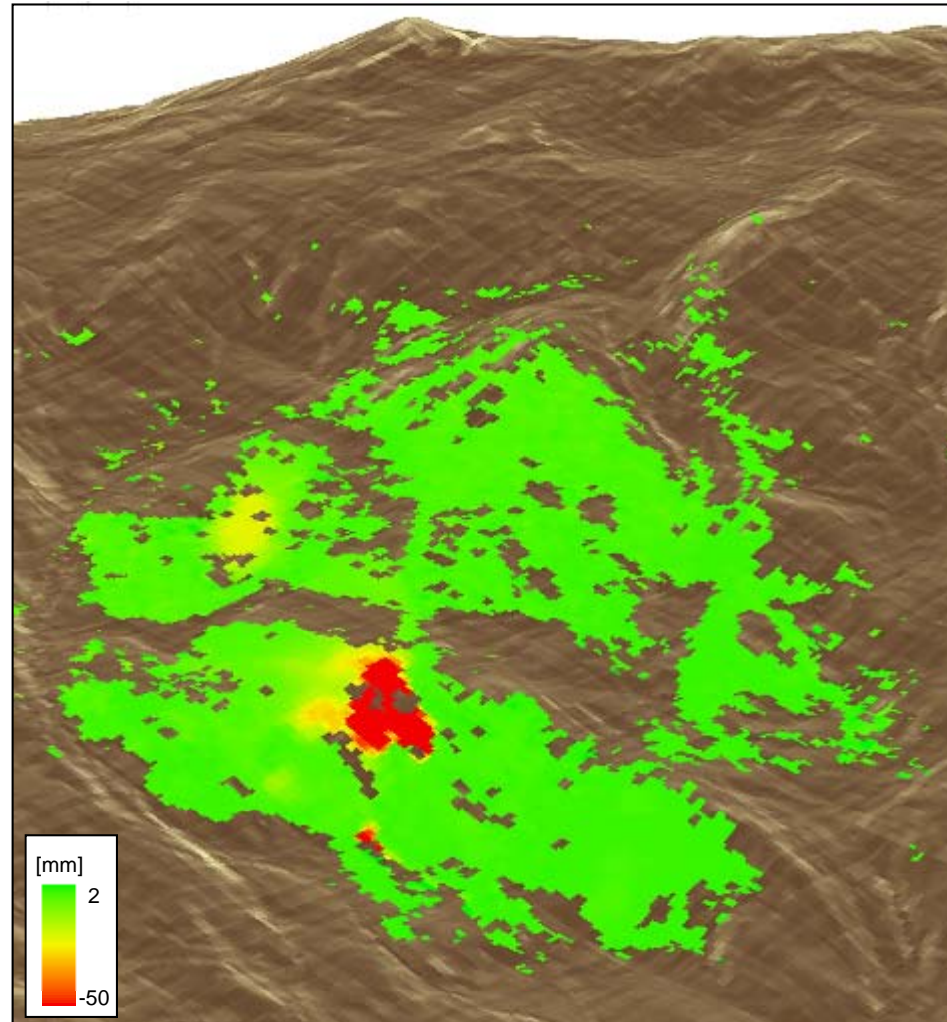
Geocoded cumulative displacement map (18 h)

Geocoded Line Of Sight Displacement Map



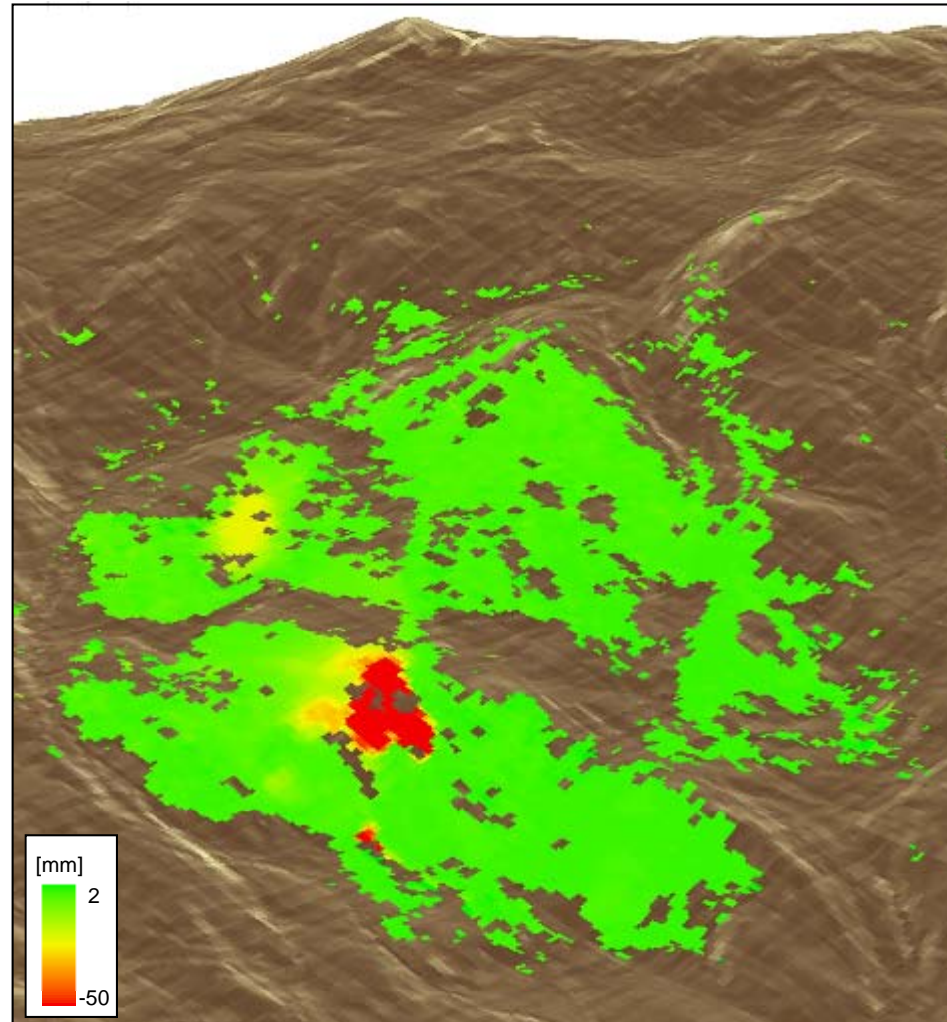
Geocoded cumulative displacement map (19 h)

Geocoded Line Of Sight Displacement Map



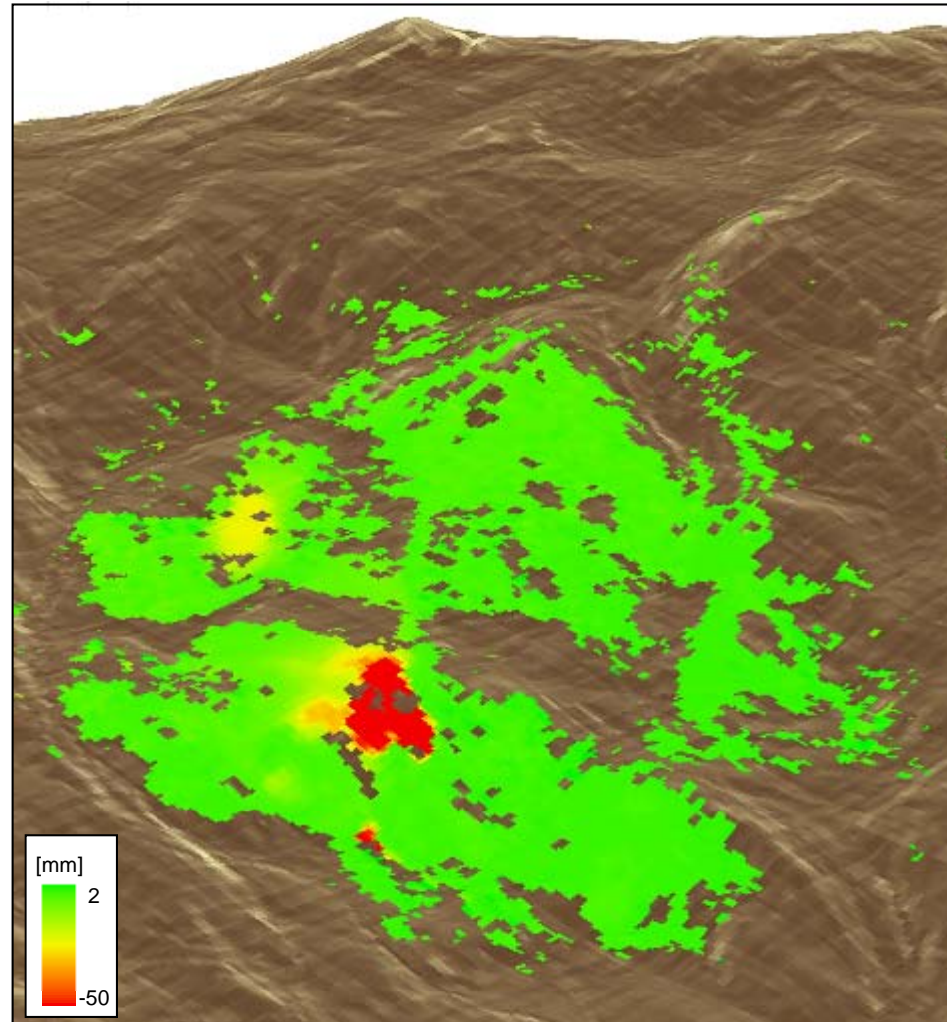
Geocoded cumulative displacement map (20 h)

Geocoded Line Of Sight Displacement Map



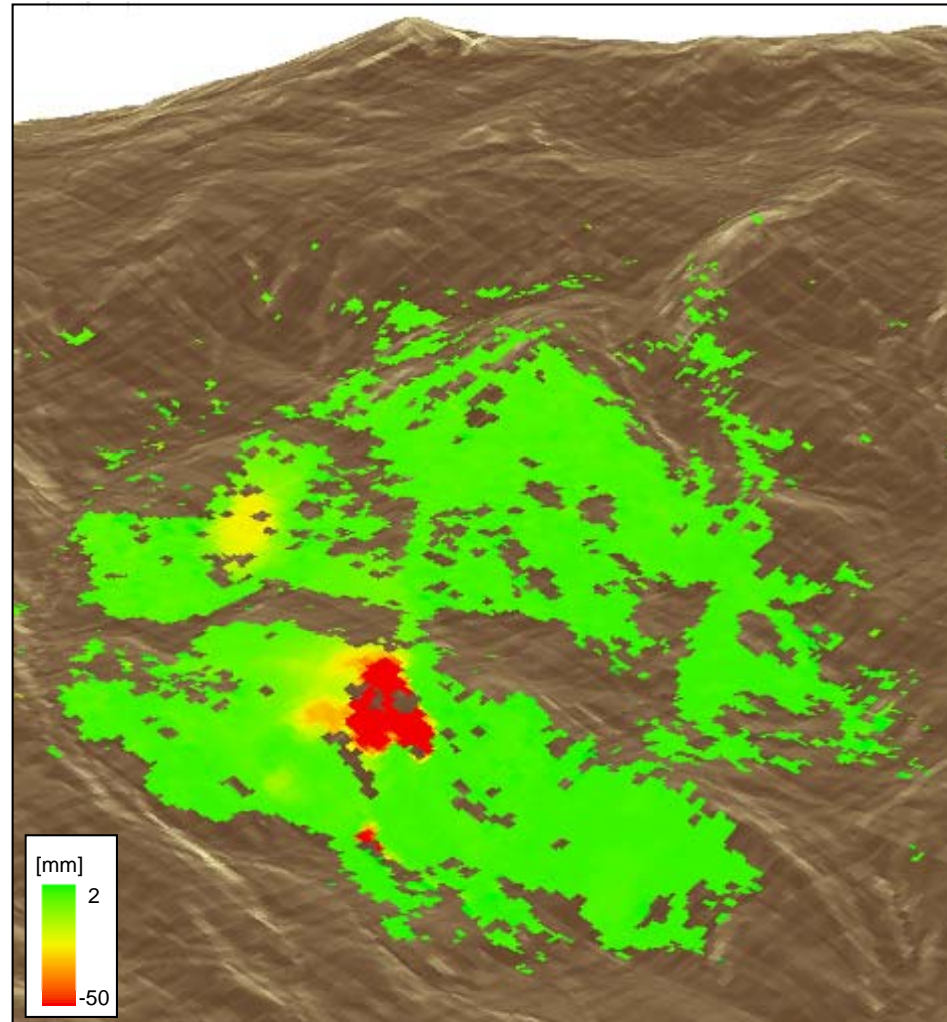
Geocoded cumulative displacement map (21 h)

Geocoded Line Of Sight Displacement Map



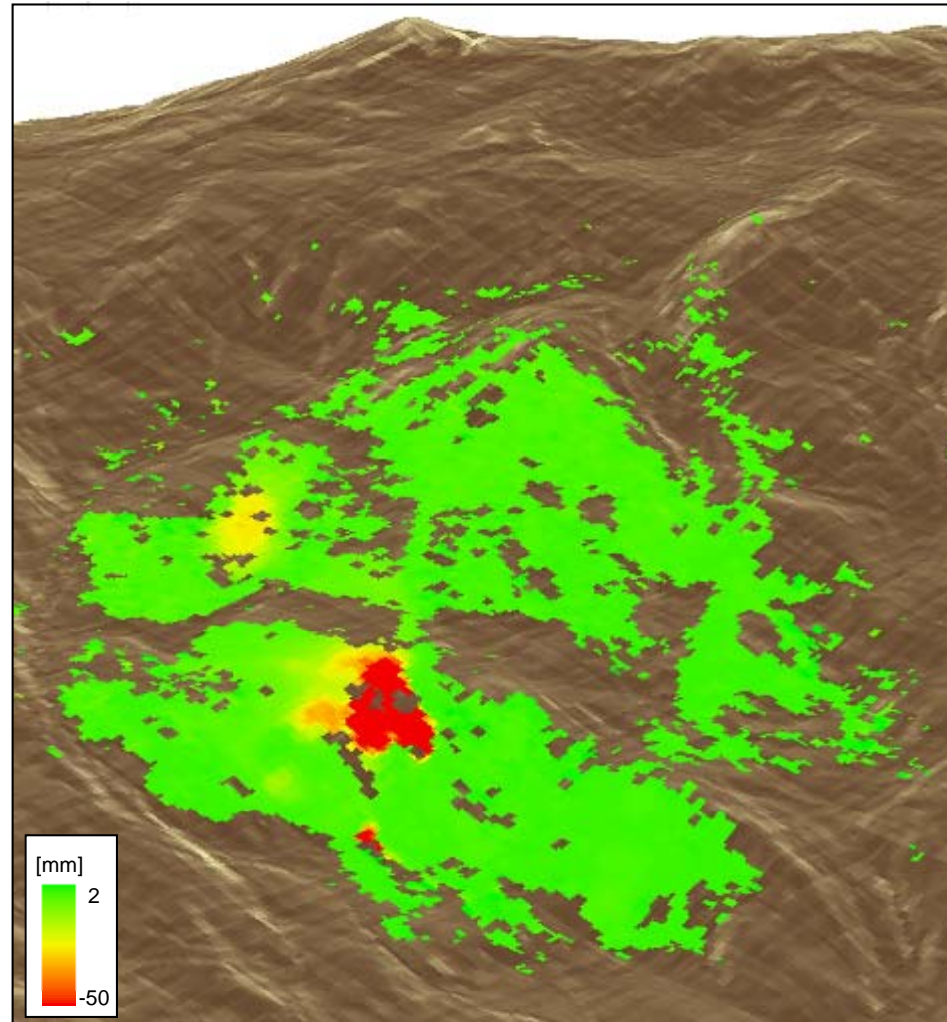
Geocoded cumulative displacement map (22 h)

Geocoded Line Of Sight Displacement Map



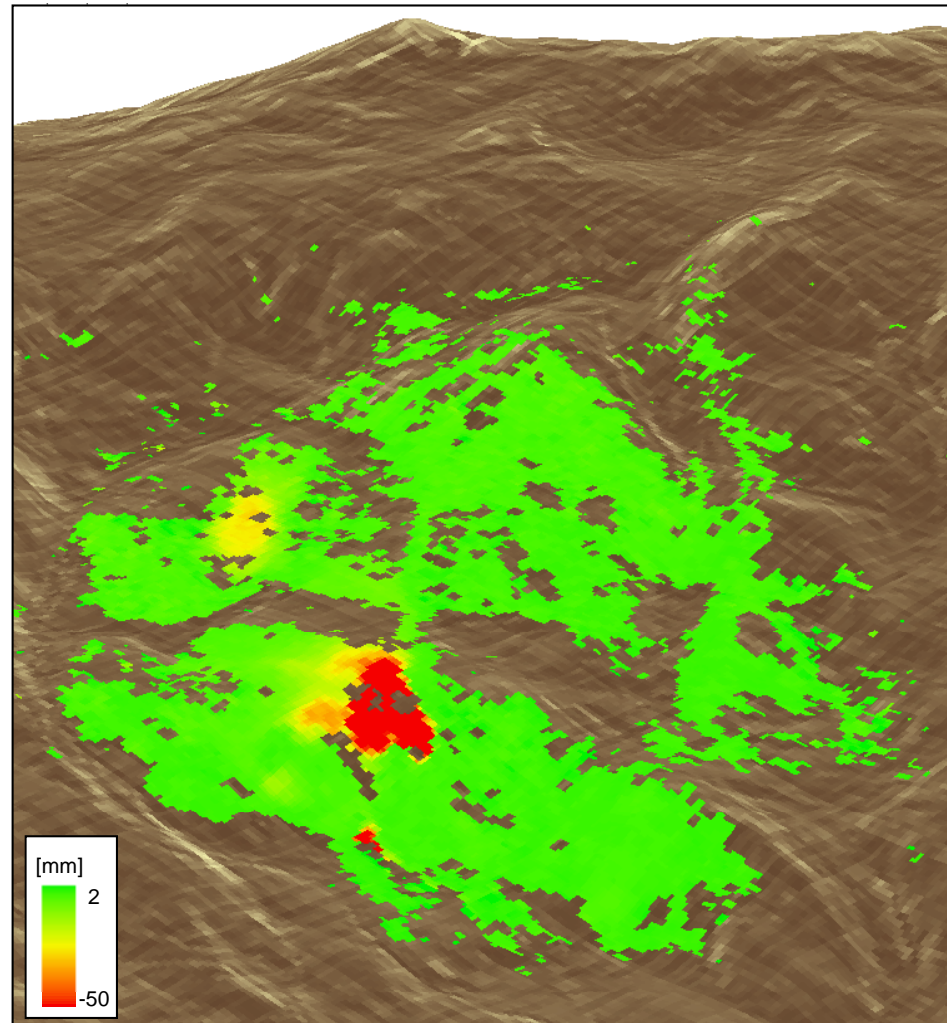
Geocoded cumulative displacement map (23 h)

Geocoded Line Of Sight Displacement Map



Geocoded cumulative displacement map (24 h)

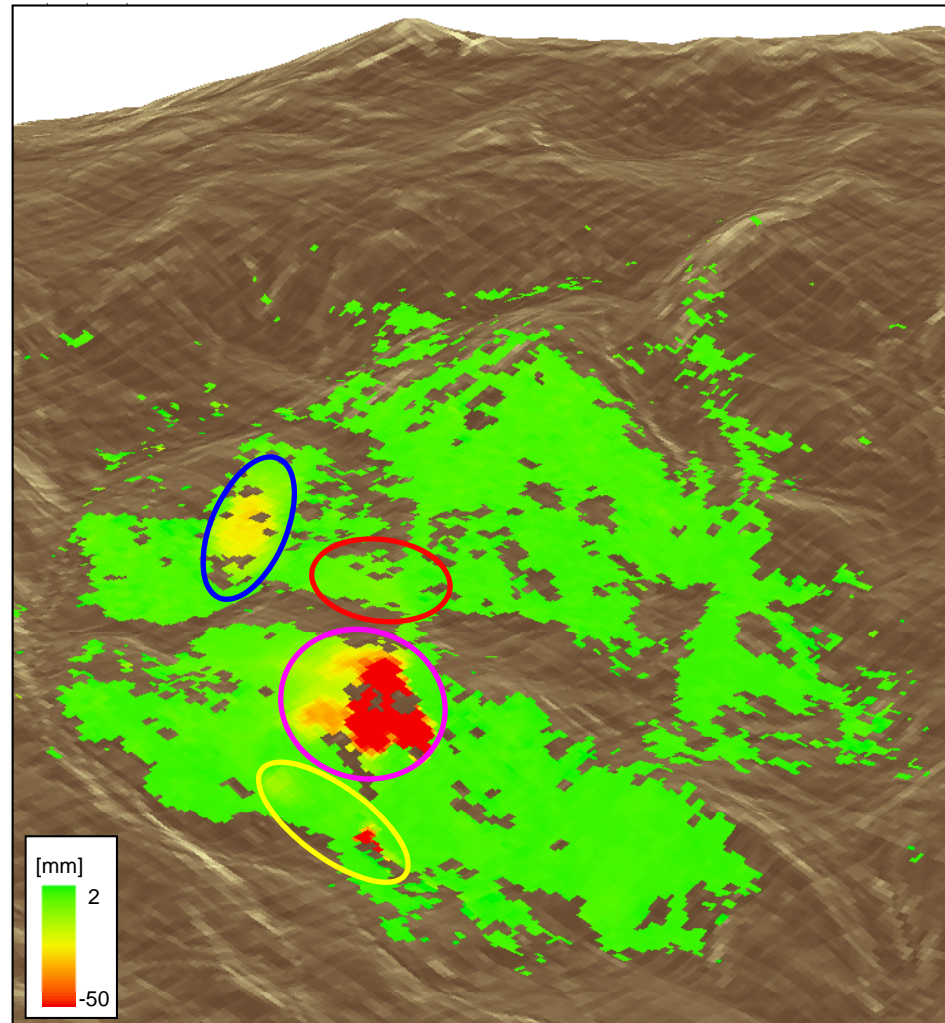
Geocoded Line Of Sight Displacement Map



Identification of moving portions of the slope

Geocoded Line Of Sight Displacement Map

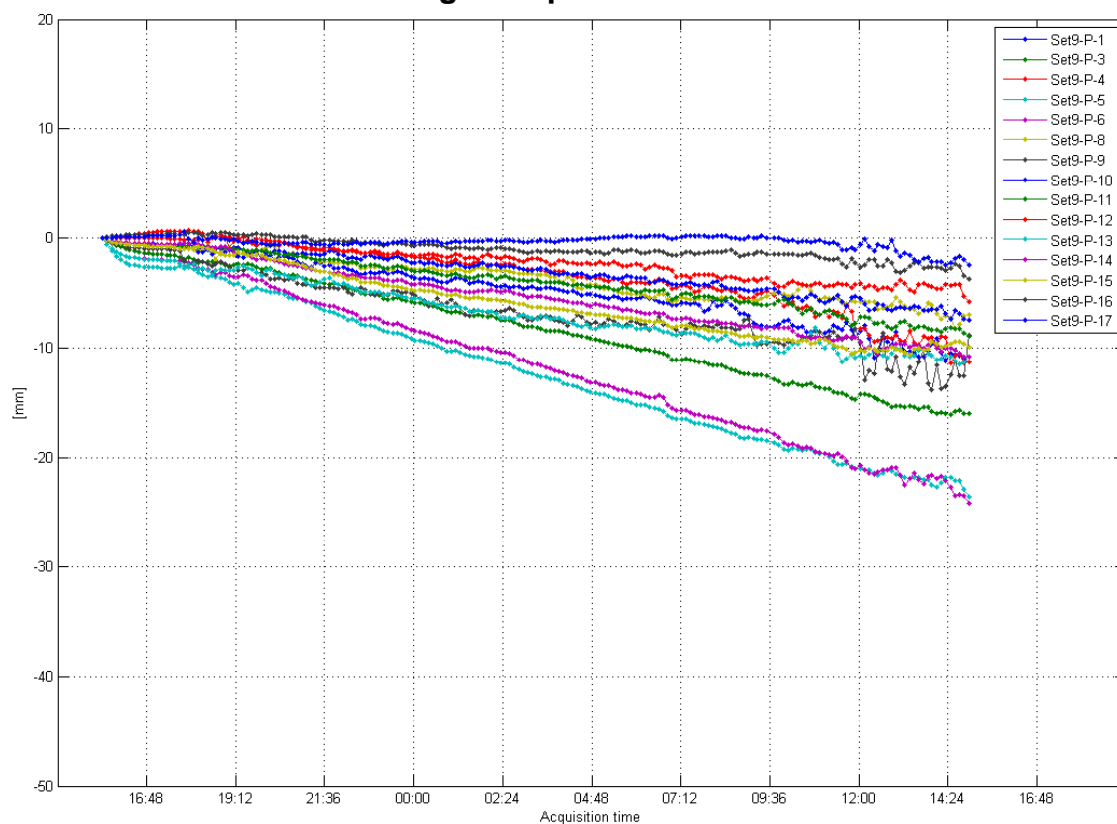
Zona A	Blue
Zona B	Magenta
Zona C	Yellow
Zona D	Red



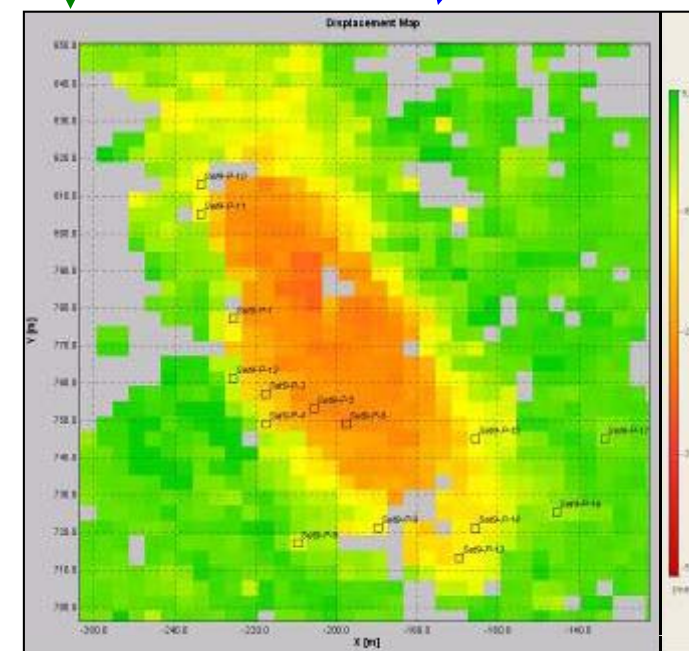
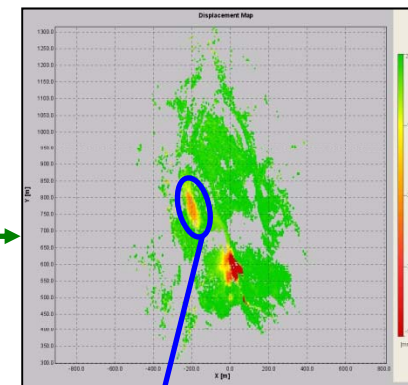
Displacement time series

ZONA A - movimento di alcuni punti di misura selezionati

Line Of Sight Displacement Time Series



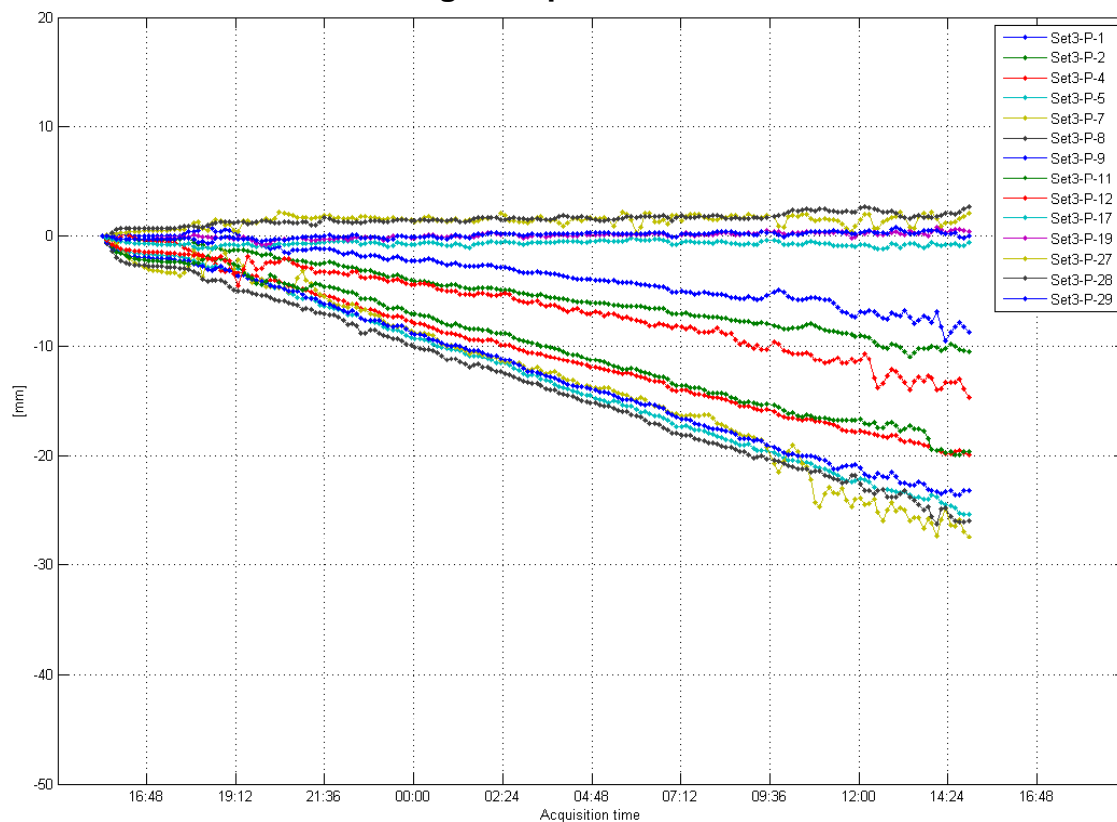
Mappe di spostamento
cumulato dopo
24 ore



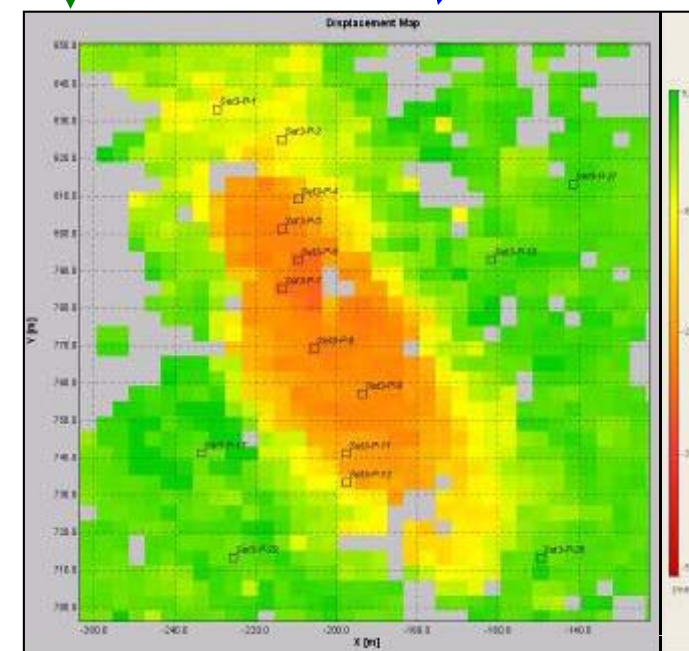
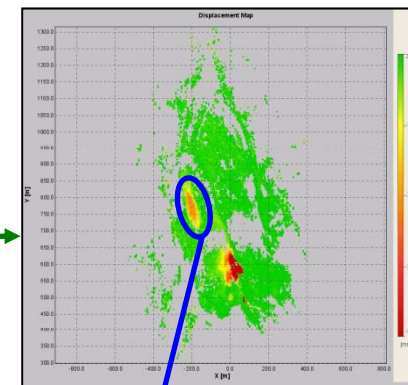
Displacement time series

ZONE A - displacement of a few points

Line Of Sight Displacement Time Series



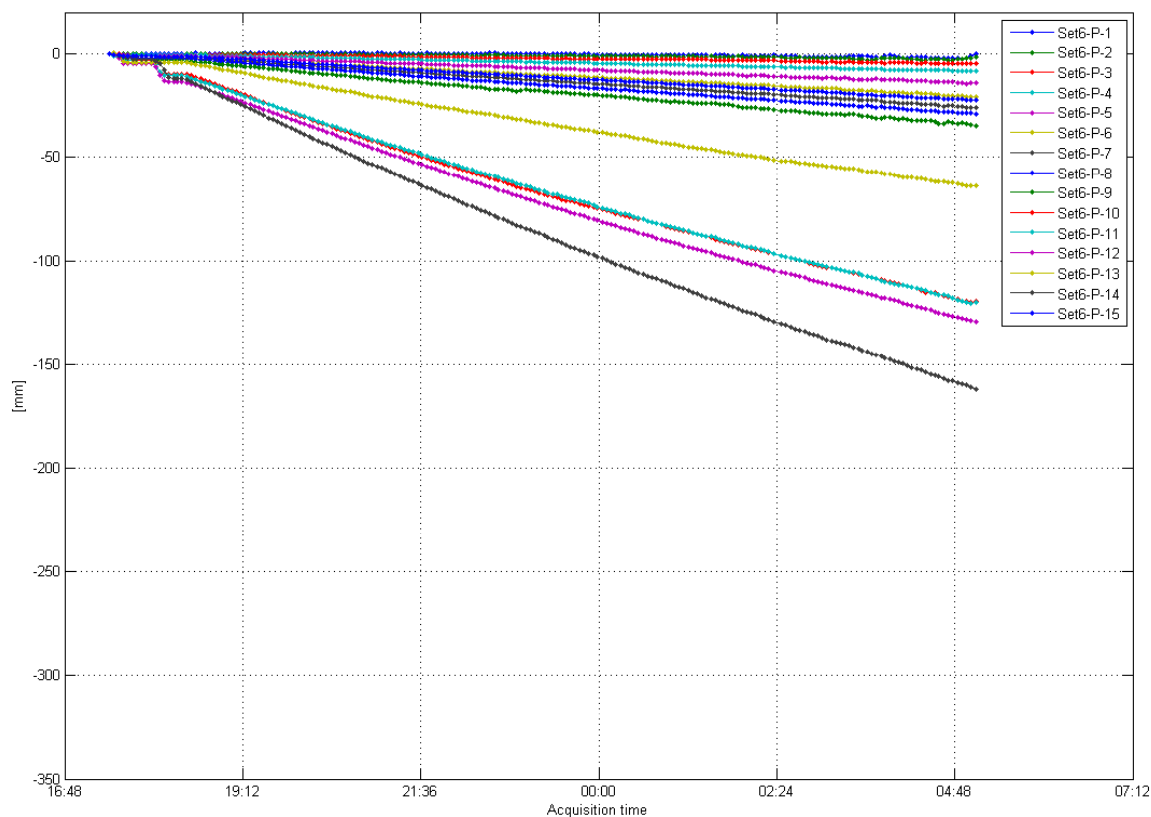
Mappe di spostamento
cumulato dopo
24 ore



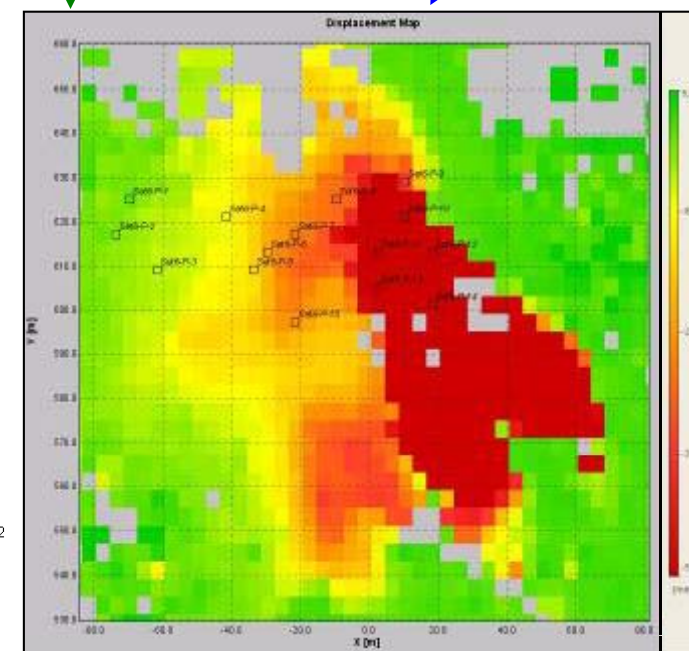
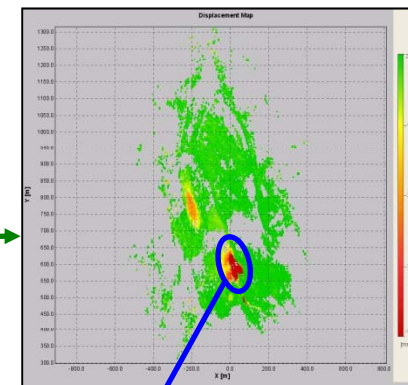
Displacement time series

ZONE B - displacement of a few points

Line Of Sight Displacement Time Series



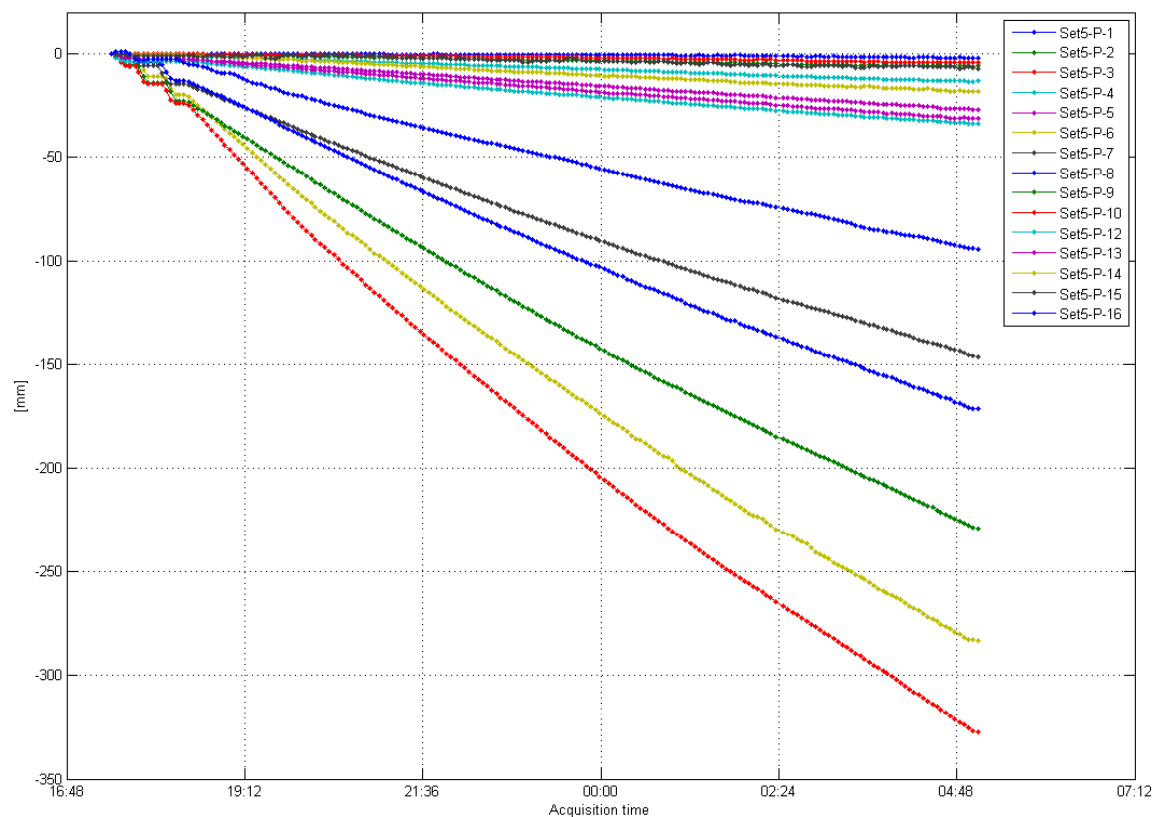
Mappe di
spostamento
cumulato dopo
24 ore



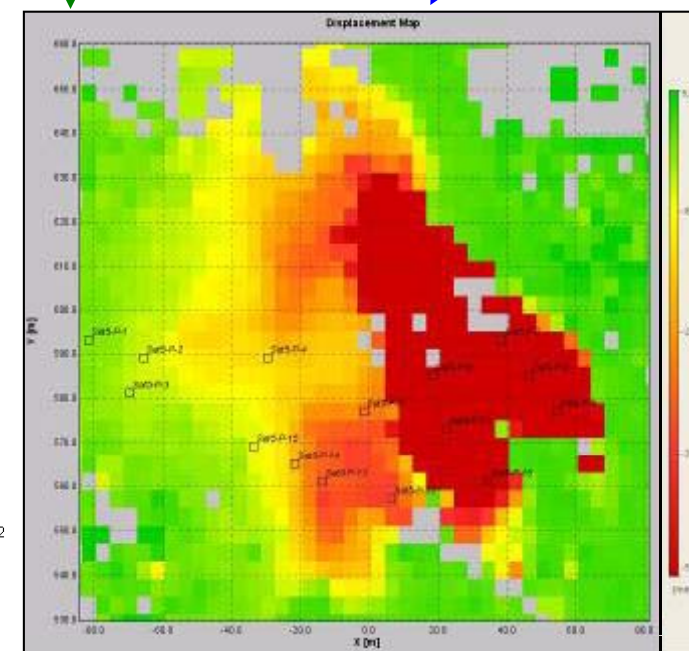
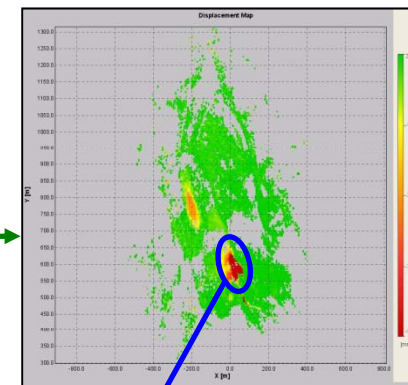
Displacement time series

ZONE C - displacement of a few points

Line Of Sight Displacement Time Series



Mappe di spostamento
cumulato dopo
24 ore



IBIS-M for open-pit mines

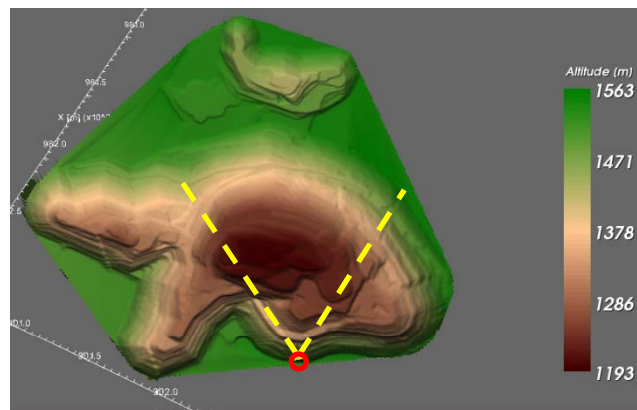


Following a 80,000 ton slip occurred in late 2009 and the consequent closure of operations, an IBIS-M unit was deployed in January 2010 at the Pipeline pit in Cortez, Nevada, owned by Barrick.

The IBIS-M system was aimed at providing early warnings and support for geotechnical evaluation purposes.

After 7 months of rental of the equipment, in July 2010, the IBIS-M unit was purchased by Barrick.

IBIS-M for open-pit mines



DISTANCE FROM THE SLOPE	[m]	800 – 1500
ANTENNA BEAM WIDTH	[deg]	68
NUMBER OF POINTS	-	90.000
RANGE RESOLUTION	[m]	0.5 (1.64 ft)
CROSS-RANGE RESOLUTION	[mrad]	4.5
SCANNING TIME	[min]	5

IBIS-M set-up

Shelter (pit rim)

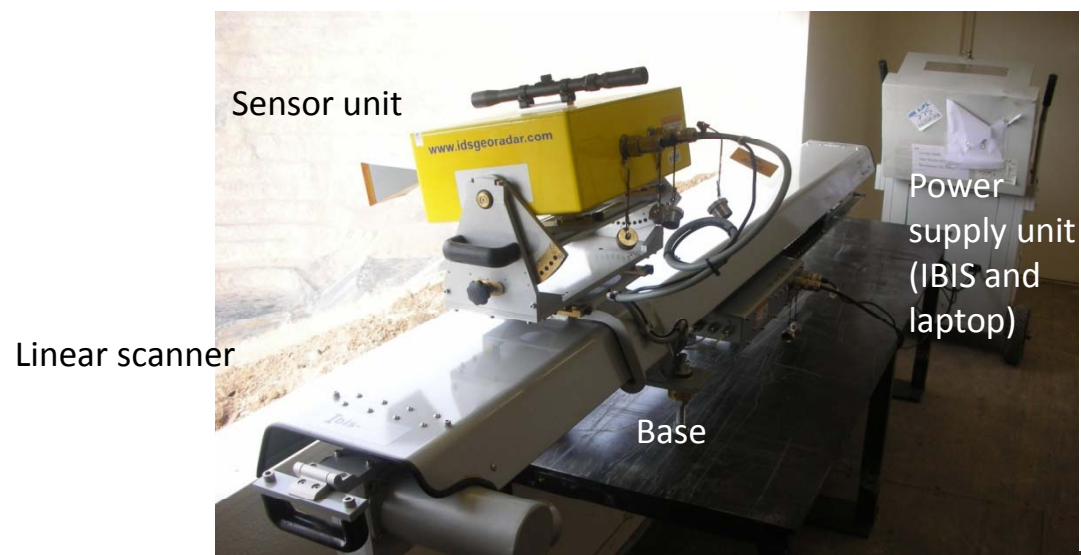
IBIS-M basic configuration unit
Fully enclosed (HVAC, WiFi)
Mine grid power supply
Backup power (1 day with genset)
IBIS Controller Software
24/7 functioning



VPN, VNC
connections

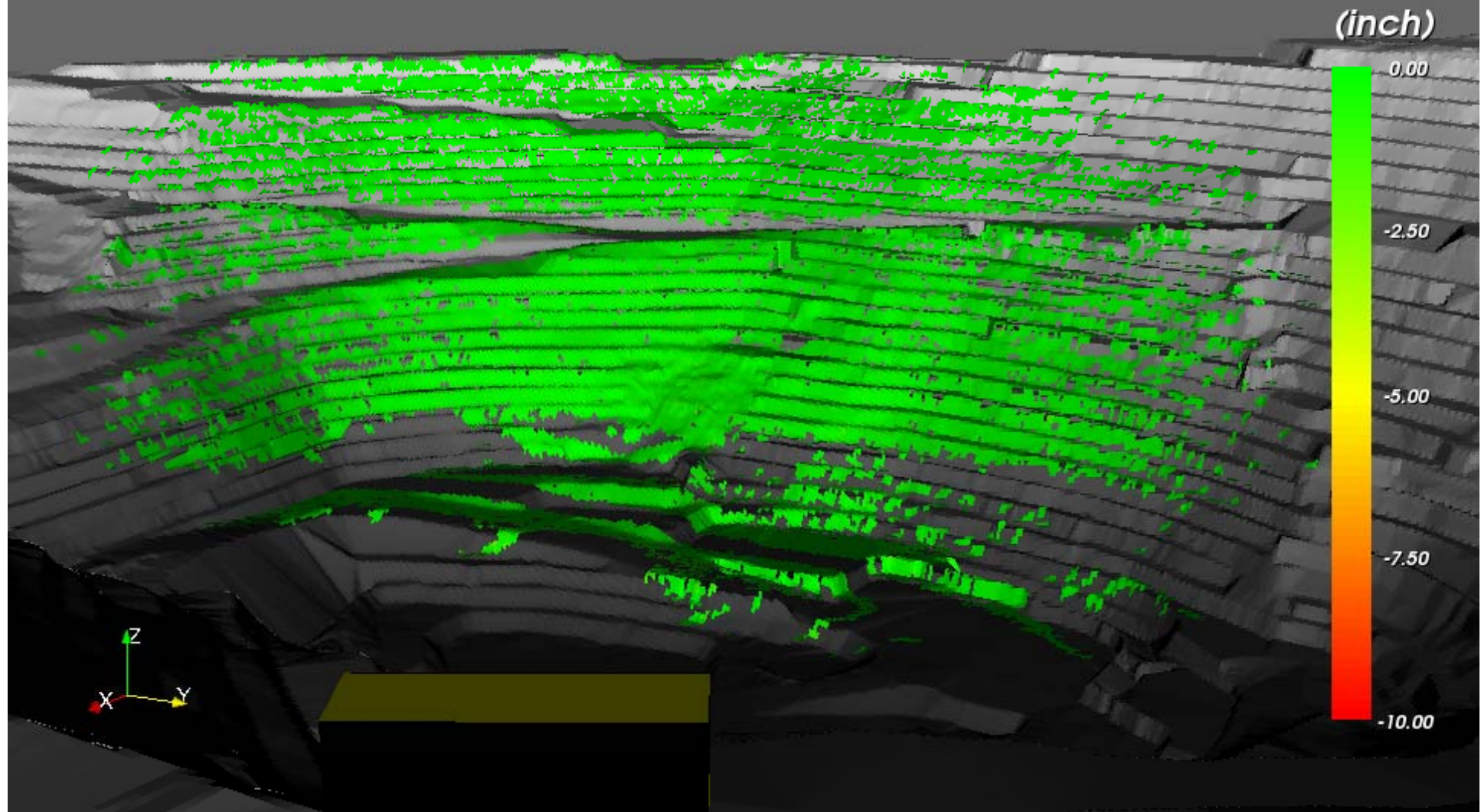


IBIS-M set-up



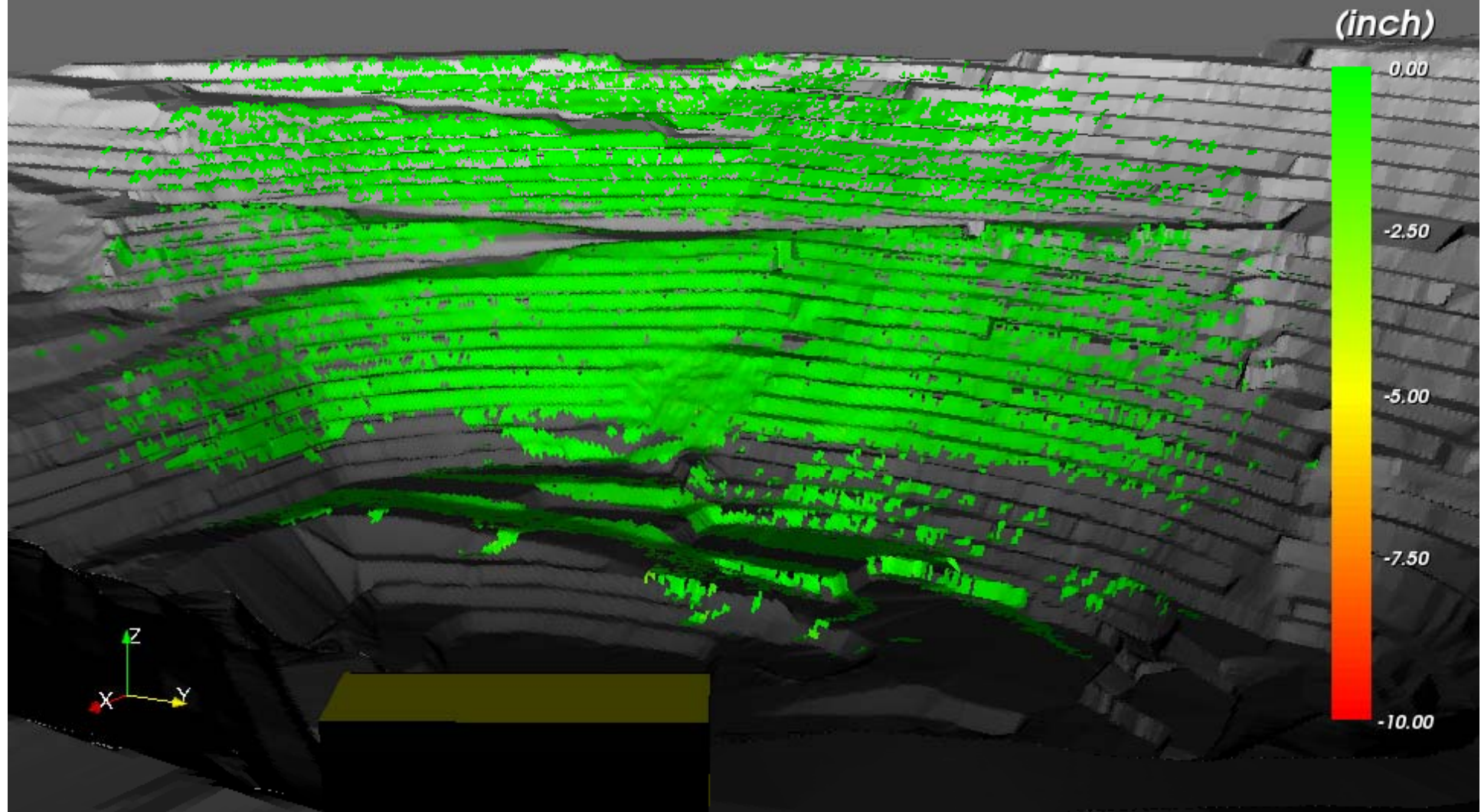
Start Time: 15:33 03/02/10
Stop Time: 14:36 18/02/10

Cumulative displacement from 03/02 to 18/02



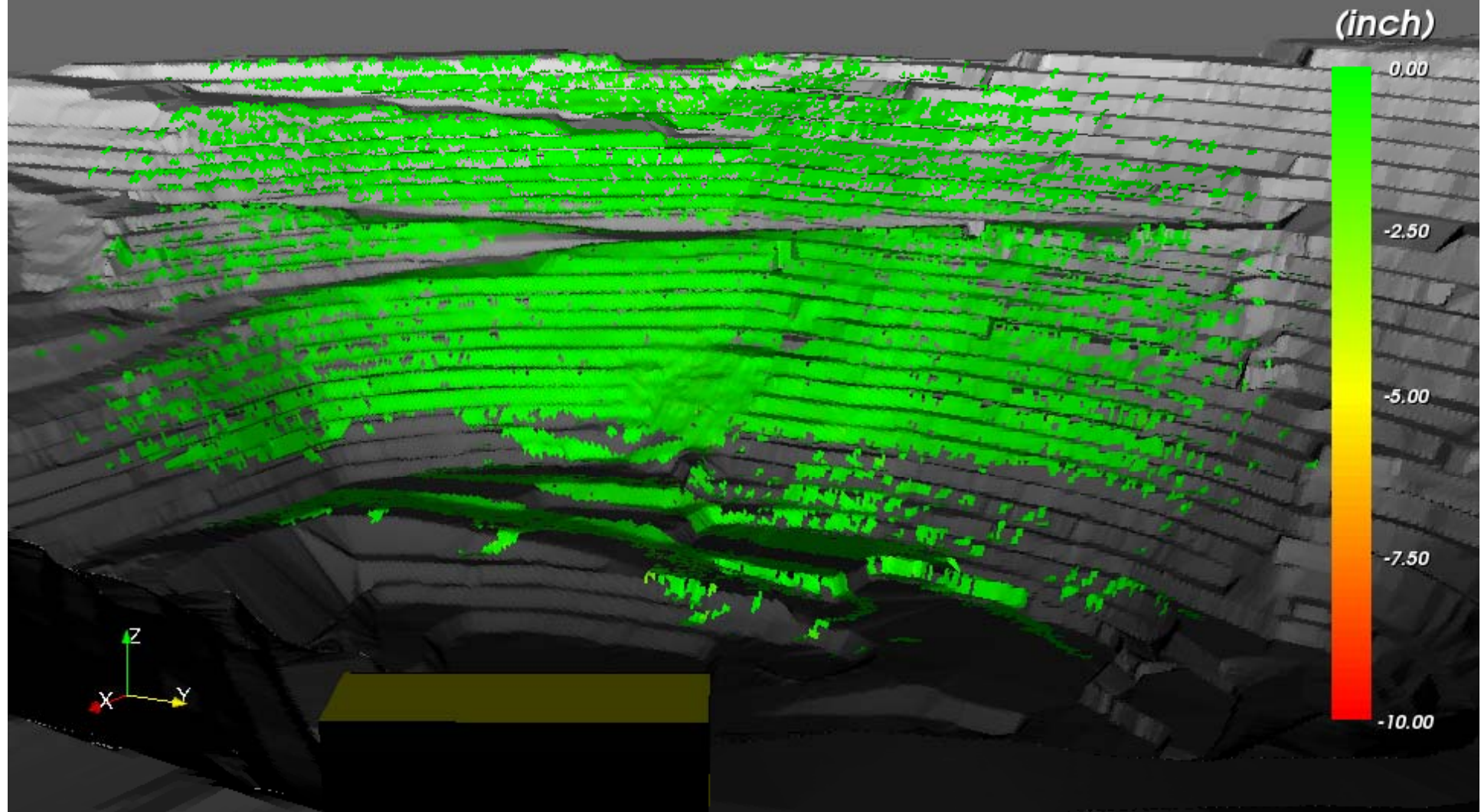
Start Time: 15:33 03/02/10
Stop Time: 10:56 25/02/10

Cumulative displacement from 03/02 to 25/02



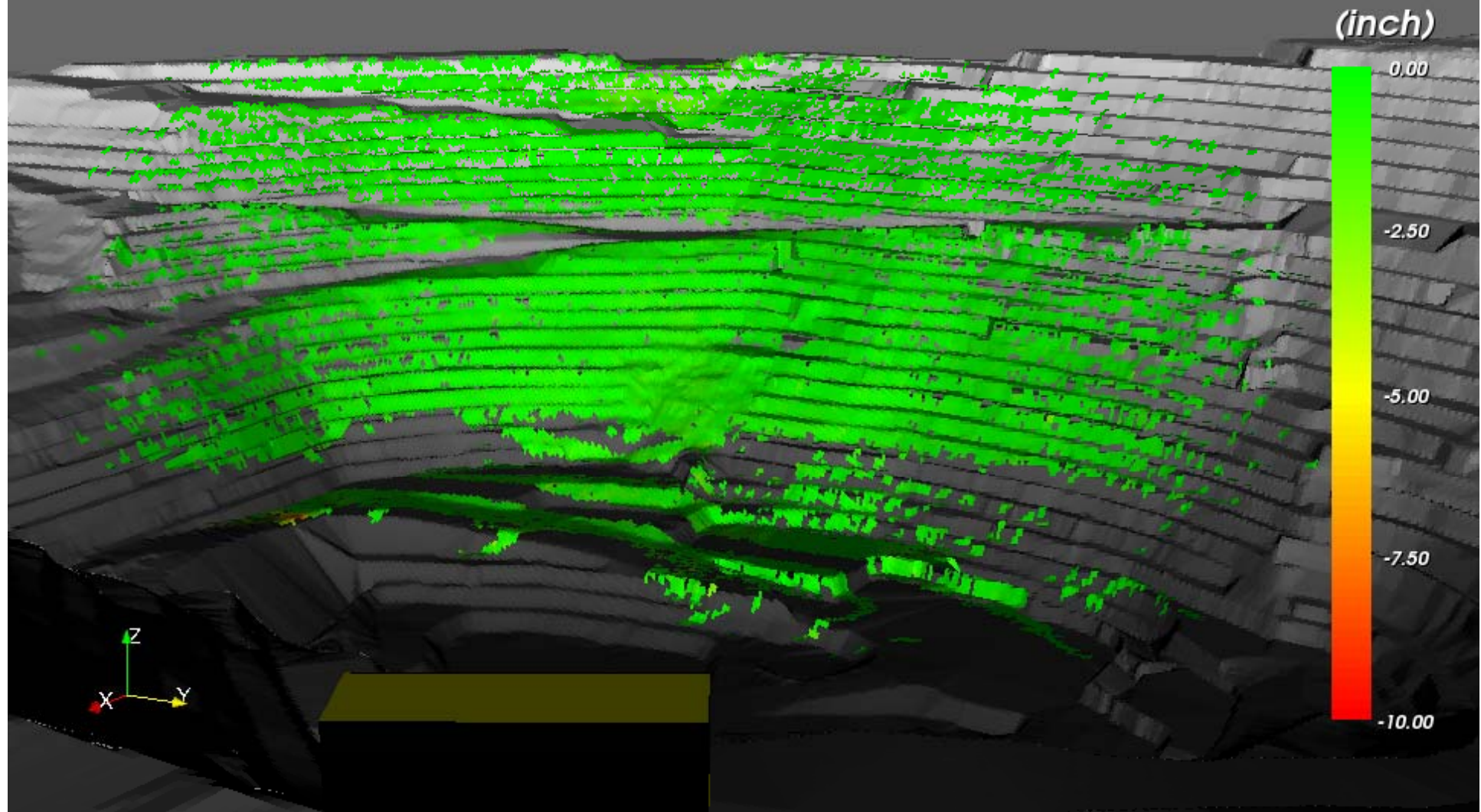
Start Time: 15:33 03/02/10
Stop Time: 17:20 07/03/10

Cumulative displacement from 03/02 to 07/03



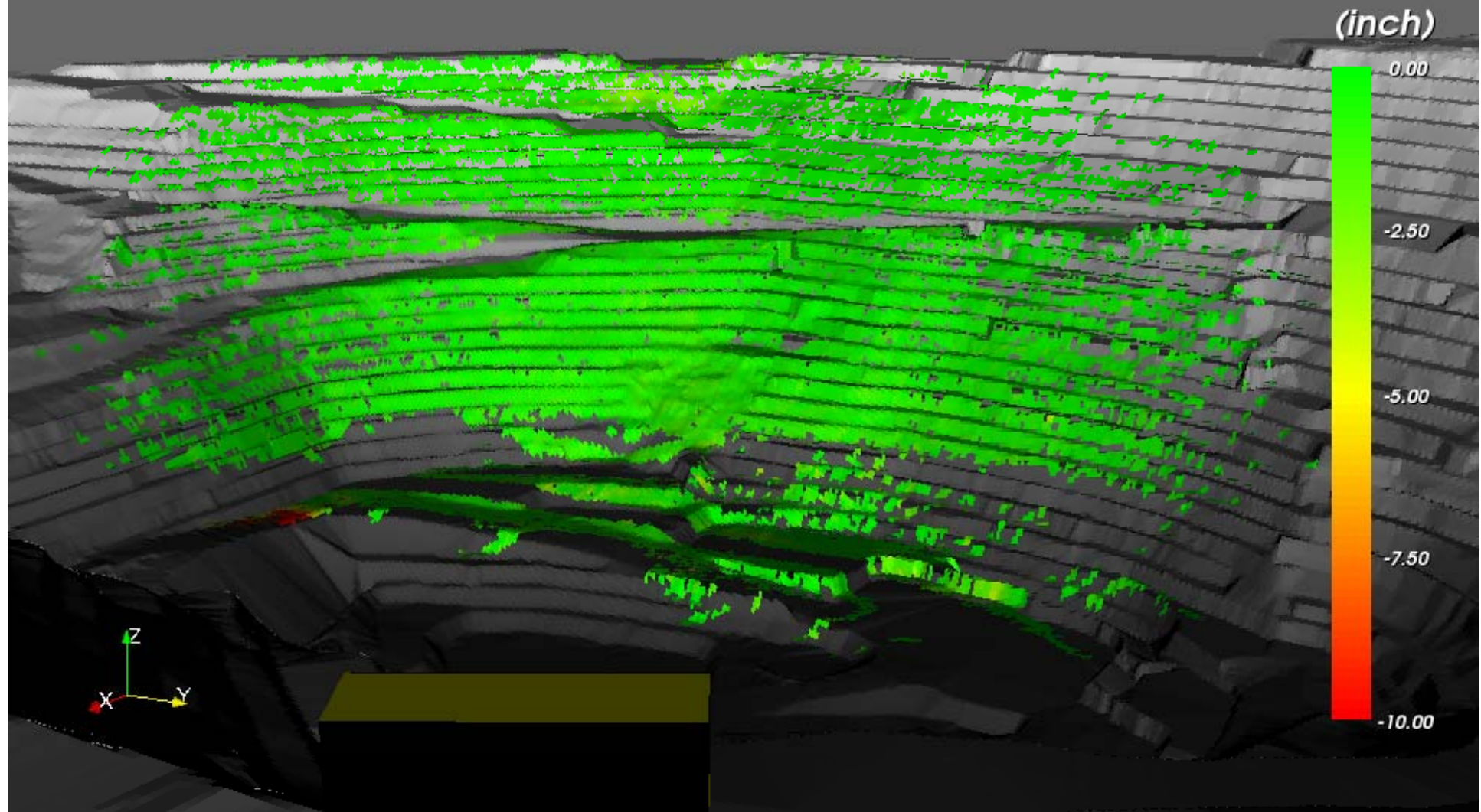
Start Time: 15:33 03/02/10
Stop Time: 18:18 21/03/10

Cumulative displacement from 03/02 to 21/03



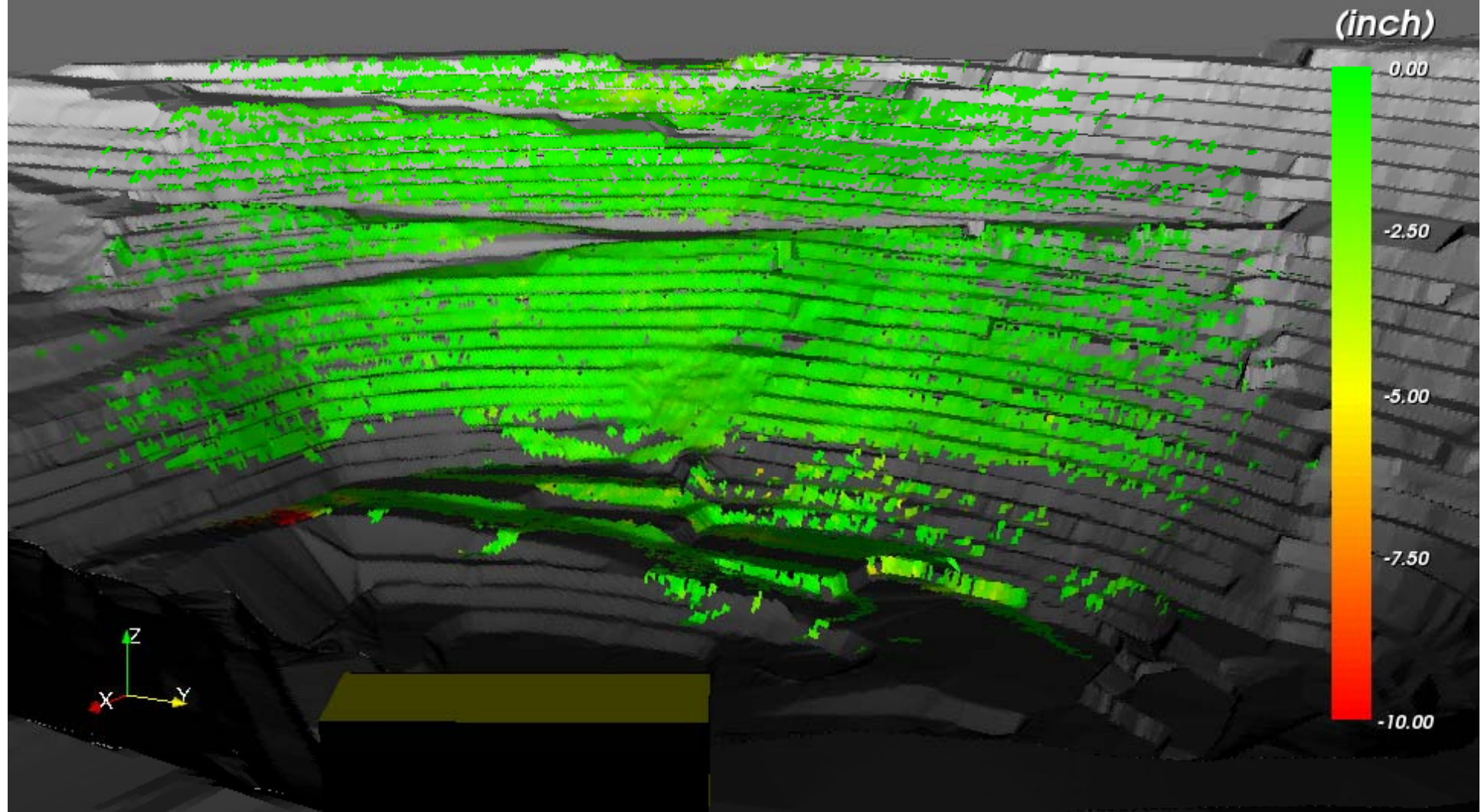
Start Time: 15:33 03/02/10
Stop Time: 16:13 04/04/10

Cumulative displacement from 03/02 to 04/04



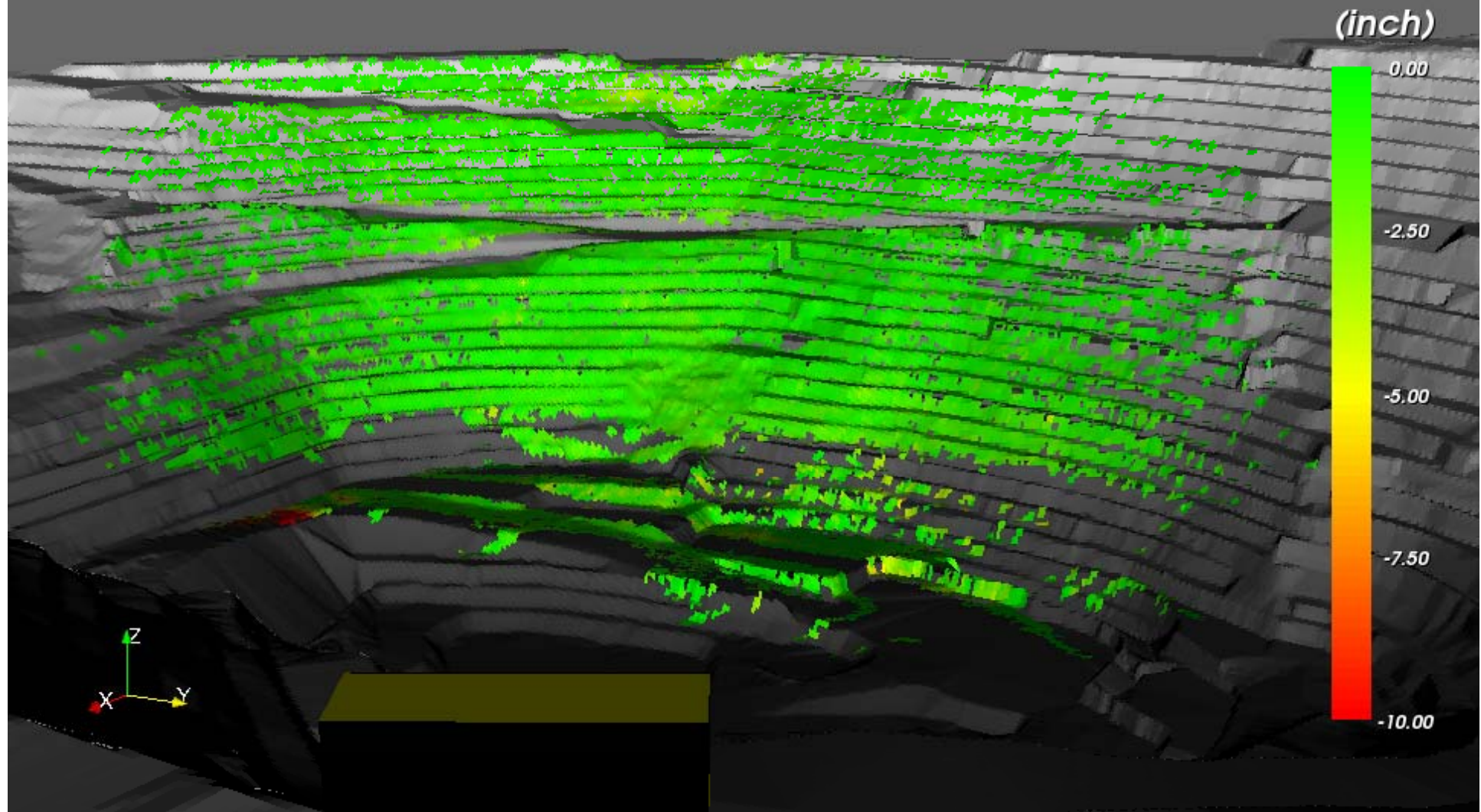
Start Time: 15:33 03/02/10
Stop Time: 12:08 19/04/10

Cumulative displacement from 03/02 to 19/04



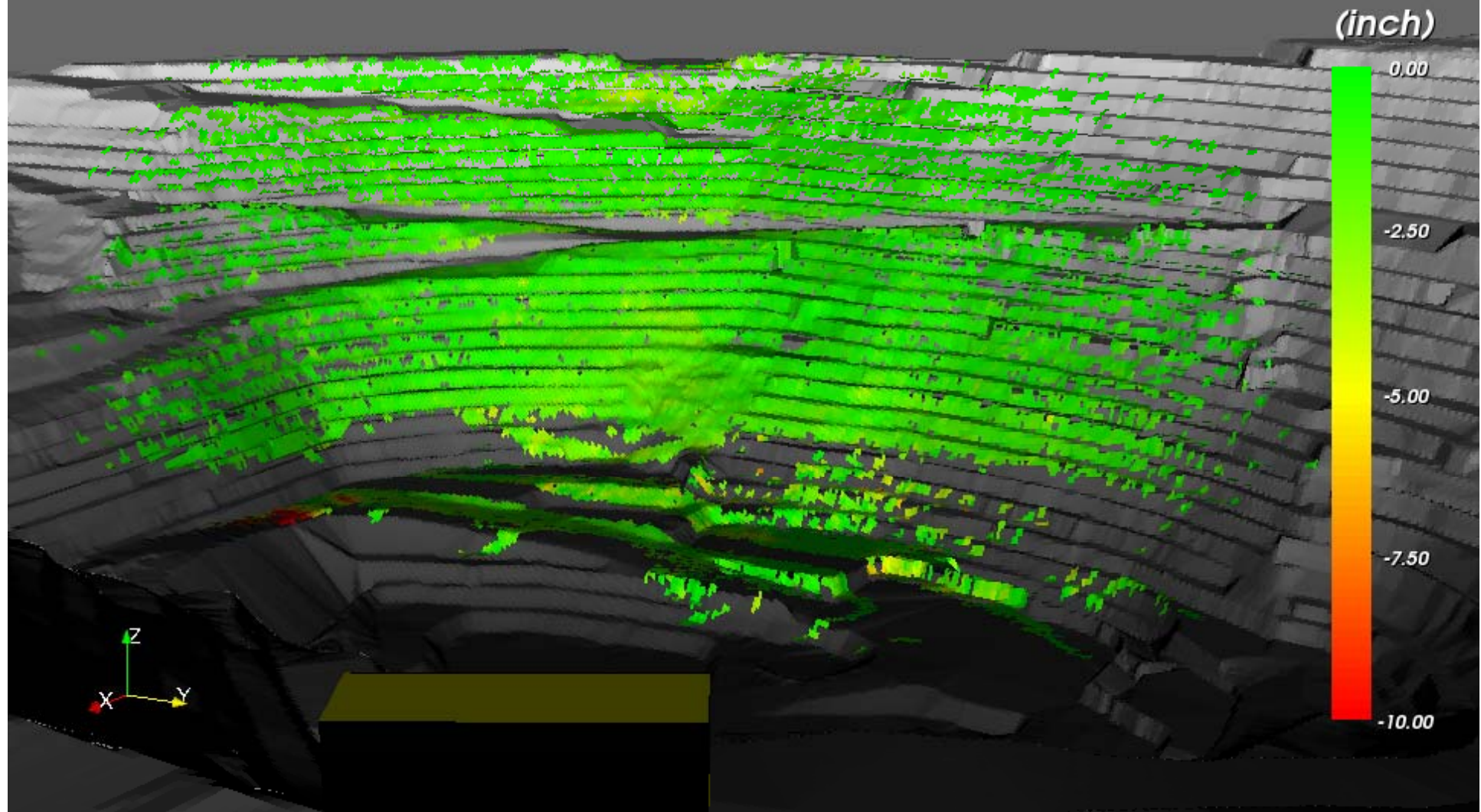
Start Time: 15:33 03/02/10
Stop Time: 16:59 04/05/10

Cumulative displacement from 03/02 to 04/05



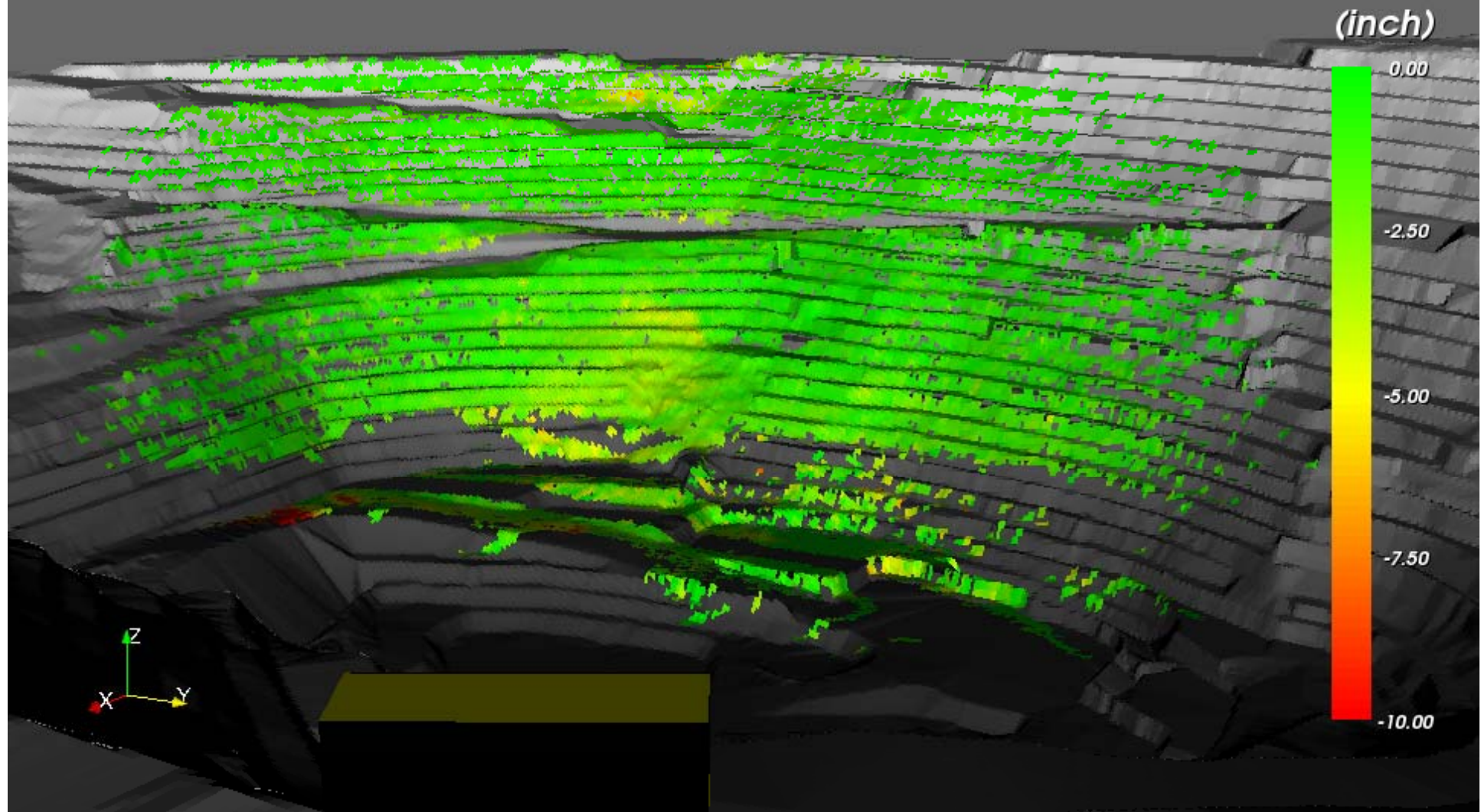
Start Time: 15:33 03/02/10
Stop Time: 18:25 18/05/10

Cumulative displacement from 03/02 to 18/05



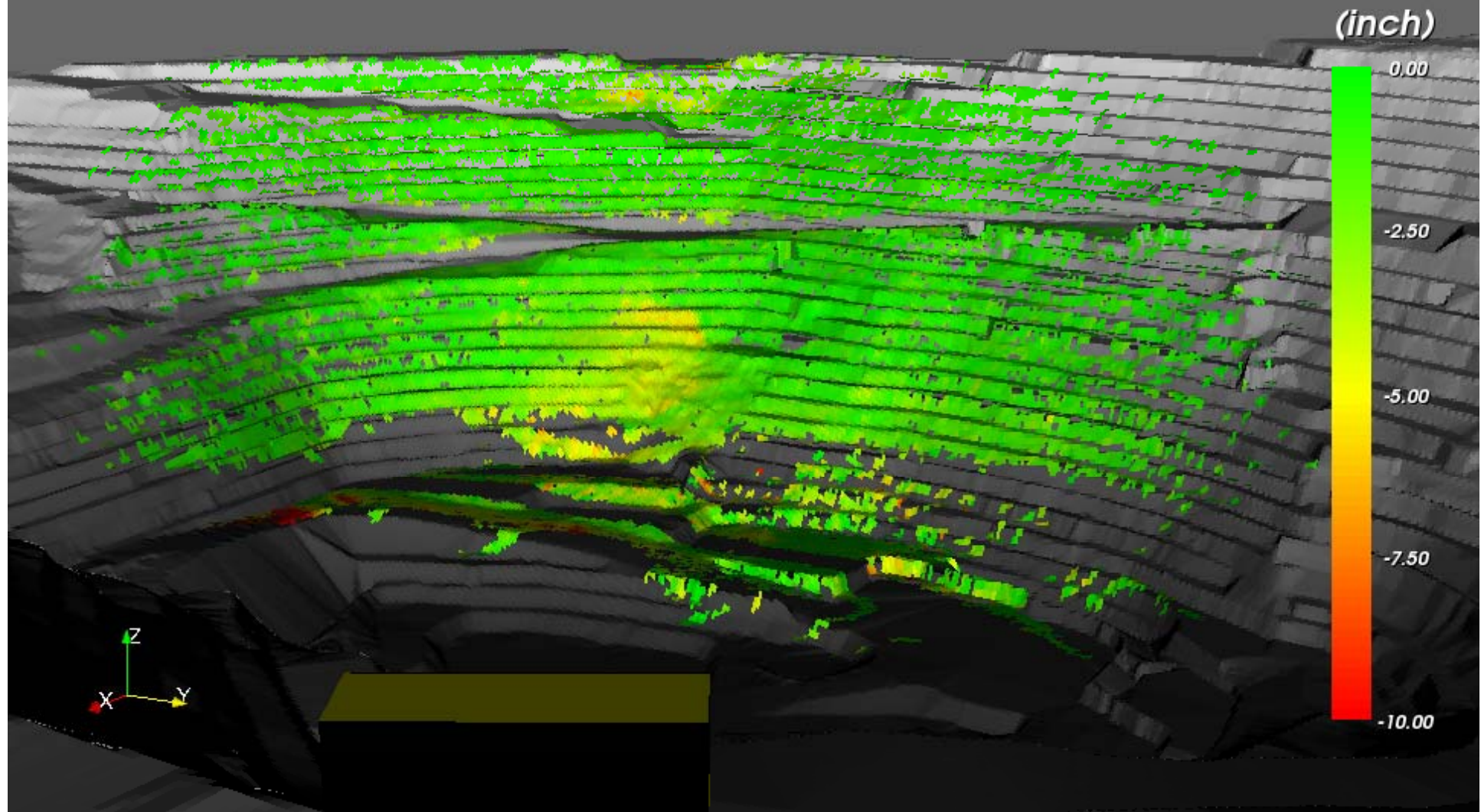
Start Time: 15:33 03/02/10
Stop Time: 12:39 01/06/10

Cumulative displacement from 03/02 to 01/06



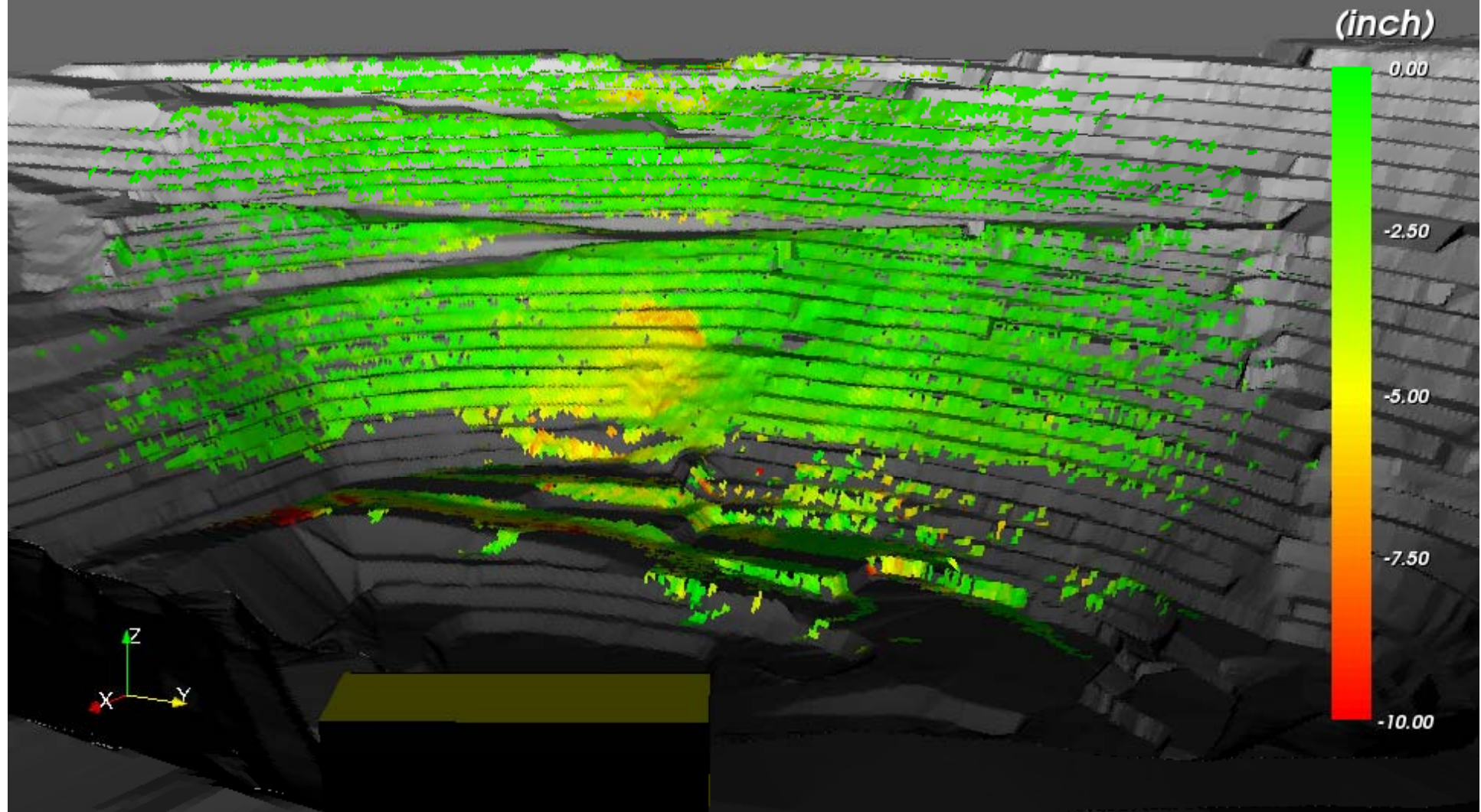
Start Time: 15:33 03/02/10
Stop Time: 16:37 15/06/10

Cumulative displacement from 03/02 to 15/06



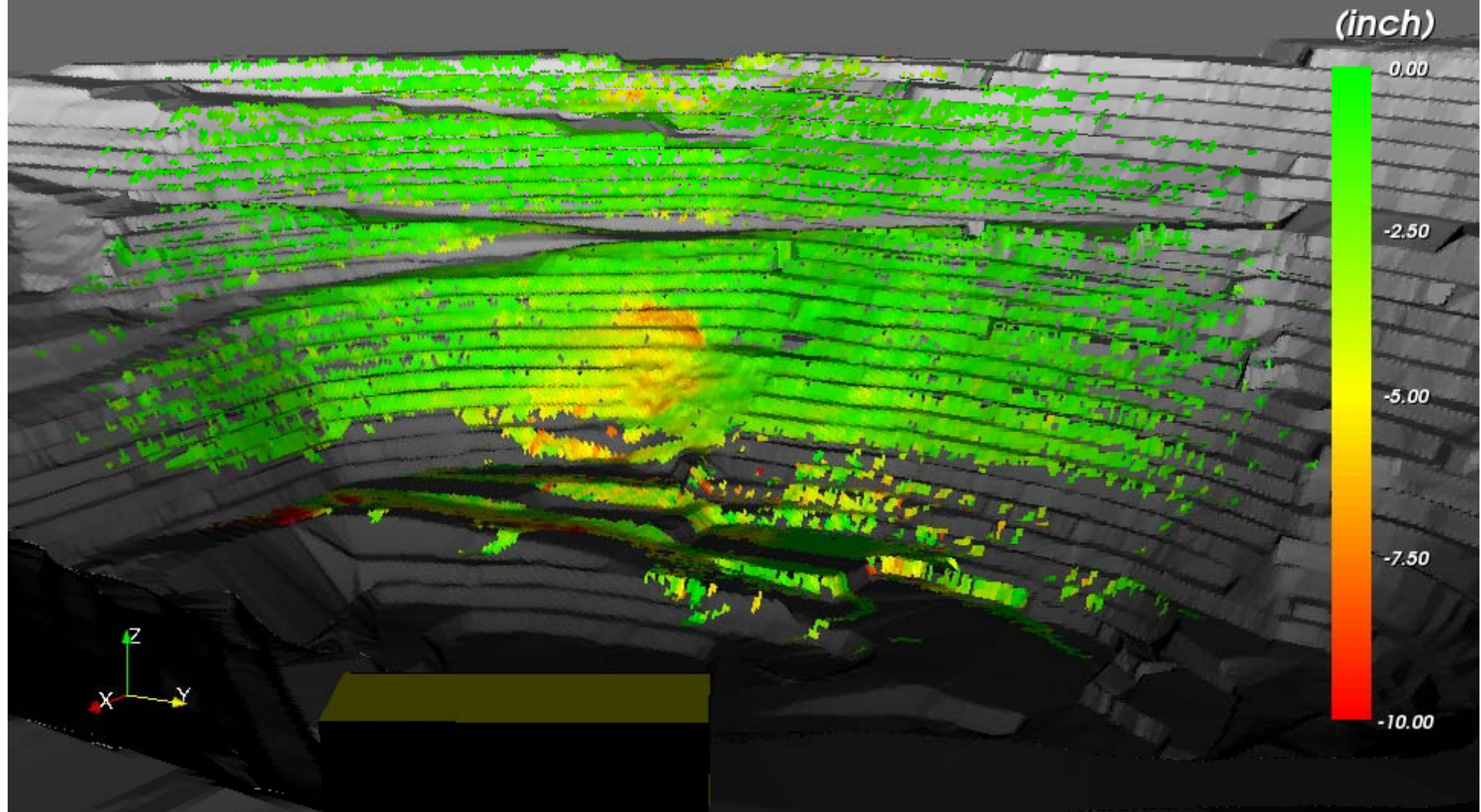
Start Time: 15:33 03/02/10
Stop Time: 13:14 29/06/10

Cumulative displacement from 03/02 to 29/06



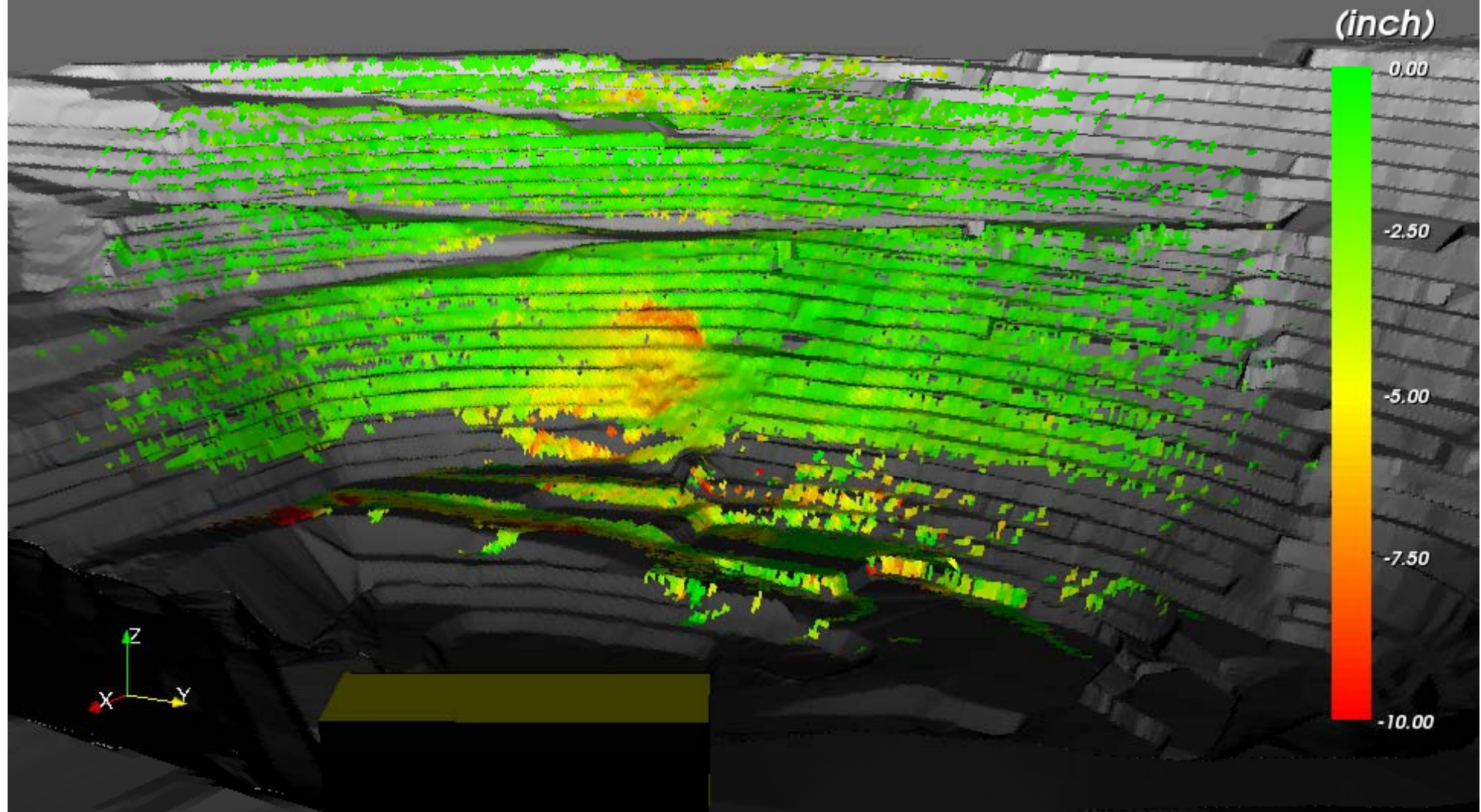
Start Time: 15:33 03/02/10
Stop Time: 13:33 14/07/10

Cumulative displacement from 03/02 to 14/07



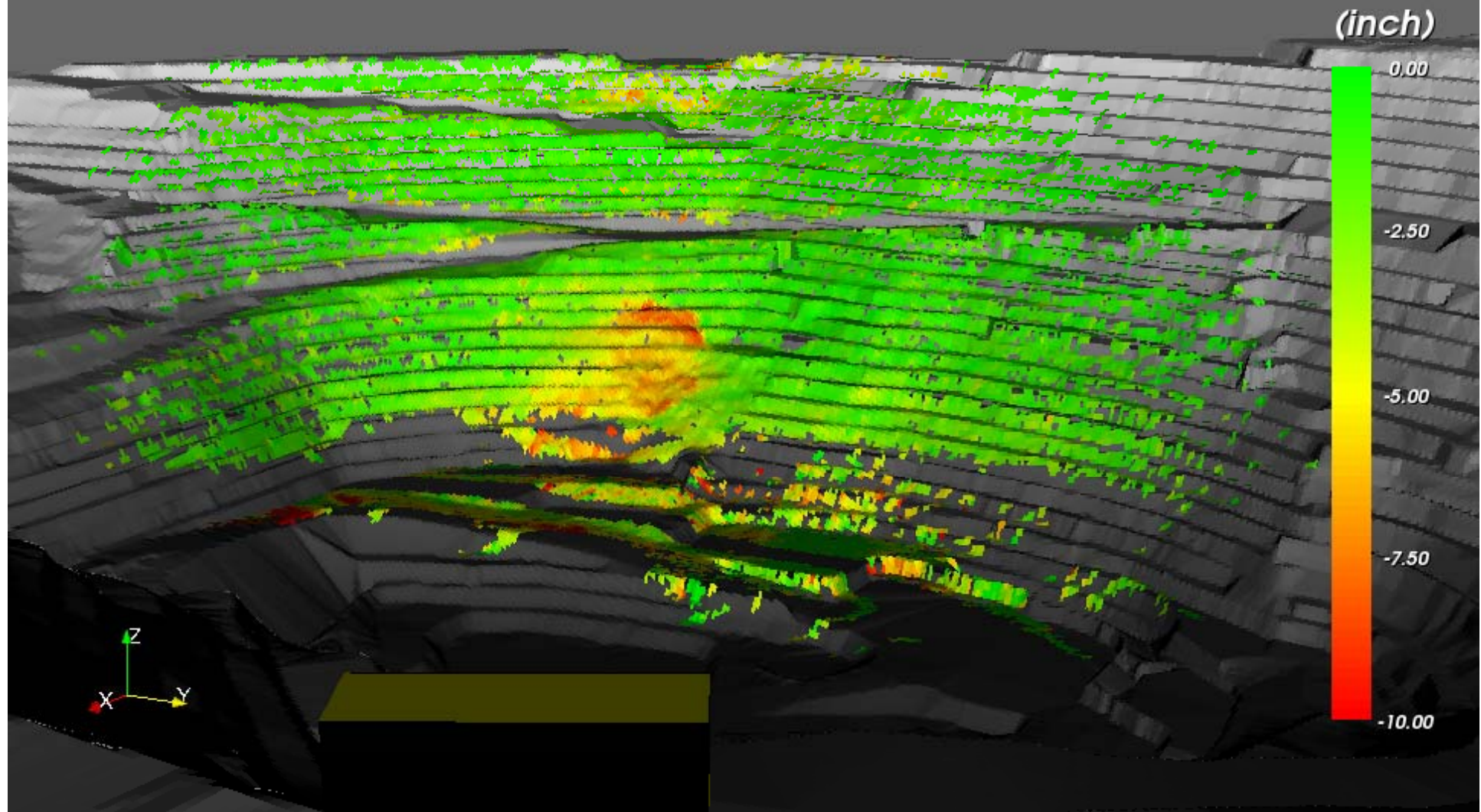
Start Time: 15:33 03/02/10
Stop Time: 13:39 29/07/10

Cumulative displacement from 03/02 to 29/07



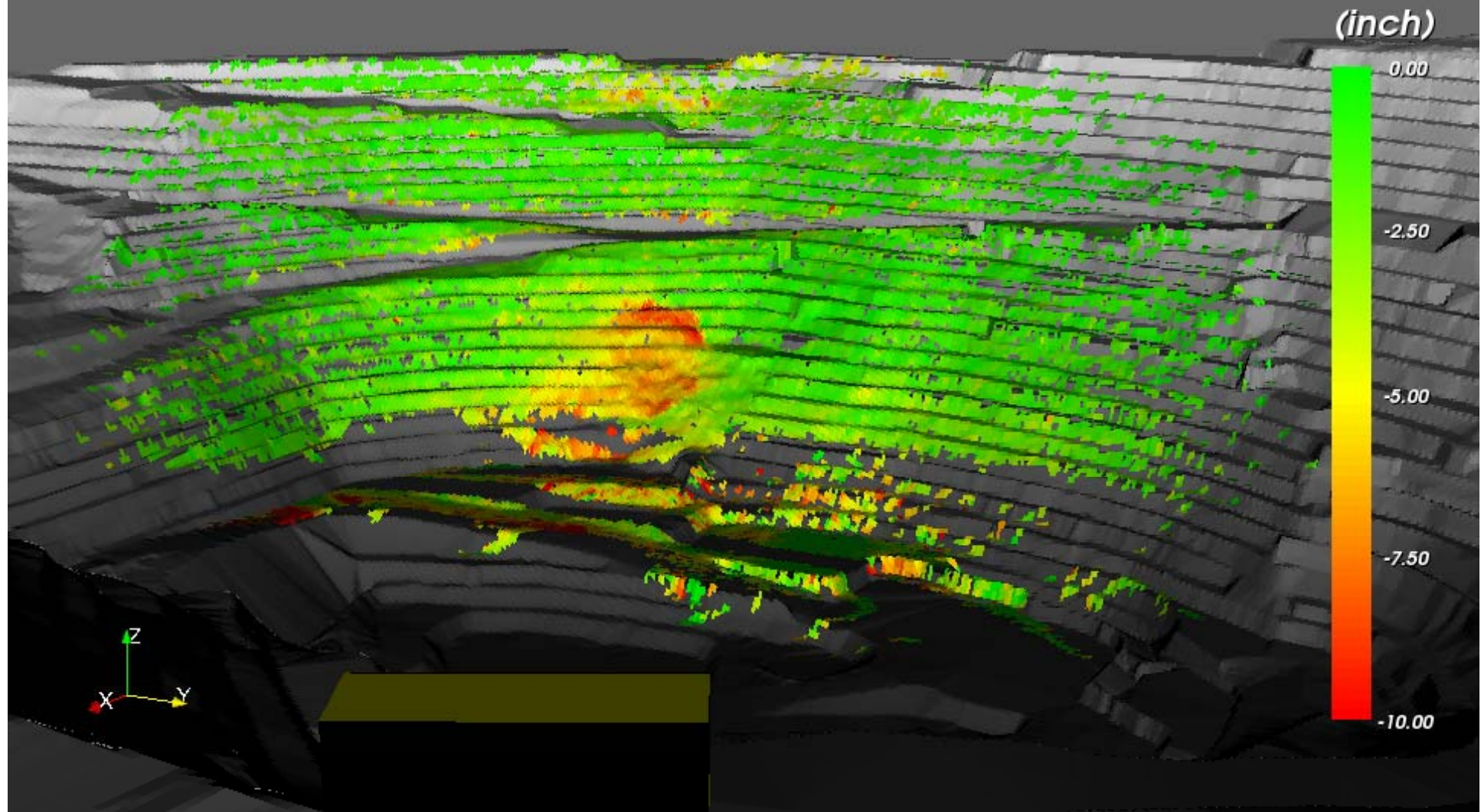
Start Time: 15:33 03/02/10
Stop Time: 13:14 13/08/10

Cumulative displacement from 03/02 to 13/08



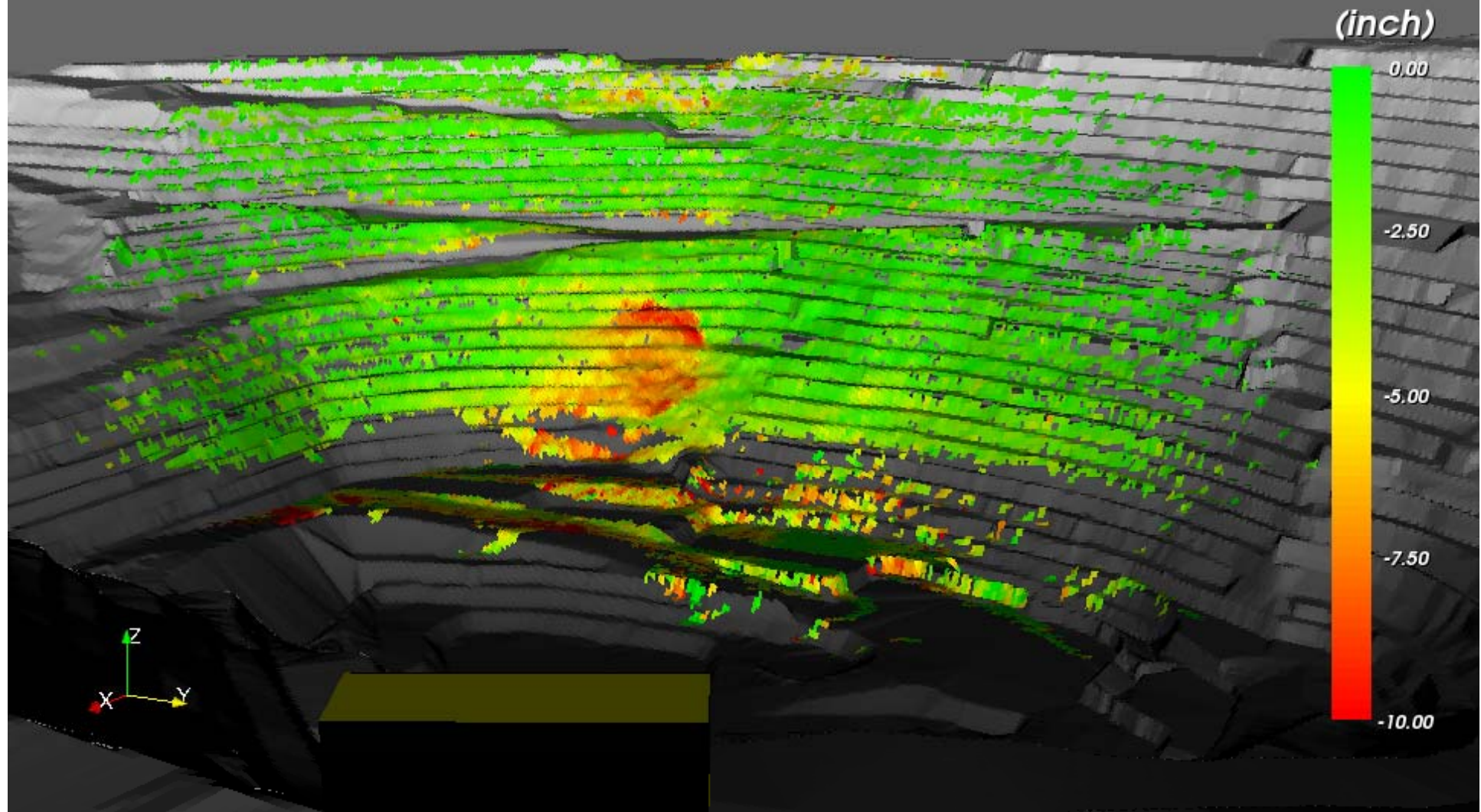
Start Time: 15:33 03/02/10
Stop Time: 15:20 27/08/10

Cumulative displacement from 03/02 to 27/08



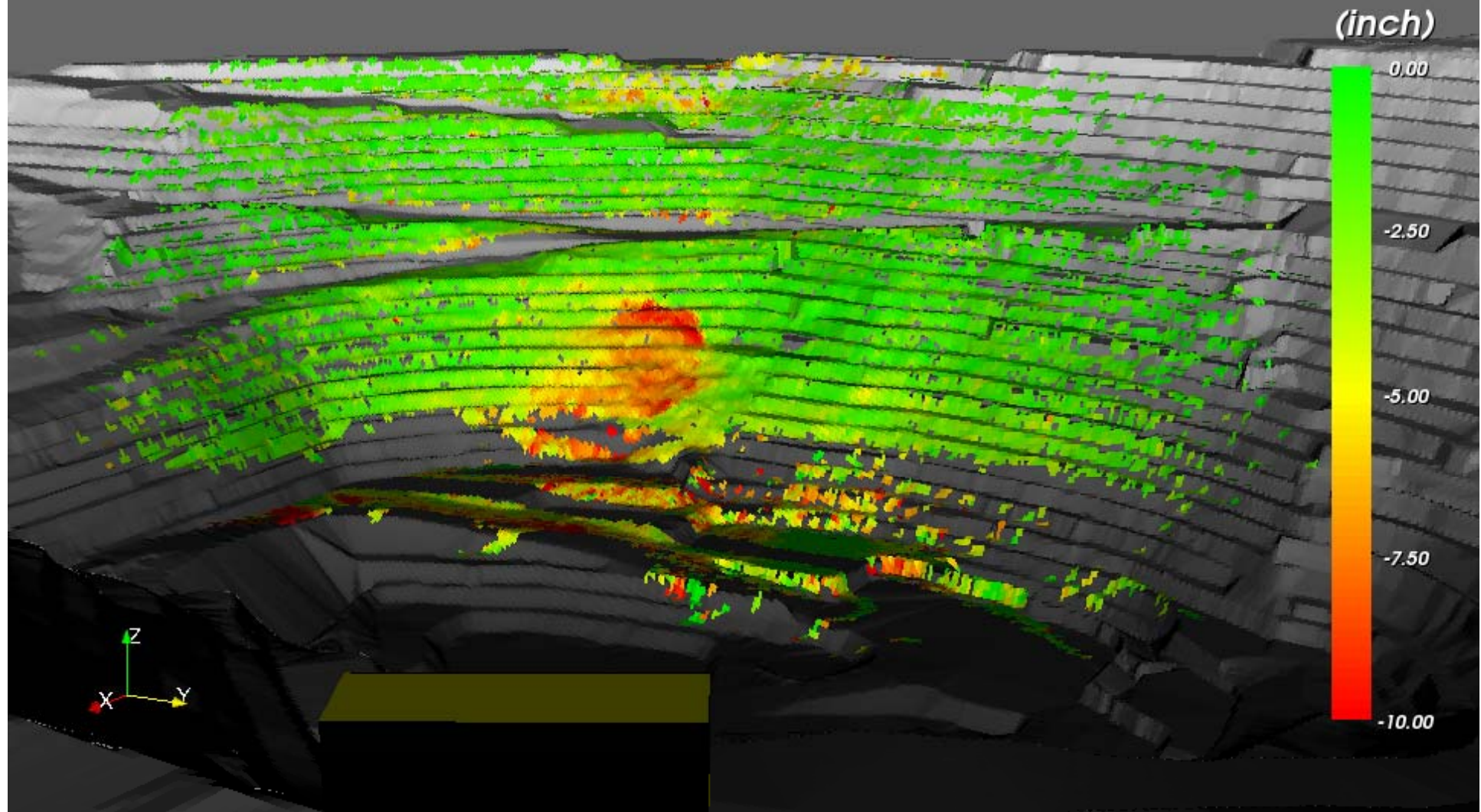
Start Time: 15:33 03/02/10
Stop Time: 10:53 10/09/10

Cumulative displacement from 03/02 to 10/09



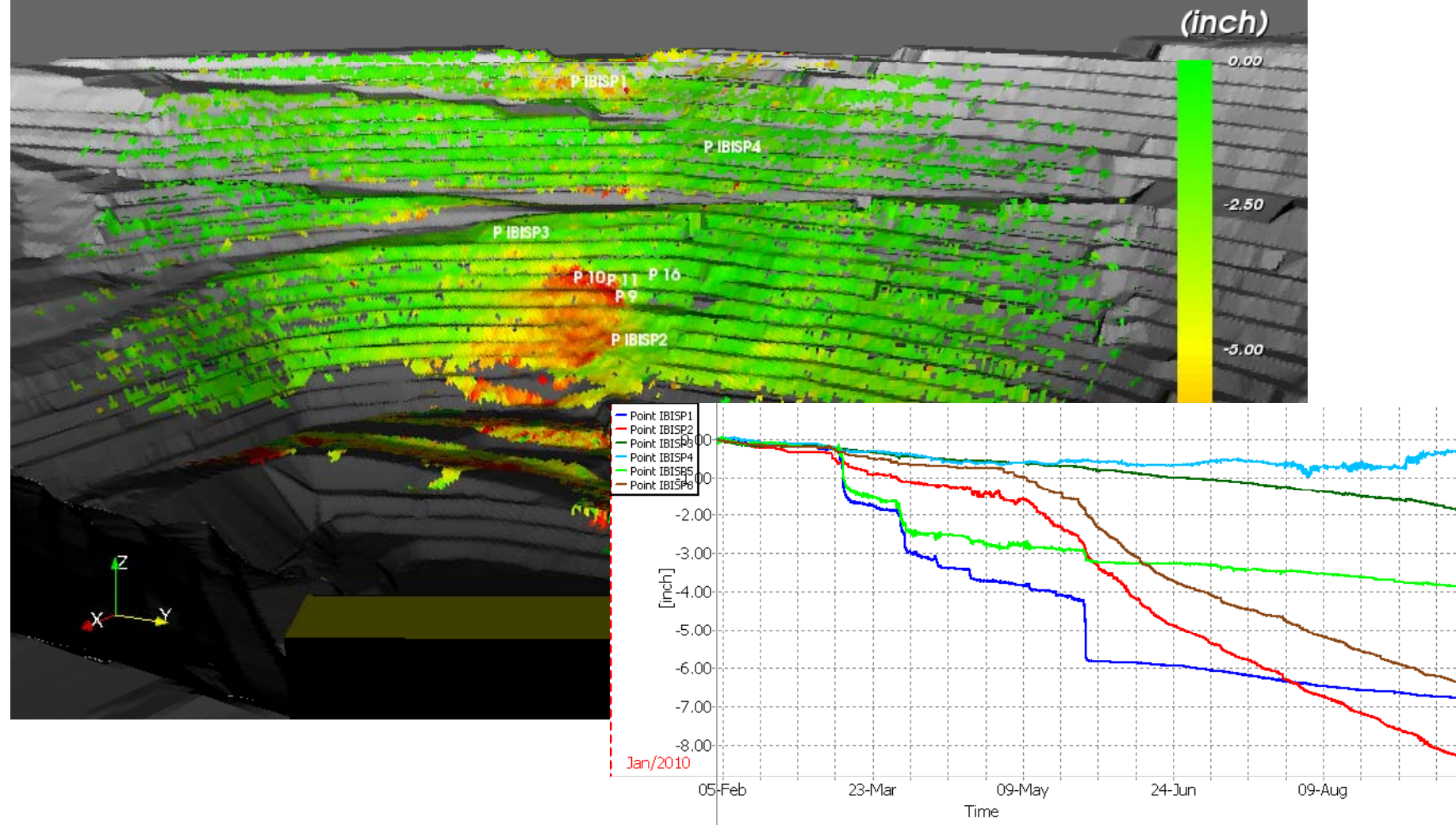
Start Time: 15:33 03/02/10
Stop Time: 08:37 21/09/10

Cumulative displacement from 03/02 to 21/09



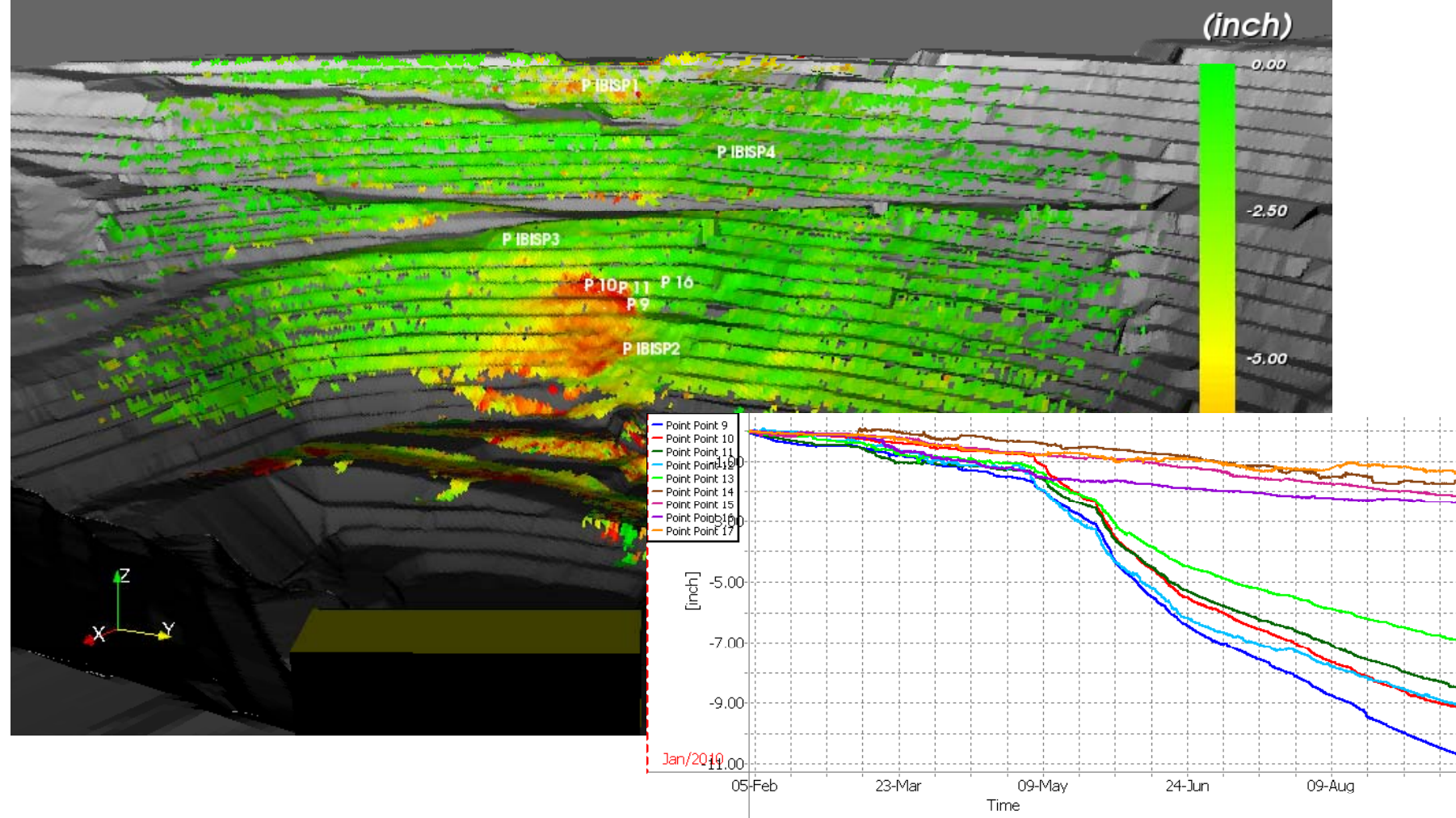
Start Time: 15:33 03/02/10
Stop Time: 08:37 21/09/10

Cumulative displacement from 03/02 to 21/09: time series



Start Time: 15:33 03/02/10
Stop Time: 08:37 21/09/10

Cumulative displacement from 03/02 to 21/09: time series

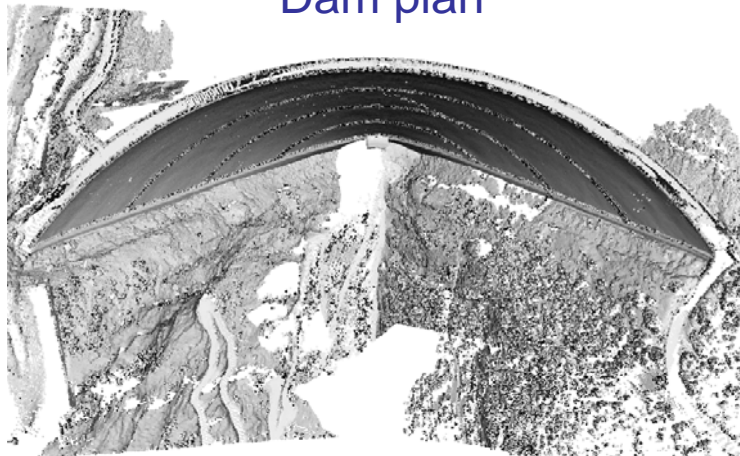


Dam monitoring

Cancano Dam view



Dam plan



Dam characteristics

Dam Type	Gravity arch
Location	Alpi Retiche - Italy
Dam height (m)	125.5
Crowing length (m)	381

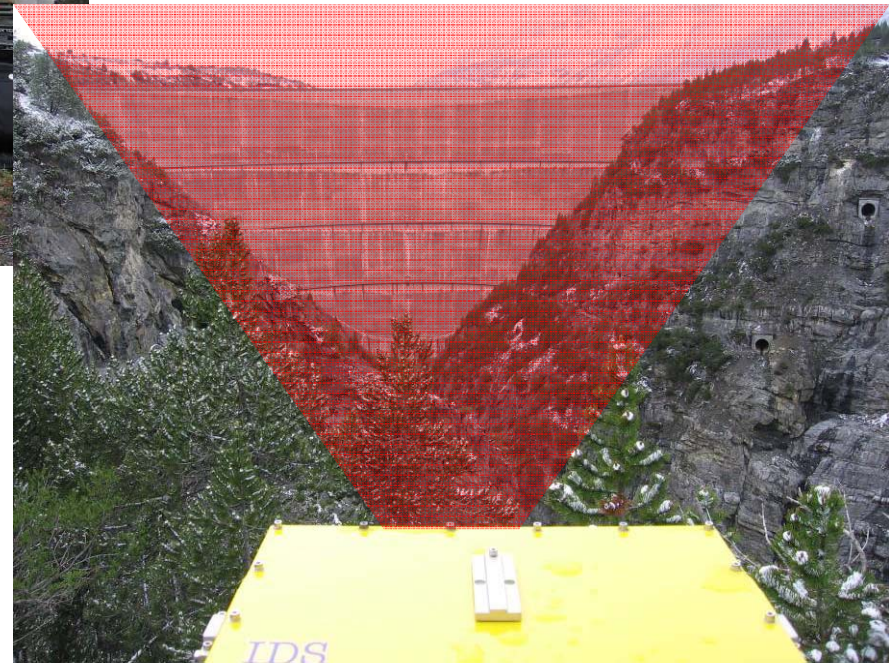
Survey performed with the
Surveying Dept. of Milan Polytechnic

Dam monitoring



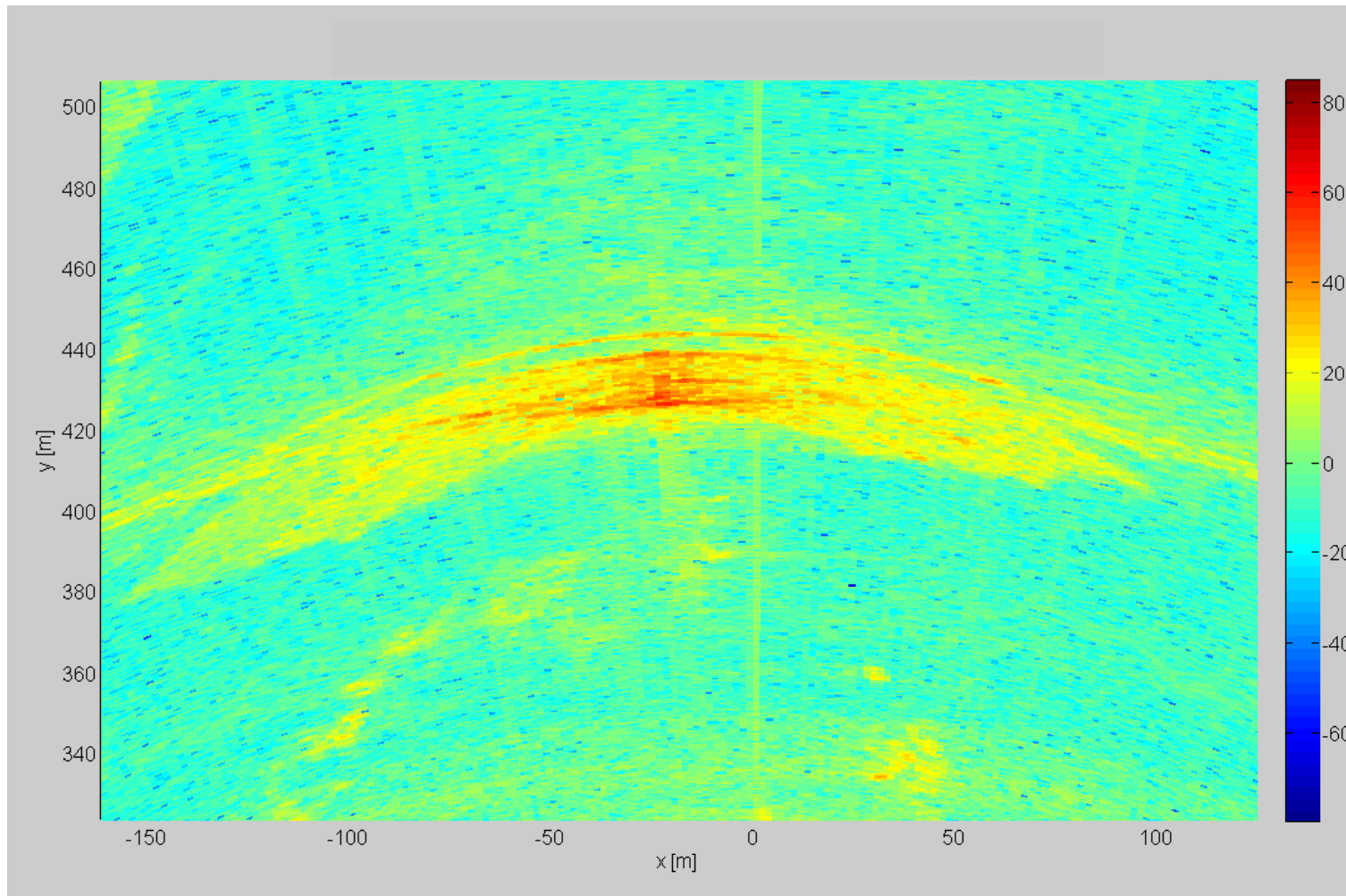
IBIS-L configuration

- Dam-sensor distance: 400m
- Range resolution: 0.5m
- Angle resolution: 4.7mrad
- Sampling interval: ca. 9 minutes



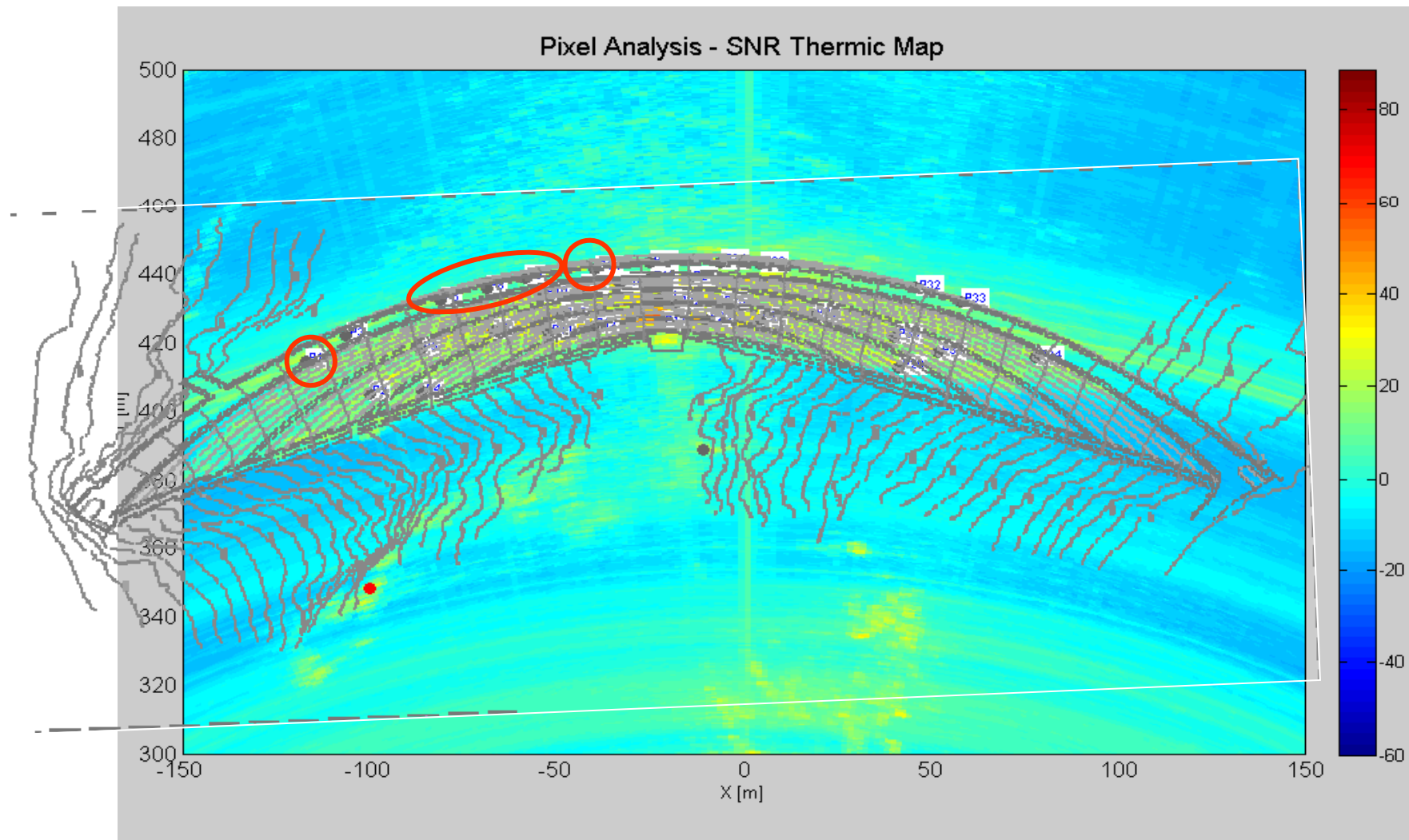
Dam monitoring

Zoom on dam area



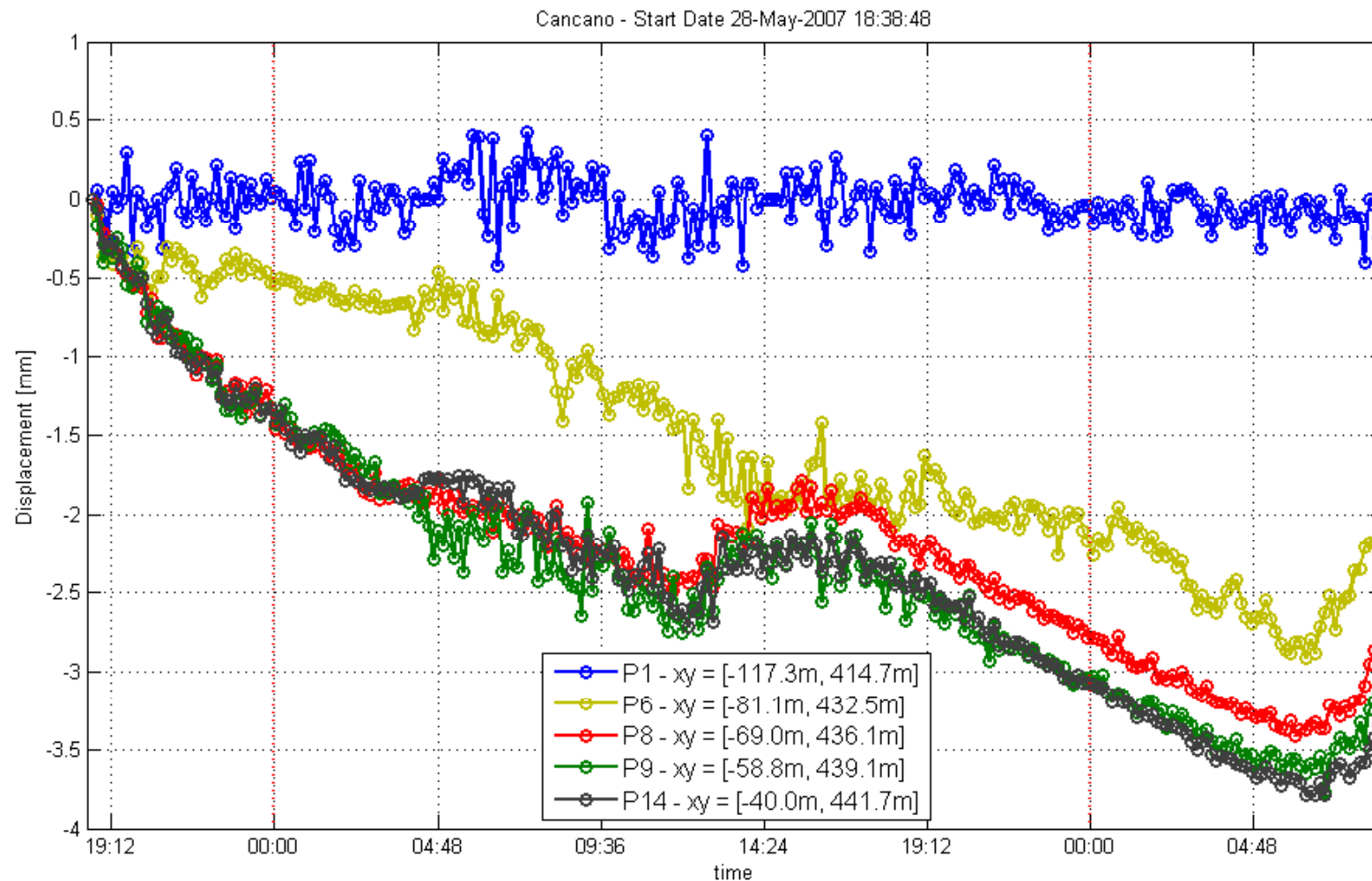
Dam monitoring

Dam Power map projected over plan

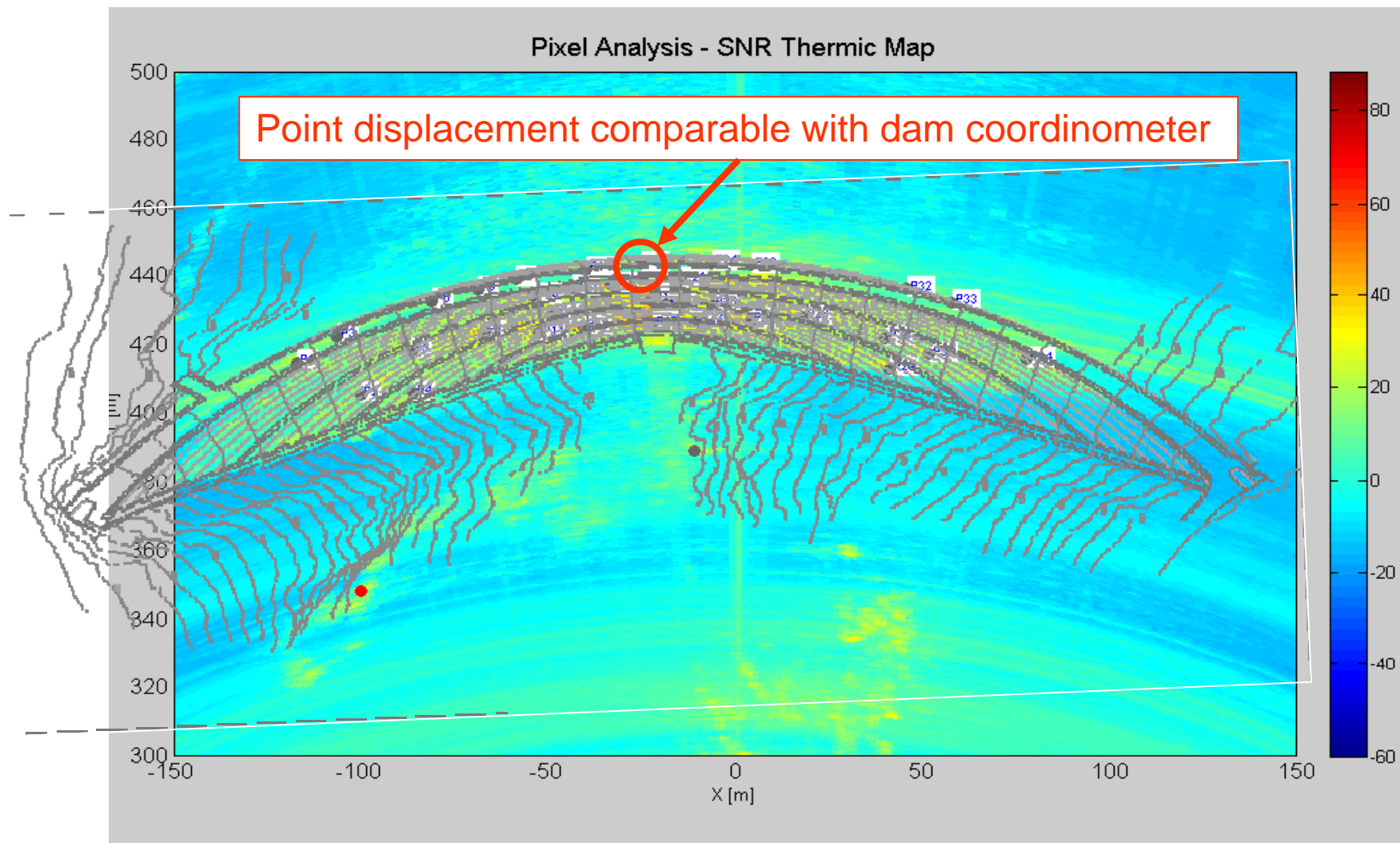


Dam monitoring

Selected pixel L.O.S. displacement – 5 pixel belonging to the dam crown

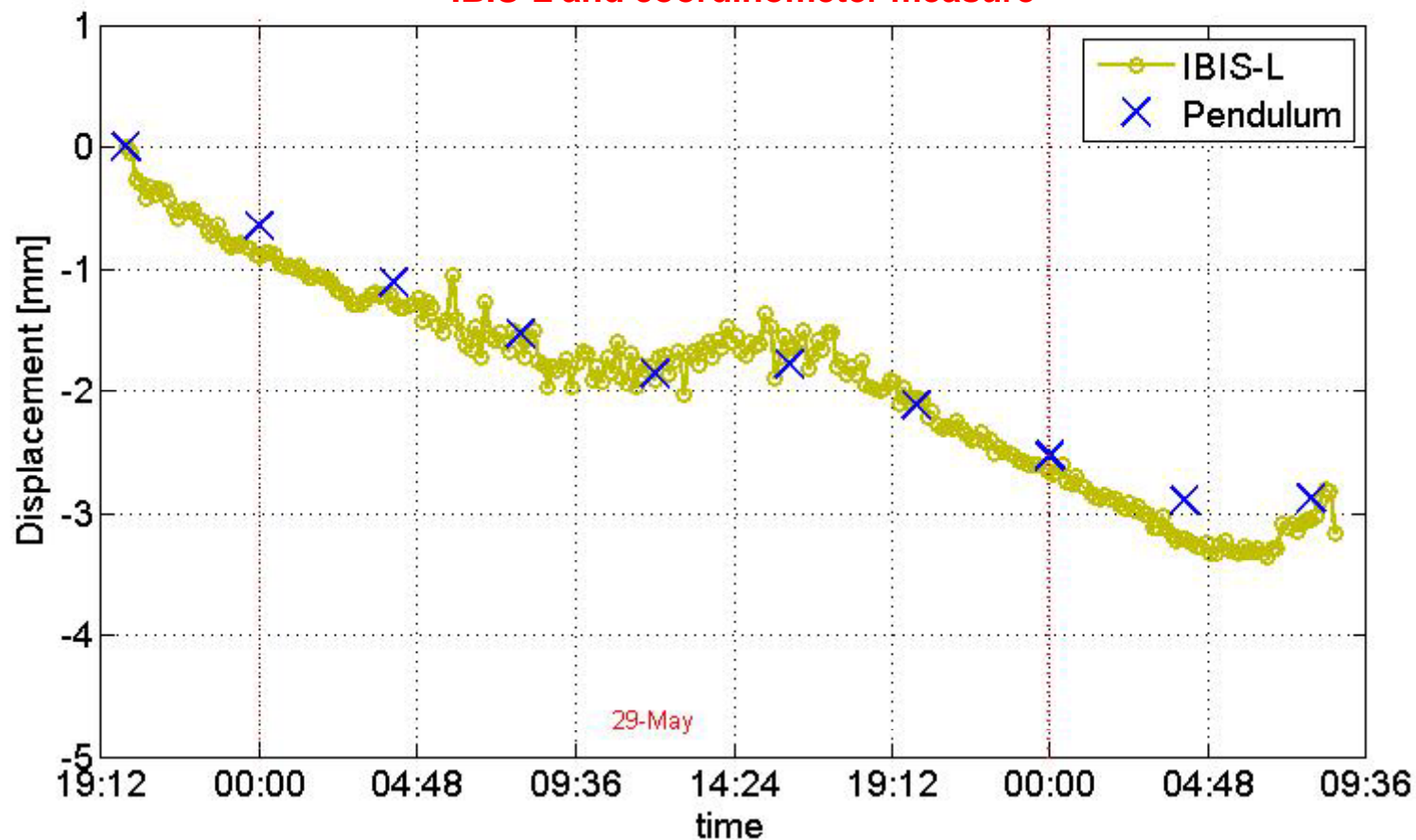


Dam monitoring



Dam monitoring

Crowning point displacement comparison between
IBIS-L and coordinometer measure



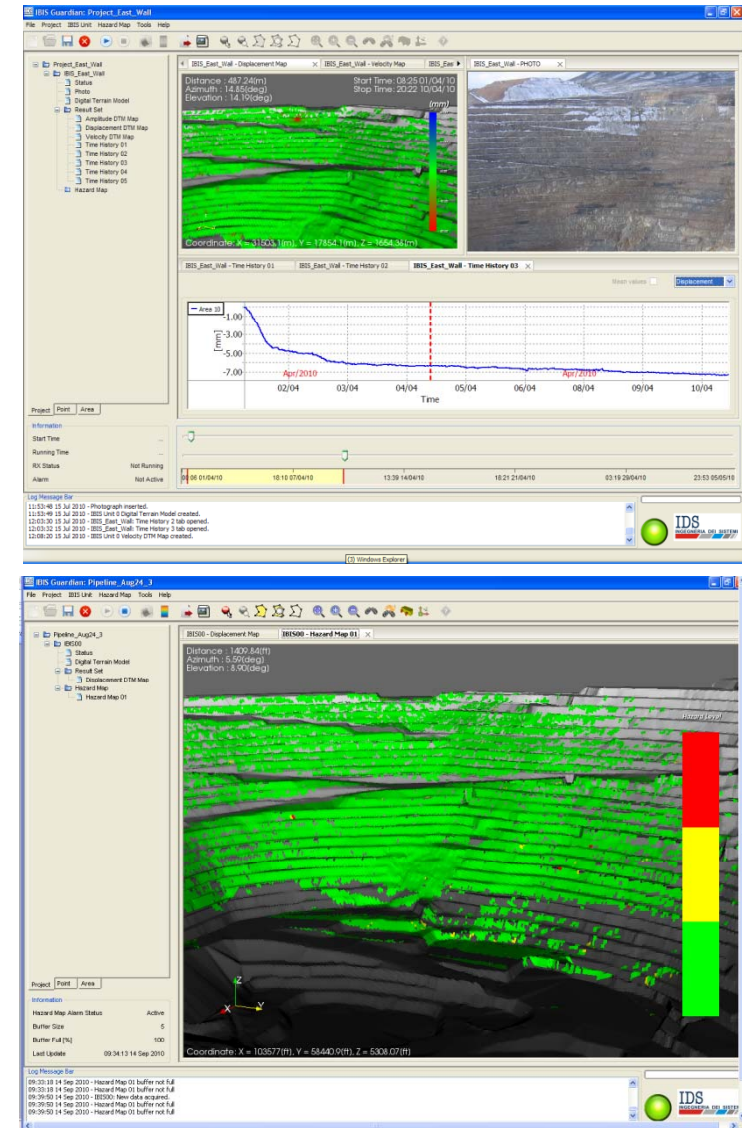
IBIS-L sampling interval: 9min

Pendulum sampling interval: 4hours

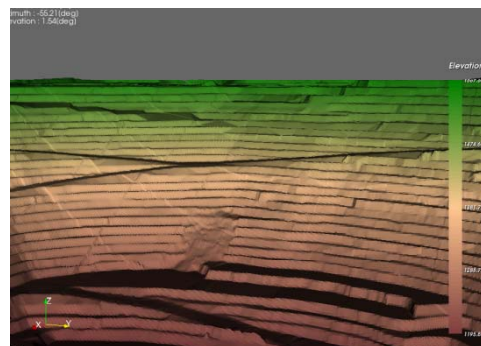
IBIS Guardian

IBIS Guardian

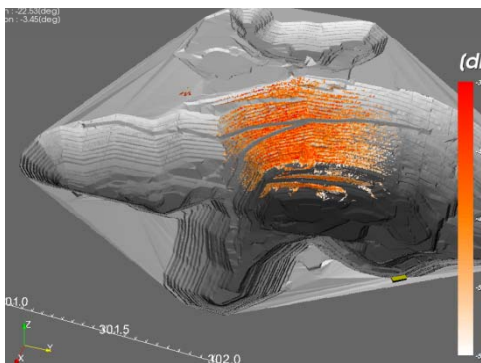
- Real time processing with automatic atmospheric corrections
- Alarm generation with user-defined levels and multiple alarm criteria
- Fully georeferenced outputs
- 3D interactive data handling
- User defined zones for alarm generation
- Exportability of outputs to GIS and mine planning software



GUARDIAN typical output

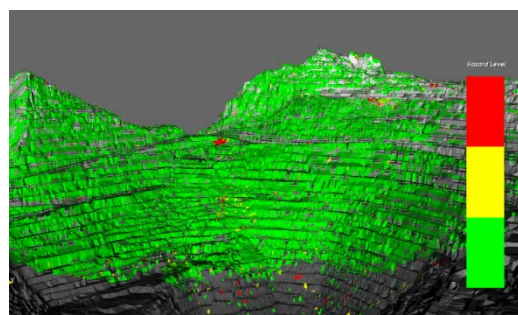
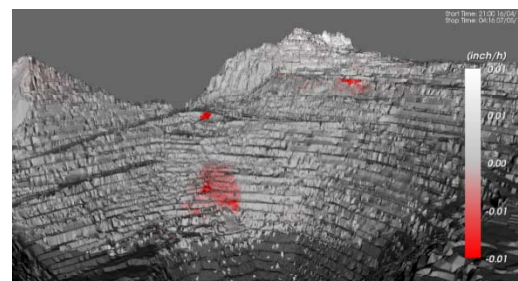
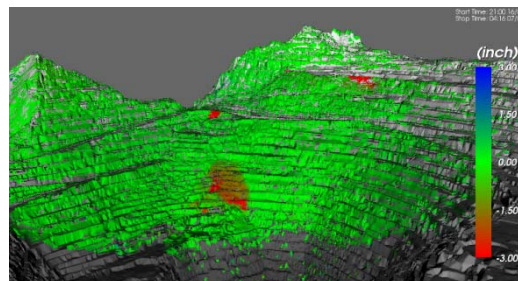


DEM



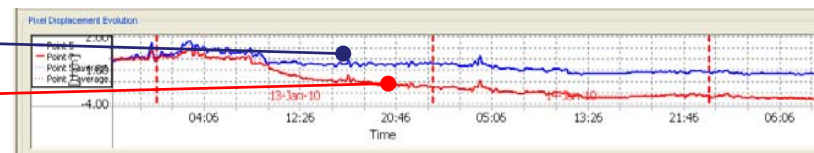
Quality Map

- Values between 0-1
- Reliability of the pixel for distance measurements



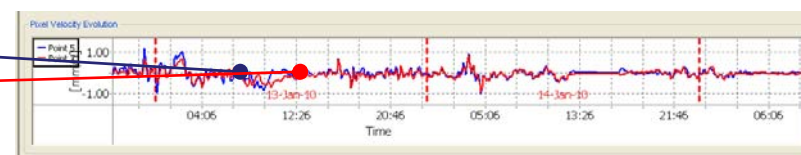
Displacement Map

- in mm for every pixel
- negative displacements are in approach



Velocity Map

- in mm/h for every pixel



Hazard Map

- Variable number of levels and thresholds
- Automatically updated with the last data
- Exclude / Differentiation of areas
- Trigger the alarms:
 - PC SCREEN
 - SMS
 - EMAIL

Alarm

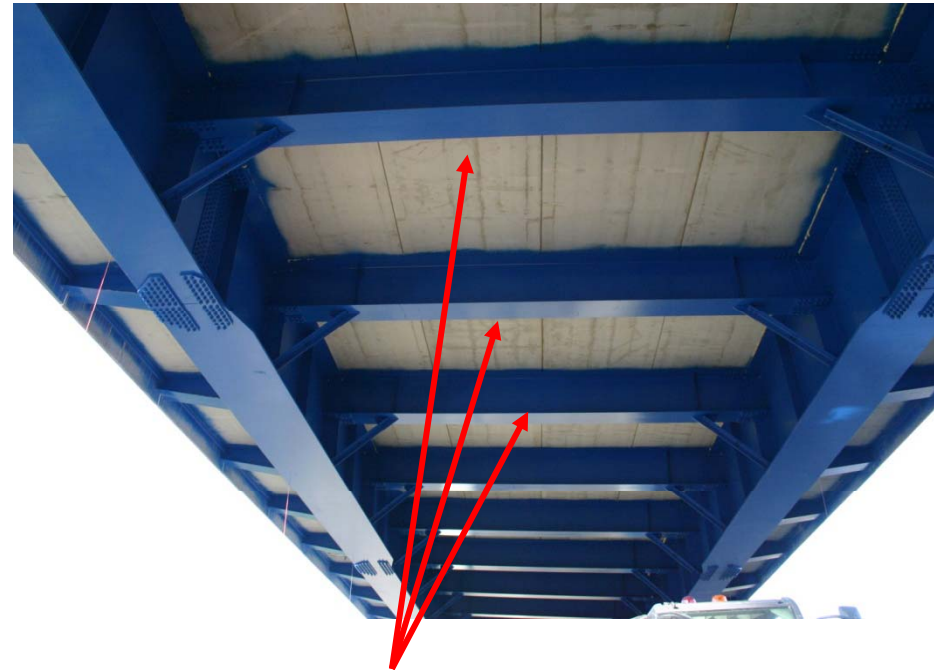
Moving

Stable

Bridge testing: static live load test



Viaducts crossing Forlanini Avenue
(Milan, Italy)



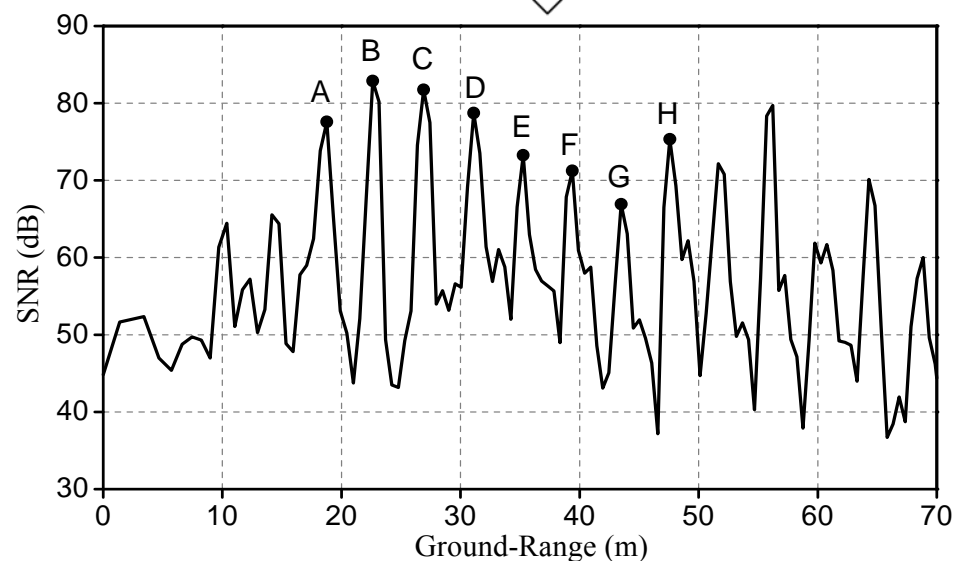
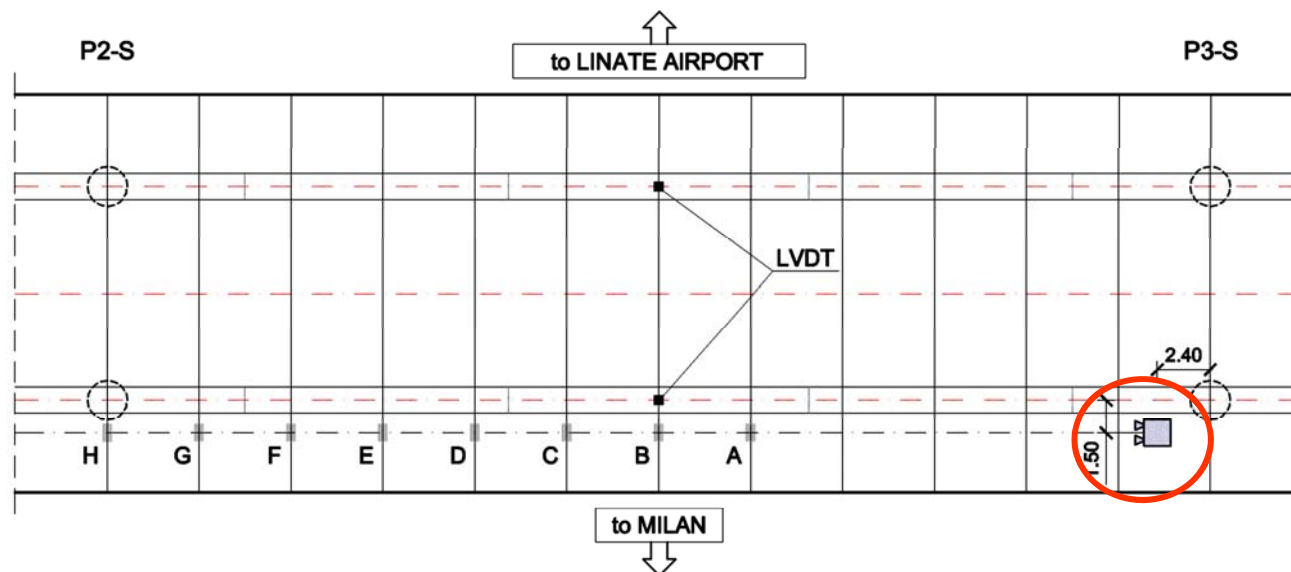
Bridge beams are good reflecting points



Static monitoring of a new bridge:

**Determination of displacement of the
bridge during a static load test**

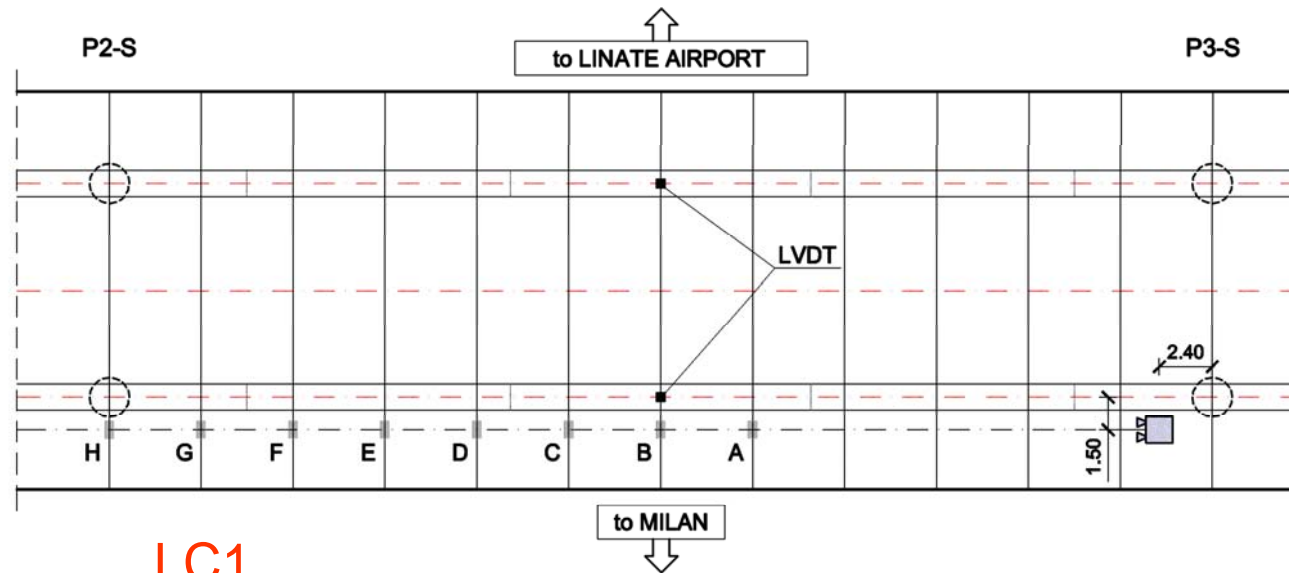
Bridge testing: static live load test



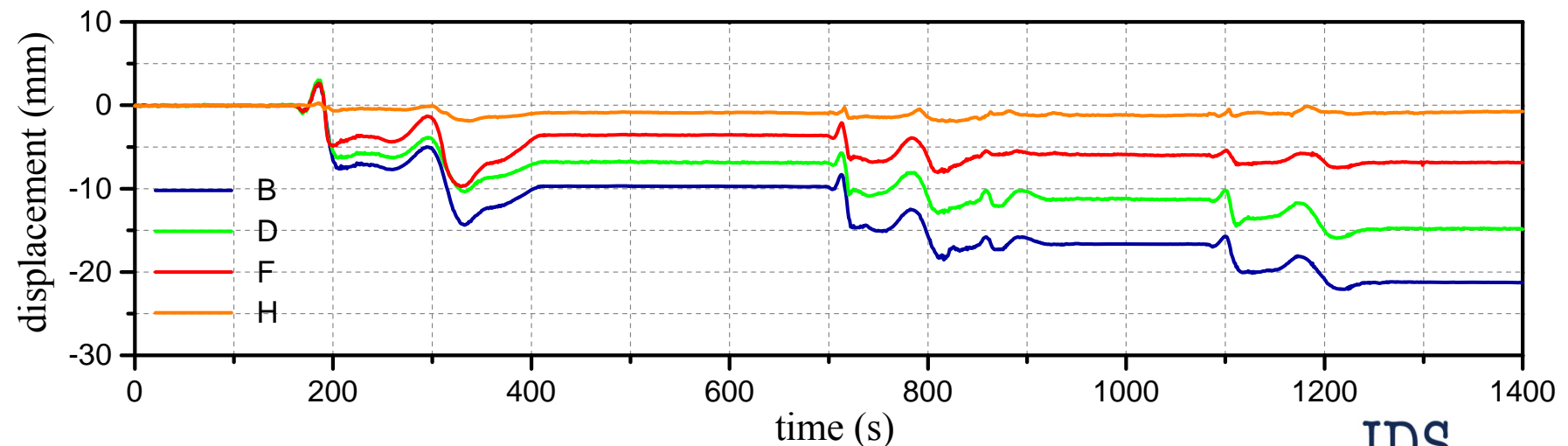
IBIS-S
installation

Range profile of
P2-S – P3-S span

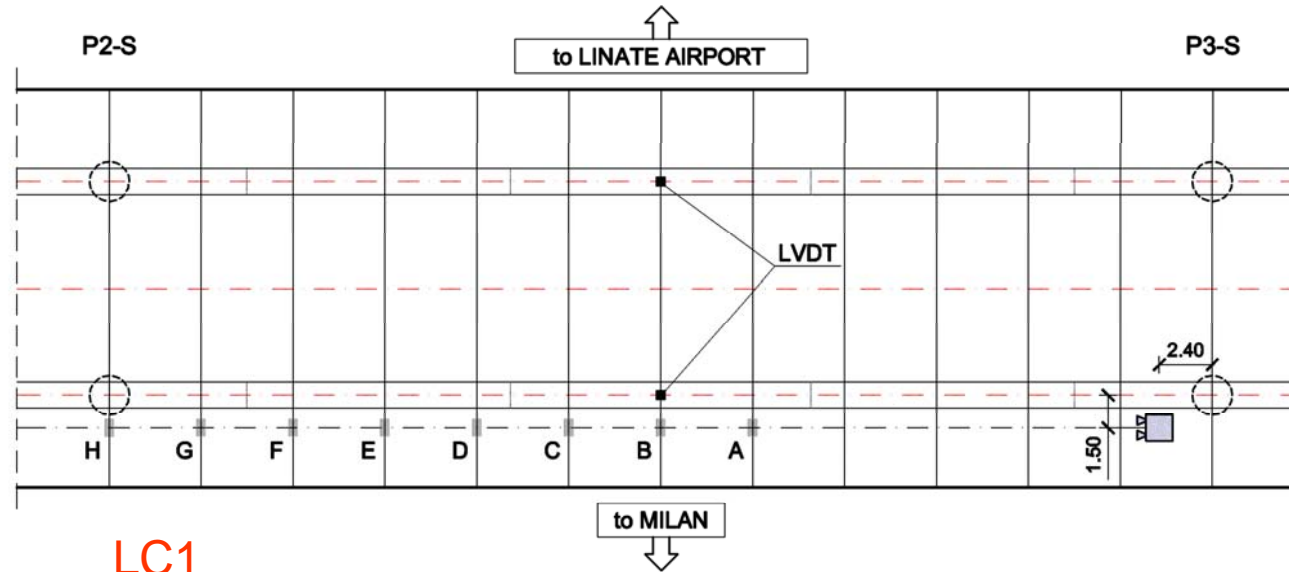
Bridge testing: static live load test



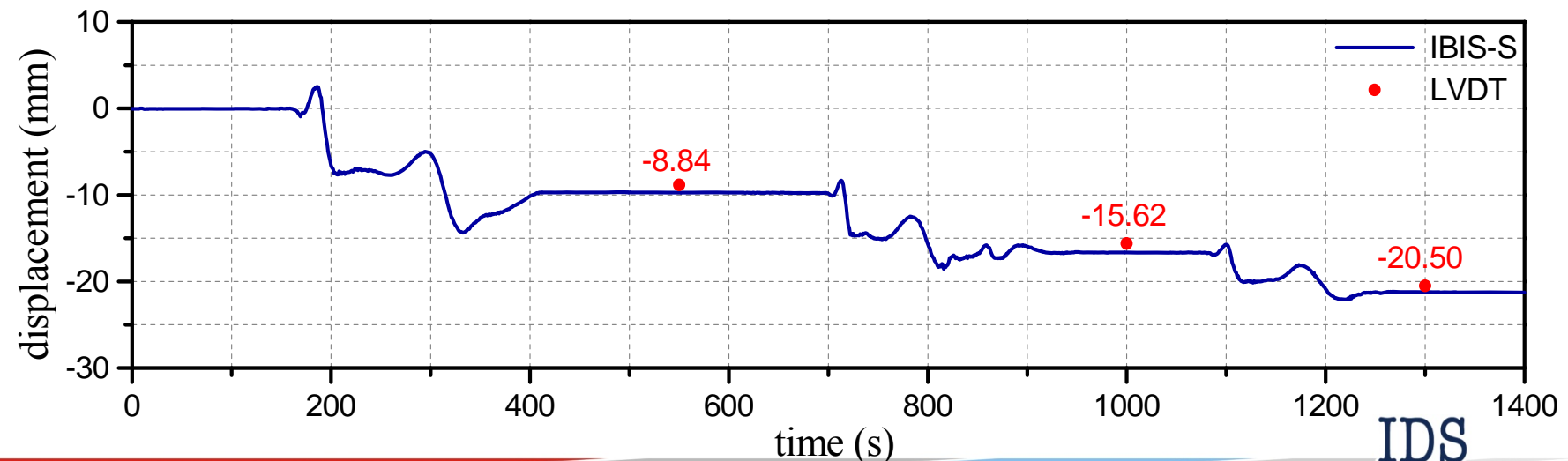
LVDT



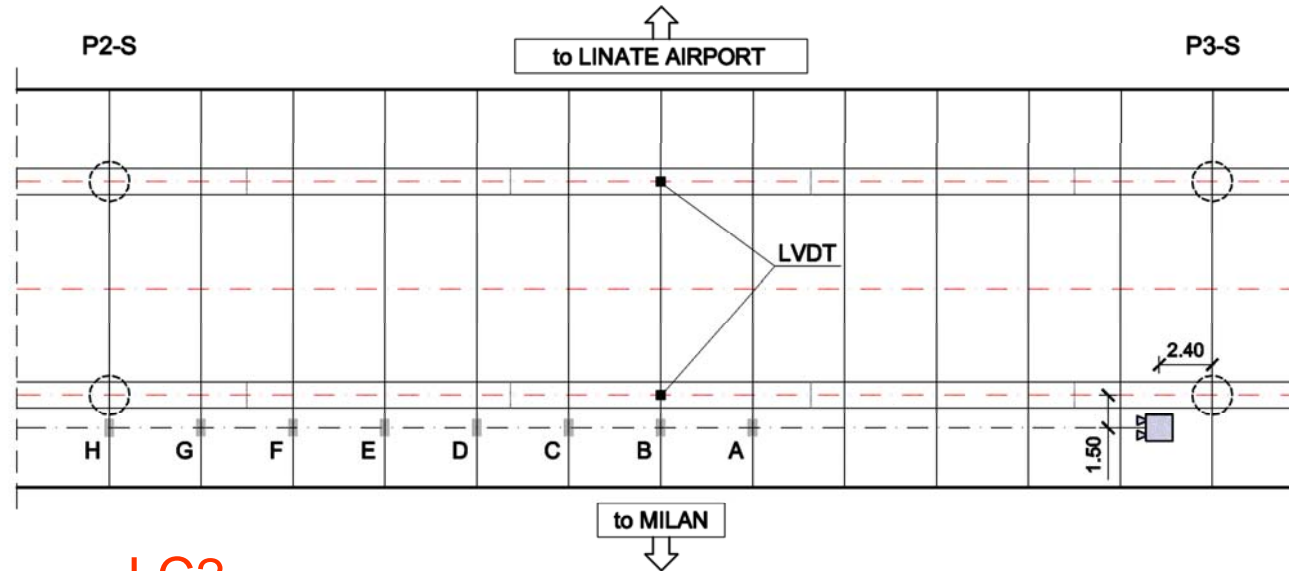
Bridge testing: static live load test



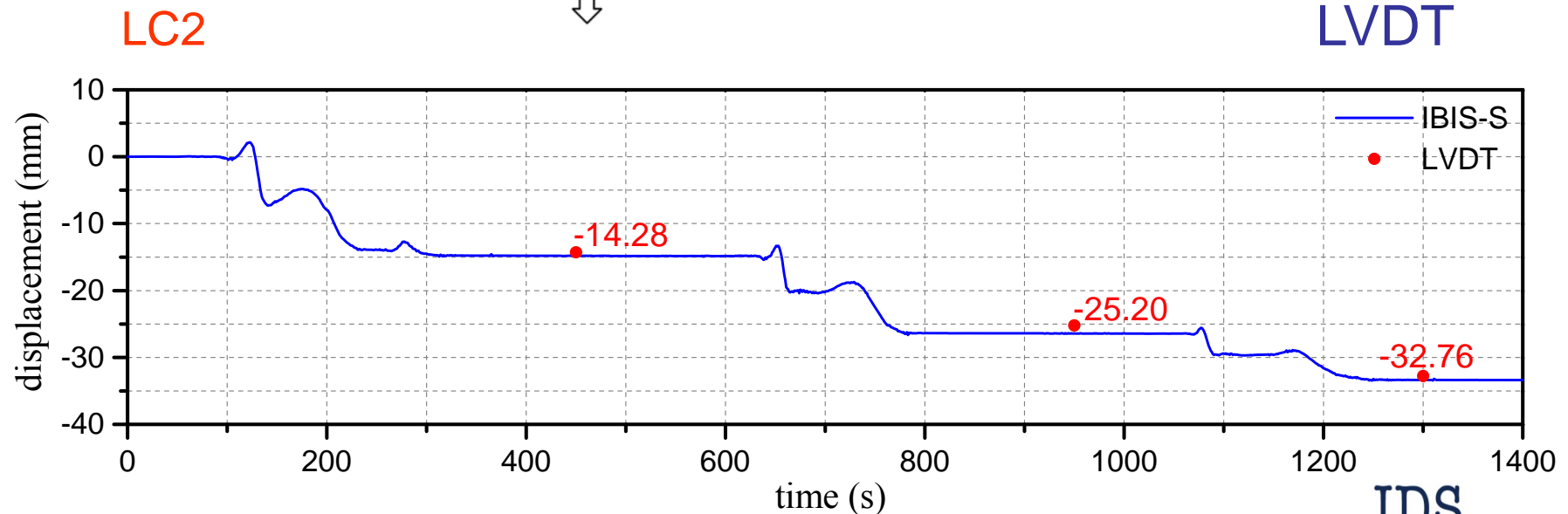
LVDT



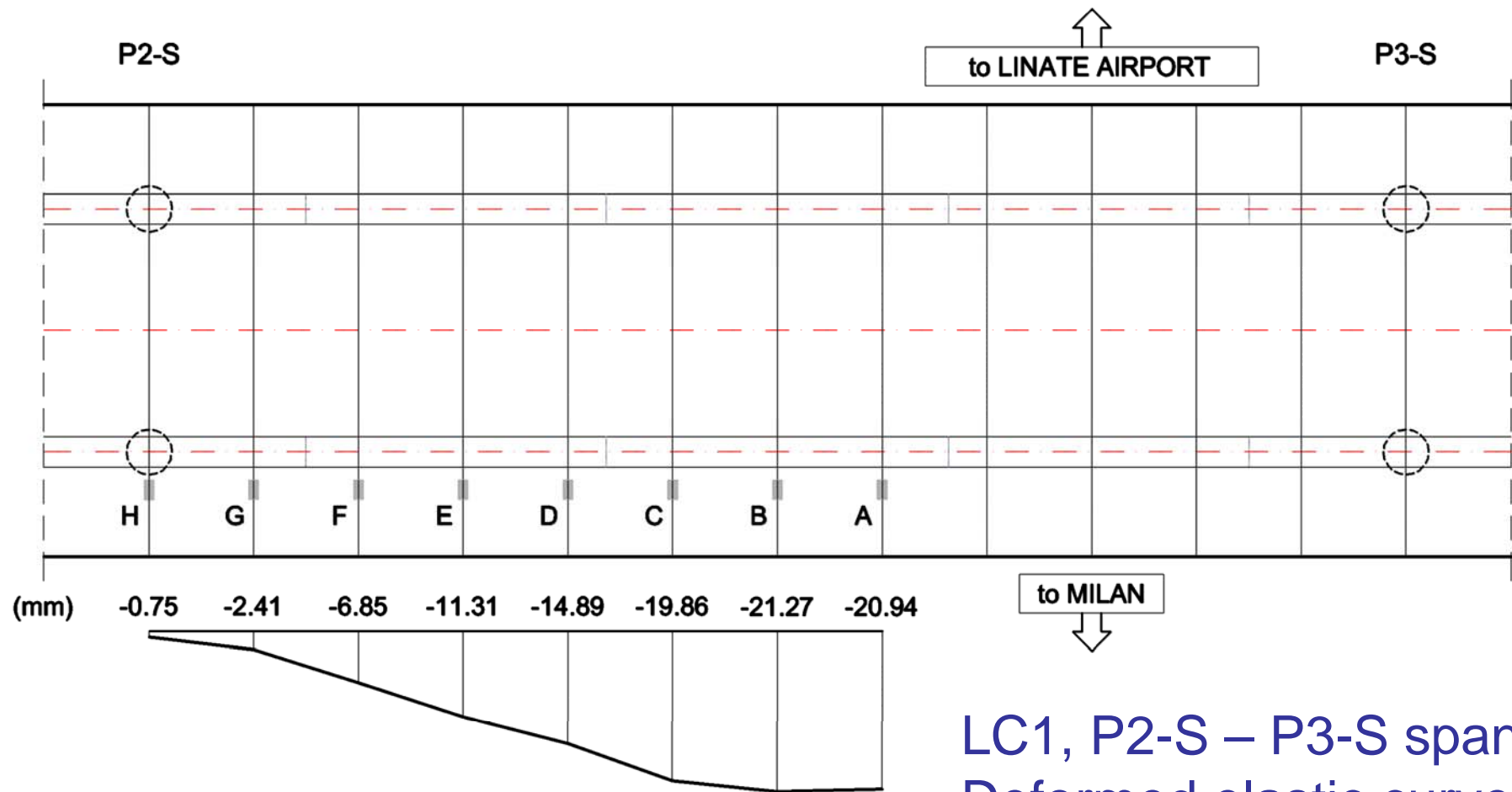
Bridge testing: static live load test



LVDT



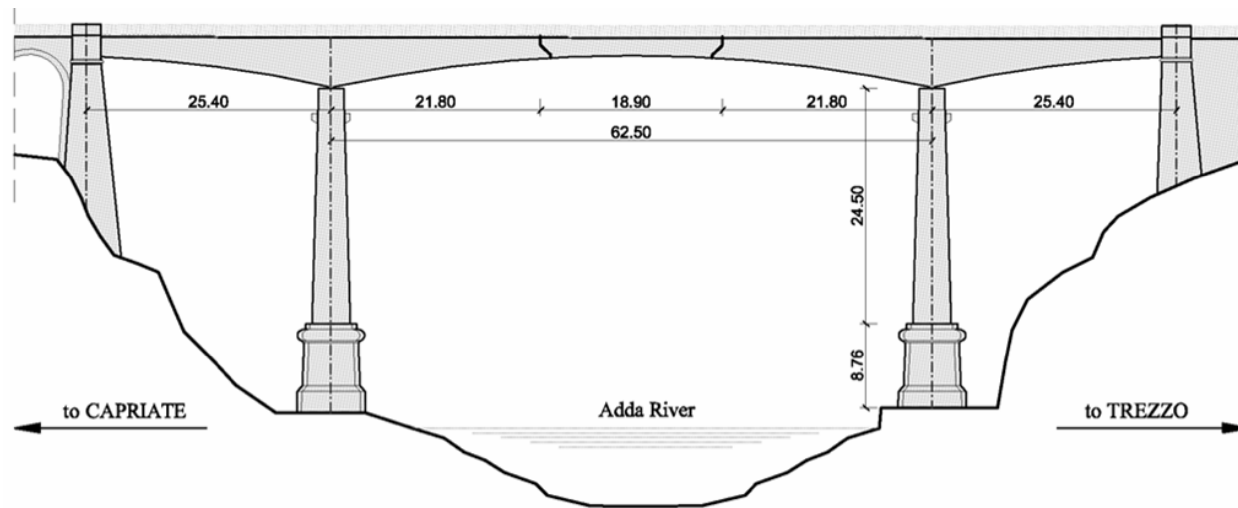
Bridge testing: static live load test



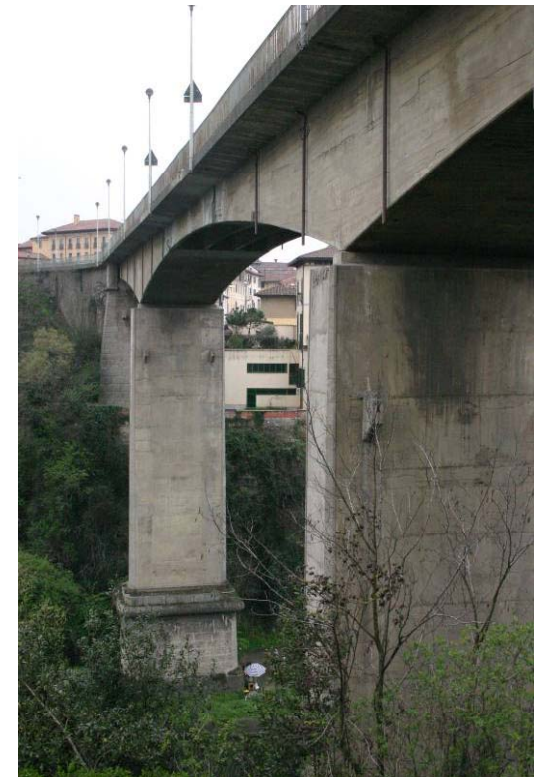
LC1, P2-S – P3-S span:
Deformed elastic curve
provided by IBIS-S

Bridge testing: dynamic test of bridge span

Measurement objective: comparison with accelerometers, resonance frequencies and modal shape retrieval



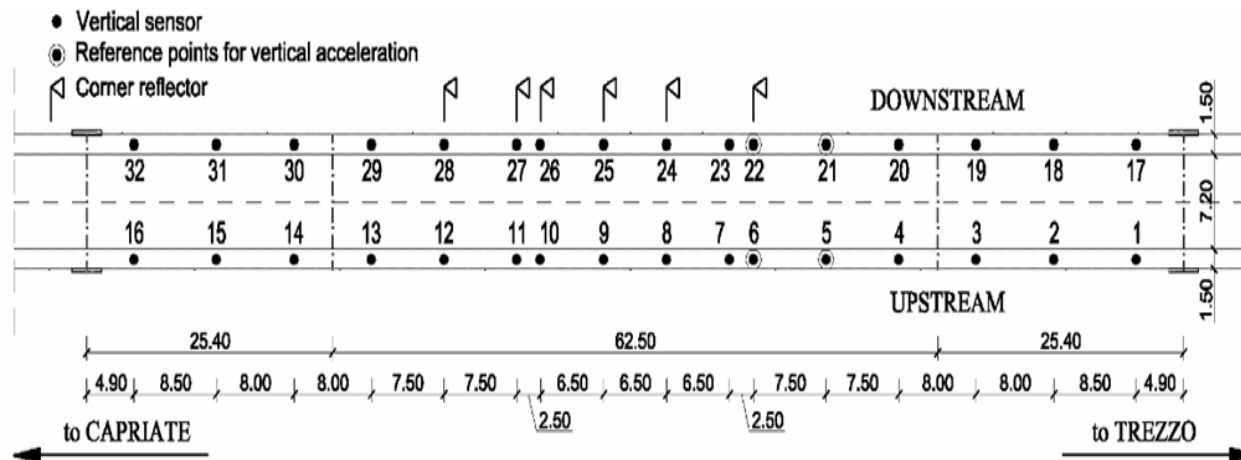
Central arch length (m): 62.5



Bridge testing: dynamic test of bridge span

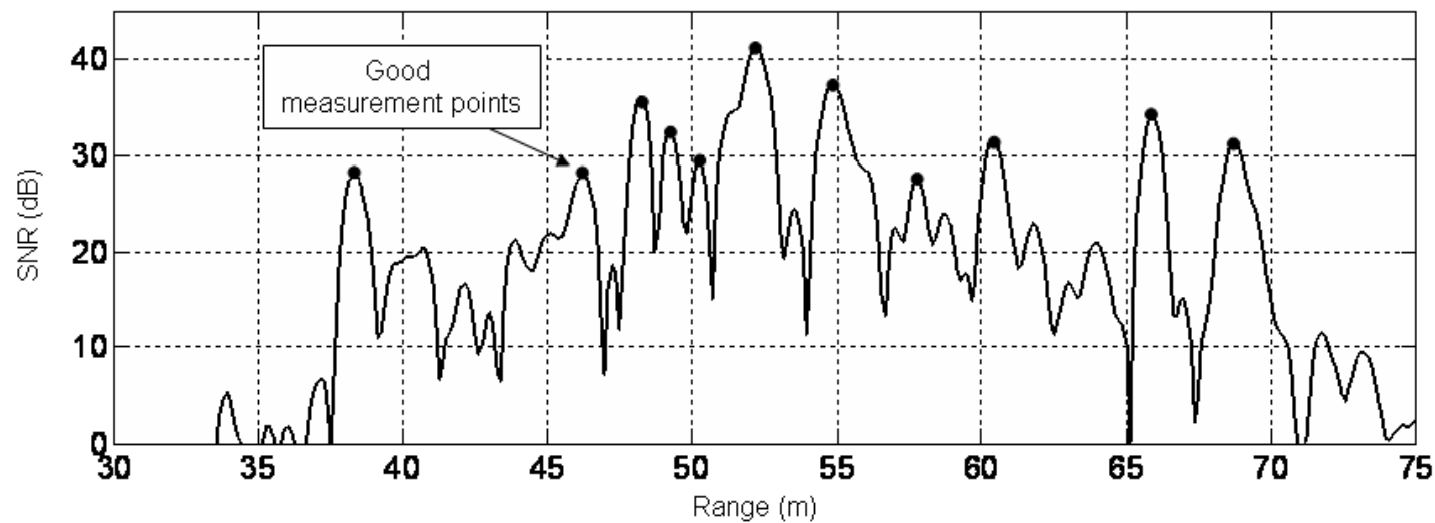


To make a comparison between the results of IBIS-S system and accelerometers system 6 corner reflector were installed at the same position of accelerometers



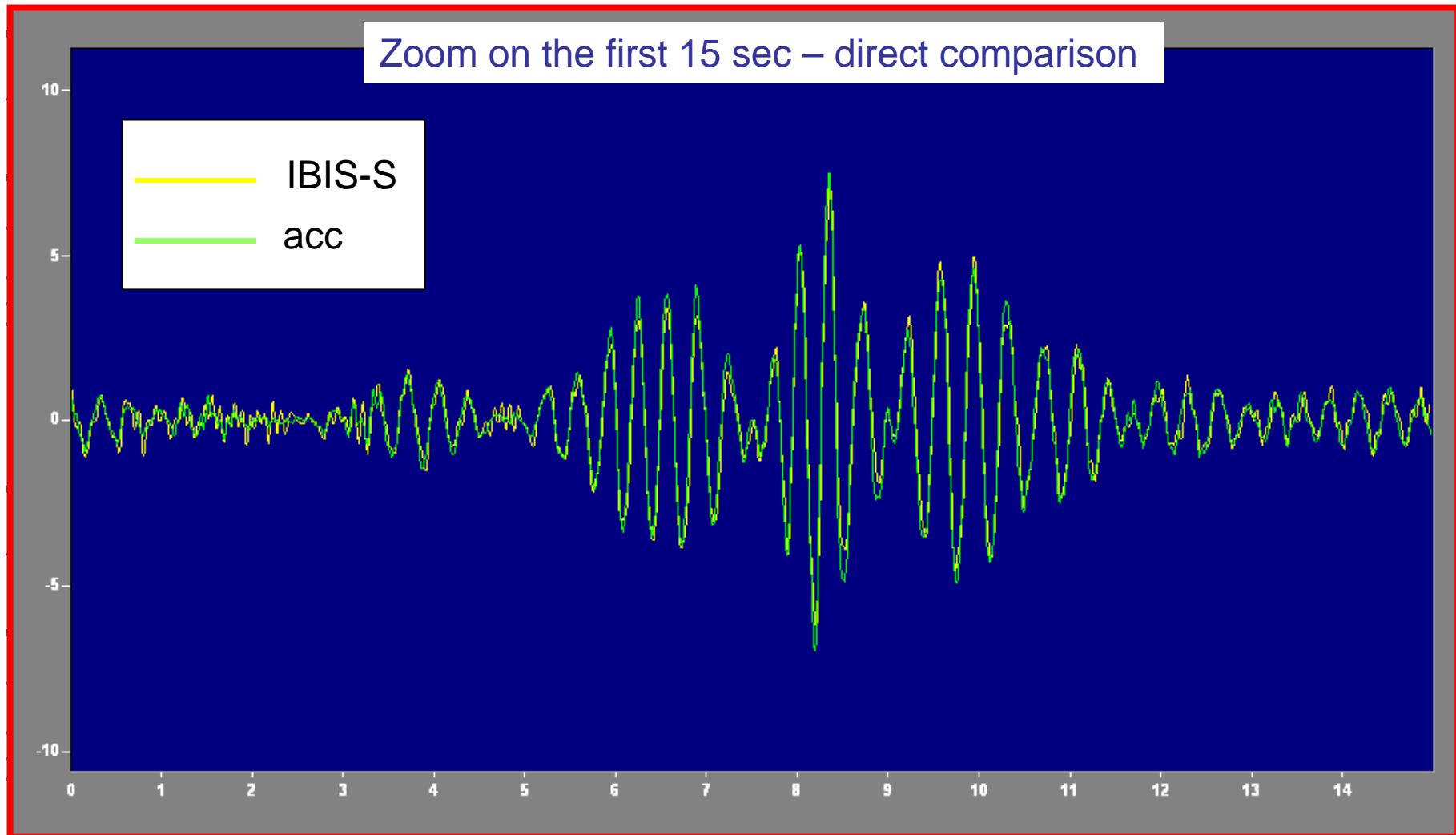
Bridge testing: dynamic test of bridge span

Bridge photograph and range profile

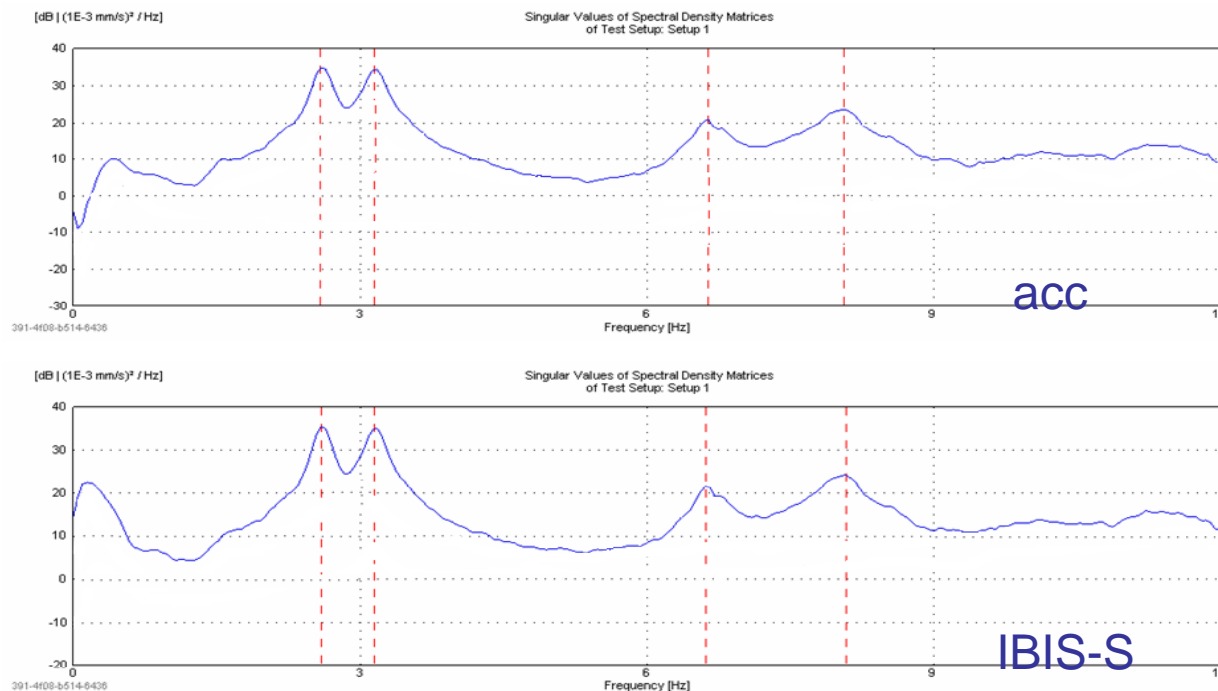


Bridge testing: dynamic test of bridge span

Velocity comparison for Test Point 22



Bridge testing: dynamic test of bridge span



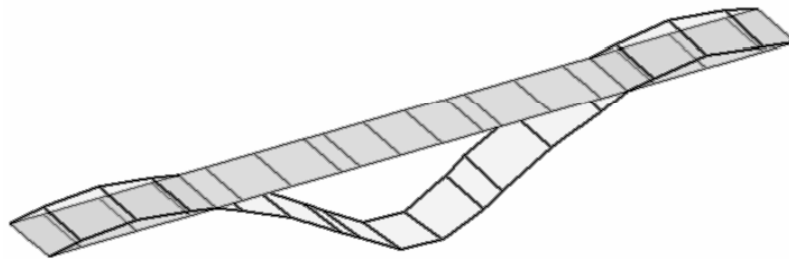
Frequency analysis
comparison on
3000sec
acquisition duration

Acc detected frequency	IBIS-S detected frequency	Percentage error
Hz	Hz	%
2,617	2,595	0,84
3,164	3,182	-0,57
6,641	6,608	0,50
8,086	8,077	0,11

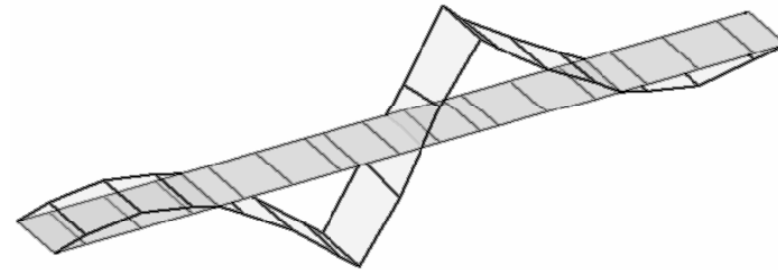
Bridge testing: dynamic test of bridge span

Modal shape obtained by accelerometer data

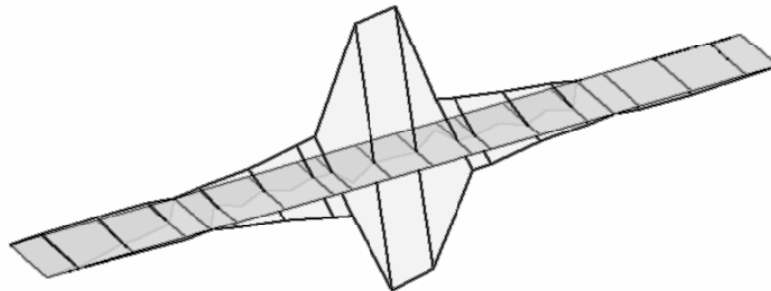
$f = 2.617 \text{ Hz}$



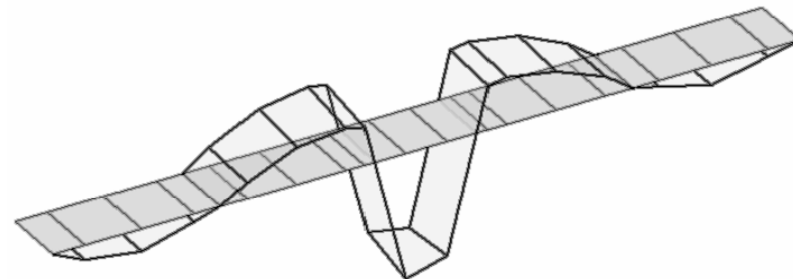
$f = 3.164 \text{ Hz}$



$f = 6.641 \text{ Hz}$

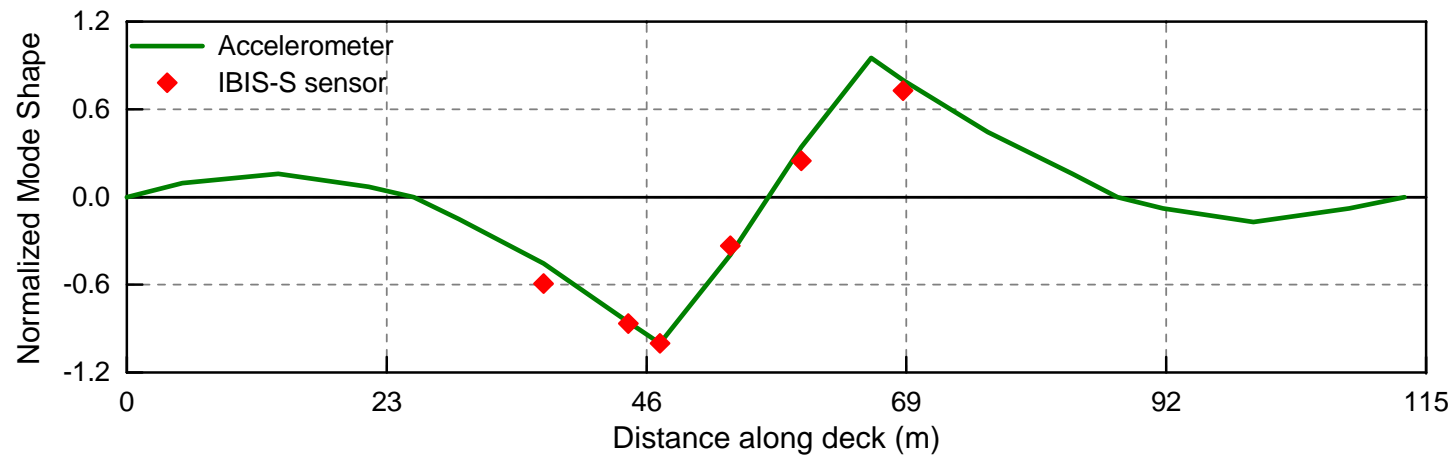
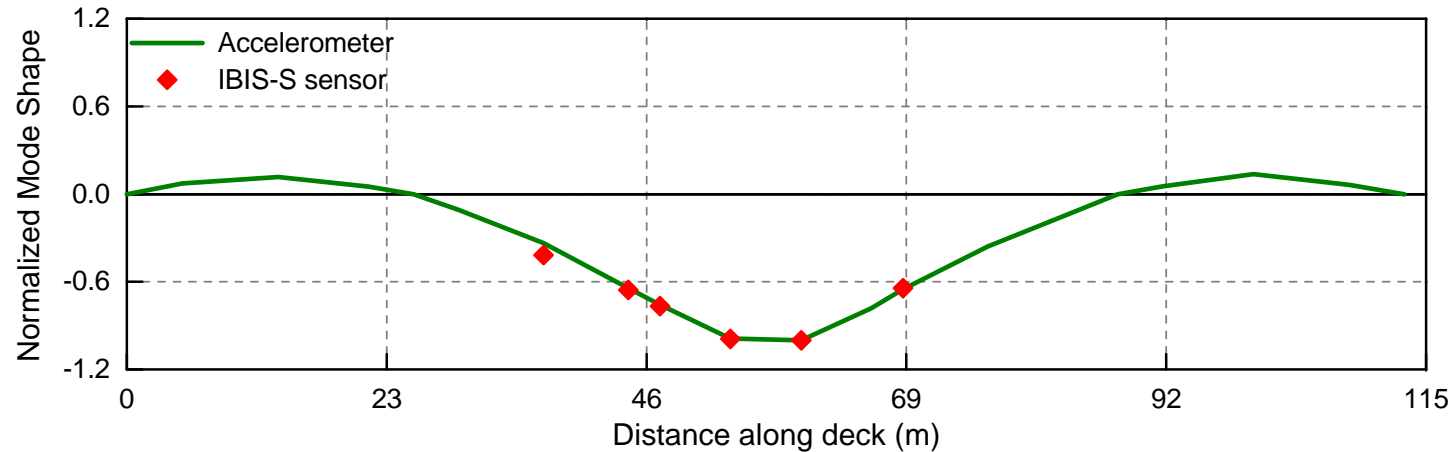


$f = 8.086 \text{ Hz}$



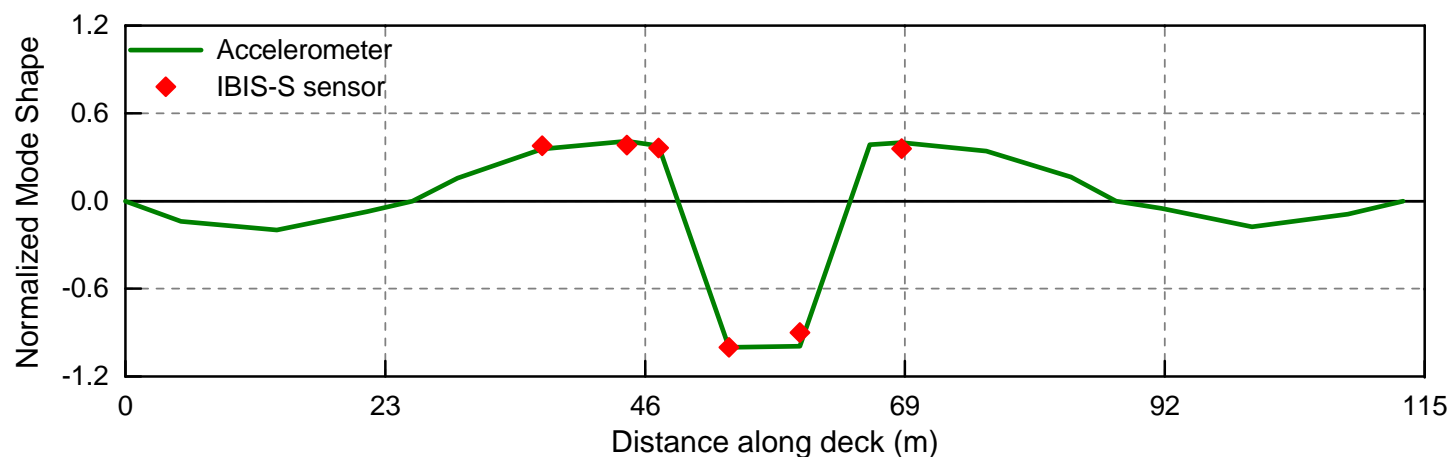
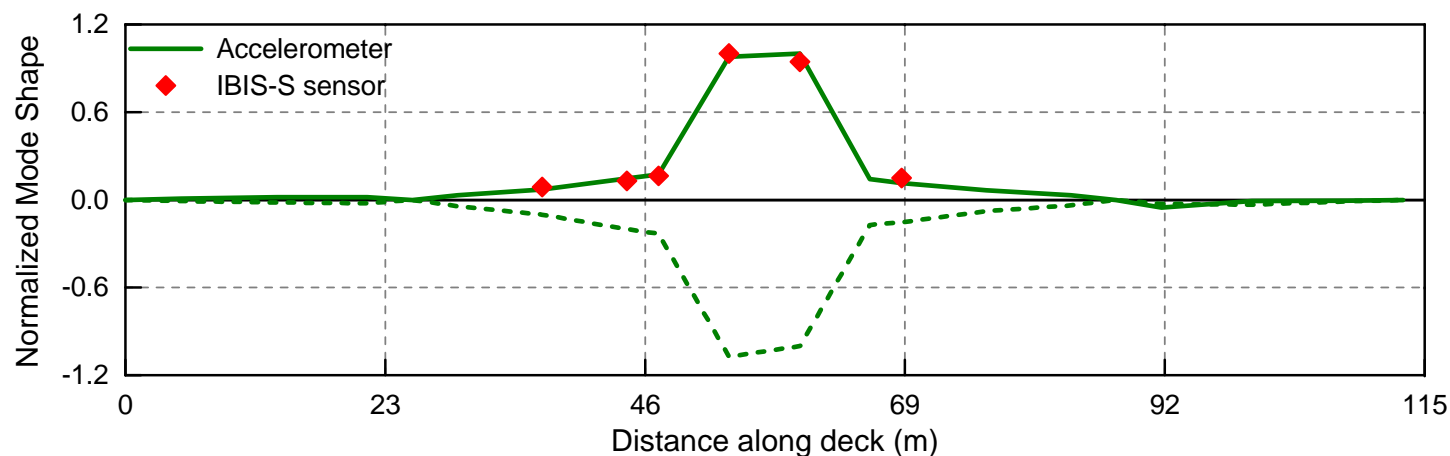
Bridge testing: dynamic test of bridge span

Modal shapes comparison



Bridge testing: dynamic test of bridge span

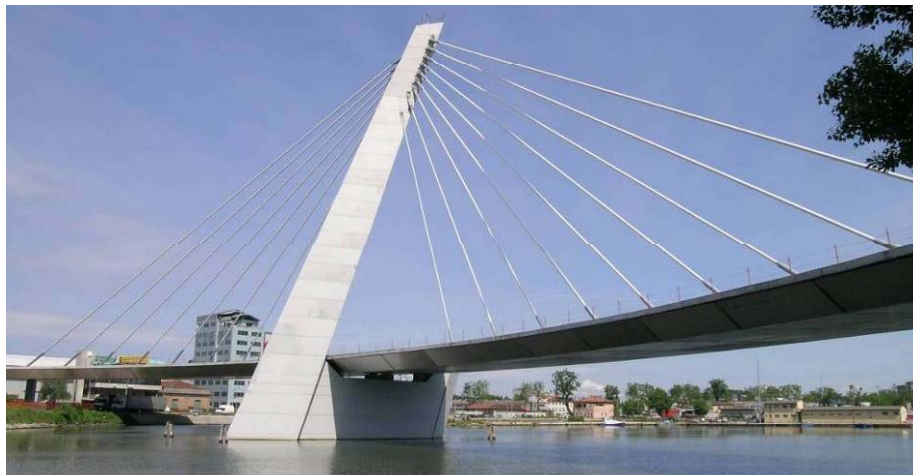
Modal shapes comparison



Bridge testing: Cable-stayed bridges

Application goal: dynamic analysis done through ambient vibration testing (AVT) aimed at:

- Identify the **amplitude** of the **cable vibrations**;
- Identify the **natural resonant frequencies** and the **cable dumping factors**
- Evaluate the **tension** and the **operating strain** of **cables** to verify the correct distribution of loads and the temporal variation of tensions along the bridge life



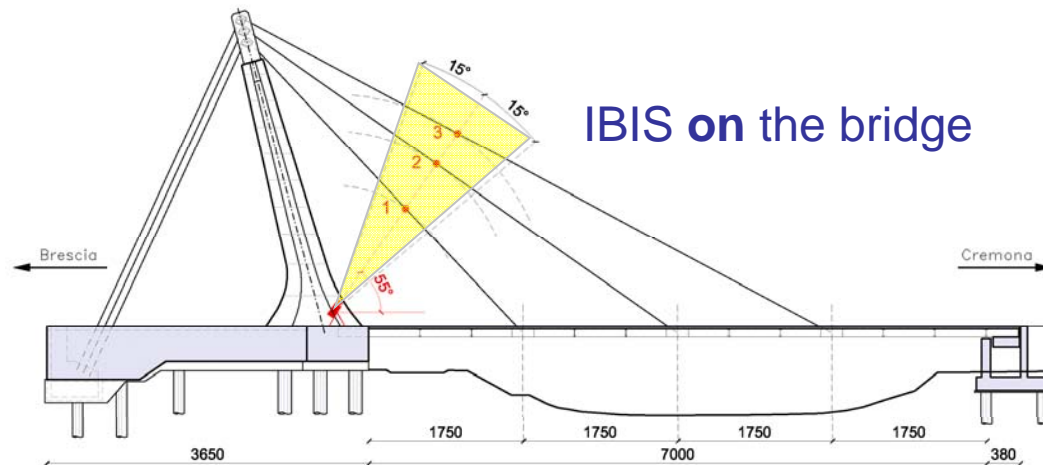
Bridge testing: Cable-stayed bridges

Advantages in the use of IBIS-S:

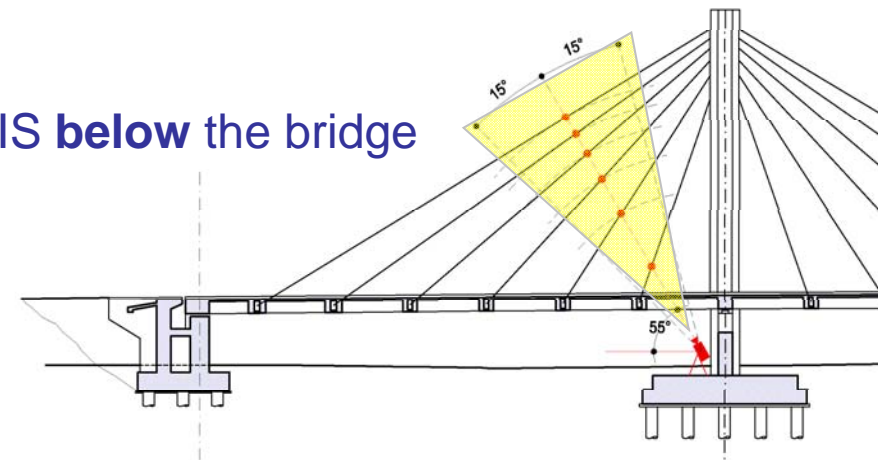
- Provide **displacement** measurements (useful to evaluate the amplitude of vibrations)
- Very **accurate** measurement: an order of magnitude higher than LDV
- **No traffic shut-down** needed (IBIS can be installed under the bridge or beside the bridge towers)
- **Simultaneous** measurement on a large number of cables (potentially all cables of each side at once)
- **Rapid** installation and measurement set-up

Bridge testing: Cable-stayed bridges

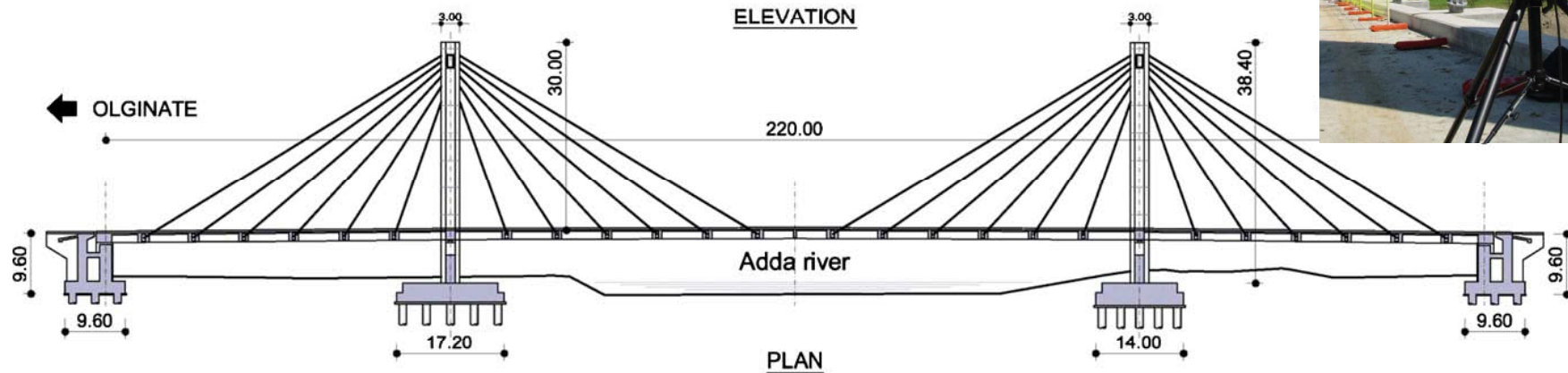
Geometrical sketch of IBIS-S set-up:



IBIS below the bridge



Bridge testing: Cable-stayed bridges

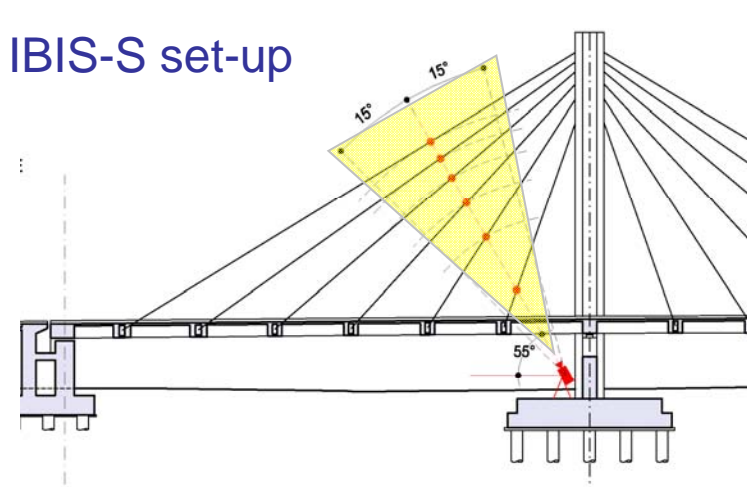


Bridge testing: Cable-stayed bridges

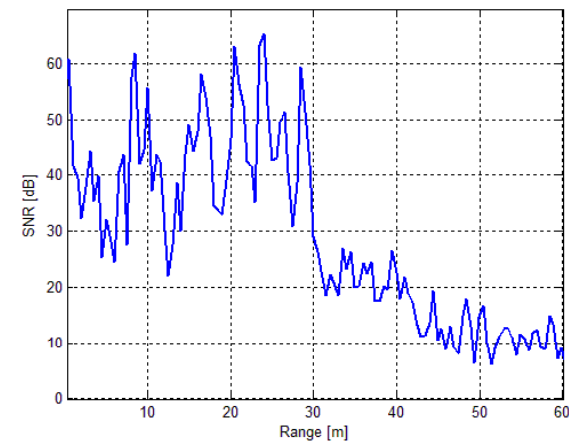


Olginate bridge (Italy)

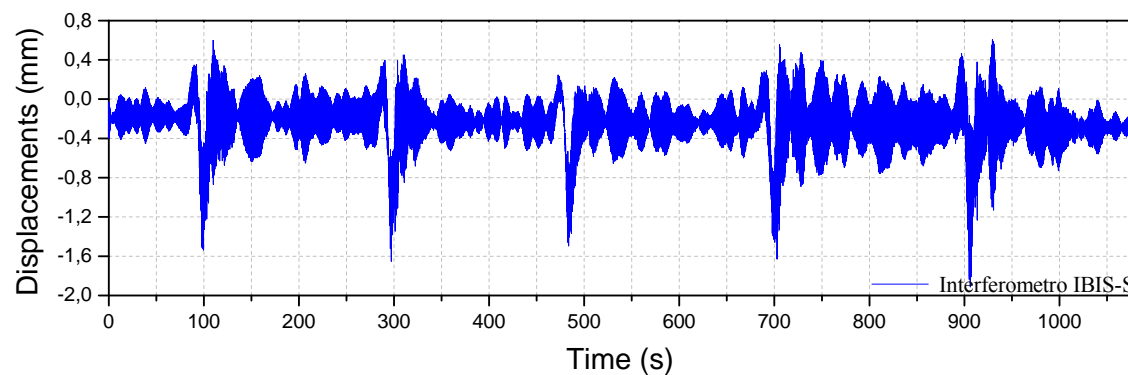
IBIS-S set-up



Range Profile



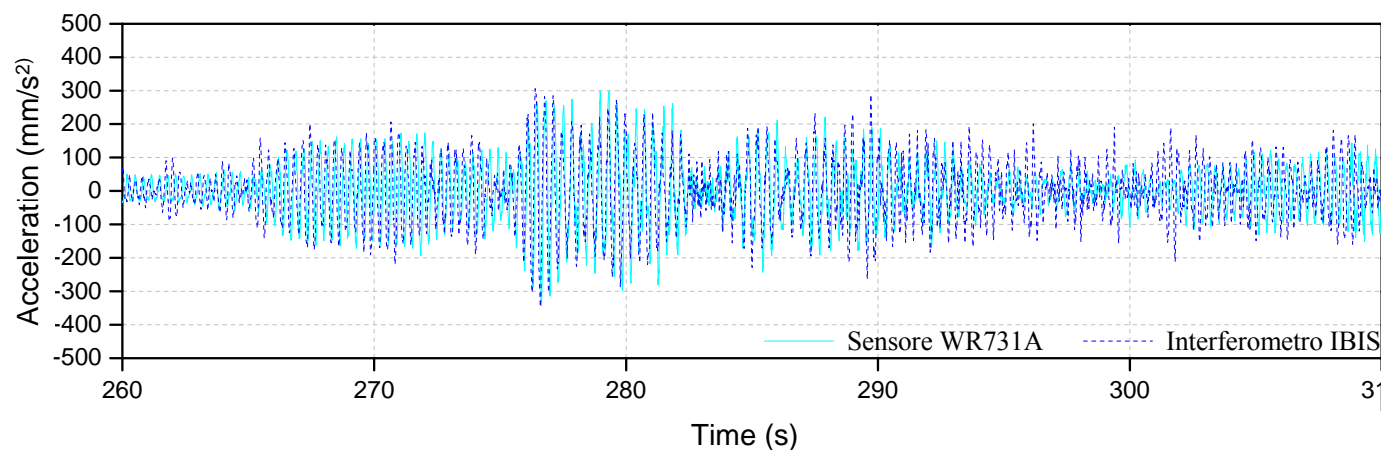
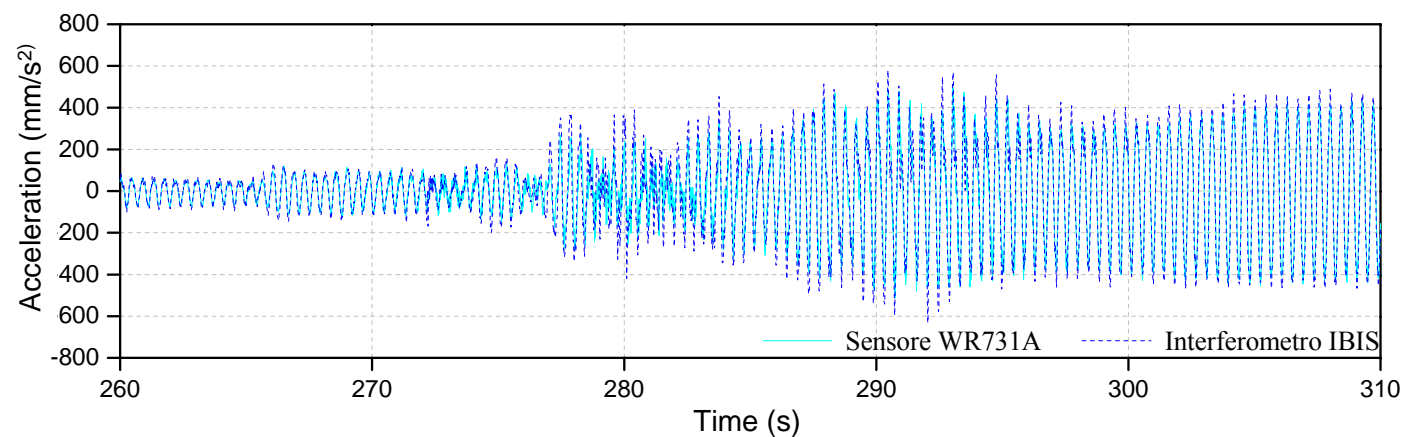
Displacement graph



Bridge testing: Cable-stayed bridges

Example: Olginate bridge (Italy)

Comparison with accelerometers

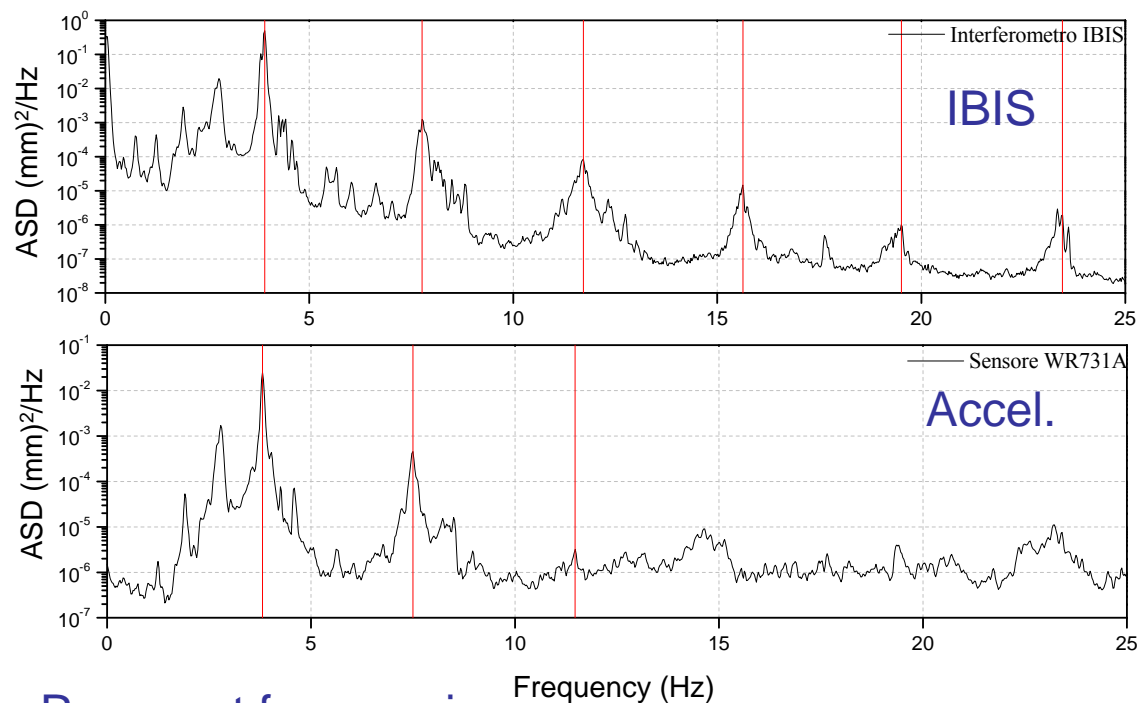


31 Piezo-electric accel. WR 731A

Bridge testing: Cable-stayed bridges

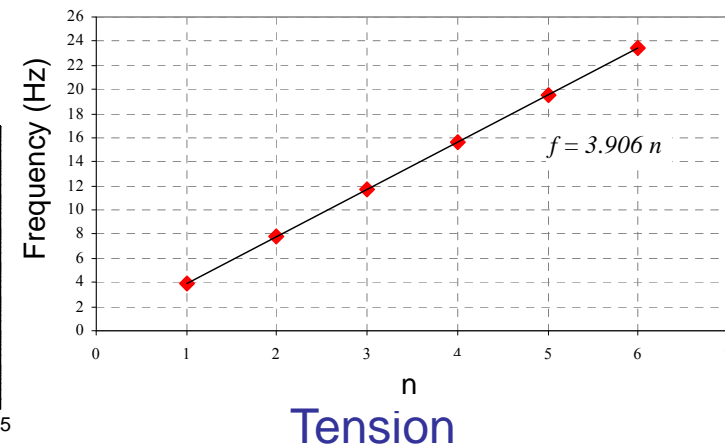
Example: Olginate bridge (Italy)

Frequency Domain Analysis



Resonant frequencies

	f_1 (Hz)	f_2 (Hz)	f_3 (Hz)	f_4 (Hz)	f_5 (Hz)	f_6 (Hz)
IBIS-S	3.906	7.764	11.720	15.630	19.510	23.460
Accel.	3.809	7.495	11.470			



Cable S09'			
IBIS-S		Accelerometer	
f_{exp} (Hz)	Tension (kN)	f_{exp} (Hz)	Tension (kN)
3.906	1883.1	3.809	1790.7
7.764	1860.0	7.495	1733.3
11.720	1883.7	11.470	1804.2
15.630	1884.5		
19.510	1879.2		
23.460	1886.9		
	1880		

High-rise structures: chimney testing

Measurement objective: measurement of the displacements of the old and new chimney and identification of their resonance frequencies

Old chimney



Chimney high: 183m

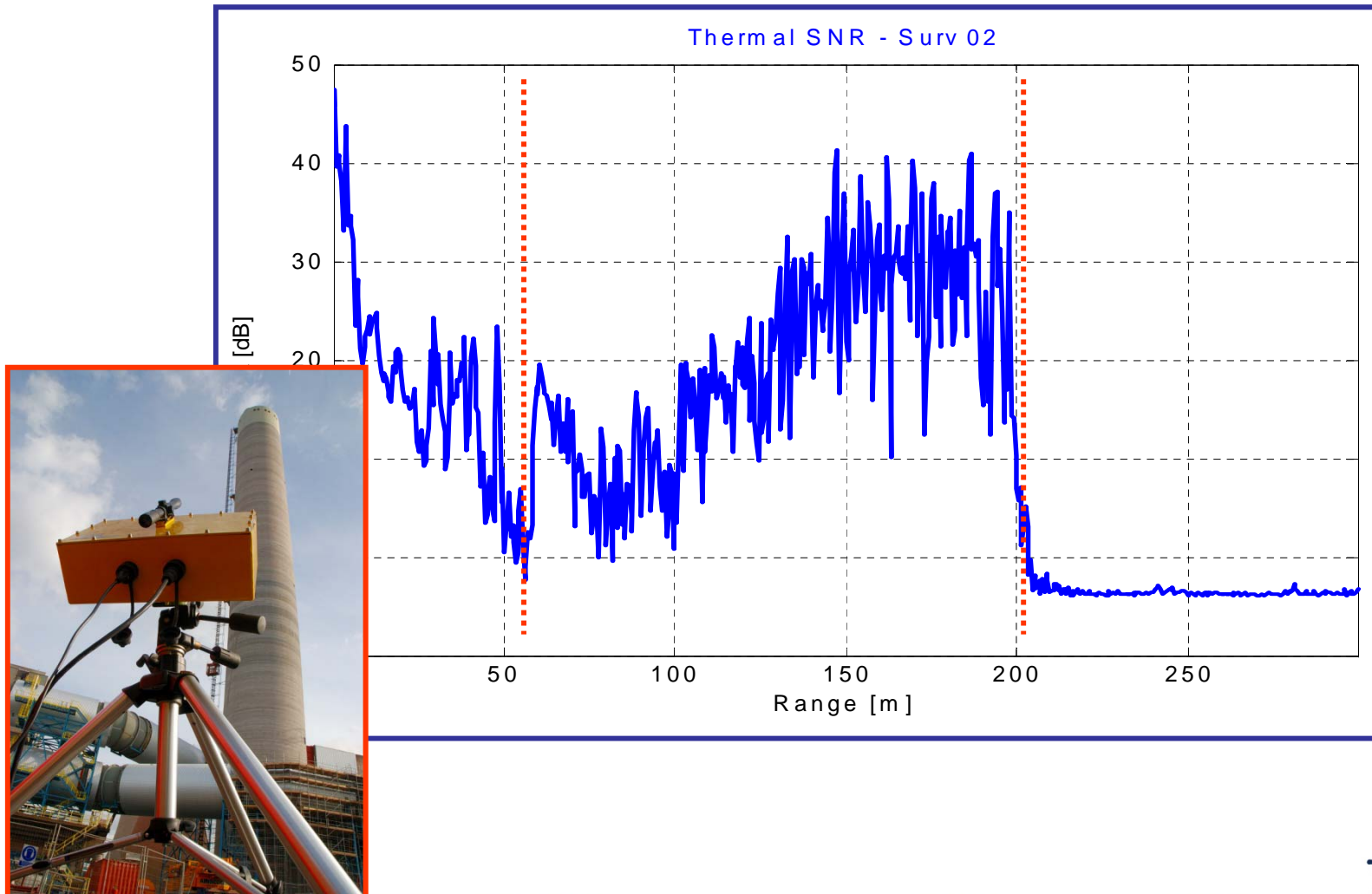
Measurement parameters:
maximum range: 300 m
sampling frequency: 50 Hz
range resolution: 0.5 m
distance from the target: ~ 50 m

New chimney



High-rise structures: chimney testing

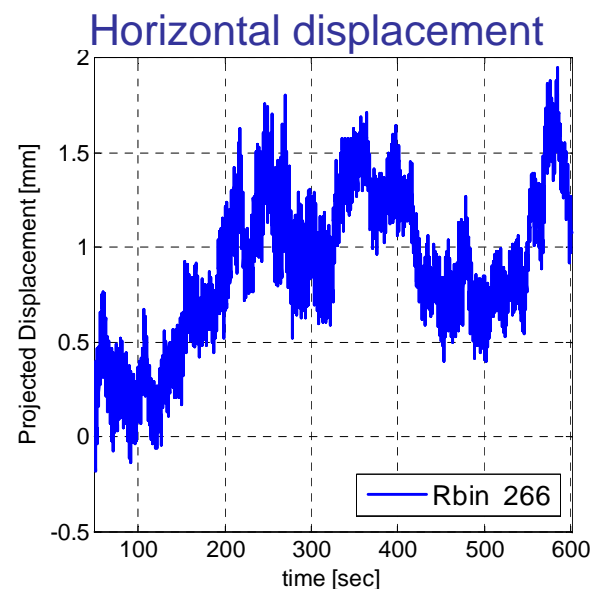
Range profile of the new chimney



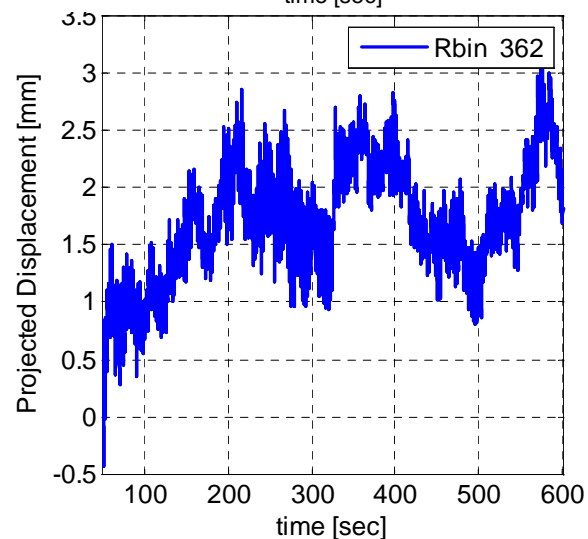
High-rise structures: chimney testing

New chimney

Point located at the middle of the chimney, at a height of 121 m

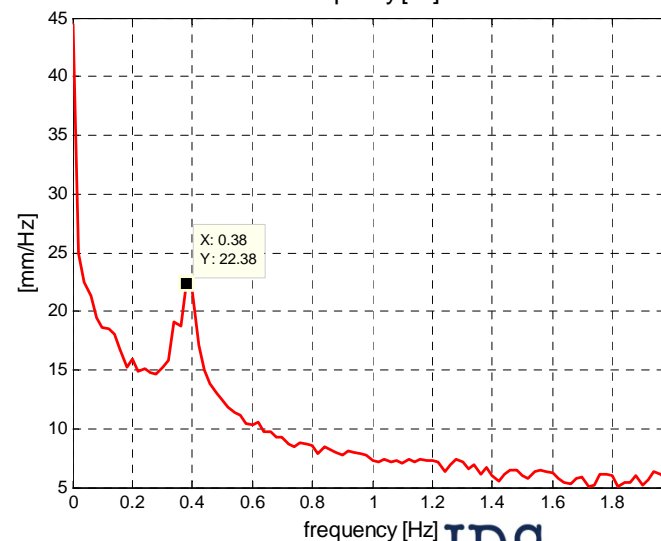
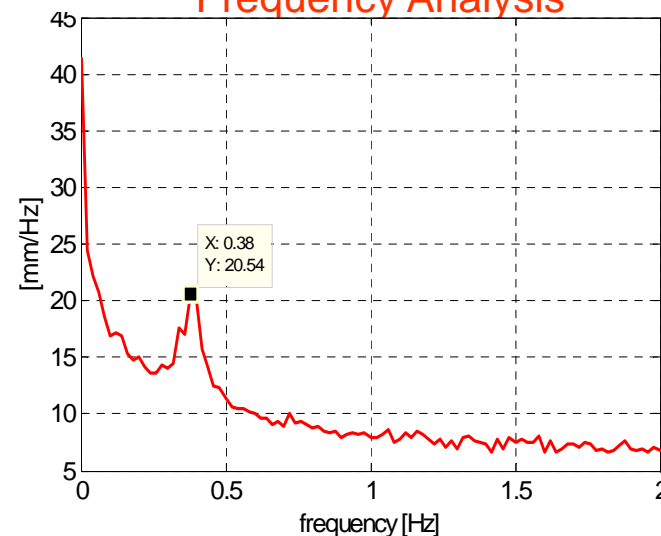


Point located at the top of the chimney, at a height of 172 m



Identified frequency: 0.38 Hz

Frequency Analysis



Convegno ALIG: La tecnologia georadar per la diagnostica non distruttiva dei manufatti

PISA 13 Maggio 2011

Paolo Papeschi

Guido Manacorda

Alessandro Simi

CONVEGNO ALIG

13 maggio 2011 ore 9⁰⁰-18⁰⁰



sede del convegno

PISA

Loc. Montacchiello via E. Calabresi, 24

NUOVE TECNOLOGIE RADAR

**COLLAUDO. MONITORAGGIO E
INDAGINI NON INVASIVE PER MANUFATTI**

con il patrocinio :

ORDINE GEOLOGI REGIONE TOSCANA



con la collaborazione :

IDS Ingegneria dei Sistemi SpA



POLITECNICO DI MILANO

BOVIAR srl

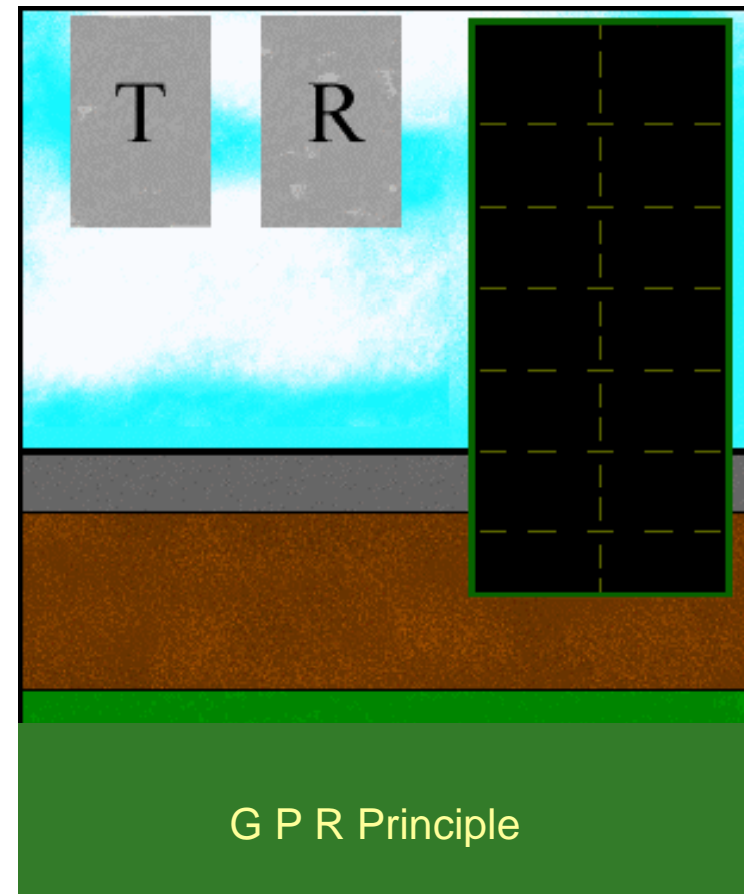
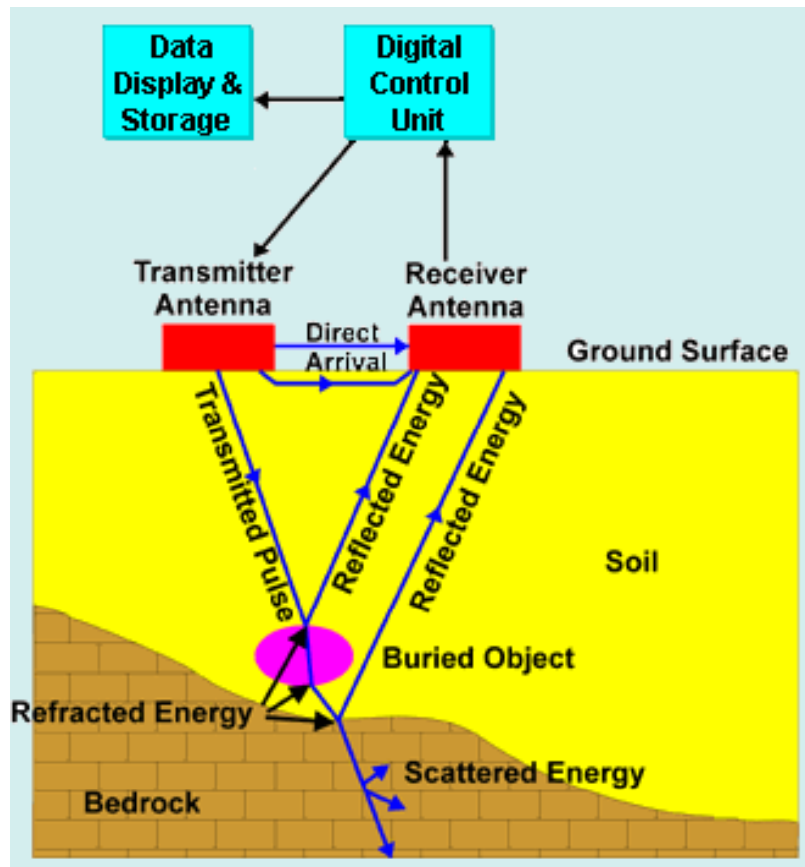


Introduzione

- IL G.P.R. (Ground Penetrating Radar) impiega l'energia elettromagnetica a radiofrequenza per l'indagine della struttura del sottosuolo o di costruzioni antropiche, senza alterarne la loro struttura fisica.
- Questo rende la prospezione molto più veloce ed economica rispetto alle tradizionali indagini invasive.
- Perciò il G.P.R. si presta ad una varietà di applicazioni tipo:
 - Ricerca di sottoservizi (tubature, cavi).
 - Individuazione di siti archeologici.
 - Valutazione dell'integrità di strutture (mura, tunnel, pavimenti).
 - Applicazioni geologiche (ricerca di cavità e fratture).
 - Verifica di fondazioni ed altro ancora.

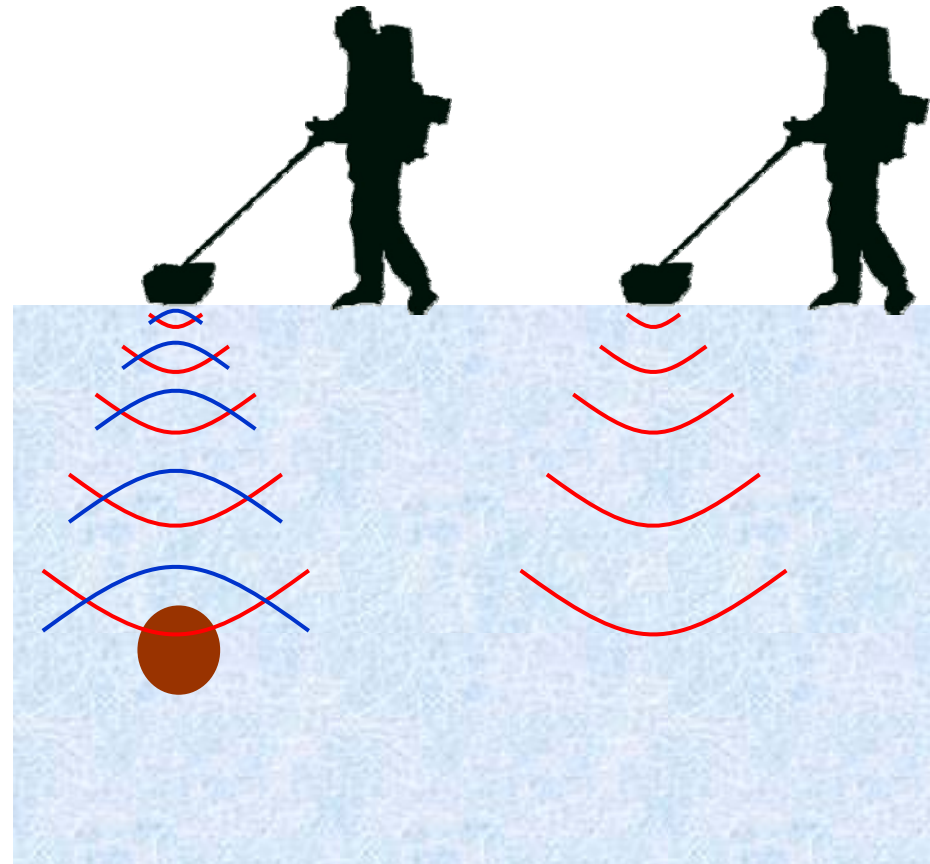
GROUND PENETRATING RADAR (GPR)

GPR è una tecnologia che è stata sviluppata per indagini superficiali ad alta risoluzione e per indagini nel sottosuolo. GPR utilizza onde elettromagnetiche ad alta frequenza impulsive tipicamente comprese tra 25 MHz e 2000 MHz.



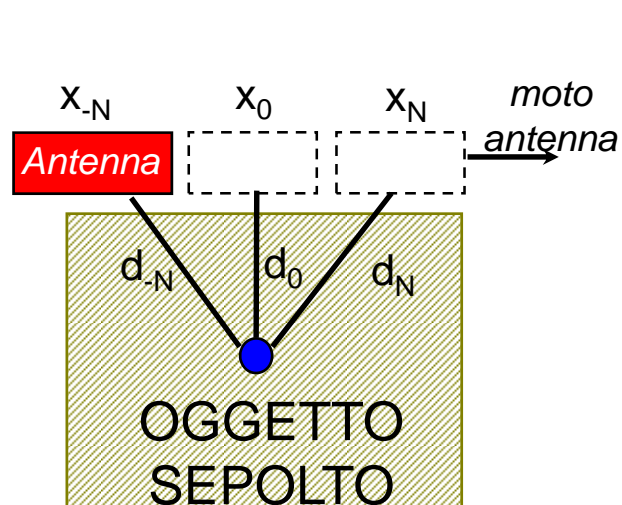
Principio di funzionamento

- ✓ Il Georadar trasmette un impulso molto breve (1-2 ns) di energia nel materiale mediante una antenna
- ✓ L'Energia riflessa dalle interfacce e dalle discontinuità viene registrata da un'antenna
- ✓ Profondità e risoluzione sono correlate alle frequenze trasmesse, all'energia trasmessa, alle proprietà elettromagnetiche dei materiali e dalle caratteristiche dei bersagli

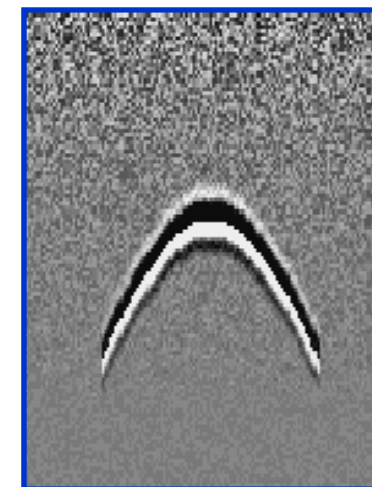
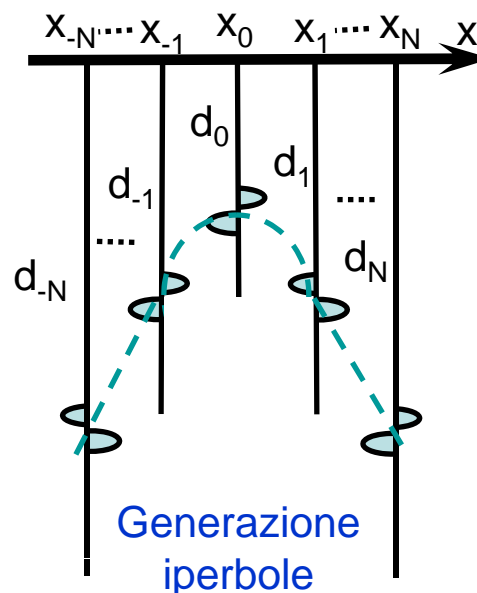


Generazione della mappa

L'oggetto sepolto viene 'visto' dal georadar in modo deformato



Acquisizione

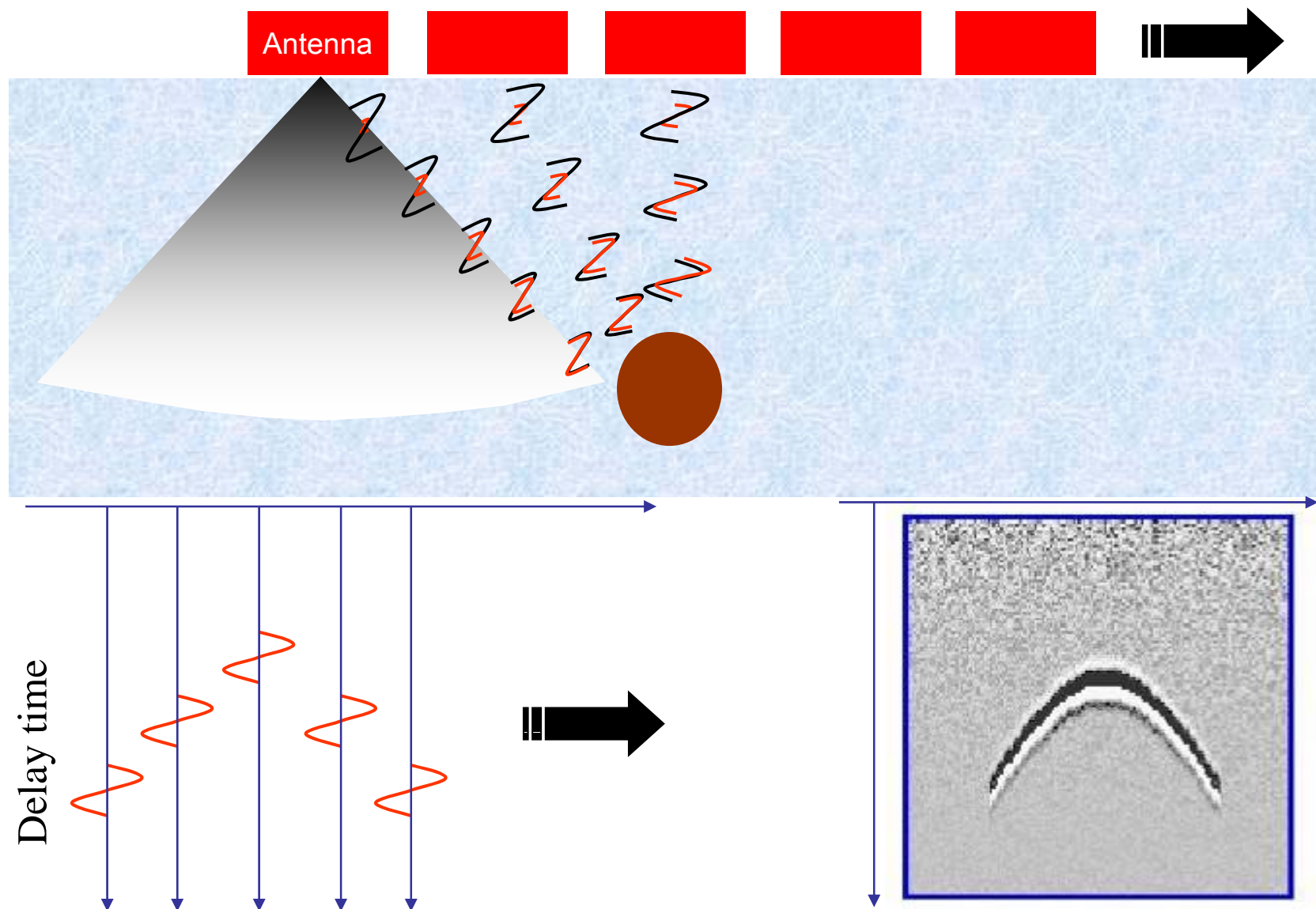


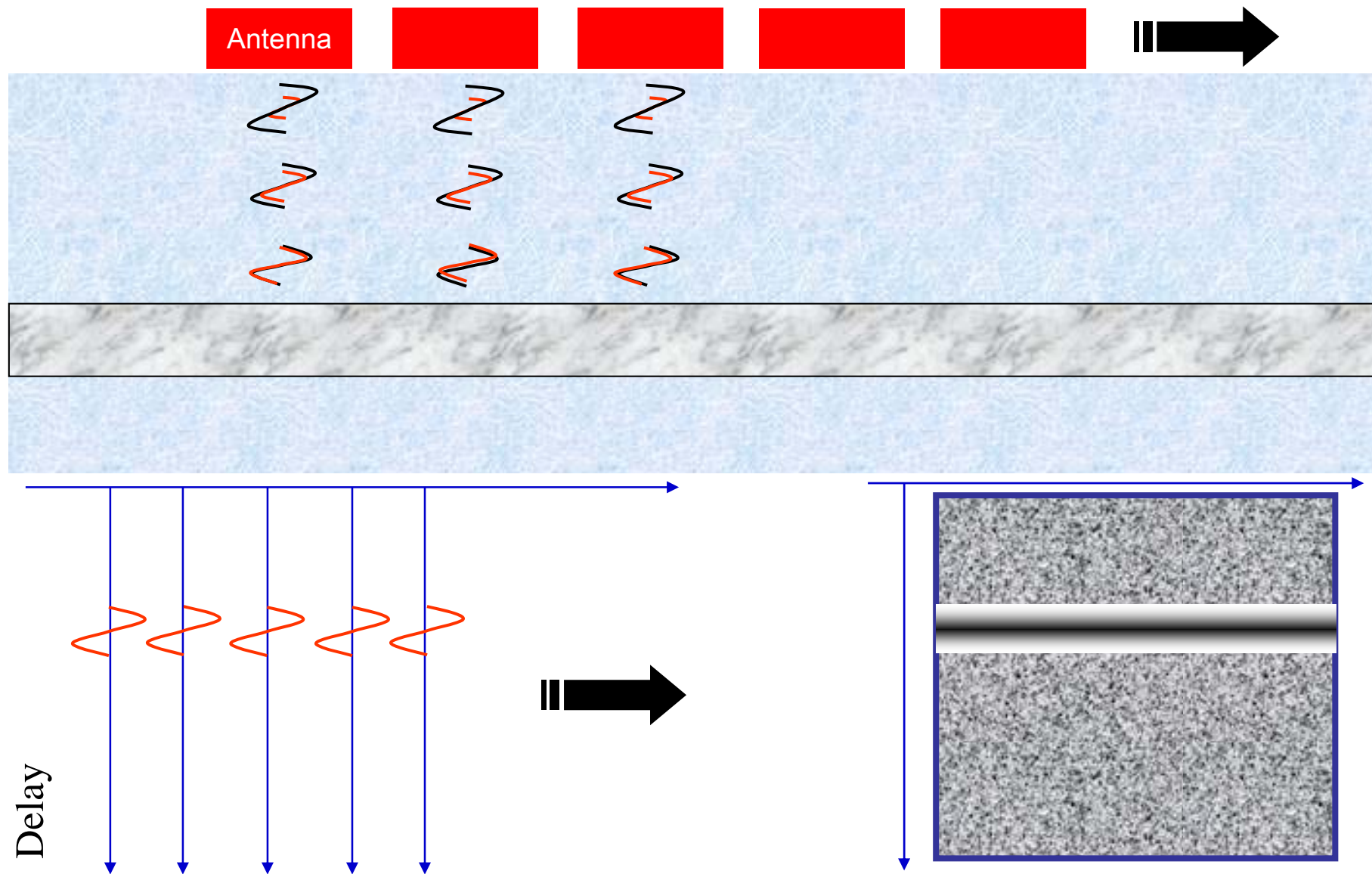
Mappa radar

Il RADAR “vede” il bersaglio in un intorno della posizione di minima distanza

L'oggetto sepolto risulta visibile se:

- si trova nel fascio irradiazione antenna
- rapporto segnale /clutter > minimo valore sufficiente alla rivelazione





Diverse antenne a diversa frequenze...



Le applicazioni



Utilities



Transportations



Civil and Structures



Geology and Environment



**Archaeology and
Cultural Heritage**



Forensic and Security



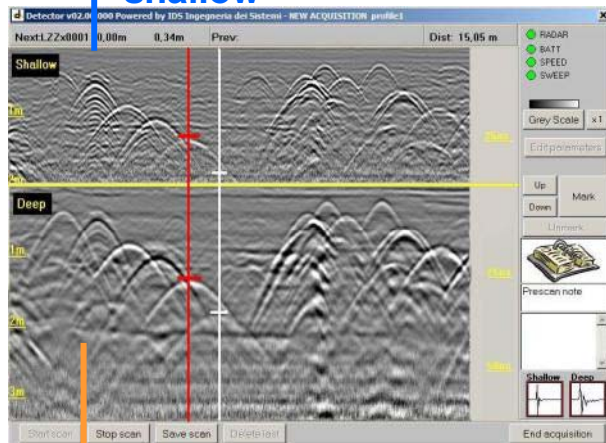
Utilities Detection and Mapping

Detector Duo:

real-time
detection of
pipes



shallow

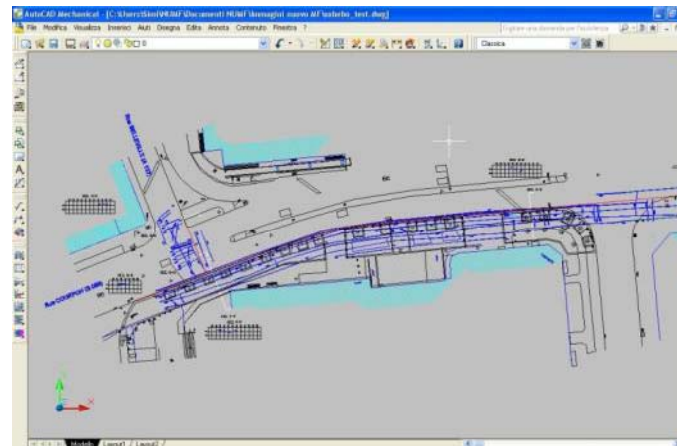


deep



RIS MF Hi-Mod:

Utilities
mapping on all
zones





Utilities Detection and Mapping

Stream: massive arrays for the fast mapping of utilities

Stream EM:

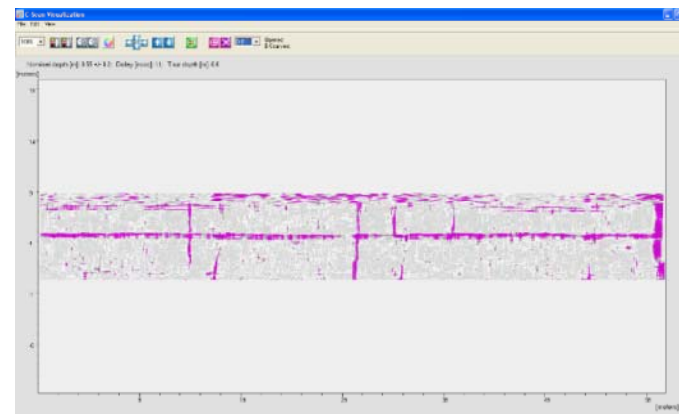
Vehicle towed
array for
extensive road
utility mapping



Stream MT:

Fast utility
mapping for
Mini-Trenching
applications

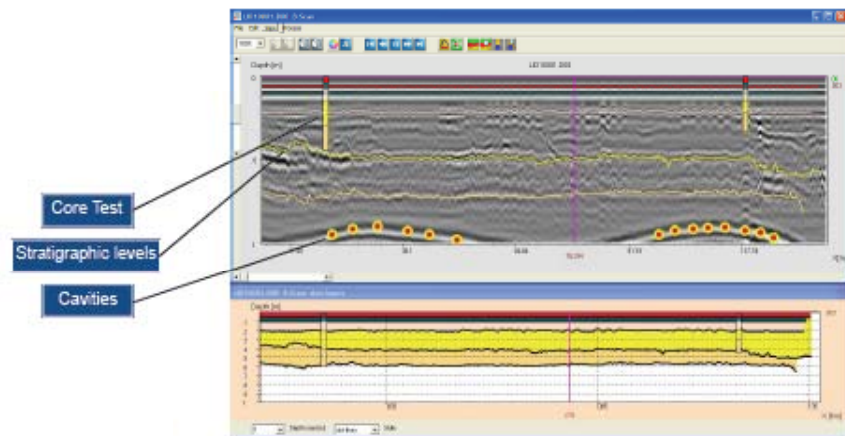
Underground road
mapping obtained by
simple vehicle
passages, up to 15
km/h



Mapping by
single,
longitudinal
passage
along the
trench line



Road Engineering



Imaging of the different levels of the road, with cores and cavities



RIS Hi-Pave:

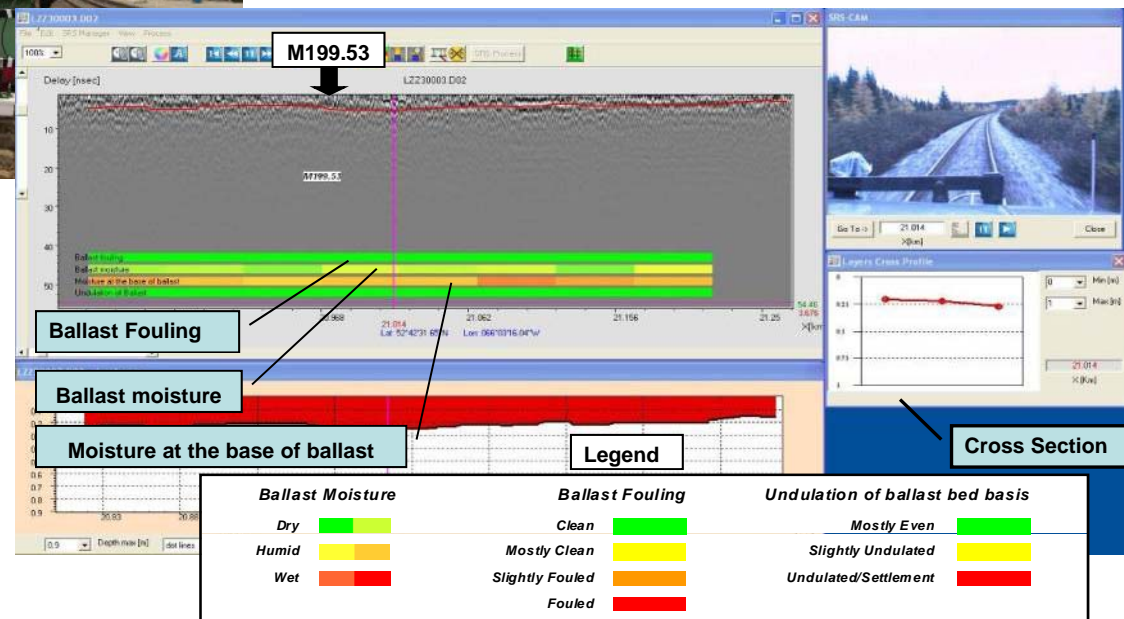
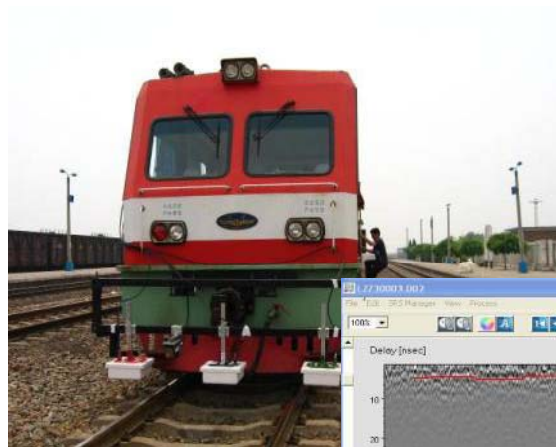
The fastest and most flexible solution for road assessment surveys



Railway Engineering

**SafeRailSystem
(SRS):**

**Continuous
mapping of
railway ballast
status**





Civil and Structure Engineering

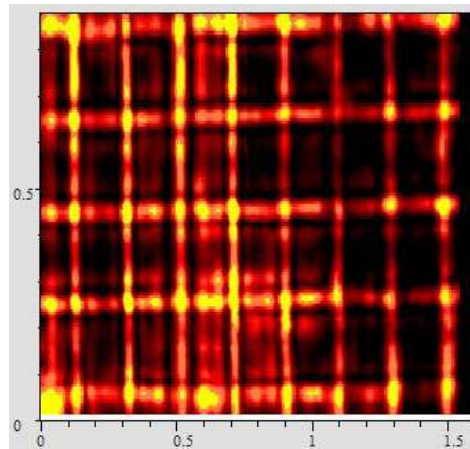
RIS Aladdin:

Analysis of the
internal status of
structures



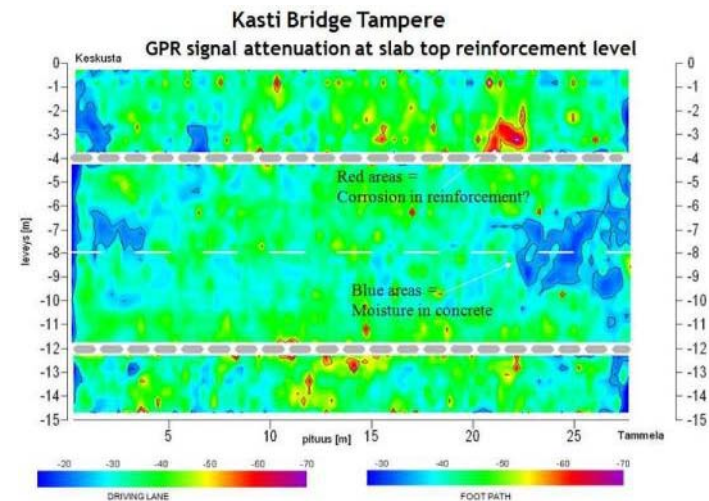
Depth: 0.10m

Imaging of concrete
rebar and internal
structures



RIS Hi-BrigHT:

Array for bridge
deck survey



Bridge
deck maps
for the
evaluation
of layer
thicknesses,
moisture
and
corrosion
damages



Civil and Structure Engineering:

Interferometric Radar: IDS is currently the only one world manufacturer of radar technology for structural displacement applications

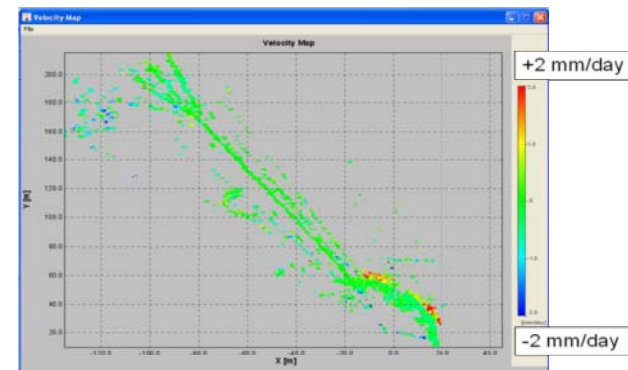
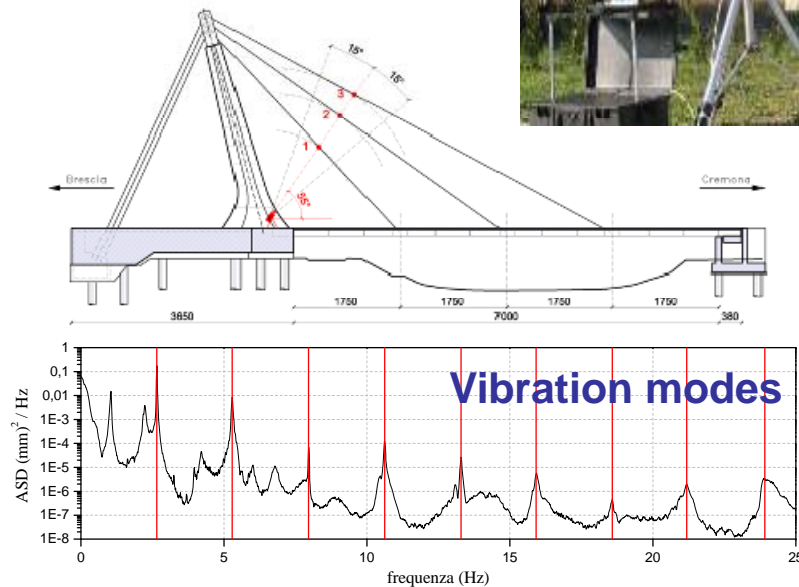
IBIS-S:

Dynamic and static monitoring of bridges and linear structures



IBIS-L:

Static monitoring of large structures



Dam displacements



Geology and Environment



Stream-X:

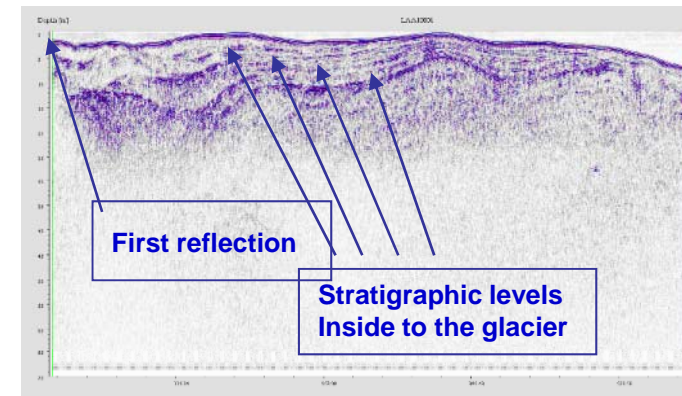
**Fast environment
survey and clearance
of large areas**



RIS ONE-PLUS:

**Flexible and
complete
solutions for
geology**

Tomographic maps showing
archeological structures in
large areas





Geology and Environment

IBIS-M, a dedicated configuration to enter into the Mining Market

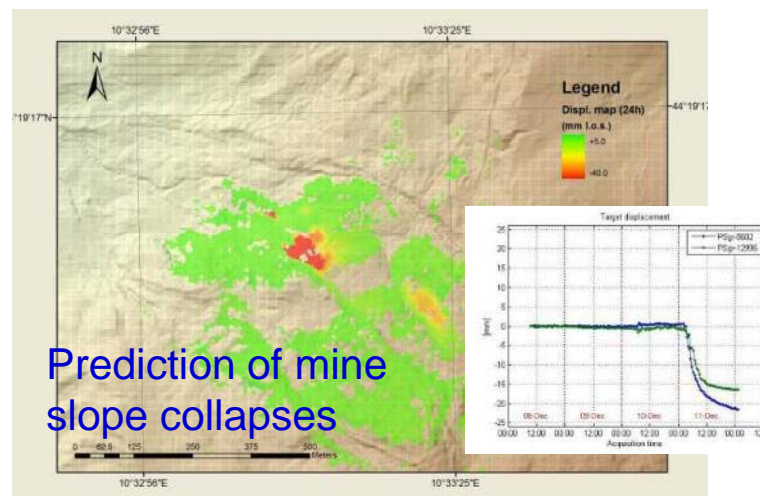
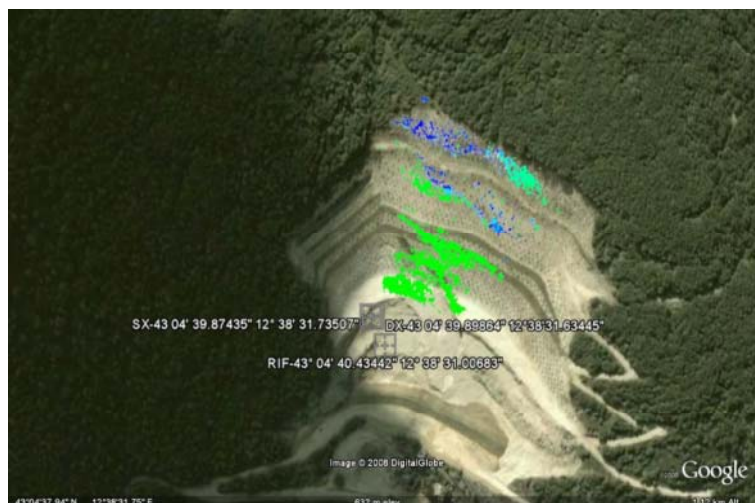
IBIS-L:
Monitoring of
landslides



IBIS-M:
Early
Warning for
mine slope
instabilities



Slope
displacement
map
overimposed
on a Google
picture



Prediction of mine
slope collapses



Forensic and Public Security

Sila system:

Location of
cavities,
tunnels, buried
bodies



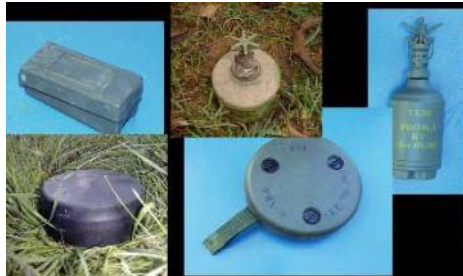
TWR

(Through
Wall Radar):

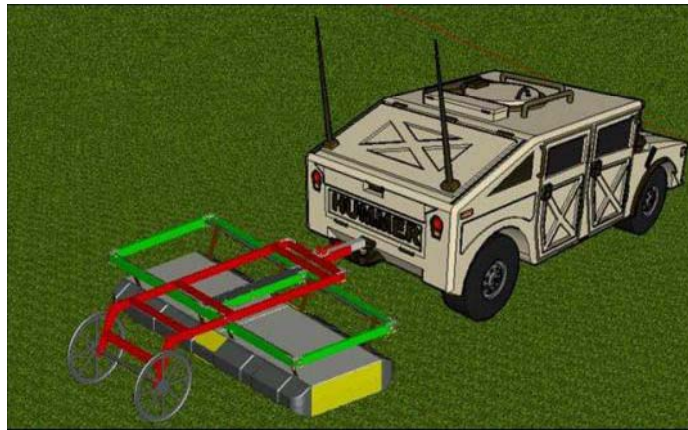
(under
development)



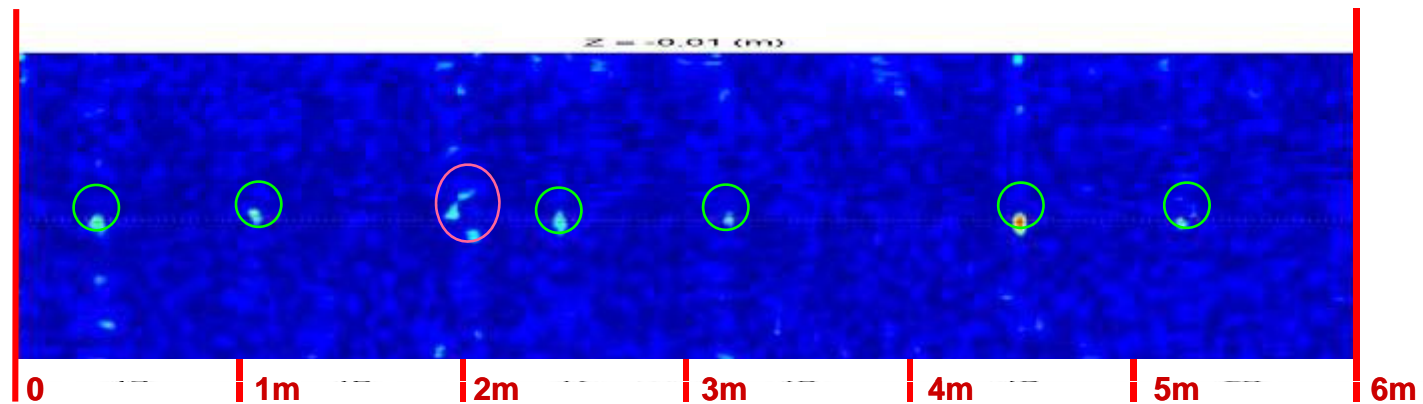
Location of
people
behind
walls



IED/UXO/mine detection



Configuration proposed for IED (Improvised Explosive Device), UXO (Unexploded Ordnance) and mine detection (under development)



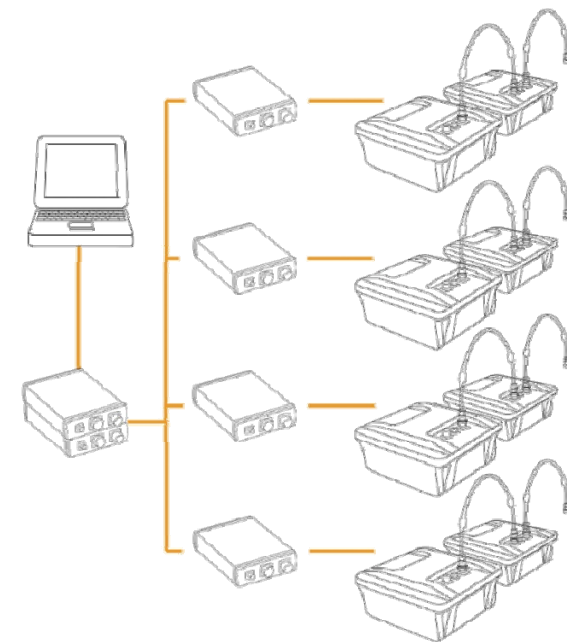
Focalised GPR data at shallow depth

IDS Radar Control Unit

FAST WAVE

New DAD FastWave unique features:

- 6 times faster than the previous DAD K2
- The fastest control unit on the market:
 - 4760 scan/sec @128 samples
 - 2 channels acquired simultaneously
- Chain connection:
 - Antenna elements connected in “cascade”
- Multiple DAD can be synchronized in a “network of DAD’s”



FOCUS

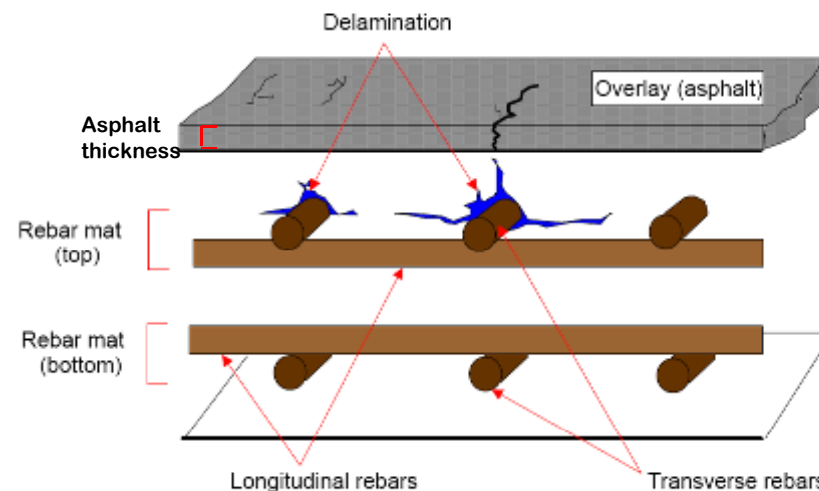
- Ponti
- Strade
- Strutture

DETECTING BRIDGE DECK DEFECTS WITH HIGH RESOLUTION GROUND PENETRATING RADAR



Bridges background

- **Factors causing damage to concrete bridge decks**
 - Traffic loading
 - Corrosion of reinforcement
 - Climate effects → Freeze thaw cycles
 - Initial damage resulting from poor design or construction
 - Inadequate maintenance practices
- **Difficulties to assess bridge deck deterioration**
 - Asphalt overlay
 - Deterioration occur below the surface
 - NDT methods required



Traditional methods for bridge deck survey



Visual Inspection:

- prone to errors
- comes too late for preventing damages
- subjective



Core samples:

- discontinuous
- destructive
- expensive

GPR Survey For Bridge Deck Assessment

GPR methods have many advantages in preventive maintenance:

- continuous mapping of bridge conditions
- non-destructive
- permits to detect hidden defects in their early stage
- permits to localize maintenance interventions
- The higher costs of GPR survey w.r.t. visual inspection are greatly compensated by savings in maintenance and repair

but...

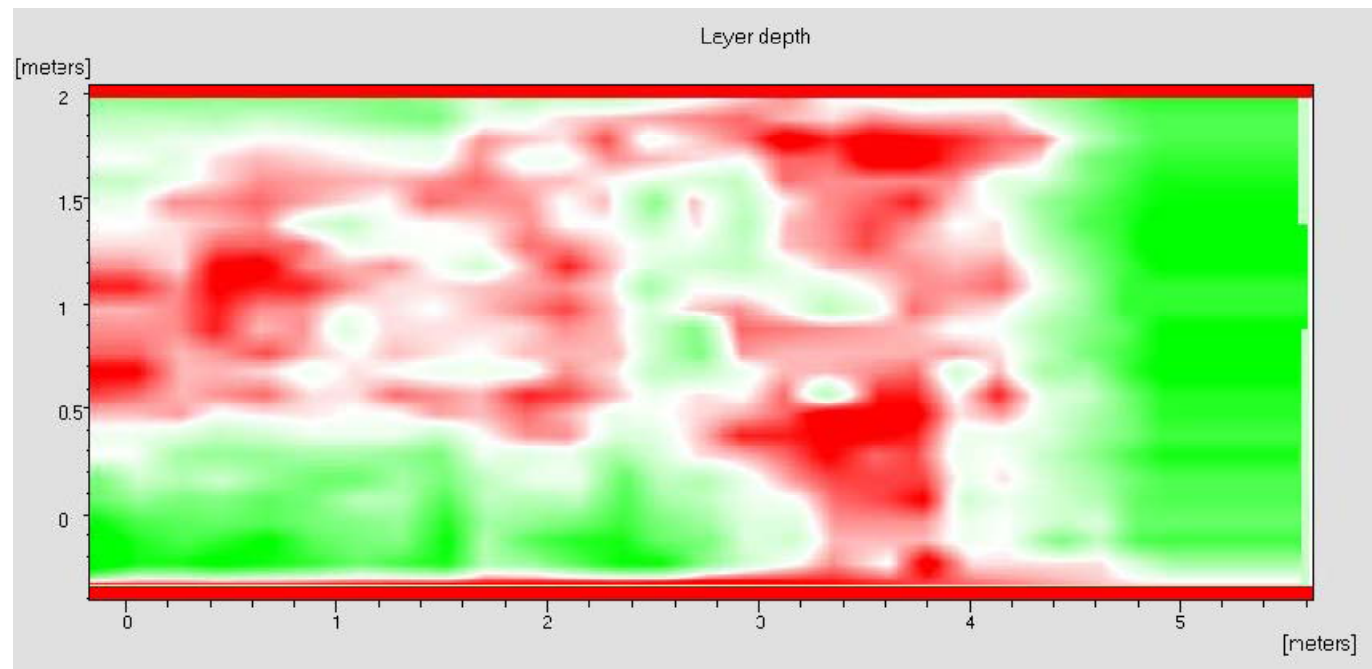


Available GPR instruments are:

- too slow in the collection phase
- not specialized; not easy to use and difficult in data interpretation

Bridge Deck survey: expected output

- Asphalt and concrete slab thickness measure
- Drainage and other buried pipes mapping
- Rebars depth measure
- Areas with defects (moisture and delamination)



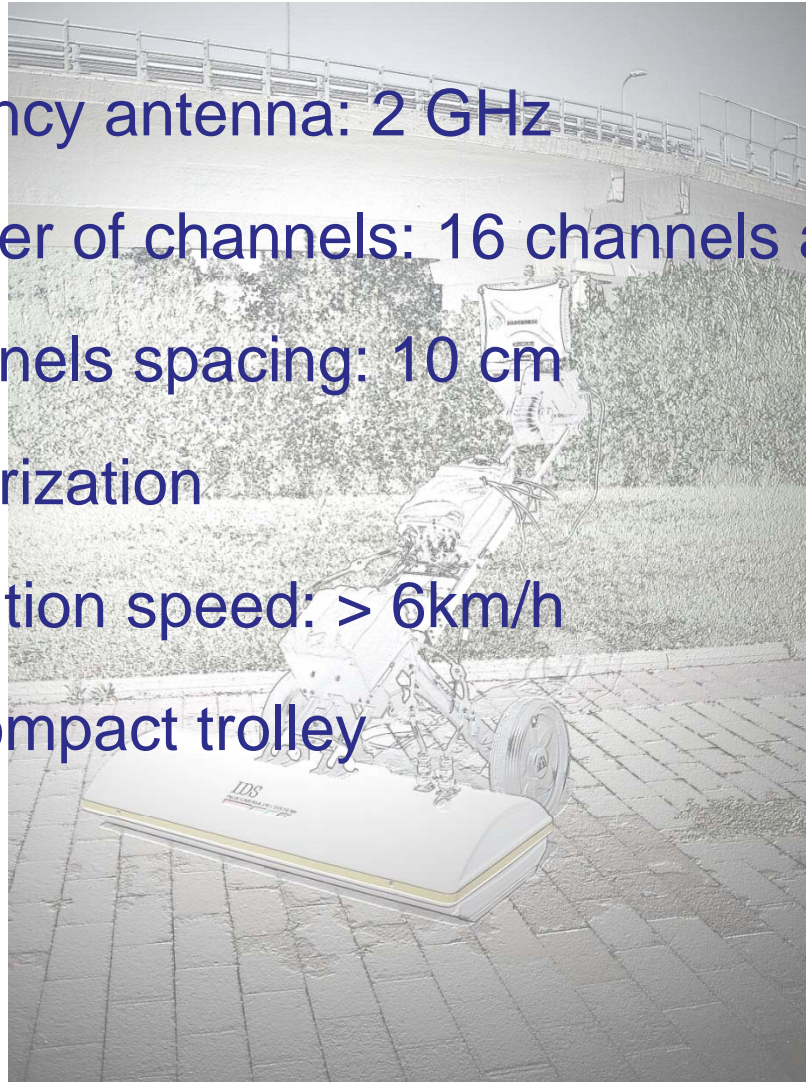
RIS HiBright system requirements

- Very dense data collection
- Double polarization
- High resolution of defects
- Quick data acquisition
- Lightweight and compact design
- High maneuverability and easiness to use

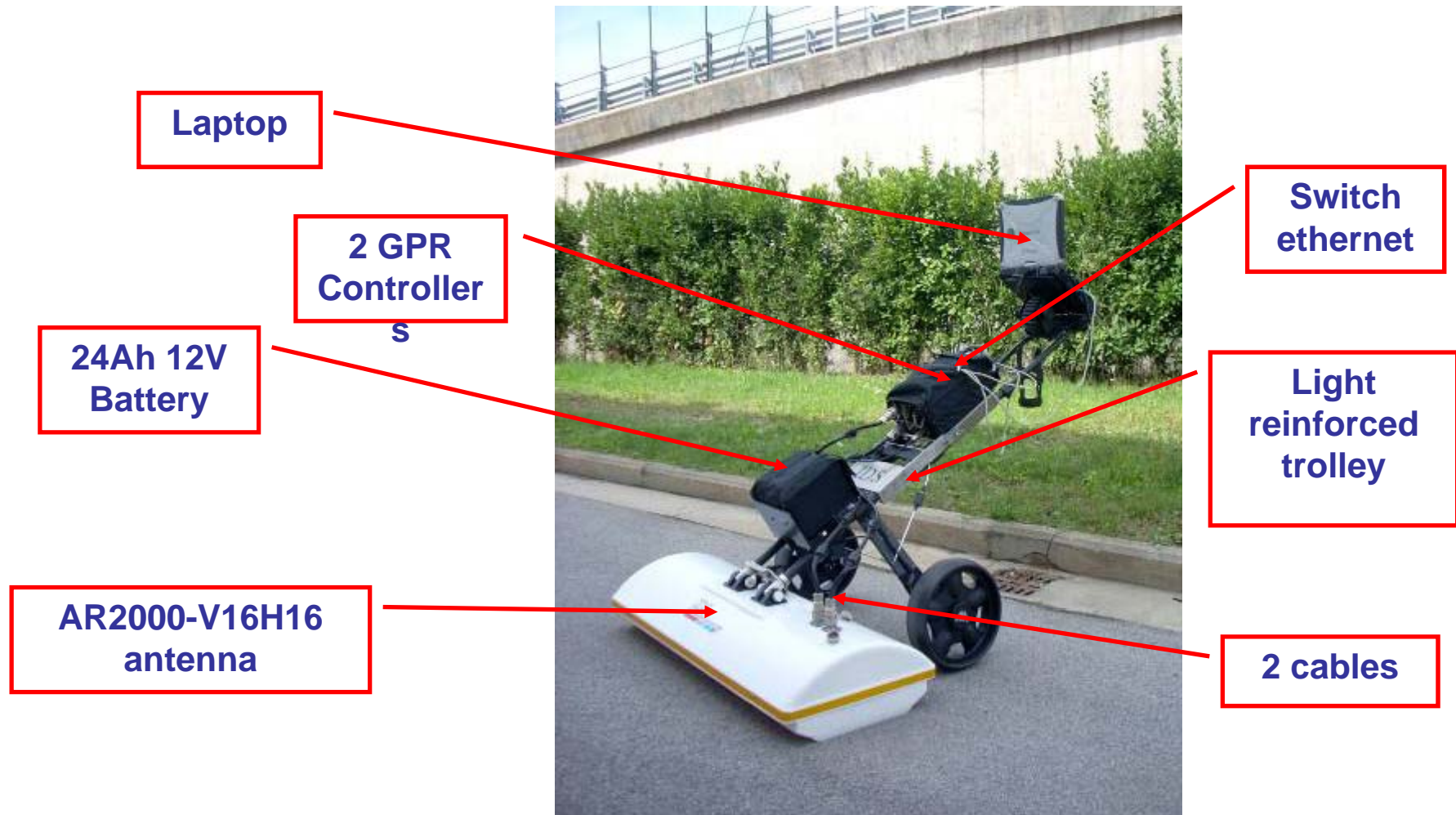


System main features

- High frequency antenna: 2 GHz
- Large number of channels: 16 channels array
- Dense channels spacing: 10 cm
- Double polarization
- High acquisition speed: > 6km/h
- Light and compact trolley



System composition



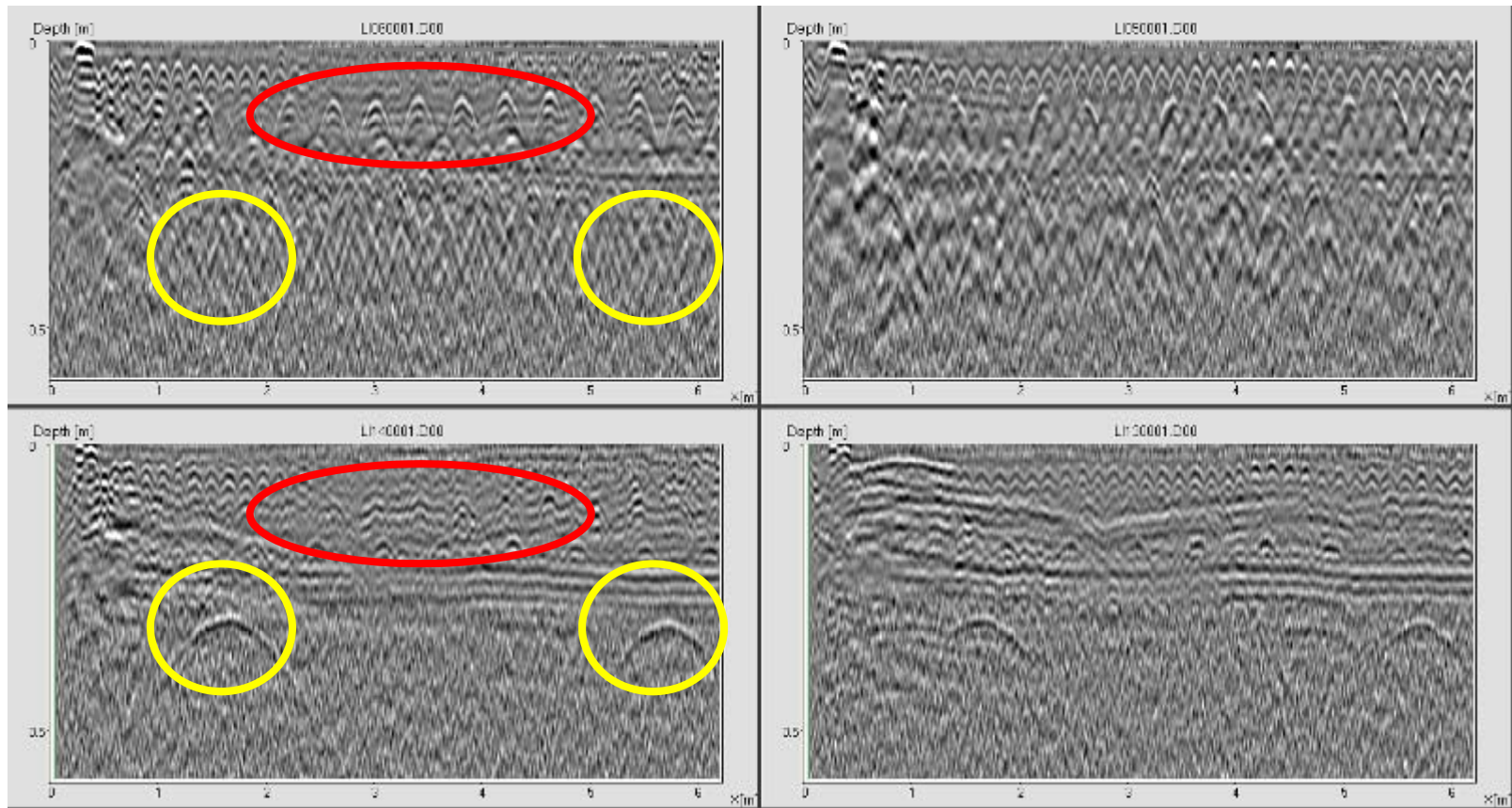
Antenna array: layout

- Total channels: 16
- Channels spacing: 10 cm
- Alignment of different polarized channels
- Aligned channels offset: 8 cm
- Swept width: 70 cm

Benefit from double polarization

- Hyperbolas produced by shallower rebars can be detected in HH data only
- Hyperbolas produced by deeper objects/rebars can be detected in VV data only

**HH
channels**

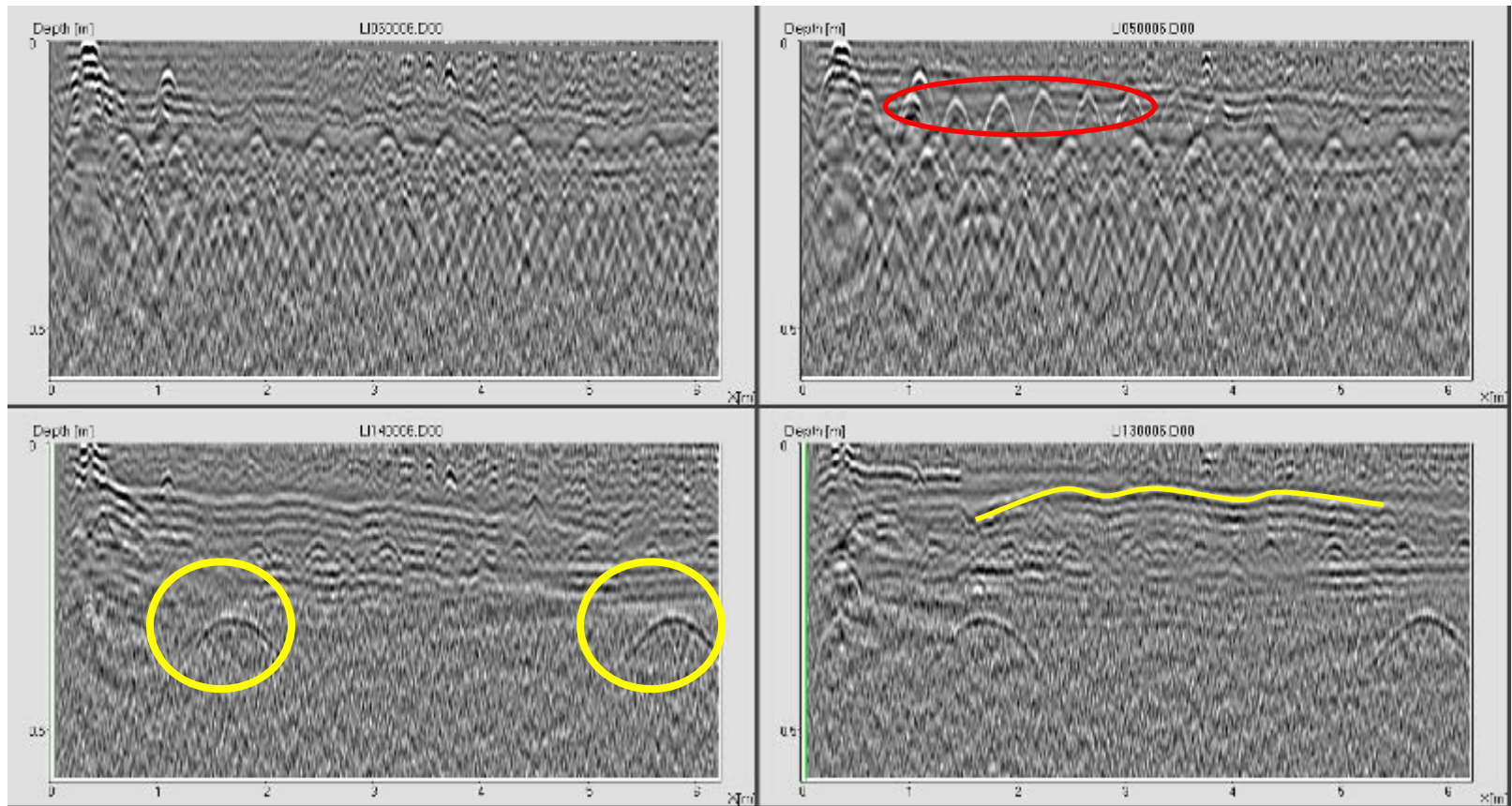


**VV
channels**

Benefit from double polarization

- VV data show a better resolution of layers (no interference from shallower hyperbolas)

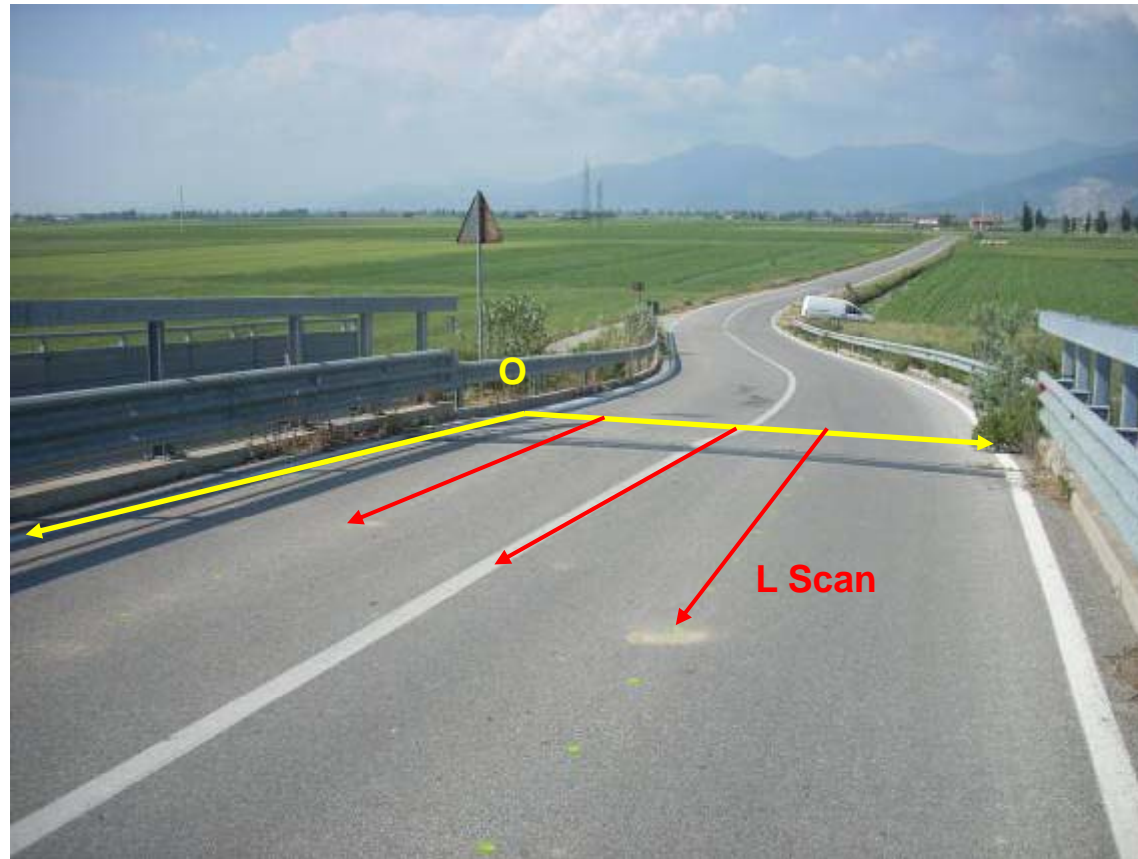
**HH
channels**



**VV
channels**

Data collection with the Hi-Bright

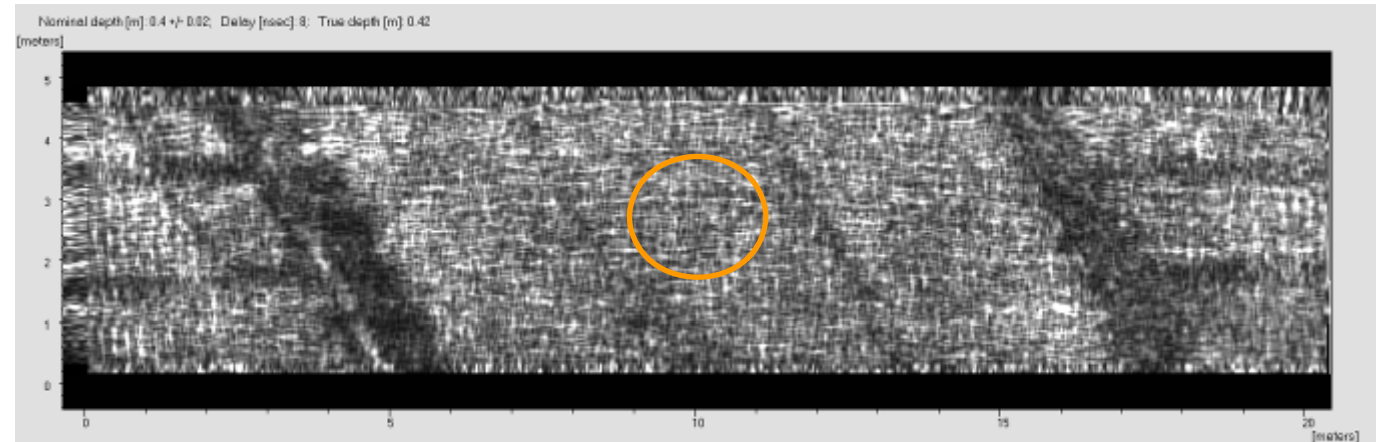
- Usually just longitudinal profiles are executed



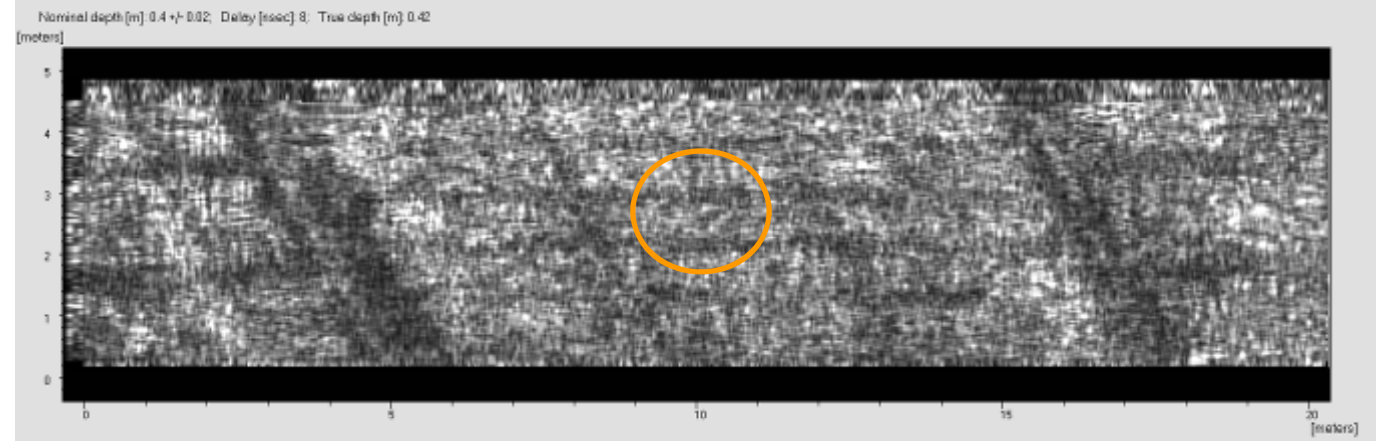
Standard output: Time Slice View

- The area marked in orange shows some possible moisture retention

L+T: HH Polarization



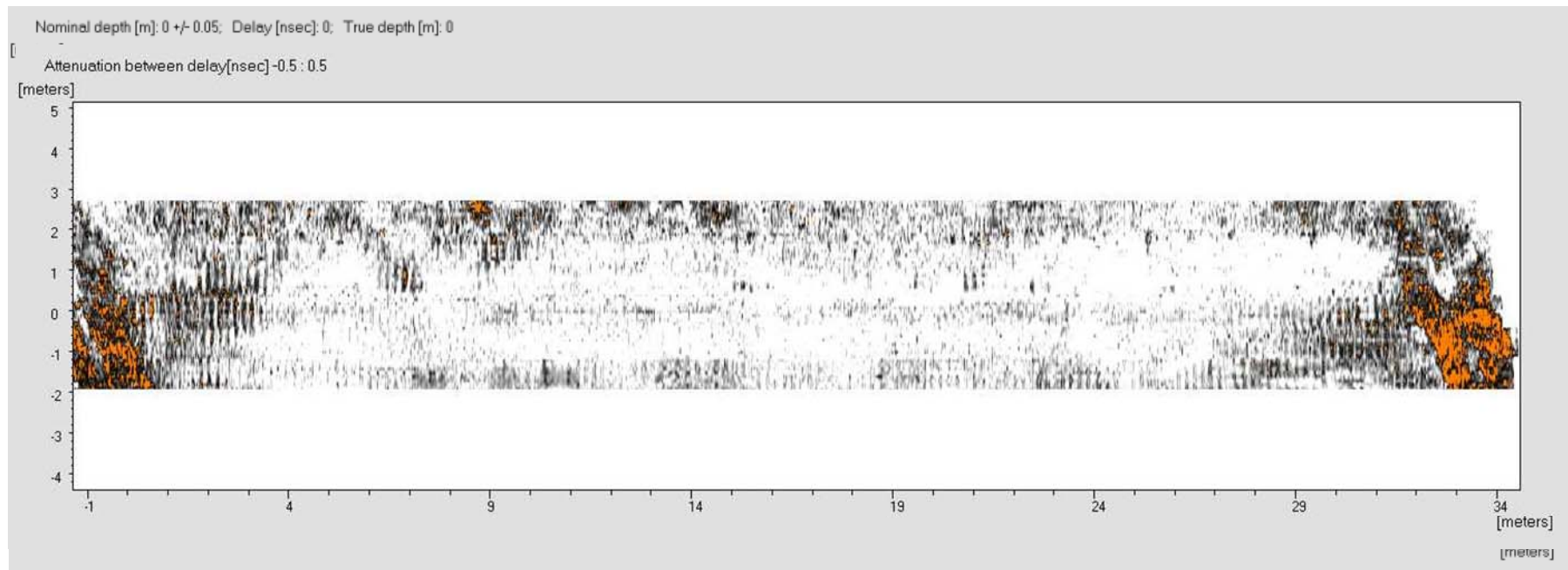
L+T: VV Polarization



Advanced output

Le zone rosse indicano zone anomale che sono indice di zone affette da difettosità.

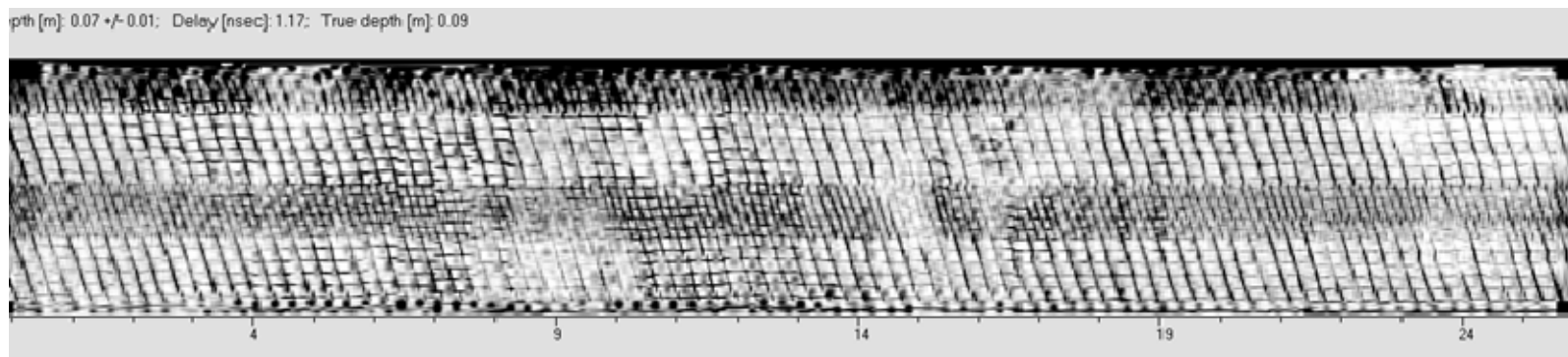
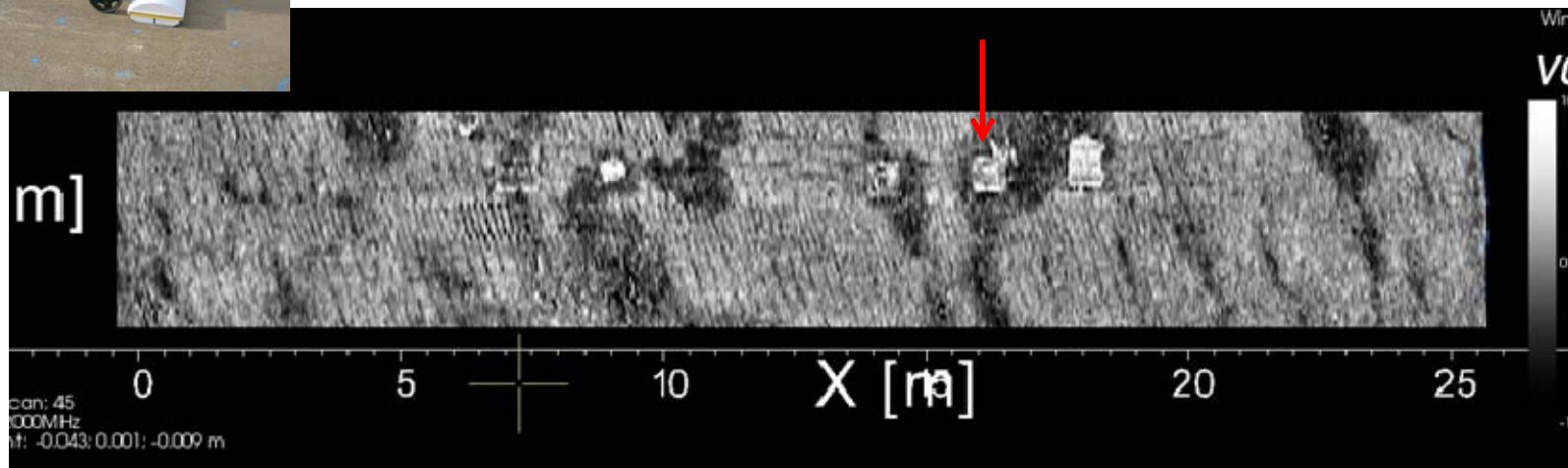
- By using dedicated algorithms, the software can produce further output, as
 - The map showing the areas where the the thickness of the protecting concrete is below the nominal value (red areas)
 - The map showing the areas where a poor reflection from rebars is present (that is correlated to the corrosion) (red areas)
 - The map showing the possible presence of moisture (orange areas)





Case histories:

I-66 Interstate Highway, Virginia -USA

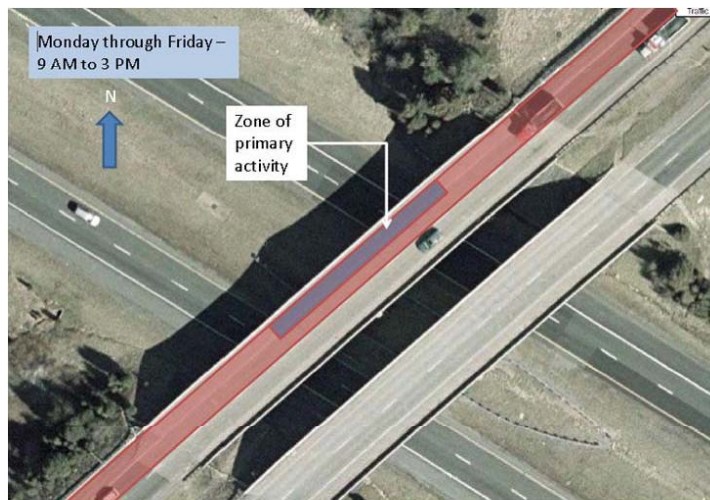
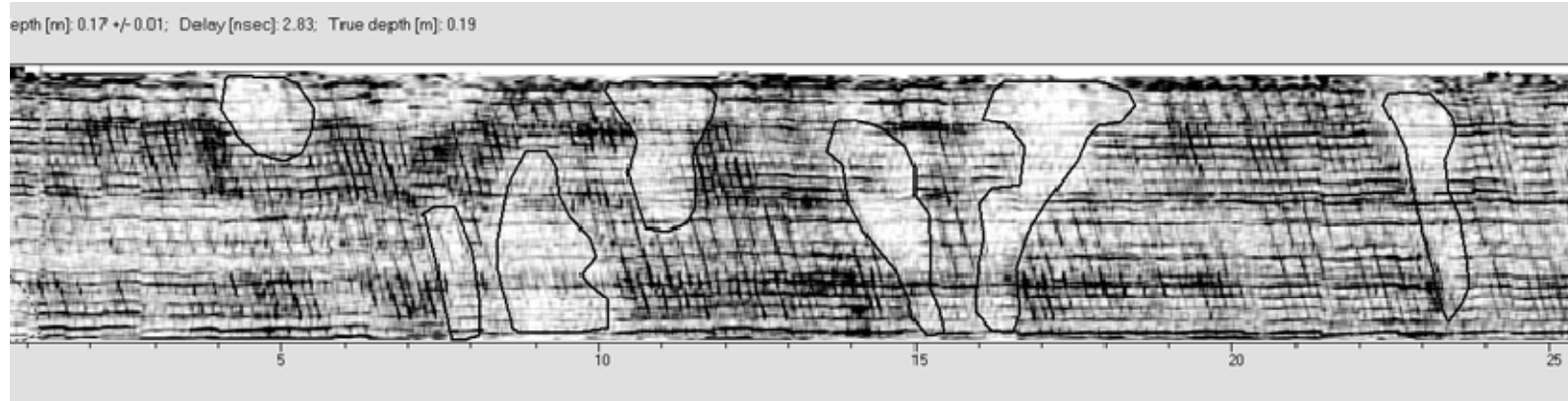


On top patches below asphalt (not visible at the surface) and rebars mesh (picture below)



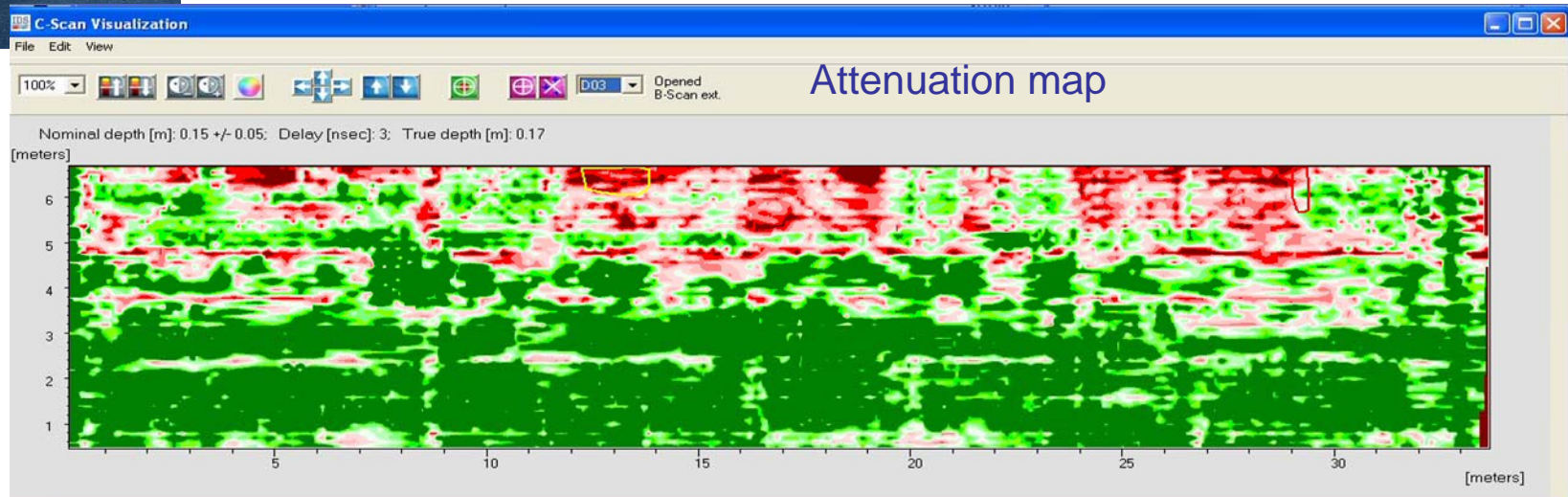
Case histories:

I-66 Interstate Highway, Virginia -USA



Position of defective areas (corrosion)
was confirmed by results from impact
echo survey

Case histories: Italy



Areas marked in red are most likely affected by corrosion; it has been confirmed by executing some inspection trenches





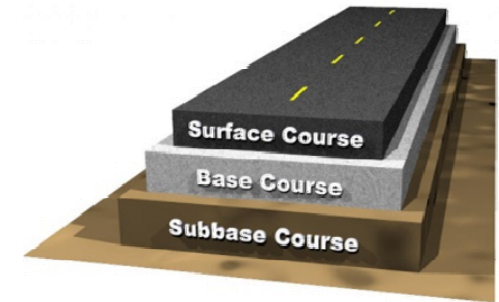
Applicazioni stradali

RIS Hi-Pave

The “*faster*” and most flexible solution for
Road Assessment Survey



RIS Hi-Pave: application



High speed multichannel radar system for Road Assessment Survey:

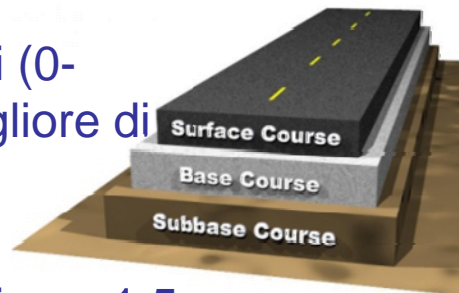
- Measure pavement thickness
- Assess surface, base and subbase road course
- Detection of cavities voids and delamination
- Location of cracks
- Detection of wet area
- Airport runway condition assessment



RIS Hi-Pave

Applicazioni

- Rileva gli strati superficiali (0-50cm) con risoluzione migliore di 4 cm ed accuratezza sub centimetrica
- Rileva gli strati profondi (fino a 1.5 – 2 metri) con accuratezza e risoluzione superiore a 15 cm
- Rileva la presenza di cavità, ferri di armatura e umidità
- Localizza la presenza dei tubi con elevata precisione



Benefits

- Acquisizione veloce dei dati (oltre 125 Km/h) radar
- Facile interpretazione dello spessore mediante un software specializzato con tracking semiautomatico dei layer
- Migliora l'efficienza nella pianificazione della riabilitazione della pista
- Riduce i costi per la manutenzione
- Supporta gli strumenti HWD per la misurazione del modulo di elasticità.



Architettura del sistema RIS Hi-Pave

Unità di controllo radar
(DAD MCh Fastwave)



PC (Data Logger)



GPS antenna + Video
Camera (option)



Ruota metrica di
posizione



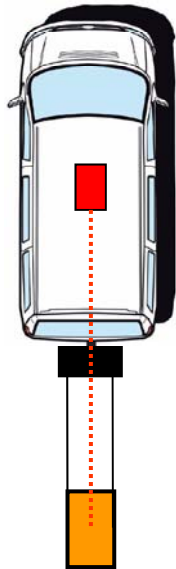
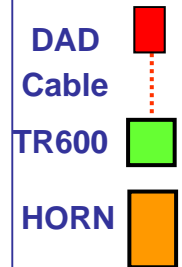
Horn antenna
1000 o 2000MHz



Kit meccanico di
installazione dell'antenna



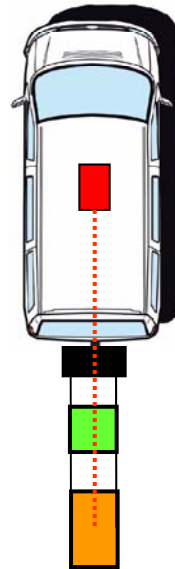
RIS Hi-Pave: possible configurations



RIS Hi-Pave HR1

The single-antenna, entry-level configuration for road and runaway pavement evaluation:

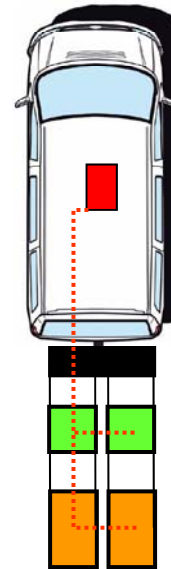
- 1 DAD FastWave control unit
- 1 HR2000 antenna (2 GHz horn) for road survey or 1 HR1000 antenna (1 GHz horn) for runaway survey



RIS Hi-Pave HT2

The double-antenna configuration for complete road and runaway evaluation (pavement, grade, subgrade):

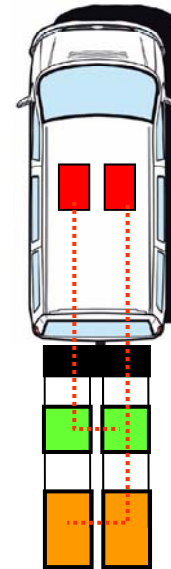
- 1 DAD FastWave control unit
- 1 HR2000 antenna (2 GHz horn) for road pavement survey or 1 HR1000 antenna (1 GHz horn) for runaway survey
- 1 TR600 antenna (600 MHz) for grade and subgrade evaluations



RIS Hi-Pave HT4

The four-antenna configuration for complete and wide road and runaway evaluation:

- 1 DAD FastWave control unit
- 2 HR2000 antennas (2 GHz horn) for road survey
- 2 HR1000 antenna (1 GHz horn) for runaway survey
- 2 TR600 antennas (600 MHz) for grade and subgrade evaluations



RIS Hi-Pave HT4 HS

or

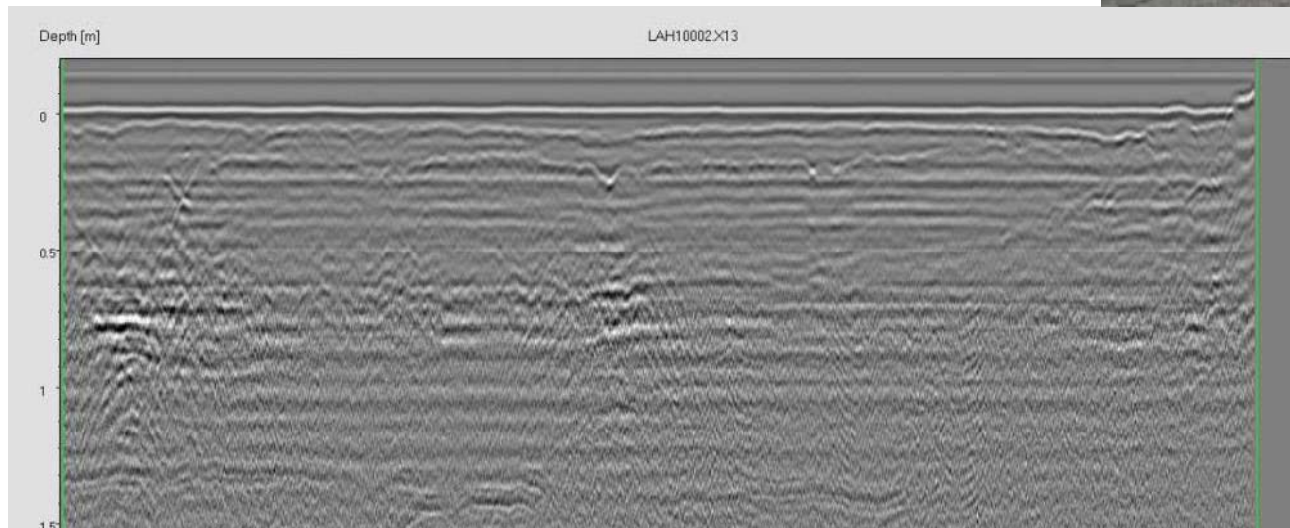
RIS Hi-Pave HT2 HS

The same as the HT4 or HT2 configuration but with 2 synchronised DAD control units for maximum speed (over 200 Km/h) or very dense sampling (5 cm. at 125 km/h)

RIS Hi-Pave: le antenne

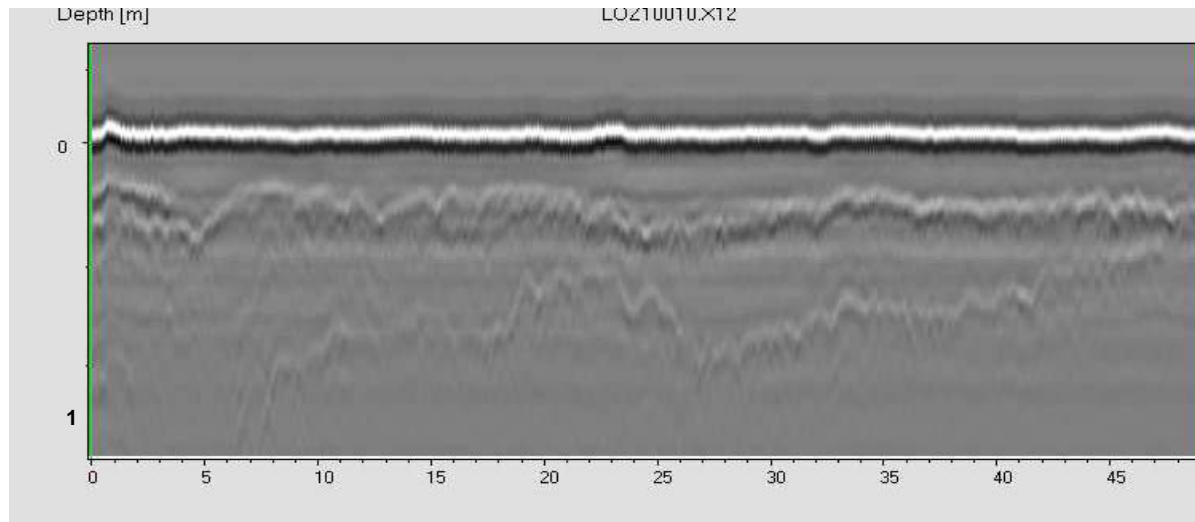
Antenne Horn : acquisiscono non a contatto

- TR 1000 (1000 MHz)
- TR2000 (2000 MHz)

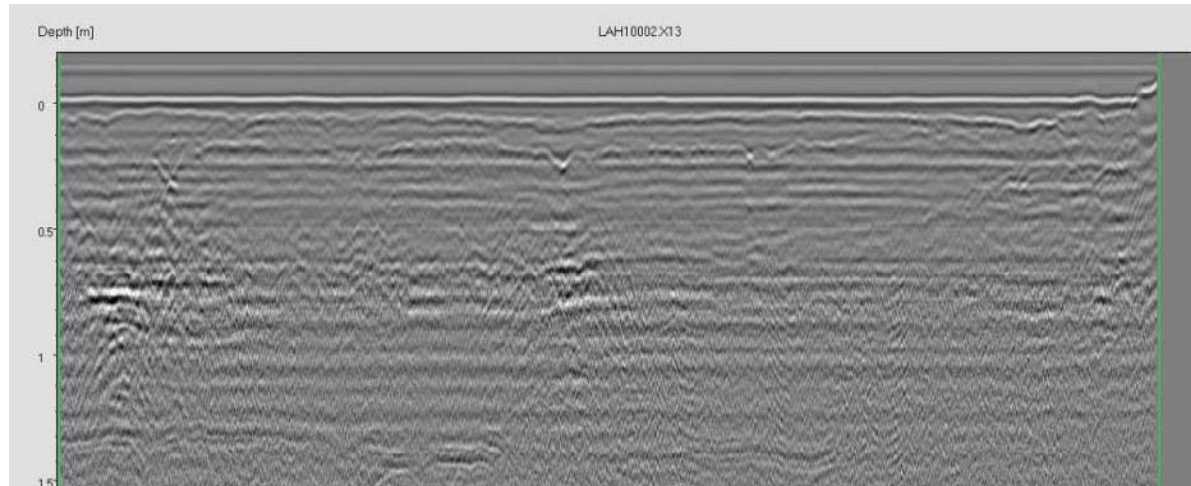


Radar map with 1000 MHz
Horn antenna.

Antenne Horn : esempio mappe radar



**Radar map with 2000 MHz
Horn antenna.**



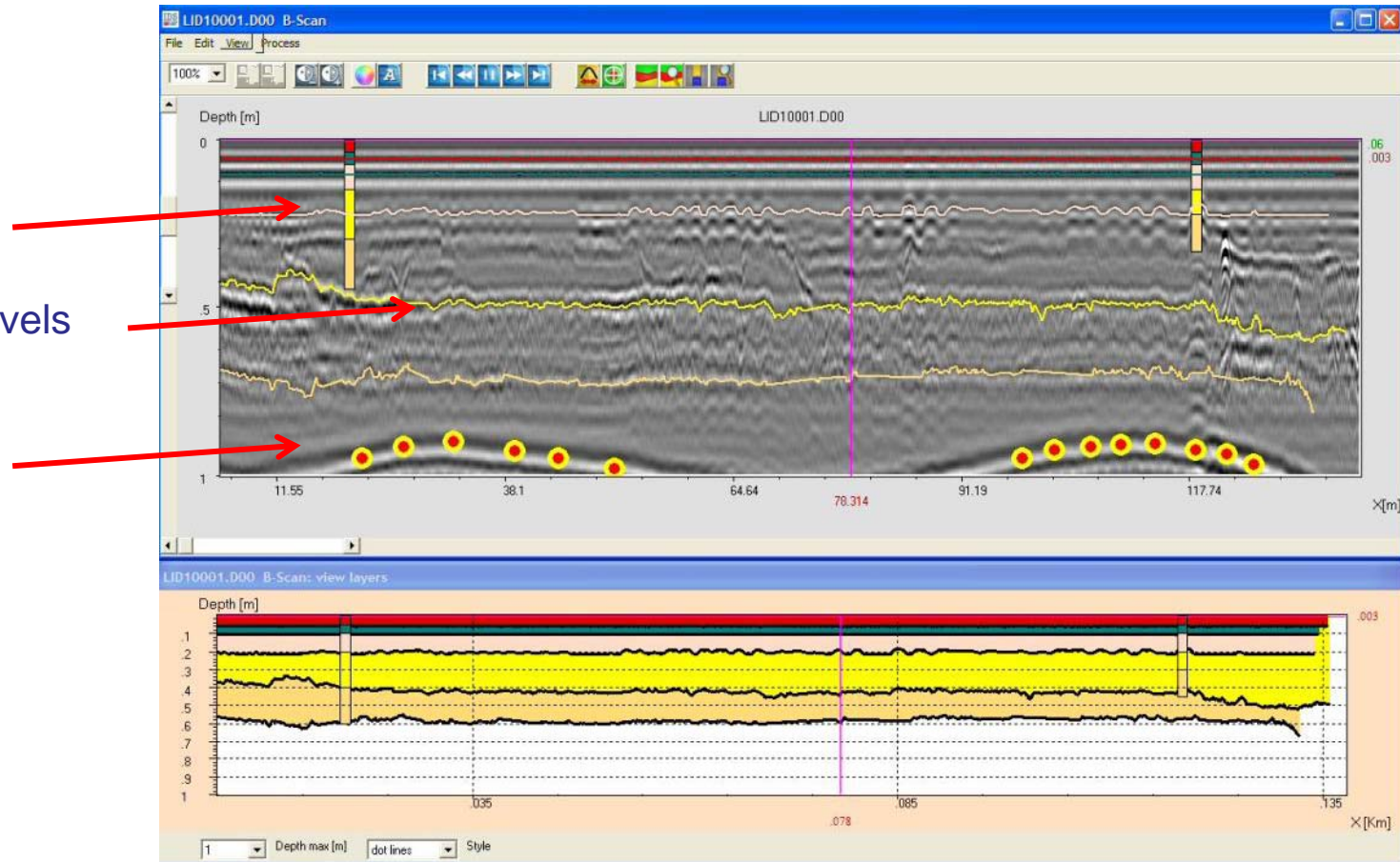
**Radar map with 1000 MHz
Horn antenna.**

RIS Hi-Pave: esempio di risultato

Core test

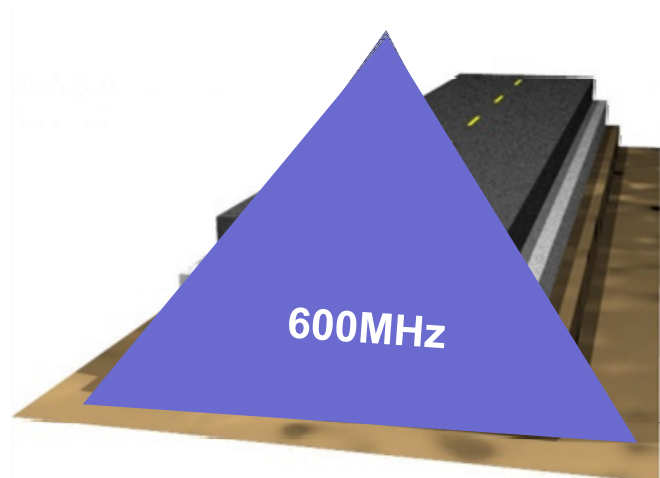
Stratigraphic levels

Cavities



Caratteristiche del sistema RIS Hi-Pave

- RIS Hi-Pave può acquisire simultaneamente a 4 antenne con una velocità di 125 Km/h (10 cm di campionamento)
- Acquisizione contemporanea di dati multifrequenza per una analisi completa degli strati più superficiali e profondi..

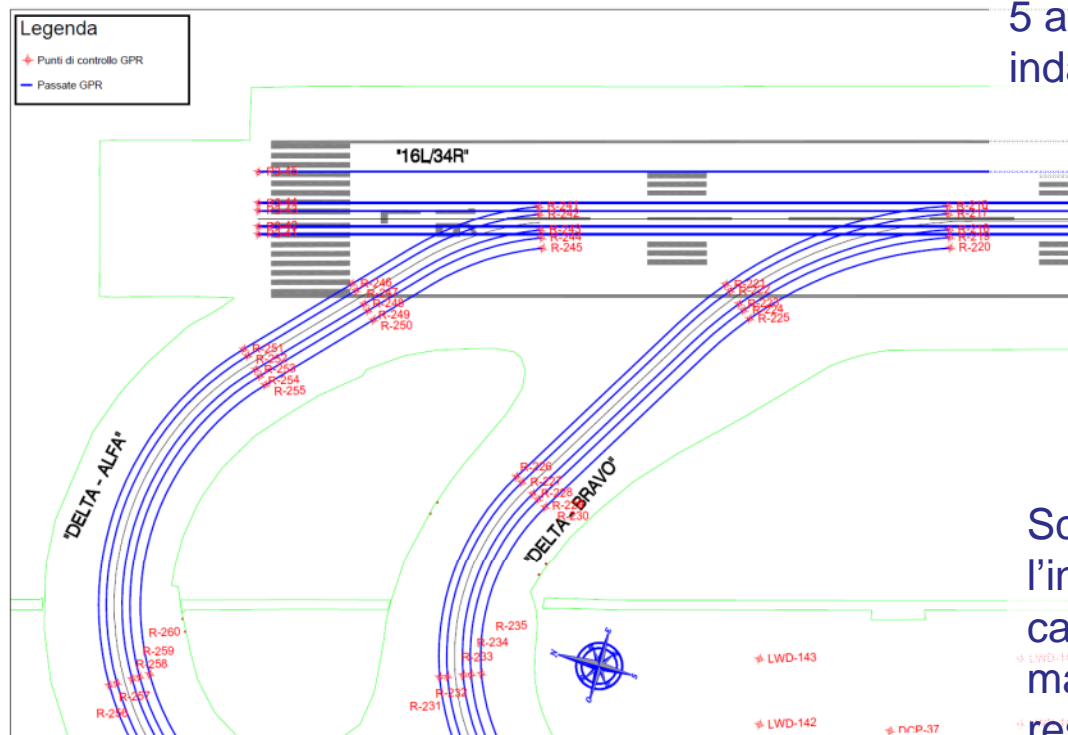


System	Collection Speed (Km/h) (@10 scan/meter, 512 samples)
RIS Hi-Pave with 2 antennas	125 km/h
RIS Hi-Pave with: 4 antennas (configuration with 1 Control Unit)	125 km/h (interlaced channels)

Case study

Campagna di indagini GPR delle sovrastrutture nell'intero sedime aeroportuale pavimentato dell'aeroporto "Leonardo Da Vinci di Fiumicino, per conto di ADR S.p.A. .

Le indagini sono state eseguite lungo 5 allineamenti in modo da non indagare la sola fascia portante.



Scopo delle indagini era verificare l'integrità della sovrastruttura e calcolare lo spessore degli strati, in maniera da conoscerne la vita residua.

Realizzazione

Per l'esecuzione delle indagini è stato utilizzato il sistema RIS Hi-Pave interfacciato ad un GPS Topcon GR3 .

Tale sistema utilizza un antenna Air Launched con frequenza di 1000MHz e permette una rapidità di acquisizione compatibile con le velocità di un veicolo.

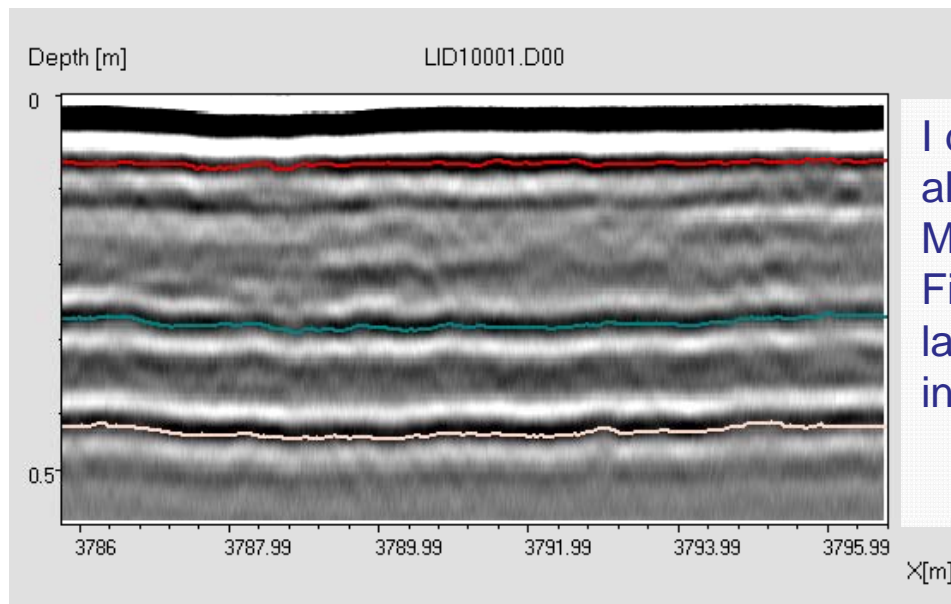


Nei tempi stabiliti, nonostante le penalizzazioni ed i limiti derivanti dall'esecuzione di rilievi durante orari notturni e in zone sensibili, è stato possibile completare l'intera campagna di rilievo, per uno sviluppo totale di oltre 2000 Km.

Risultati

Utilizzando il software GRED 3d IDS è stato possibile valutare gli spessori dei diversi strati componenti la sovrastruttura in maniera da individuare poi i tratti omogenei ed in seguito determinare i punti dove eseguire i carotaggi.

Dall'interpretazione dei dati GPR, unitamente ai dati deflettometrici ottenuti attraverso l'Heavy Weight Deflectometer "Dynatest 8081" e ai dati di traffico, è possibile stimare il modulo elastico e la vita residua delle sovrastrutture indagate.

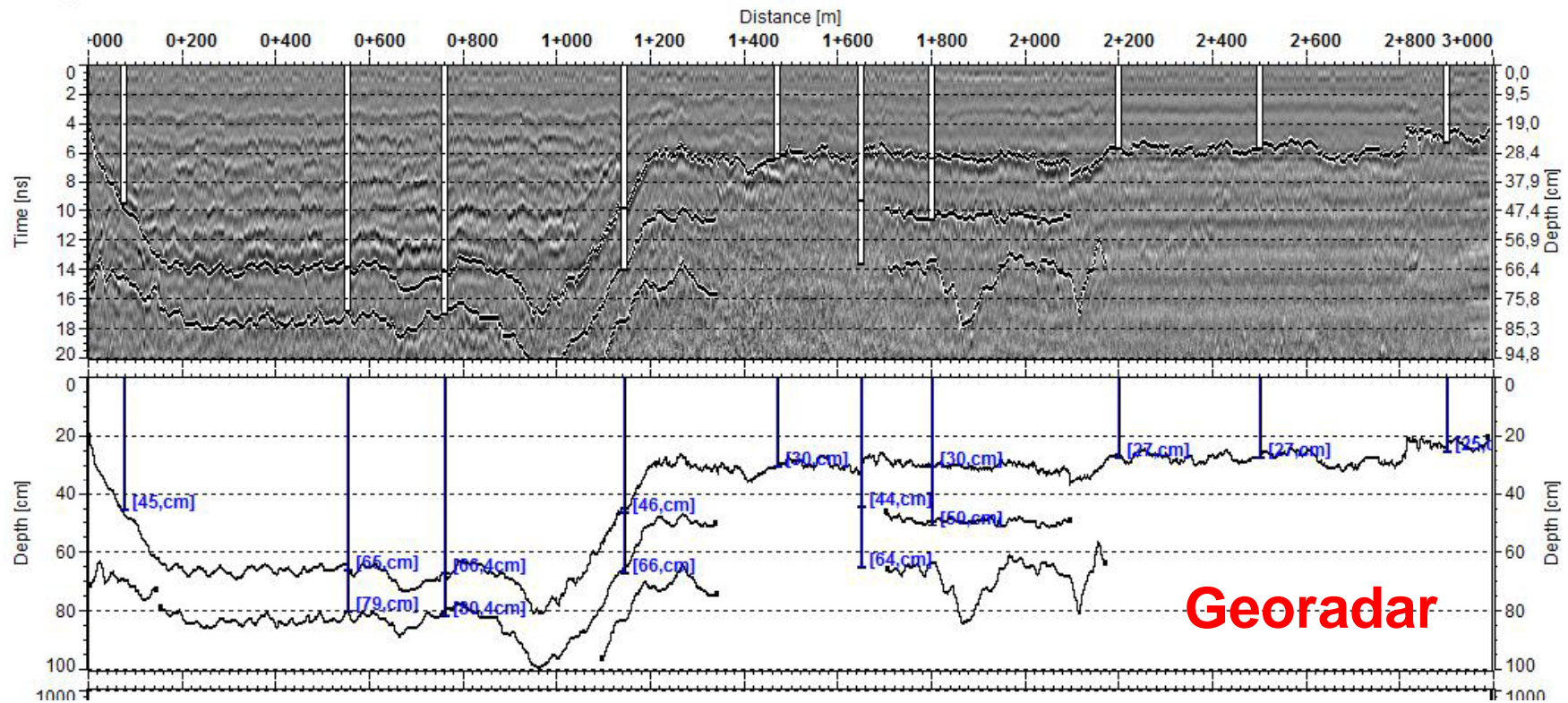


I dati ottenuti saranno poi implementati all'interno del PMS (Pavement Management System) dell'aeroporto di Fiumicino, in maniera da pianificare sia la tipologia che la tempistica degli interventi.

Airport Linz - Austria



Links 5,0m von CL



Georadar

ALADDIN

an advanced radar based sensor for
Non-Destructive structural analysis

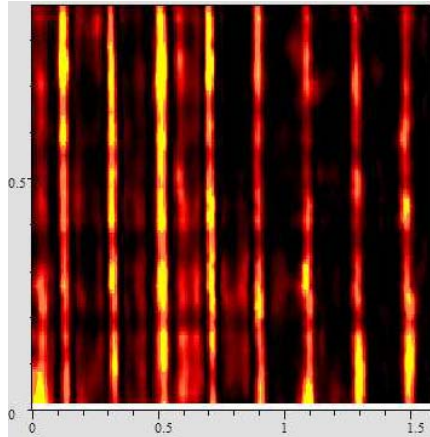


Civil engineering & Cultural heritage applications

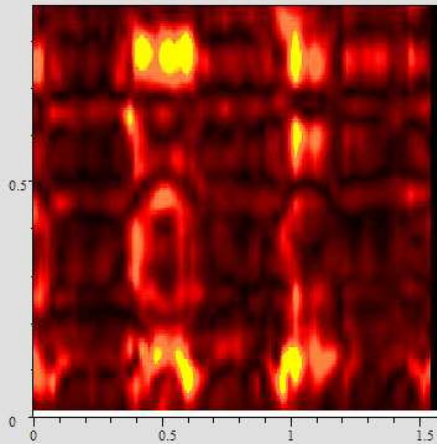
- 3D imaging of shallow and deep rebars in concrete;
- Inspection of concrete for location of voids;
- Inspection of concrete thickness, integrity;
- 3D imaging of pre-tension and post-tension cables;
- Inspection and analysis of old structures and monuments;
- Inspection of walls and floors for the location of pipes, objects, caches, etc..

Standard Products

Depth: 0.10m



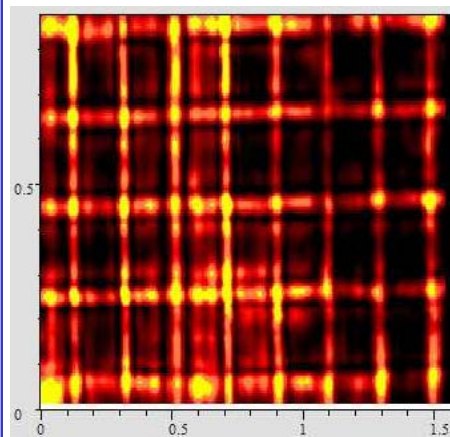
Depth: 0.40m



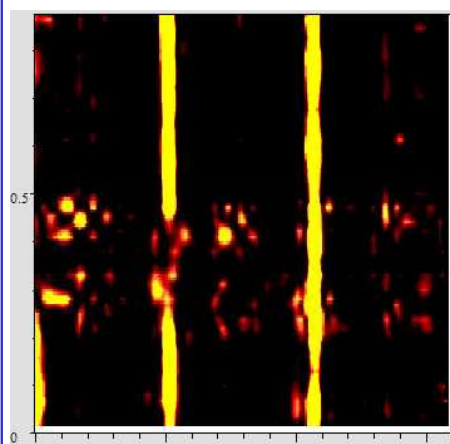
The standard antenna can read the shallow targets (rebars), but is not able to reveal the lower structures

ALADDIN

Depth: 0.10m

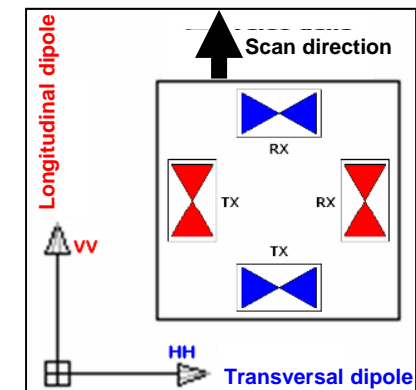


Depth: 0.40m



Instead, the FULL-POLAR antenna is able to identify both targets (shallow and deep) in just one scan.

The **SPECIAL FULL-POLAR** high-frequency (2 GHz) antenna combined with the **patented Pad Survey Guide (PSG)** permit joint orthogonally polarized scans to be acquired in a single pass, detecting shallow and deep structures and halving acquisition time compared to standard methods.



ALADDIN



No-destructive tool for structural analysis.

High frequency antennas

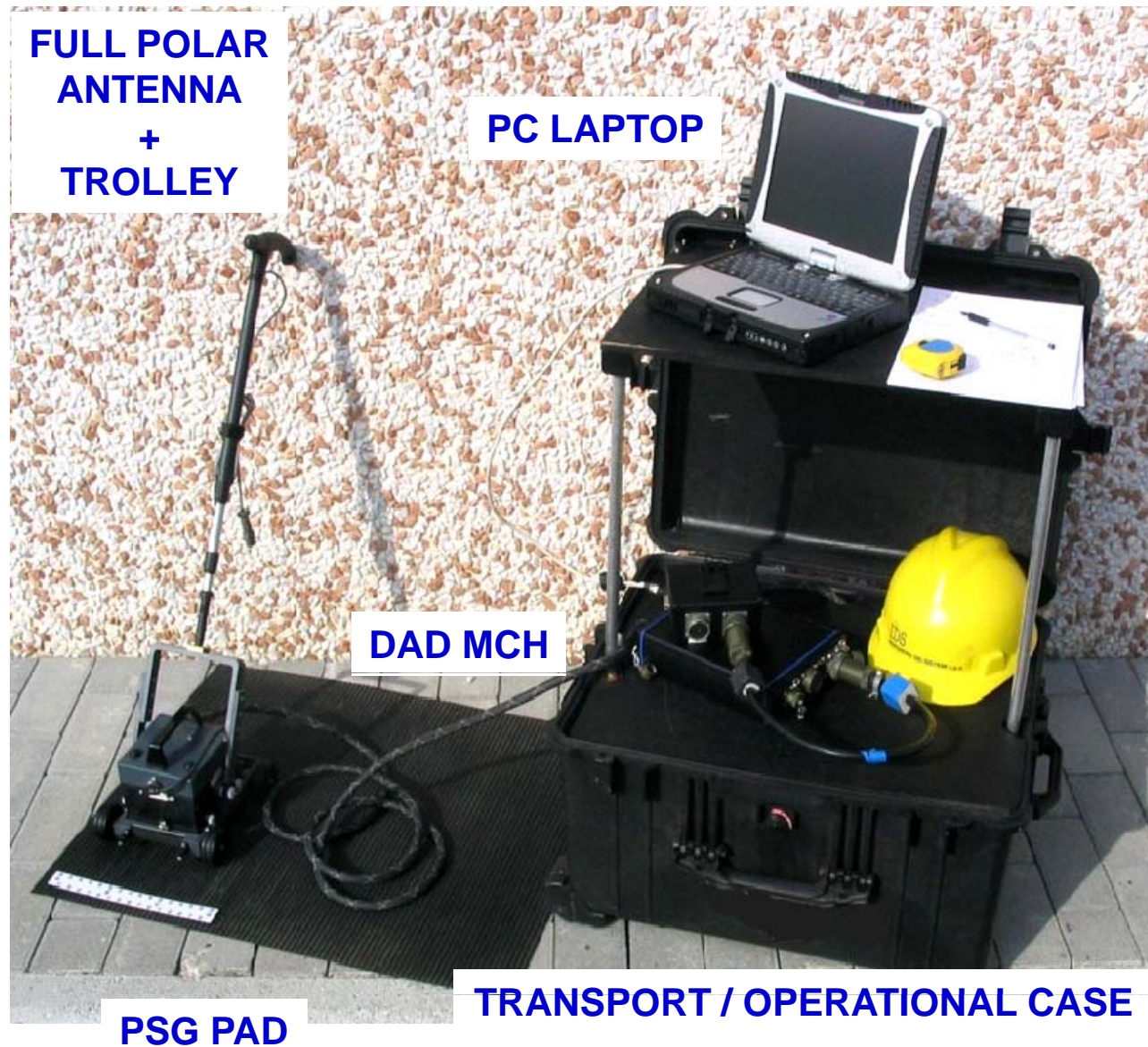
3D processing software

APPLICATIONS

- ☐ Locate rebar, tension cables, conduits, voids and measure slab thickness.
- ☐ Inspection of walls, floors, decks, slabs, tunnels, balconies and garages.
- ☐ Detect and map the relative concrete condition for rehab planning.
- ☐ Detect and map cavities inside walls
- ☐ Concrete thickness, water and inner rebar structure inspection
- ☐ Reconstruction of wall inner structure detection of structural defects

USER BENEFITS

- 1. EASY TO USE**
- 2. ACQUISITION TIME OF RADAR DATA REDUCED DRASTICALLY**
- 3. FLEXIBLE CONFIGURATION FOR ANY USE: PAD or OPTICAL READER**
- 4. 3D DATA COLLECTION BY PERFORMING ONLY PARALLEL SCANS**
- 5. AUTOMATIC START/STOP OF DATA COLLECTION SYNCHED UP WITH PAD LENGTH**
- 6. REMOTE CONTROL ON THE STICK**
- 7. DUE TO POLARISED CHANNEL, IT UNVEALS DEEP TARGETS SHADOWED BY SHALLOWER ONE**
- 8. EXPANDIBLE CONTROL UNIT (DAD) CAN BE USED WITH ALL IDS ANTENNAS FOR USE IN OTHER APPLICATIONS**
- 9. DEDICATED 3D SW INCLUDED IN THE PACKAGE**
- 10. HIGH RESOLUTION DATA**
- 11. DETECTION AND MAPPING OF THINEST CABLES**



ALADDIN COMPOSITION

ADVANTAGES



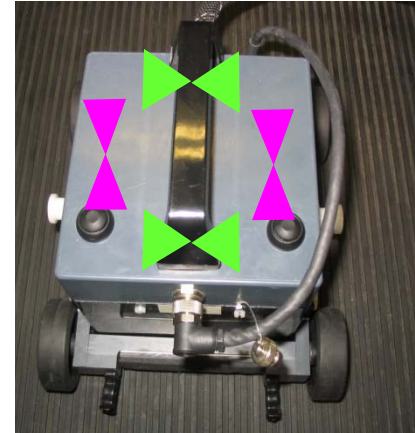
1

OPERATIONAL CASE



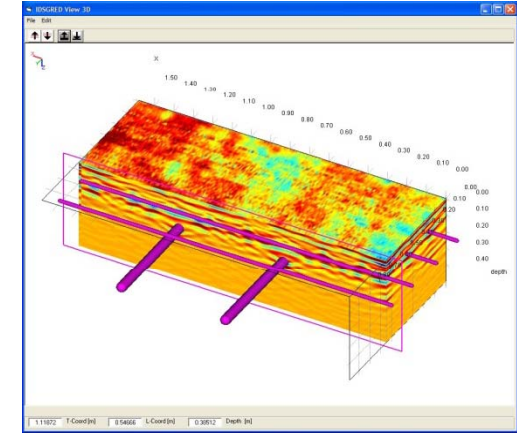
2

PSG: INNOVATIVE SURVEY KIT



3

FULL POLAR ANTENNA



4

3D SW FOR ON-SITE PROCESSING

1. DEDICATED TRANSPORT/OPERATIONAL CASE

2. PSG: INNOVATIVE SURVEY KIT FOR AN EASY AND TOTAL 3D ACQUISITION DATA

3. FULL POLAR ANTENNA (2 GHz): IMPROVES THE IMAGING OF SHALLOW AND DEEP
REINFORCING BARS

4. QUICK ON-SITE DATA PROCESSING

5. OPTION: OPTICAL READER SURVEY KIT POINTER

Full line of high frequency antennas

DAD MCH (Aladdin radar control unit): is compatible with all the IDS antennas



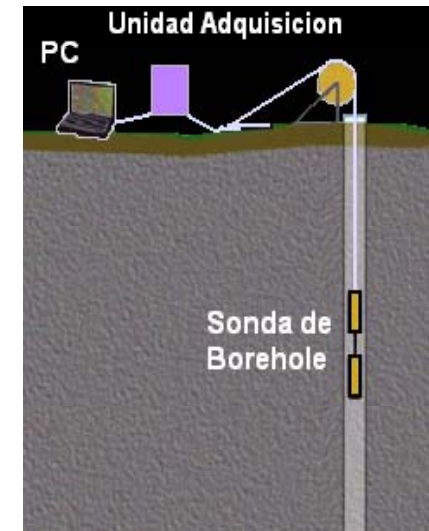
Borehole antenna for no destructive test

DAD MCH (Aladdin radar control unit): is compatible with all the IDS antennas

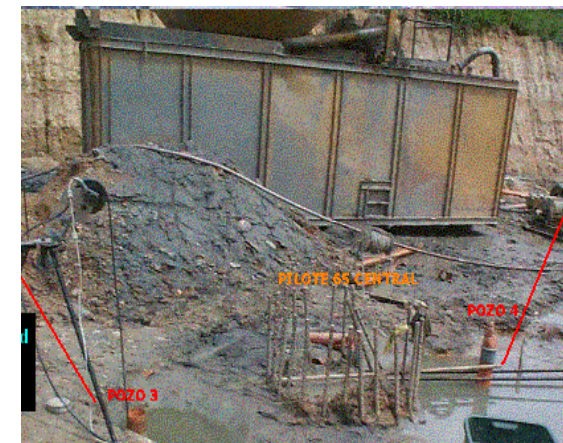


Available models/frequency antennas :

- BA 600 MHz



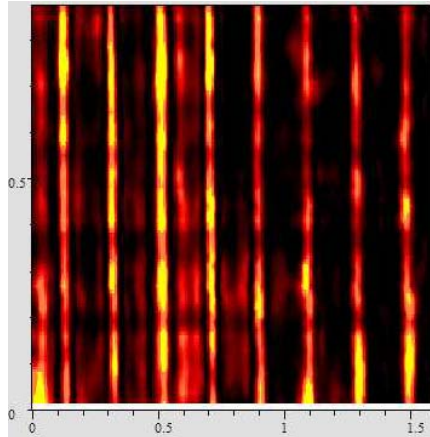
- Borehole antenna cable (40 m) (BAC 4000)
- Antenna Type: Unshielded Dipole
- Nominal Frequency: 600 MHz
- Operation Mode: Single hole reflection, Cross-hole tomography
- Length: 1.6 or 1.0 meter
- Diameter: 40 mm
- Weight: 1.5 Kg
- Water-proof: up to 5 bar



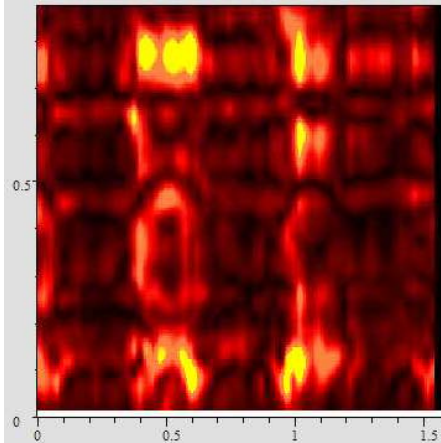
Grazie per l'ascolto

Standard Products

Depth: 0.10m



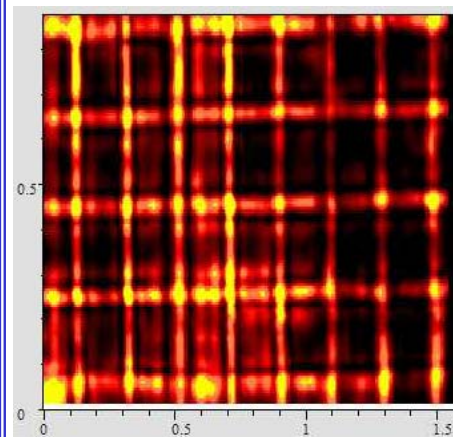
Depth: 0.40m



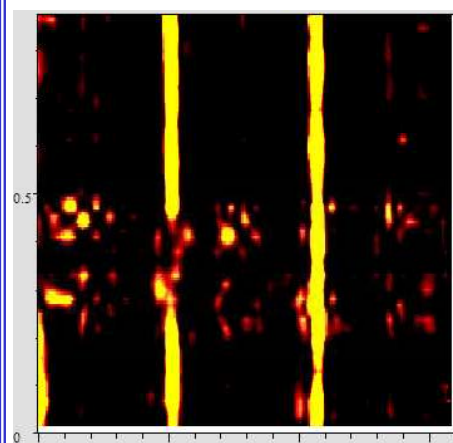
The standard antenna can read the shallow targets (rebars), but is not able to reveal the lower structures

ALADDIN

Depth: 0.10m

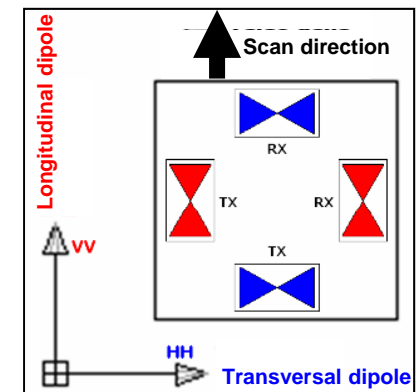


Depth: 0.40m



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ANTENNA FEATURES

Antenna Frequency	2 GHz Bipolare
Offset RX and TX	6 cm
Antenna dimension	12×12 cm



Indagine GPR con antenne ad alta frequenza

Test site in Cemento

Highways Department - Bangkok – Thailand (1/4)



Indagine GPR con antenne ad alta frequenza per localizzare vuoti sotto lo strato di cemento (2/4):



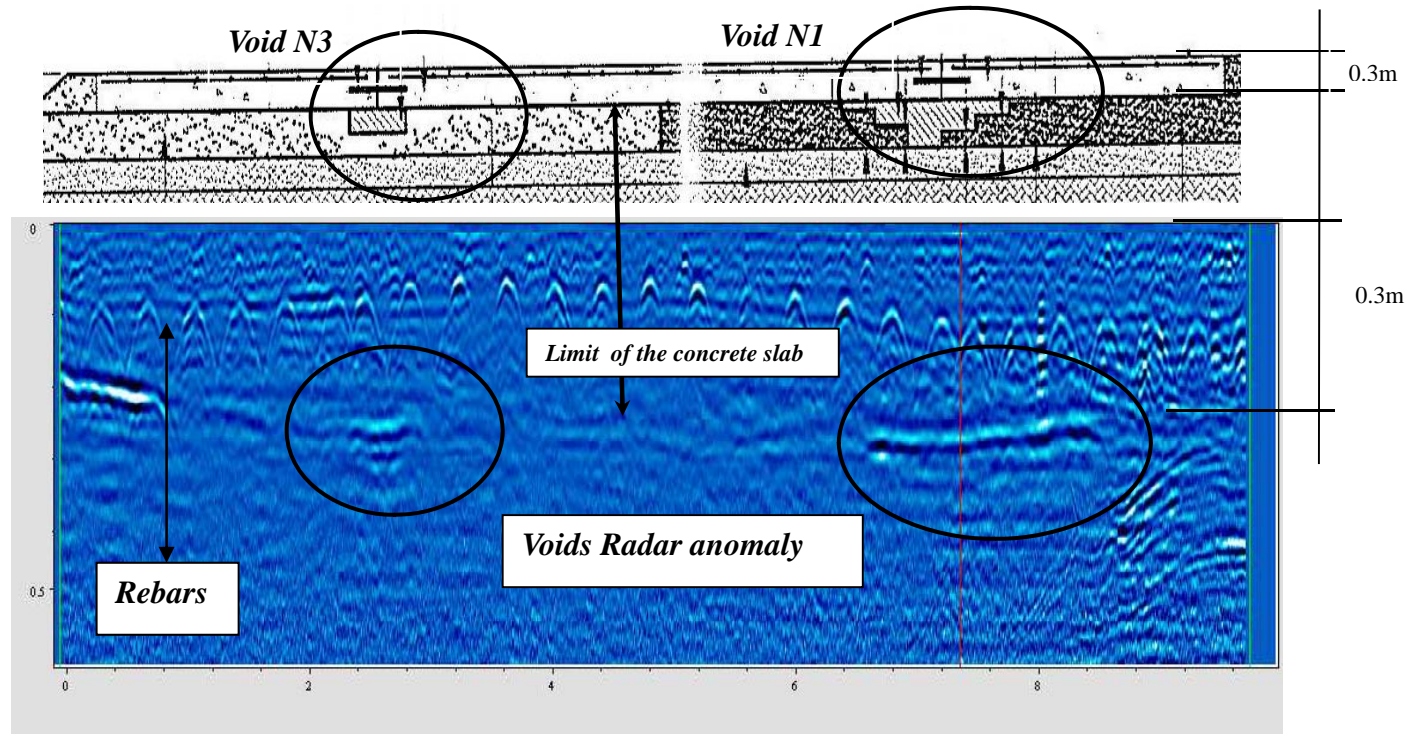
Tets site in the *Asian Institute of Technology*

Indagine GPR su un test site in cemento della *Highways Department of Bangkok* per valutare:

- La presenza e la posizione di vuoti sotto lo strato di cemento
- La presenza e la posizione dei ferri di armatura nello strato di cemento

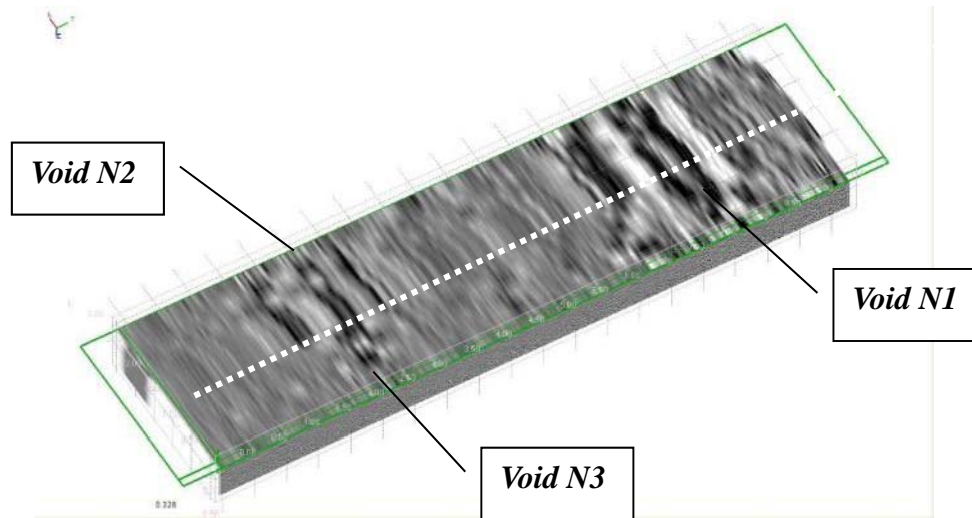
Configurazione Usata: Sistema con antenna a 2 GHz

Indagine GPR con antenne ad alta frequenza per localizzare vuoti sotto lo strato di cemento (3/4):



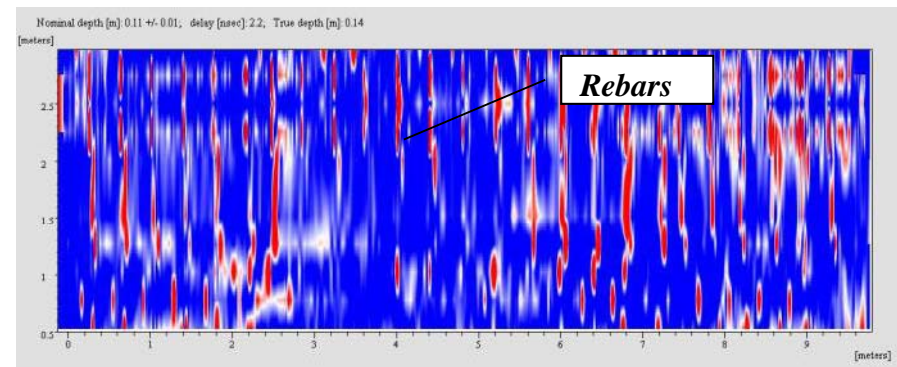
Mappa radar a 2Ghz comparata con il disegno schematico della struttura;

Indagine GPR con antenne ad alta frequenza per localizzare vuoti sotto lo strato di cemento (4/4):



Vista 3D tagliata a 32cm di profondità che mostra la presenza di 3 anomalie create da vuoti

Time slice con le anomalie create dai ferri nel cemento



Indagine GPR ad alta frequenza in AOT

Airports of Thailand Public Company (1/4)



Indagine GPR ad alta frequenza per la localizzazione dei ferri nel cemento (2/4):



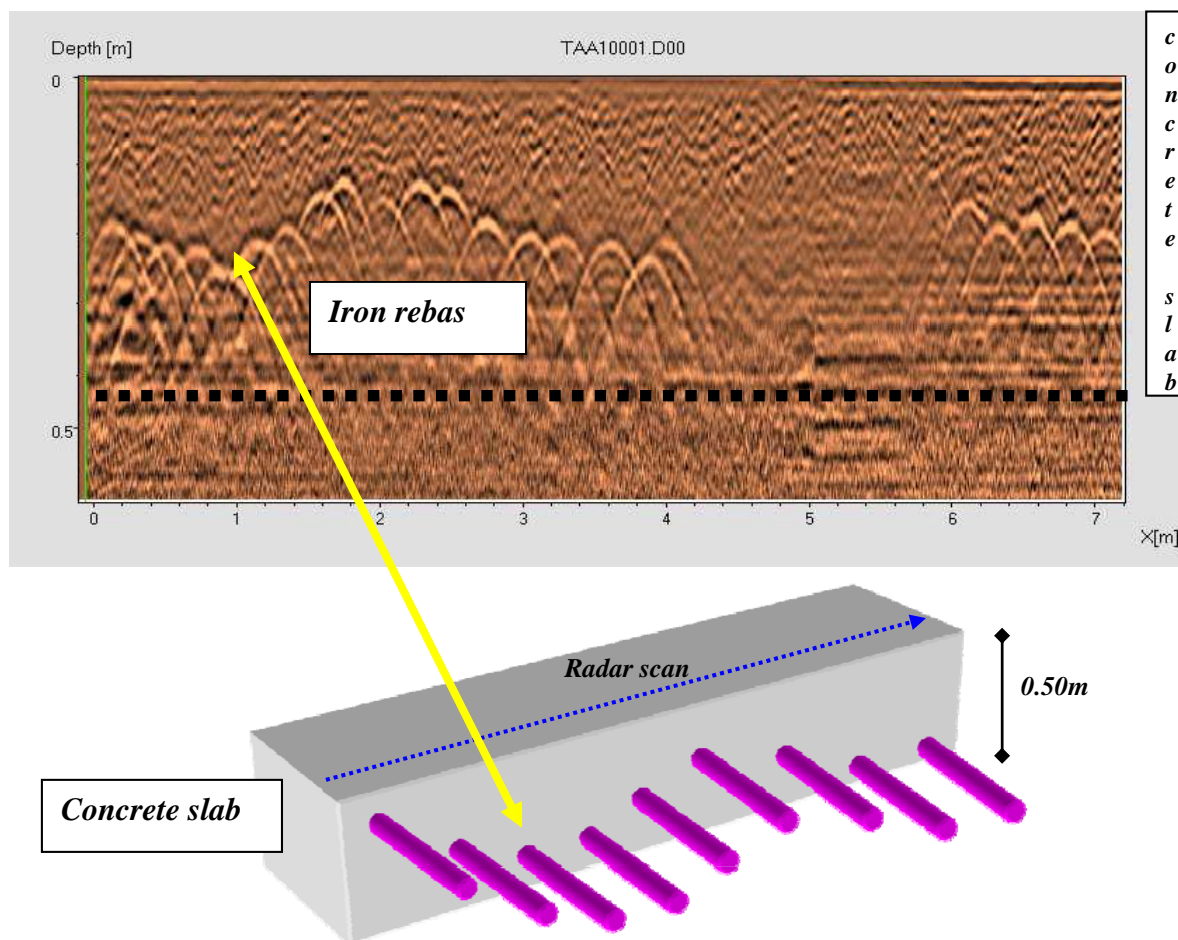
Test site in the International Airport of Bangkok

Indagine GPR nell'area test di *Airports of Thailand Public Company* **per valutare:**

- La presenza e la posizione dei ferri nel cemento

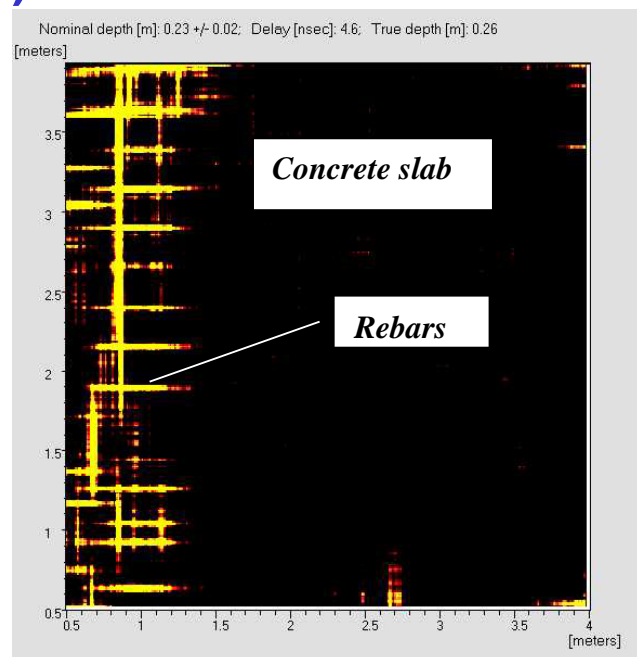
Configurazione Usata: Sistema con antenna a 2 GHz

Indagine GPR ad alta frequenza per la localizzazione dei ferri nel cemento (3/4):



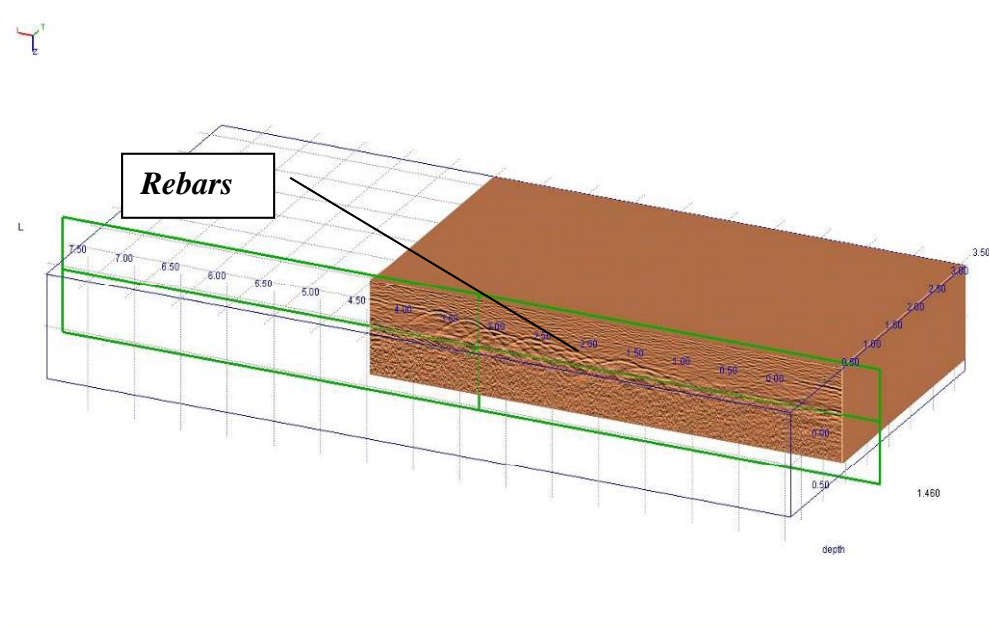
**Mappa radar a 2GHz acquisito lungo la giunzione di due slab di cemento;
ferri a diversa profondità**

Indagine GPR ad alta frequenza per la localizzazione dei ferri nel cemento (4/4):



Time slice, anomalie generate dai ferri nel cemento

Viosta 3D con le anomalie generate dai ferri

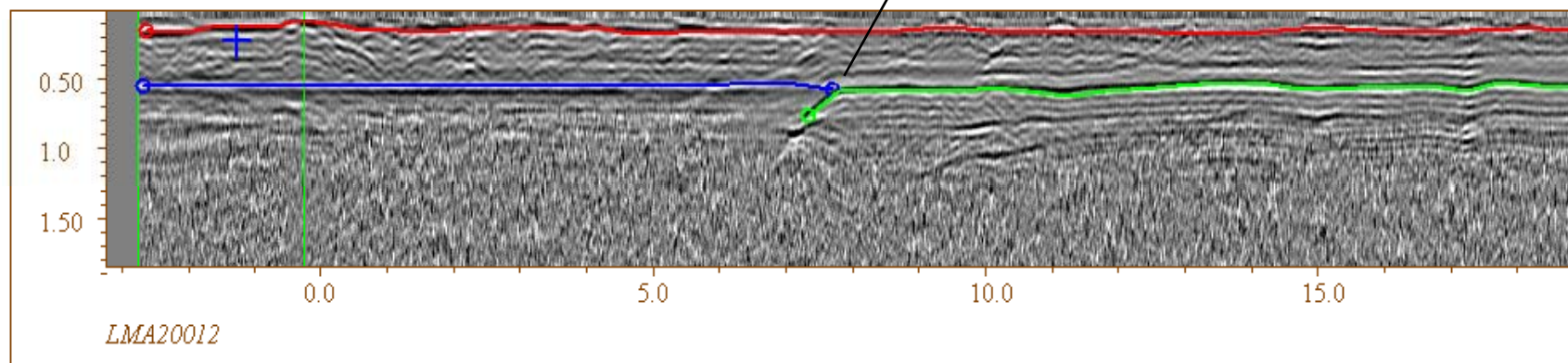


Maiquetía Airport - VENEZUELA



Fratture nell'asfalto

La mappa radar mostra la presenza di fratture nell'asfalto e nello strato sottostante (fino ad 1 m di profondità)

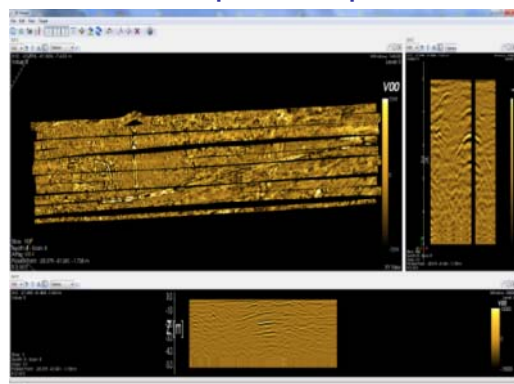


Mappatura estesa delle reti sottoservizi: Stream-EM

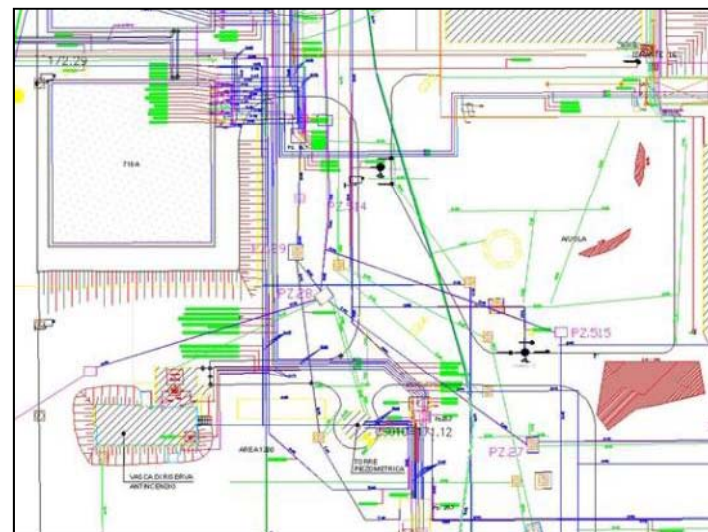
Un sistema georadar trainato da veicolo (fino a 15 km/h) consente la mappatura veloce delle reti sottoservizi senza degrado delle prestazioni



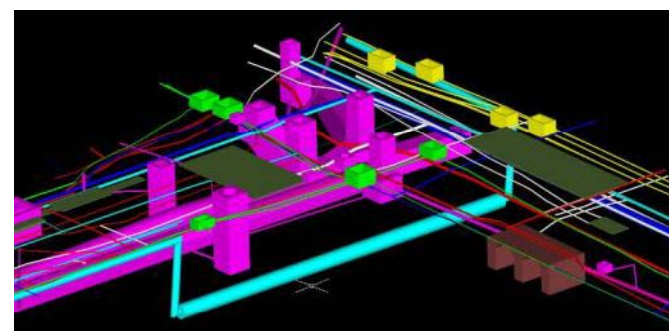
1. Stream EM per l'acquisizione dei dati radar



2. Elaborazione di dati



3. Cartografia delle reti esistenti

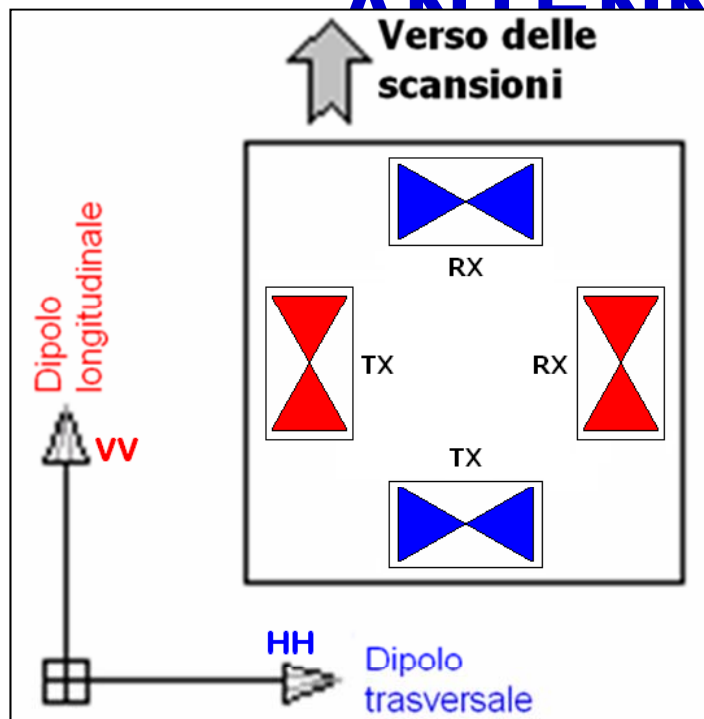


3. Rappresentazione 3D delle reti rilevate

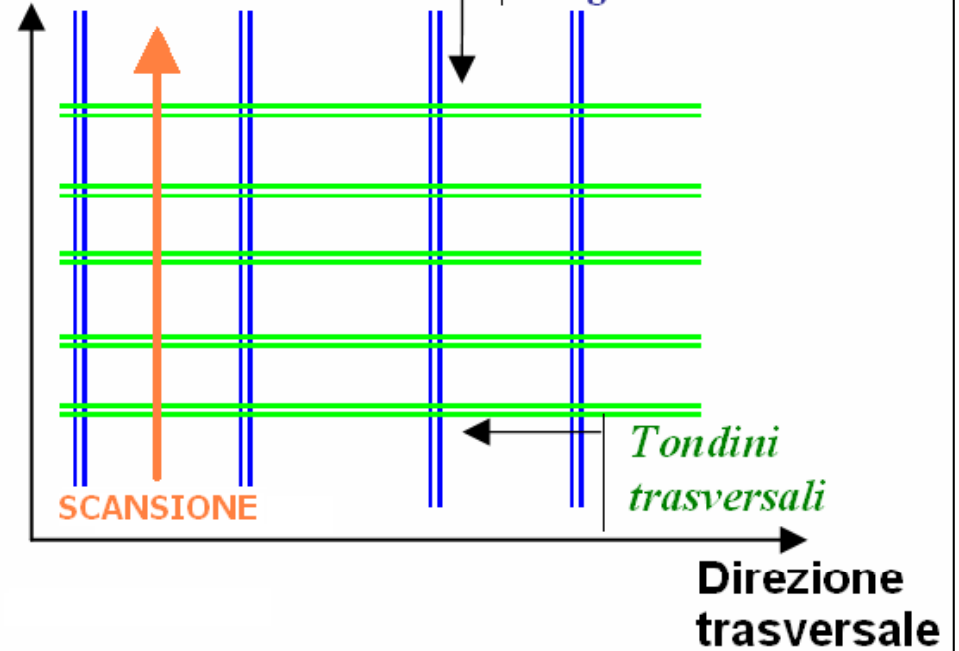


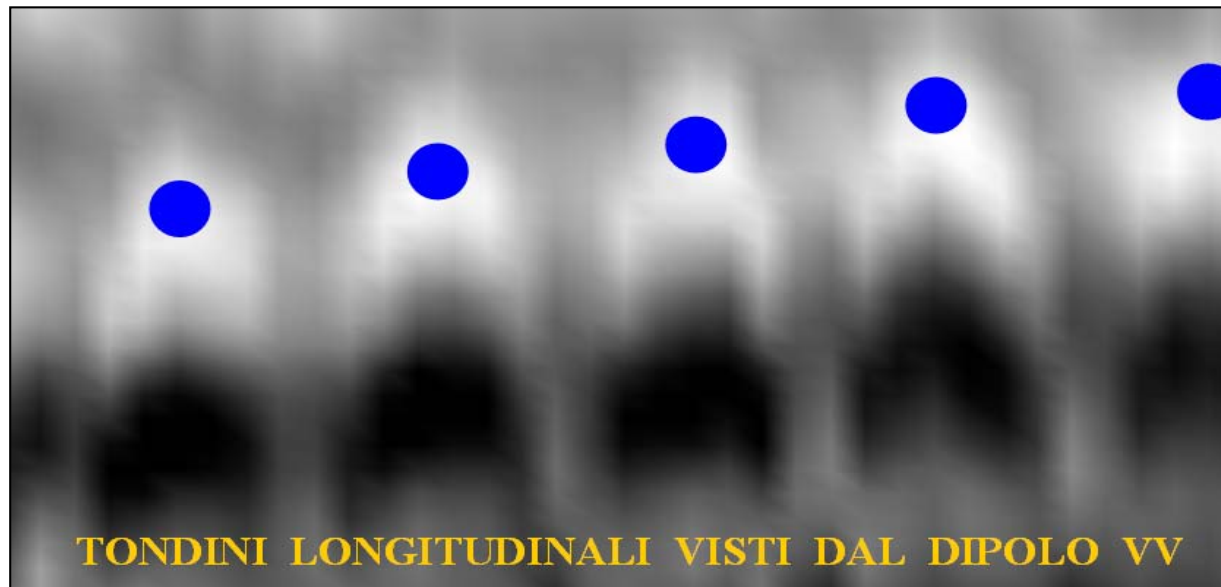
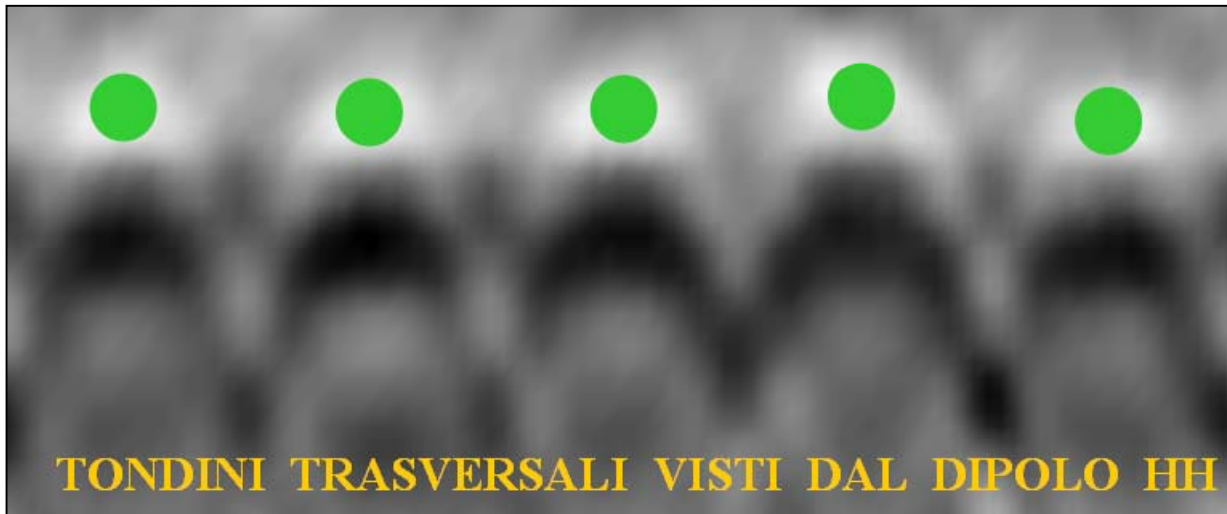
APPLICAZIONI PER L' INGEGNERIA CIVILE

ANTENNA

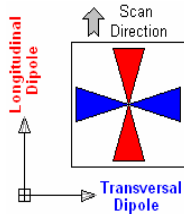


Direzione
longitudinale





FULL POLAR antenna (2000 MHz)

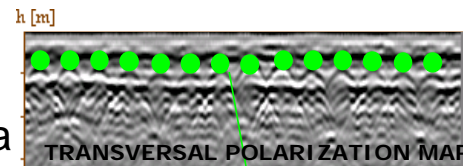
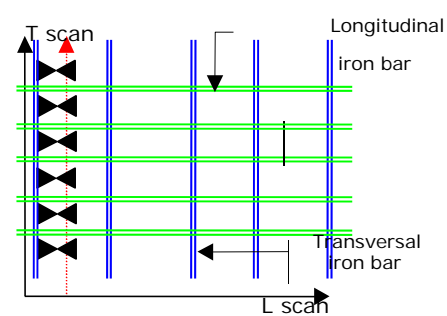


The **ALADDIN** features the **unique** high-frequency (2 GHz) antenna **with two polarizations** (transversal and longitudinal).

It permits to acquire joint orthogonally polarized scans in one pass, improving images of the shallow and deep structures.

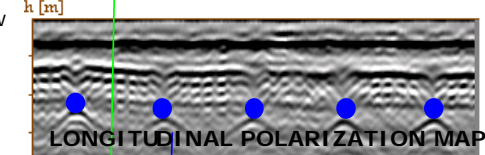
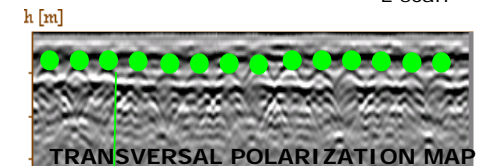
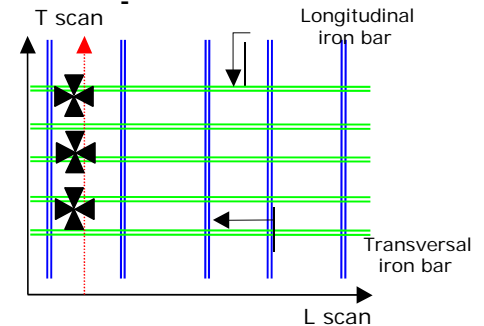
ALADDIN includes the multi-channels radar control unit that can be connected with all the IDS antennas

STANDARD TECHNOLOGY

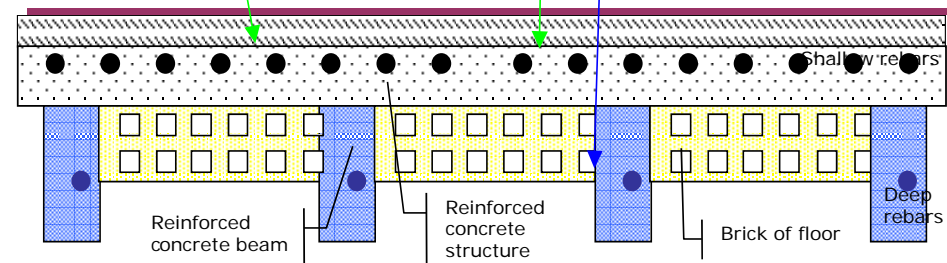


The standard antenna can read the shallow target (rebars), but is not able to reveal lower structures.

FULL POLAR TECHNOLOGY



Instead the FULLPOLAR antenna is able to identify both targets (shallow and deep) in only one scan.



Example of a reinforced concrete hollow tile floor.

Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (1/4):



Sao Paulo (Brasil)

Indagini GPR su strutture nella stazione Metro di Sao Paulo (Brasil) Metro per valutare:

- La presenza e la spaziatura dei ferri nelle colonne.
- La presenza e la spaziatura dei ferri e/o tiranti.

Strumentazione utilizzata: Sistema con antenna Bipolare a 2 GHz

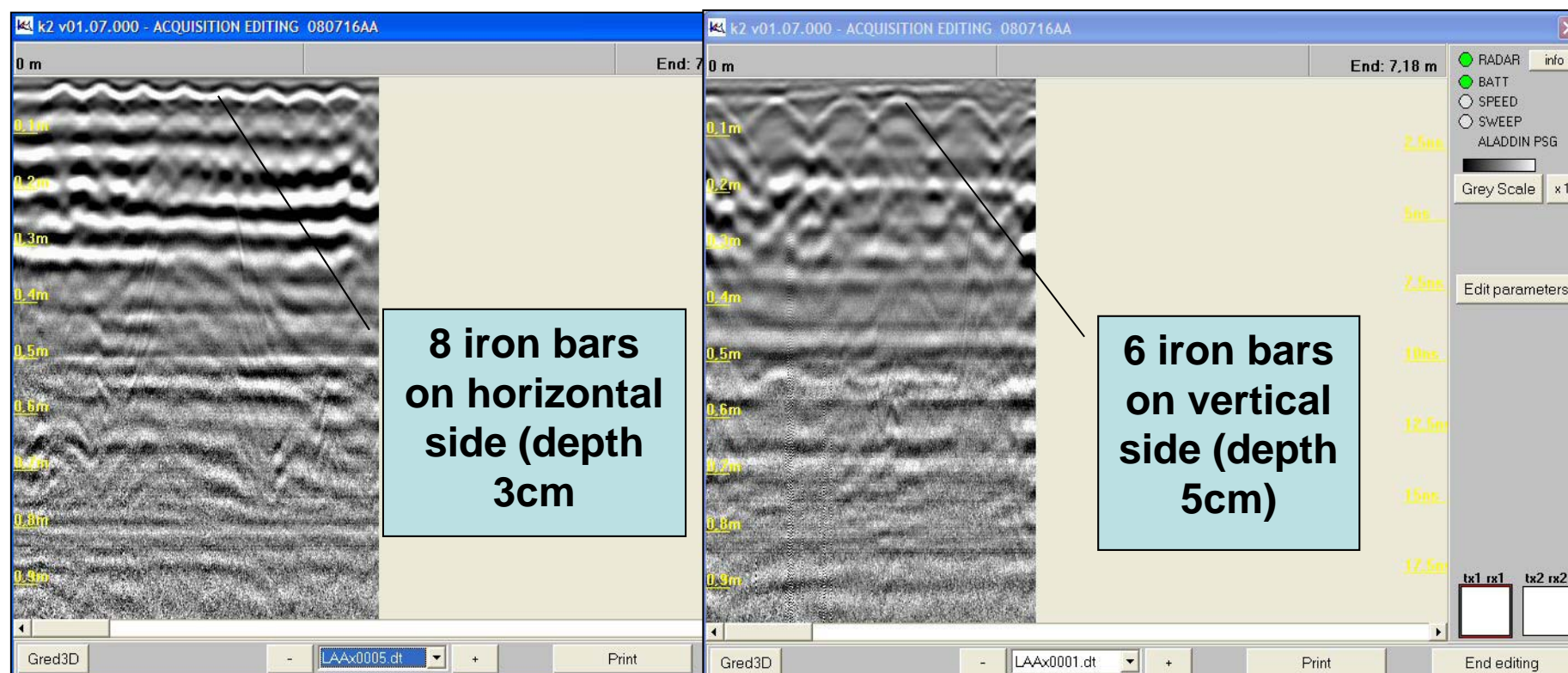
Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (2/4):

Fase di acquisizione: Sao Paulo (Brasil) Metro Line



Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (3/4):

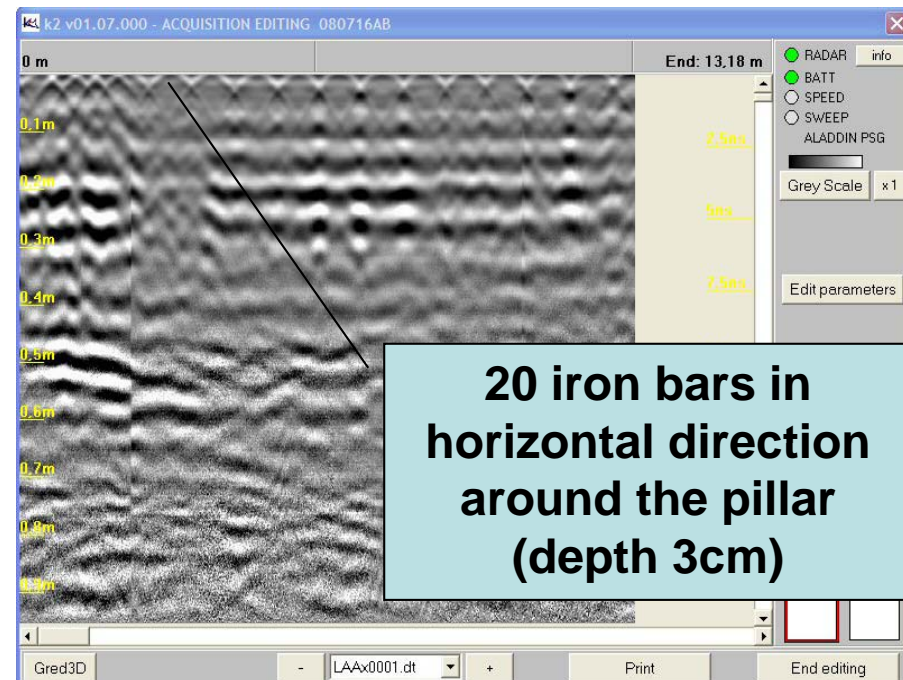
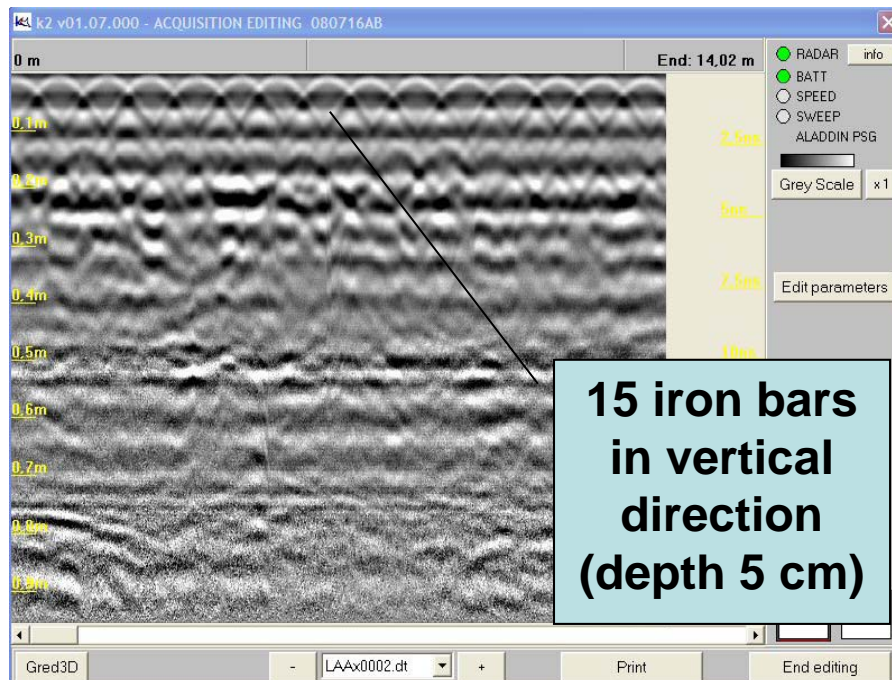
Mappe Radar che evidenziano la presenza e la spaziatura dei ferri di armatura



Spaziatura orizzontale tra i ferri: 20-25cm

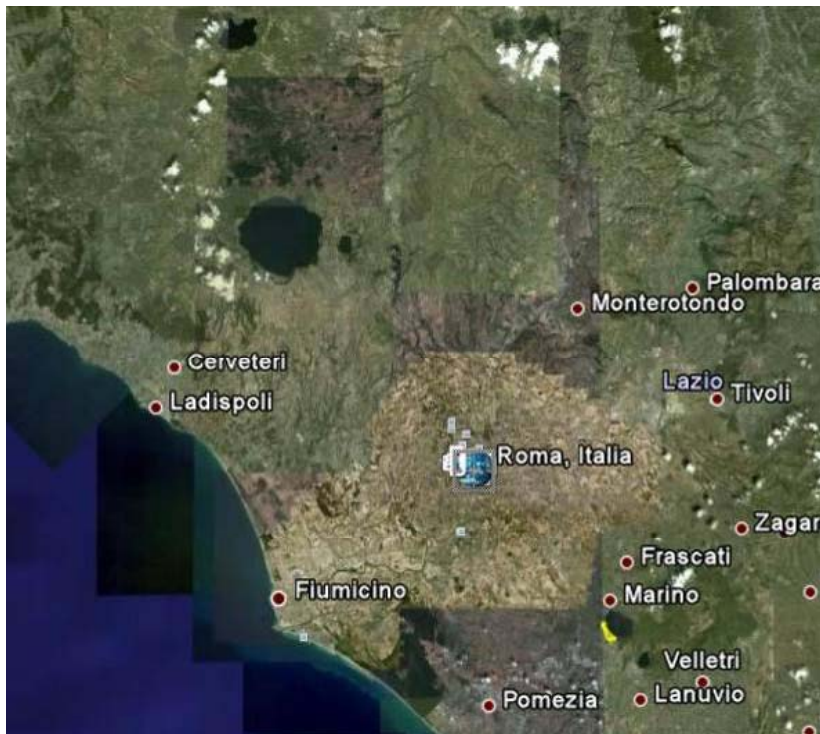
Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (4/4):

Mappe Radar che evidenziano la presenza e la spaziatura dei ferri di armatura nella colonna



Doppia linea di armature. Spaziatura orizzontale: 10-20cm

Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (1/3):



Rome, Italy

Indagini GPR su un sito test lungo la linea Metro di Roma per valutare:

- La presenza di vuoti e cavità dietro lo strato di cemento.

Configurazione usata: sistema con antenne a 900MHz e 2GHz

Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (2/3):

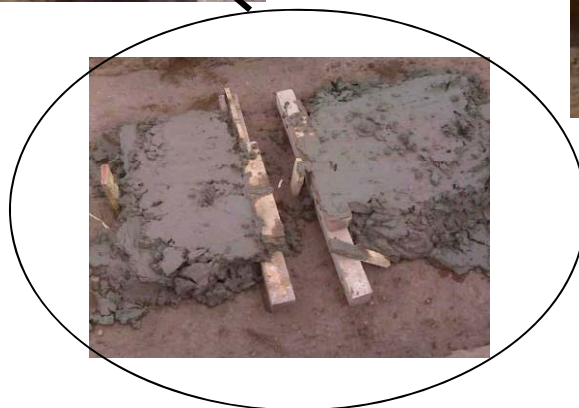
Fase di acquisizione: test site lungo la linea Metro di Roma (nuova linea)



Concrete layer

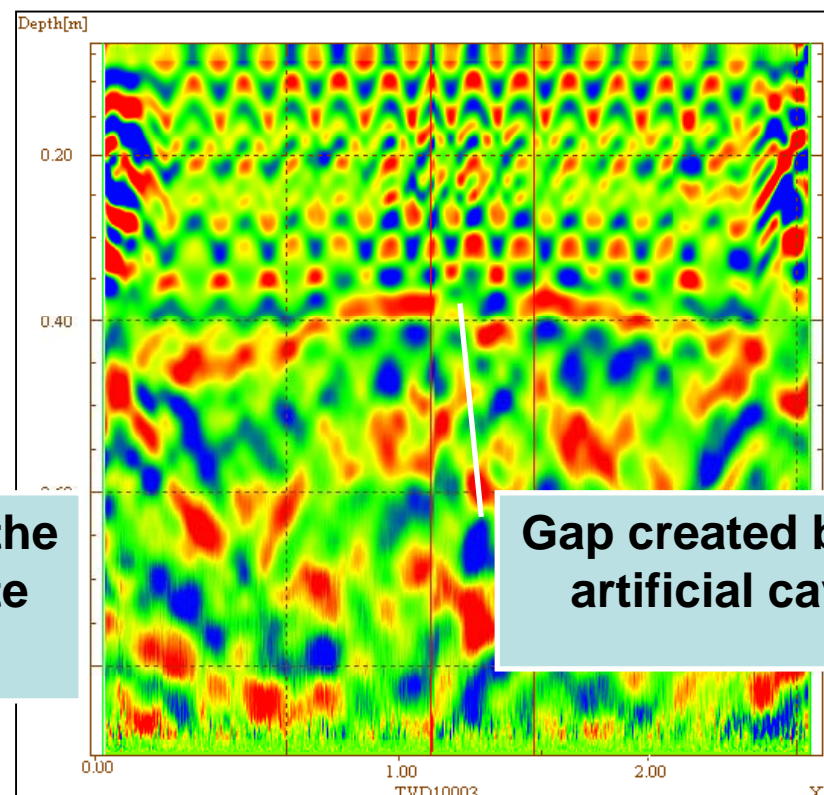
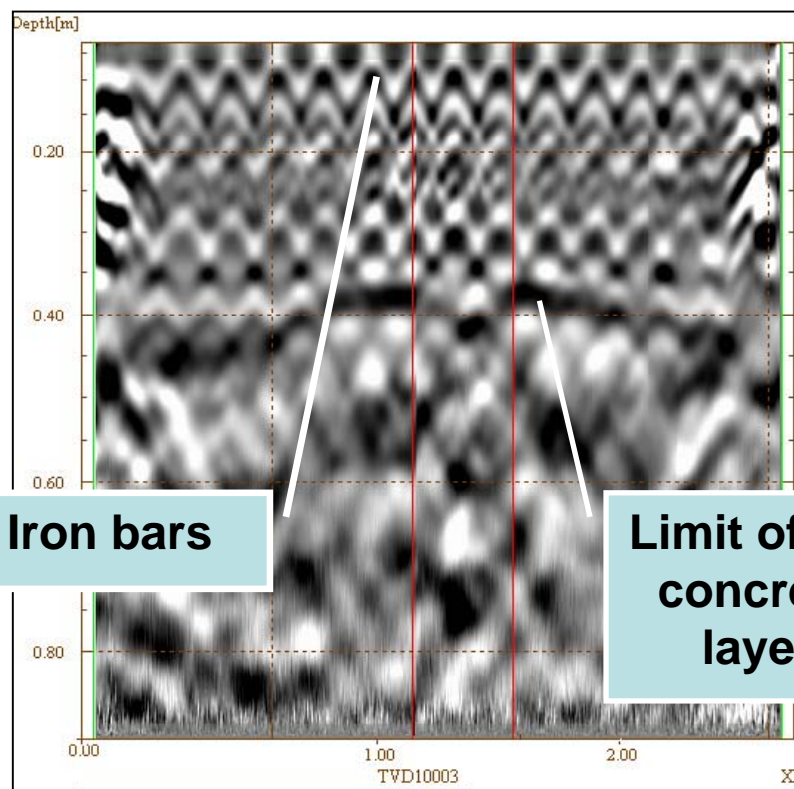


Artificial cavity



Indagini GPR con antenne ad alta frequenza per applicazioni strutturali (3/3):

Risultati



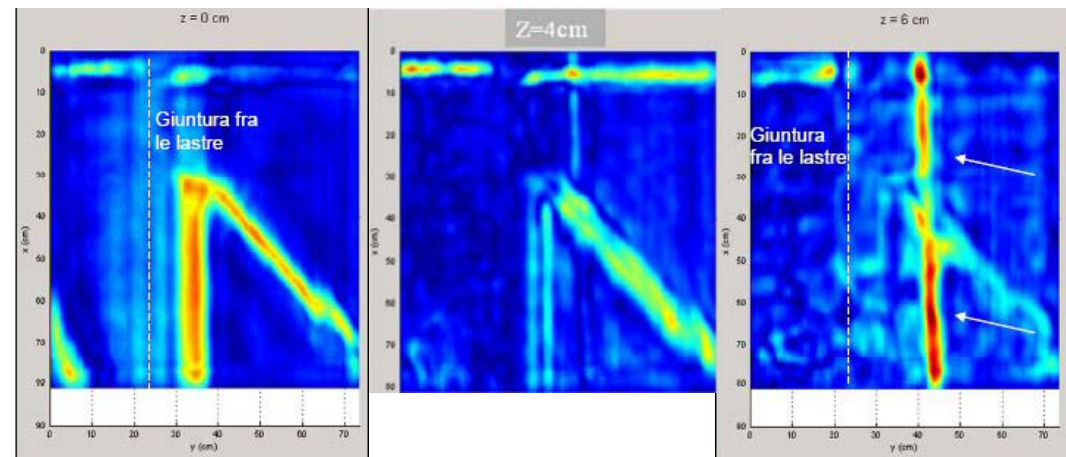


Teatro DONIZZETTI- Bergamo (Italy)

(by Polytechnic of Milan)

Indagine strutturale sulla facciata del teatro per la localizzazione di un sistema di fratture.

Sistema utilizzato: georadar con antenna bipolare a 2 GHz.
Dimensioni dell'area test: 1 x 2 m
Tempo di acquisizione 20 min .



Z = 0 cm

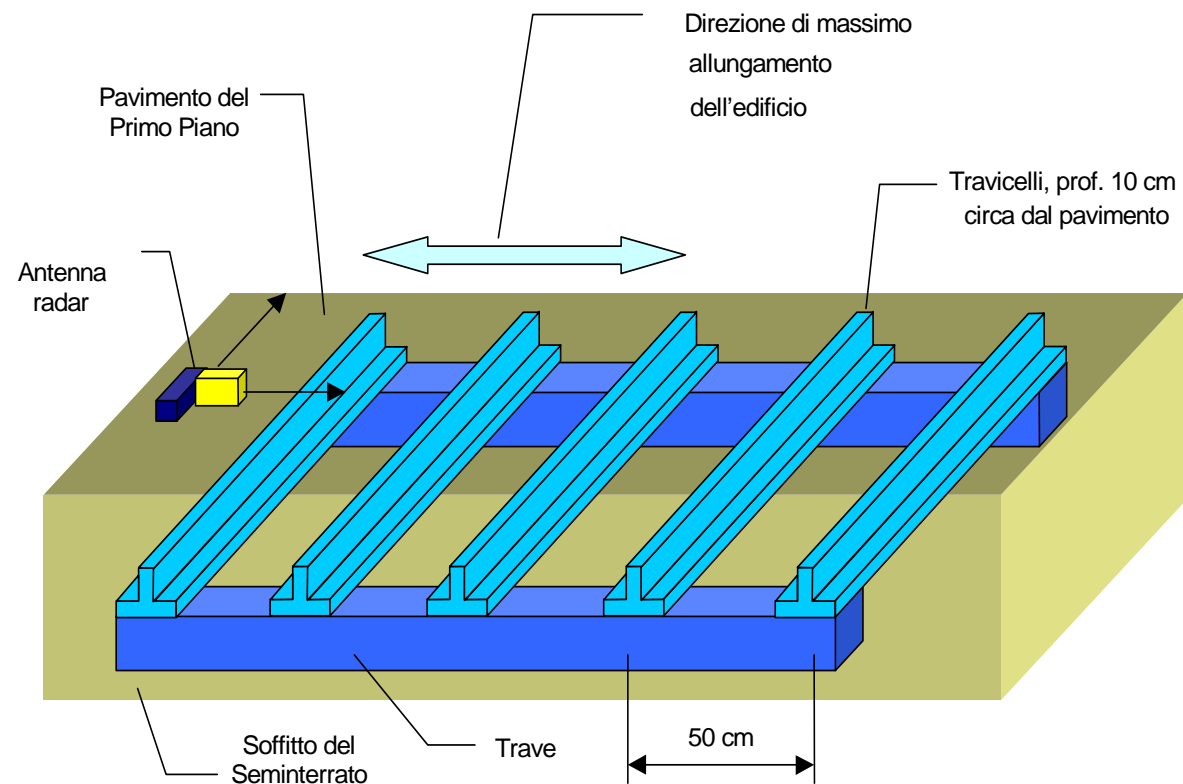
Z = 4 cm

Z = 6 cm

UN EDIFICIO DELL'AEROPORTO DI MILANO - LINATE:

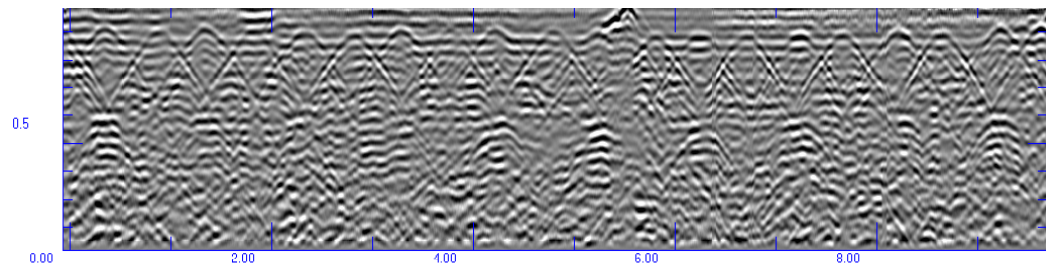


- esempio di verifica della disposizione degli elementi strutturali



**Ricostruzione 3D
della disposizione
degli elementi**

**Sezione radar di
riferimento**

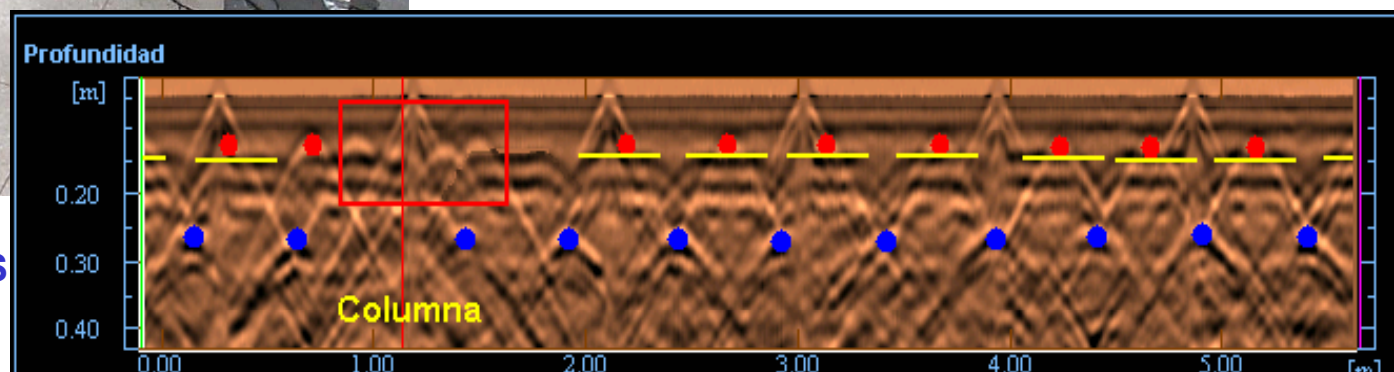


Indagini GPR su pavimento

Localizzazione di due livelli di armatura



REINFORCED BARS



Indagini GPR con antenna da foro per il controllo di Dighe (1/2):



Badana Dam – Genova Italy

Problemi strutturali sulla Diga di Badana
Genova -Italy:

- Presenza di fratture nella diga.
- Infiltrazione di acqua.
- Configurazione Usata; sistema GPR con antenna BoreHole da 300 MHz



Badana Dam – Genova Italy

Indagini GPR con antenna da foro per il controllo di Dighe (2/2):

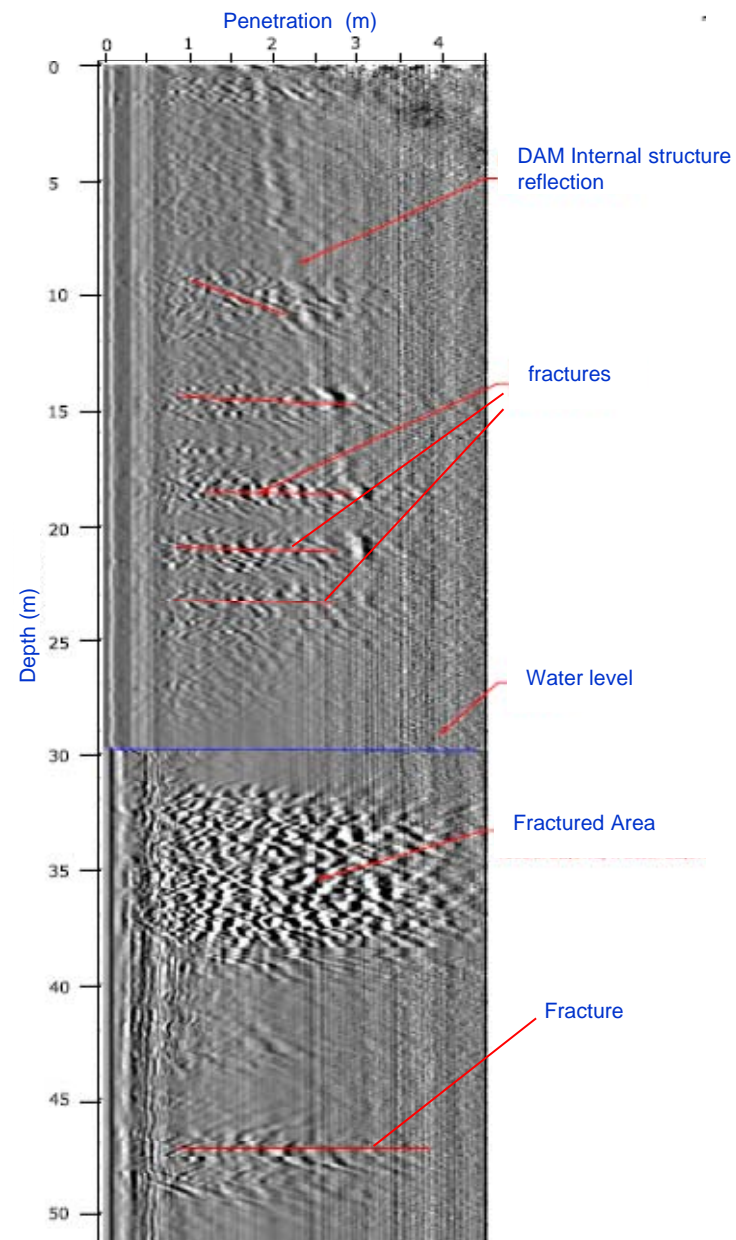
Field Acquisition Phase



Survey Wheel

Tripod

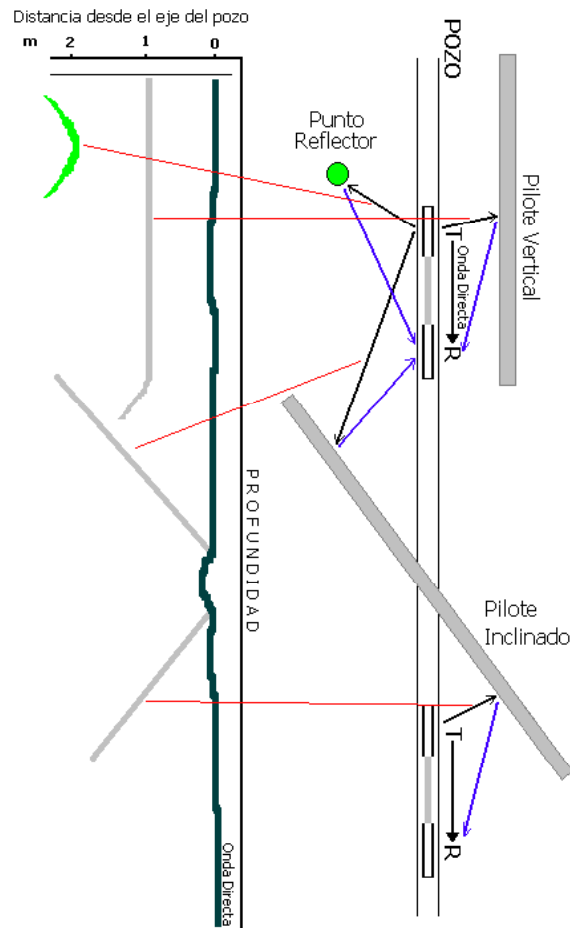
Bore- Hole Antenna 300 MHz



Indagini Borehole per applicazioni geotecniche (1/2)

Indagini Borehole per il controllo di pali in
Caracas – Venezuela:

- Valutazione della profondità del palo.
- Valutazione dell'integrità del palo.
- Configurazione usata: sistema GPR con antenna borehole da 300 MHz



Sketch of GPR Bore Hole Technique

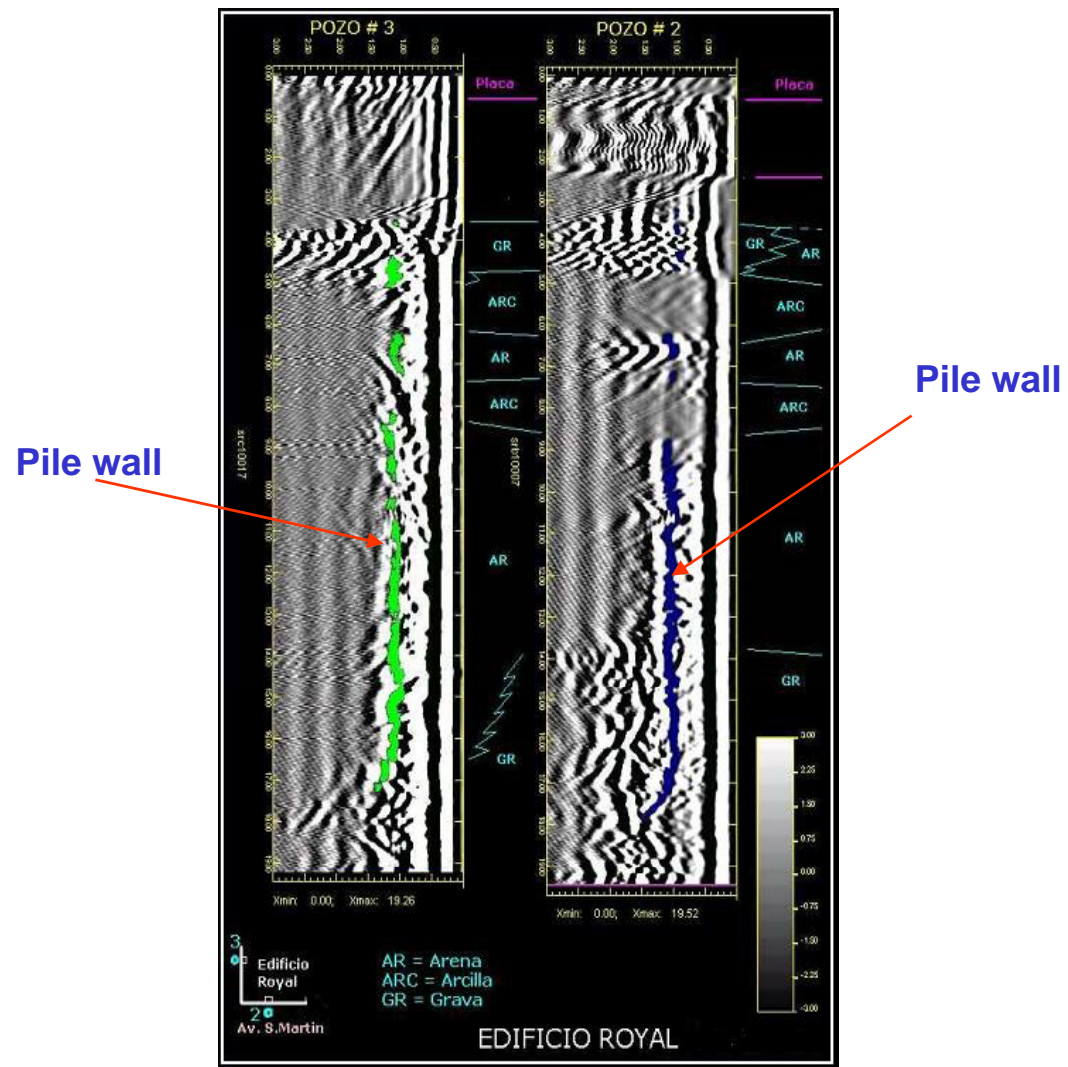


Caracas - Venezuela

Indagini Borehole per applicazioni geotecniche (2/2)

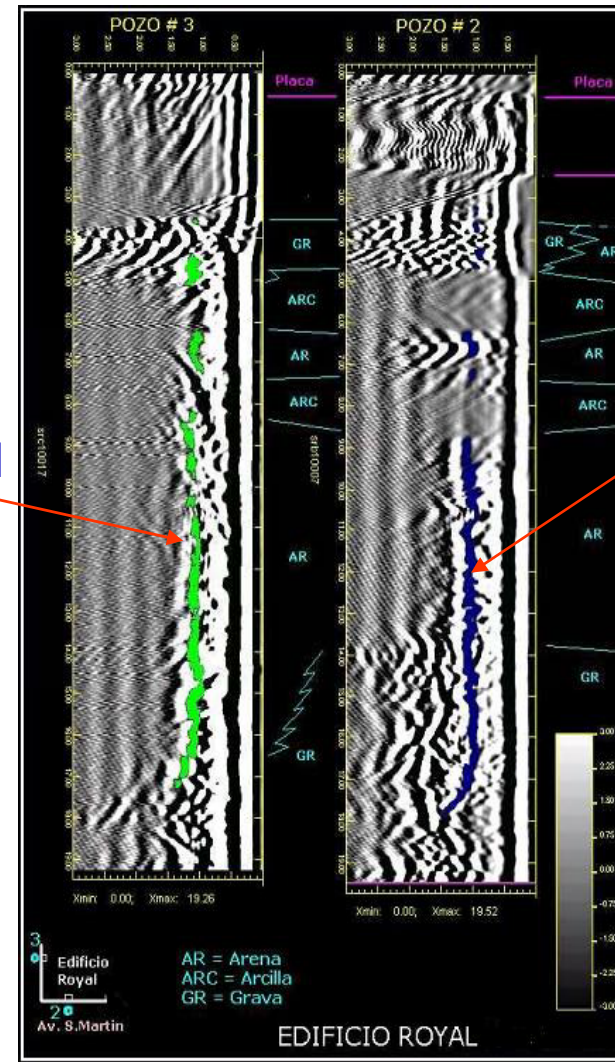
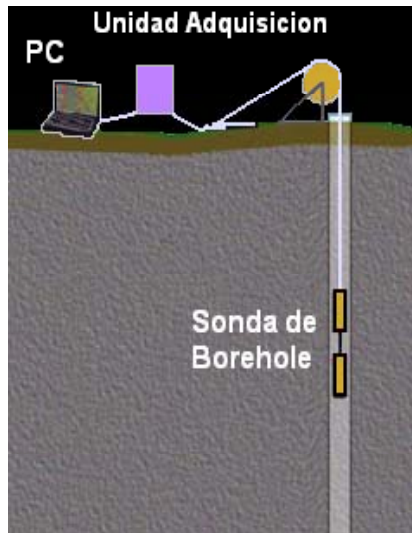


Hole for GPR investigation
Edificio Royal



Bore Hole Results

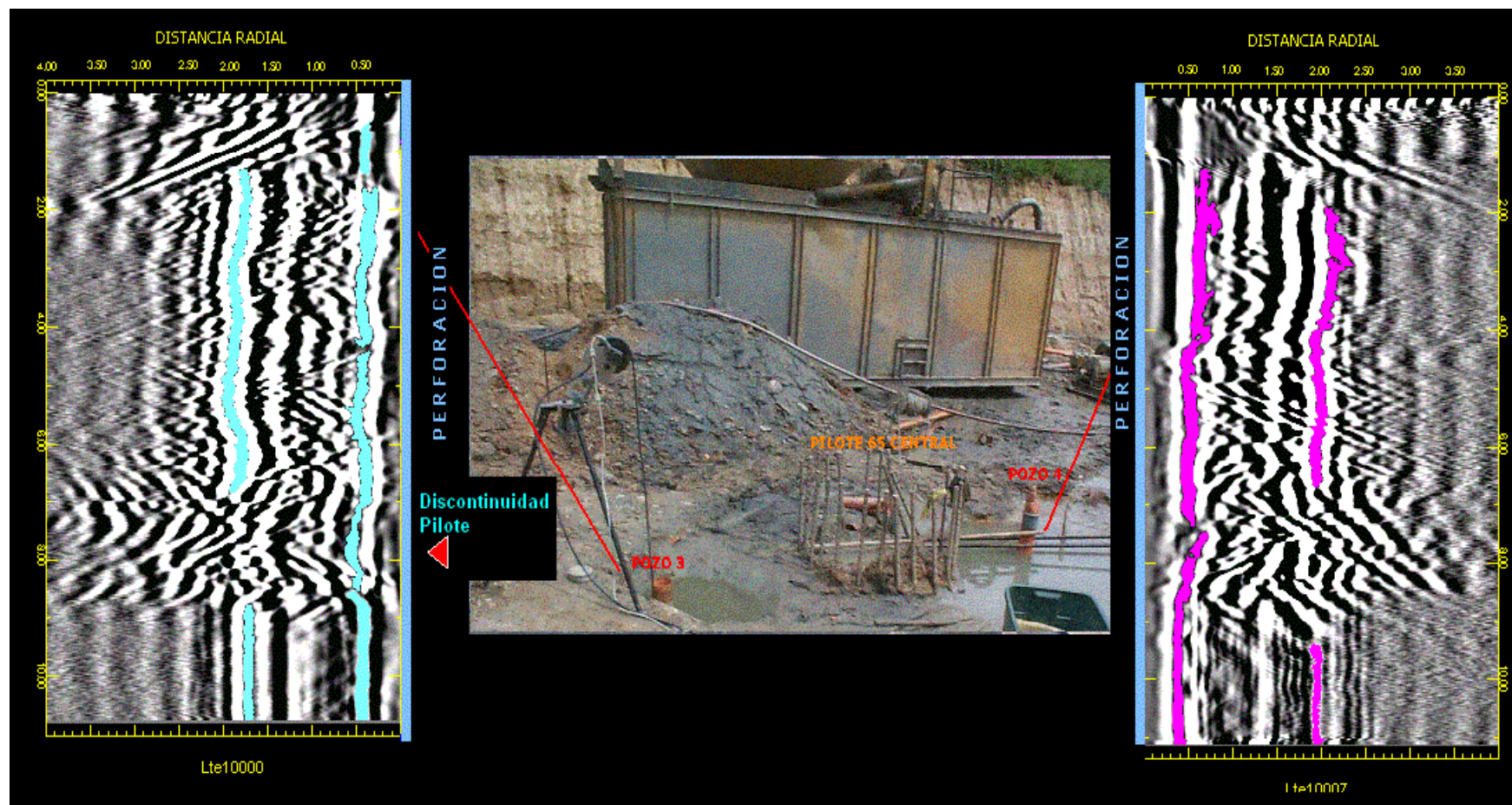
Profondità ed integrità dei pali



Pile wall

Profondità ed integrità dei pali

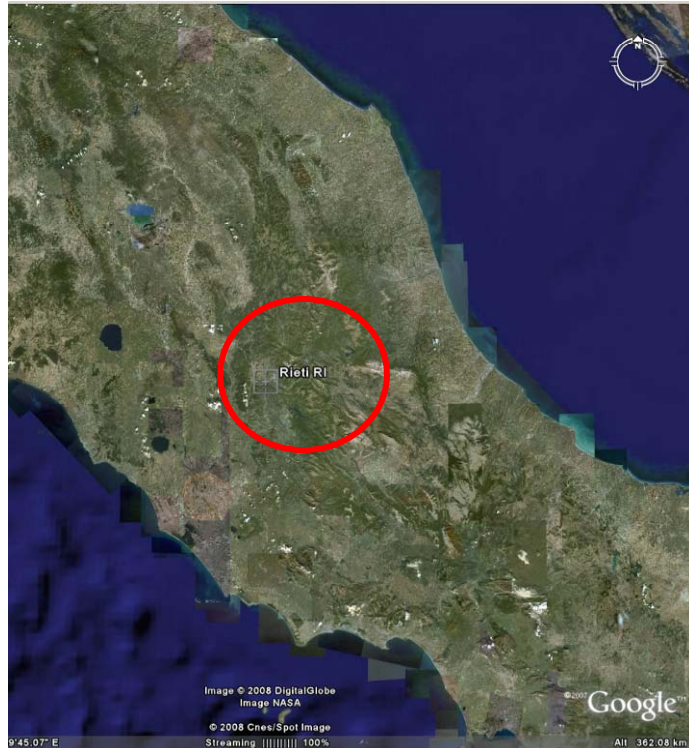
Ricostruzione della Parete dei pali e localizzazione di eventuali discontinuità





TUNNEL e PONTI

Indagini GPR Borehole in tunnel (1/2):

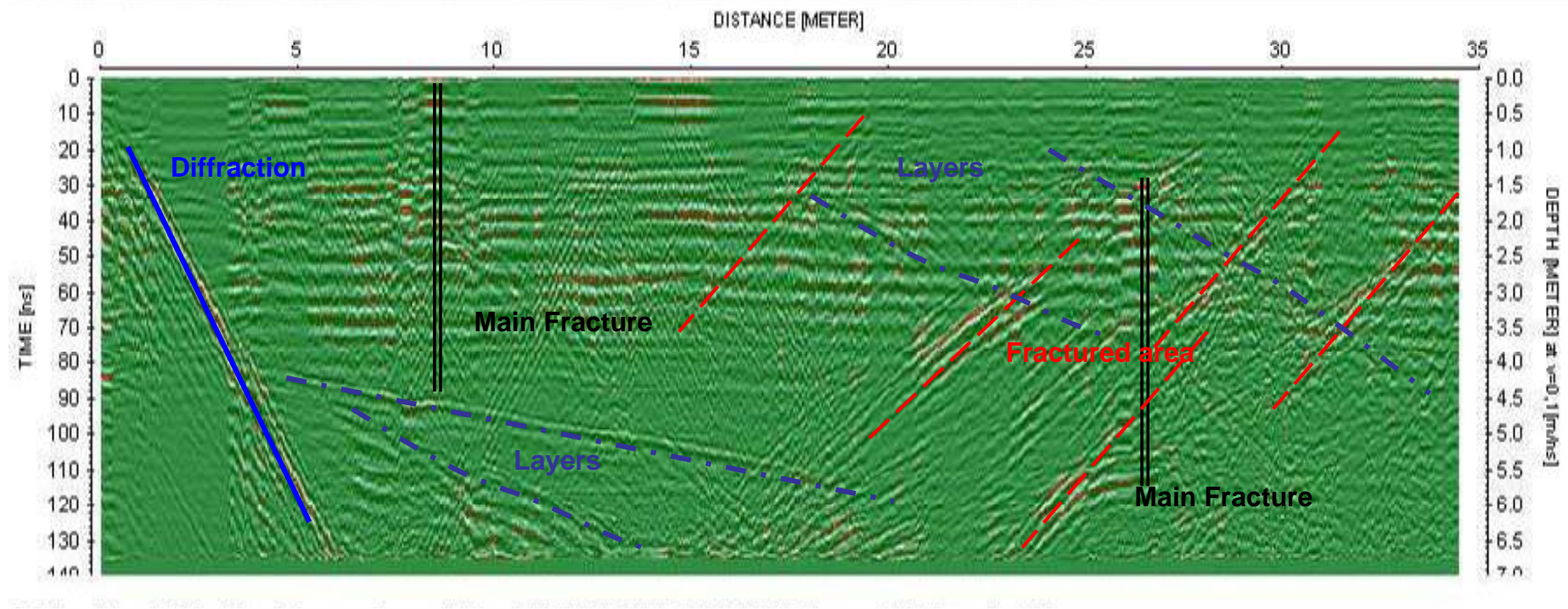


Rieti area-Italy

Presenza di problemi strutturali in un tunnel lungo la linea ferroviaria tra Terni e Rieti - Italy:

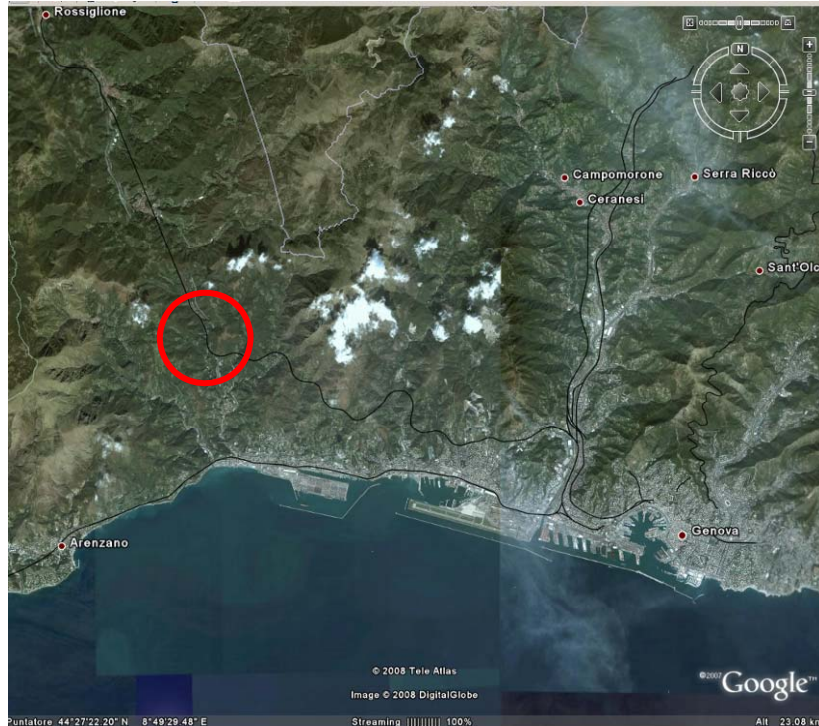
- Presenza di fratture nella struttura del ponte e nella roccia
- Presenza di stratificazione nella roccia
- Configurazione usata: Antenna Borehole a 150 MHz – Acquisizione Orizzontale

Indagini GPR Borehole in tunnel (2/2):



Bore Hole Results

Indagini GPR in un Tunnel ferroviario (1/2)



**Gorsexio tunnel along the rail line Genova-Ovada
(Italy)**

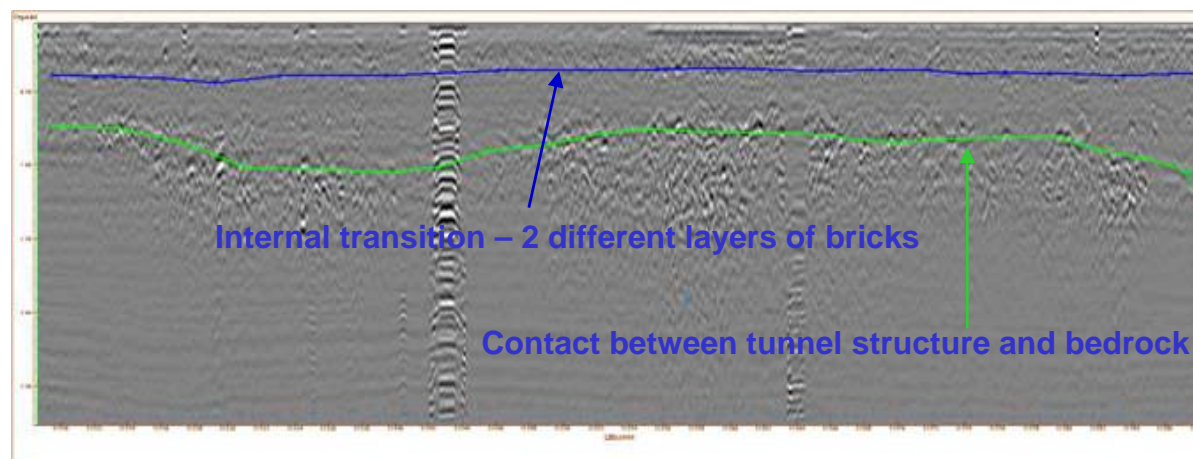
Applicazione Geotecnica nel Tunnel di Gorsexio lungo la tratta ferroviaria Genova-Ovada (Italy):

- Studio delle fratture, della stratigrafia e delle anomalie per valutare la stabilità della struttura e le aree a rischio di infiltrazioni di acqua.
- Configurazioni usate: Sistema GPR con antenne a 200MHz e 600 MHz



Gorsexio Tunnel – Acquisition phase

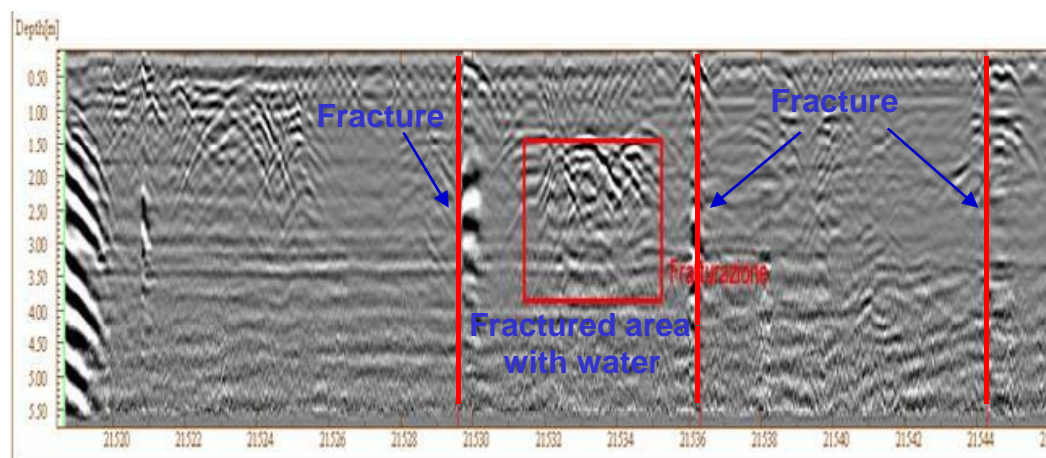
Indagini GPR in un Tunnel ferroviario (2/2)



600 MHz Results

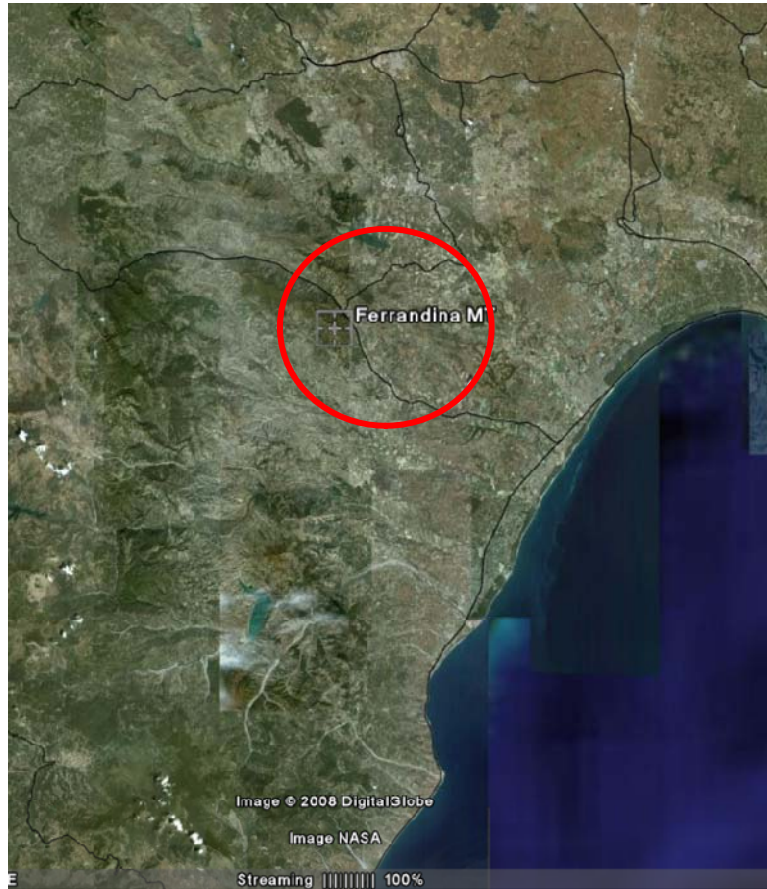


Gorsexio Tunnel
Acquisition phase



200 MHz Results

Indagini GPR in un Tunnel ferroviario (1/2)



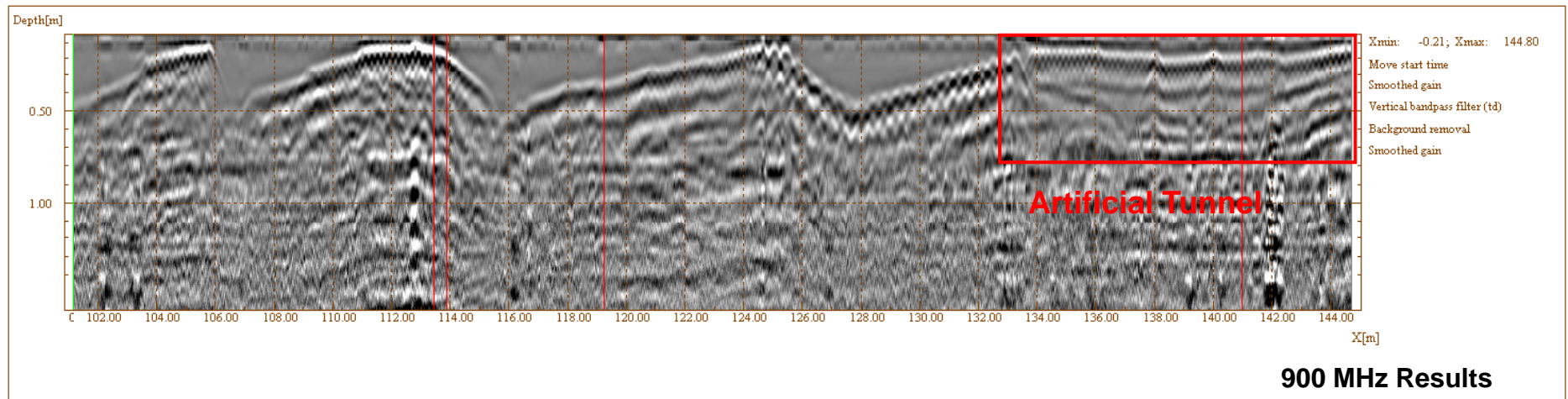
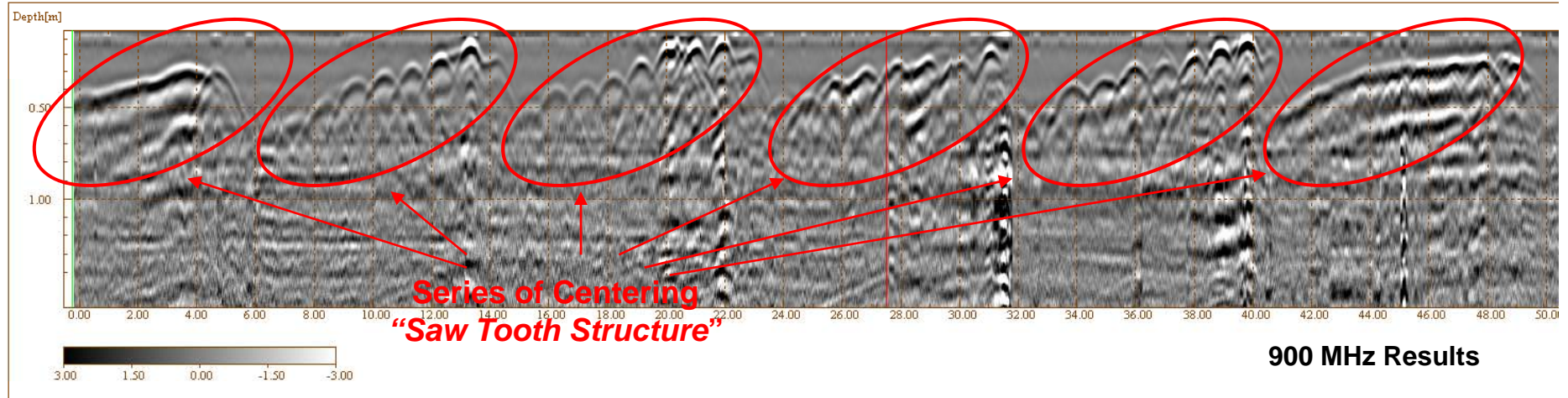
Ferrandina rail line (Italy)

Applicazioni Geotecniche in un Tunnel in costruzione lungo la tratta ferroviaria Ferrandina - Matera (Italy). La tecnica GPR ha permesso di valutare:

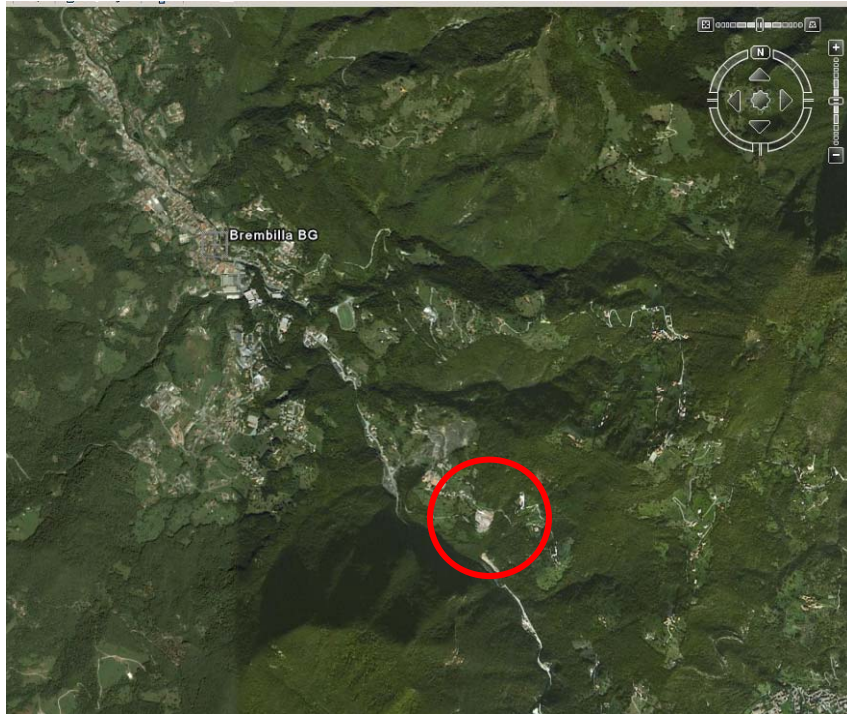
- La presenza di centine nel tunnel (numero e profondità) con una struttura a “dente di sega”
- La presenza della galleria artificiale

Configurazione Usata: Sistema GPR con antenna a 900MHz

Indagini GPR in un Tunnel ferroviario (2/2)



Indagine GPR a bassa frequenza in una galleria di servizio di una cava (1/2)



Brembilla Quarry -Italy

Applicazione Geotecnica in un tunnel nella cava di calcare di Brembilla (Bergamo)-Italy:

- Studio delle fratture e della stratigrafia in un tunnel per la valutazione della stabilità delle pareti.
- Configurazione Usata: Sistema con antenna ad 80MHz

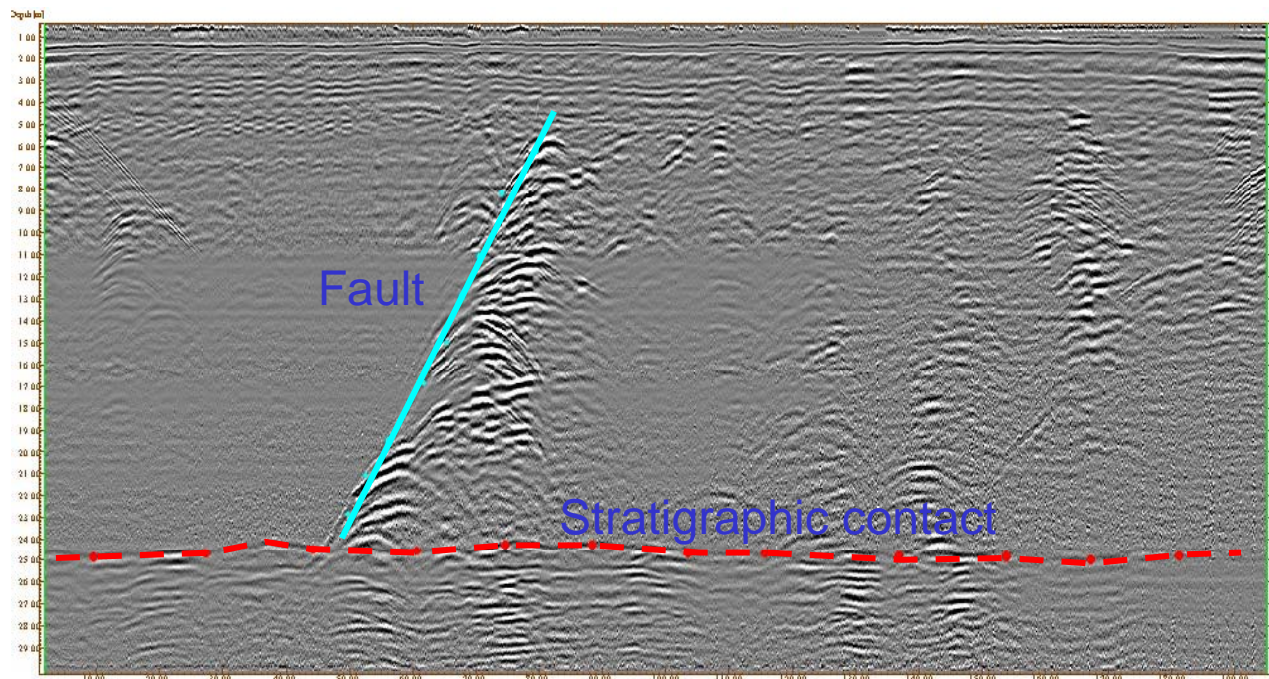


Brembilla Quarry – Italy

Indagine GPR a bassa frequenza in una galleria di servizio di una cava (2/2)



RIS Configuration with 80 MHz
Shielded Antenna- Acquisition Phase



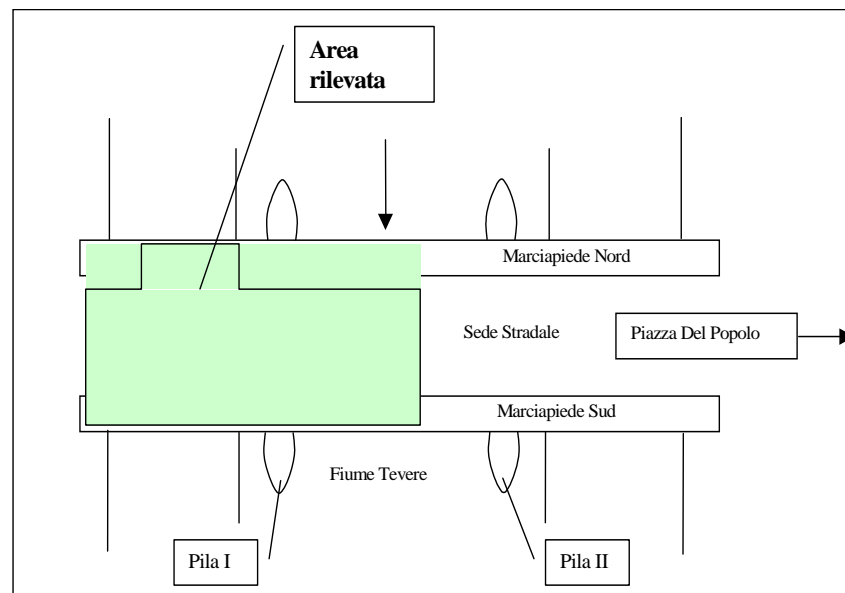
80 MHz Antenna Results

PONTE: REGINA MARGHERITA – ROMA (ITALY)



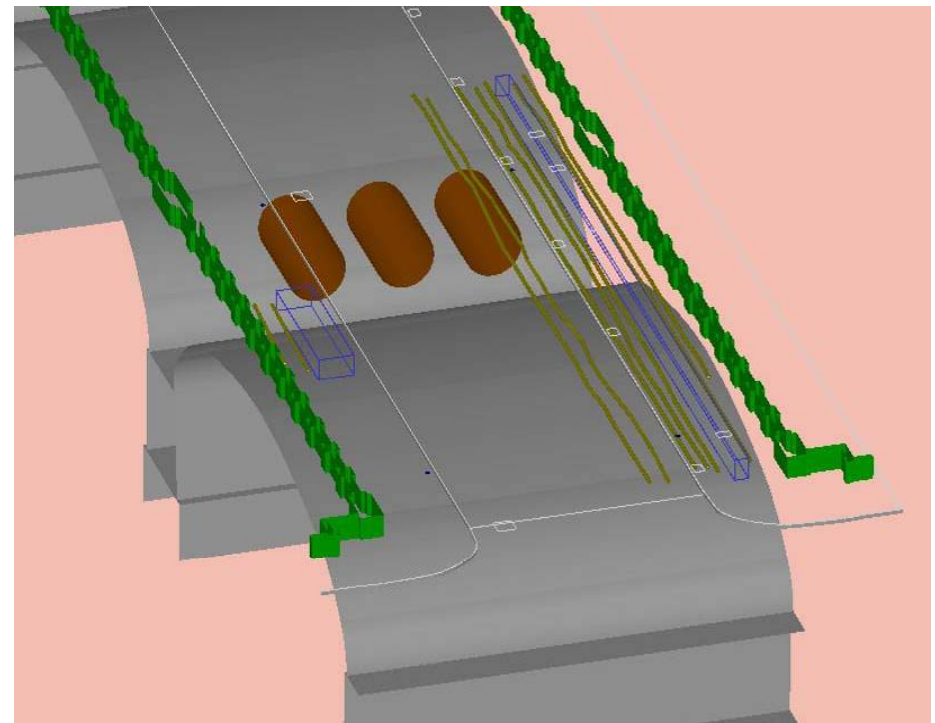
Luglio 2010

L'indagine sul ponte Regina Margherita

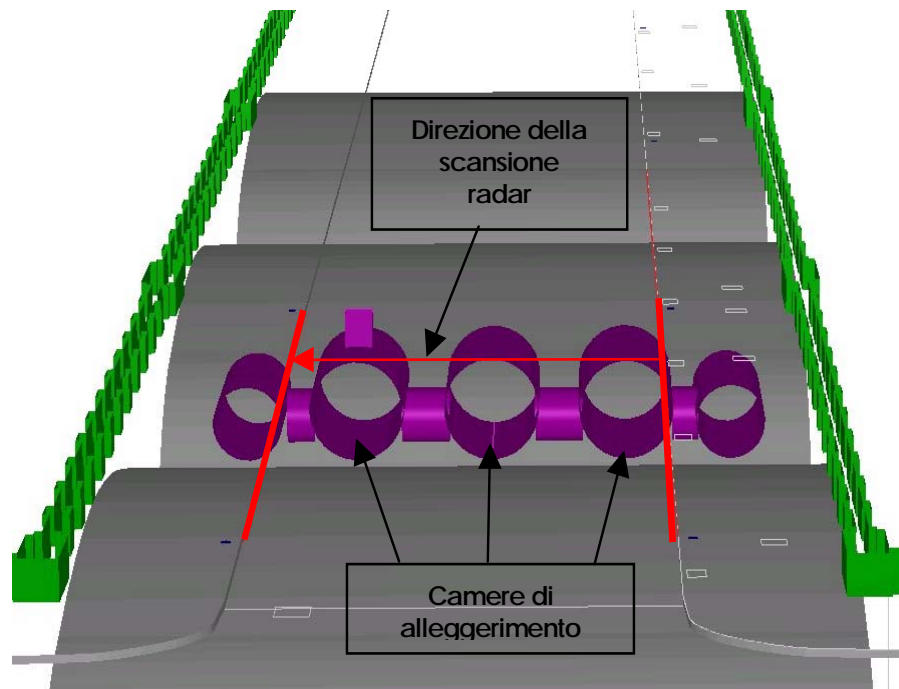


L'area di indagine sul ponte

I target rilevati



L'indagine sul ponte Regina Margherita



Sede stradale

